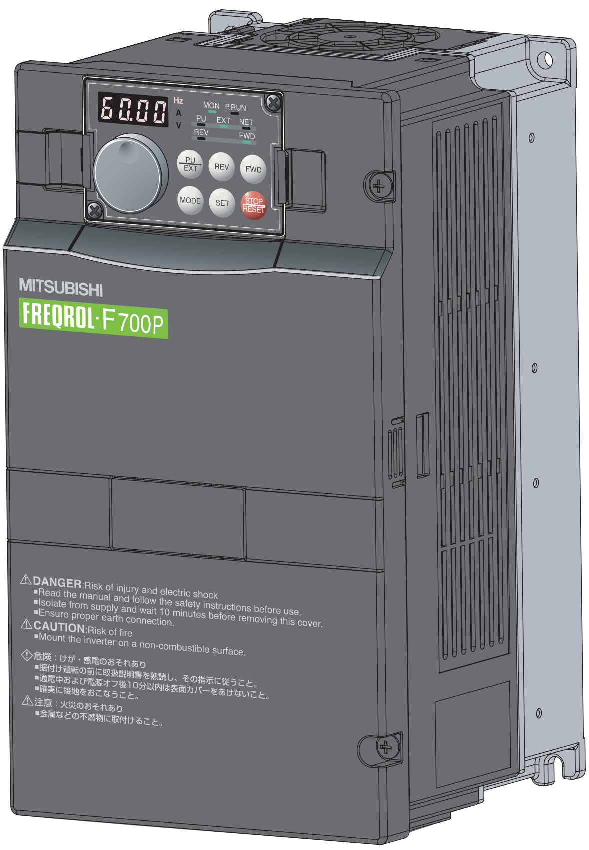
MITSUBISHI ELECTRIC

700 series

INVERTER
FR-F700P
INSTRUCTION MANUAL (Applied)

FR-F720P-0.75K to 110K
FR-F740P-0.75K to 560K



Thank you for choosing this Mitsubishi Inverter.
This Instruction Manual (Applied) provides instructions for advanced use of the FR-F700P series inverters.
Incorrect handling might cause an unexpected fault. Before using the inverter, always read this Instruction Manual and the Instruction Manual (Basic) [IB-0600411ENG] packed with the product carefully to use the equipment to its optimum.

This section is specifically about safety matters

Do not attempt to install, operate, maintain or inspect the inverter until you have read through Instruction Manual (Basic) and appended documents carefully and can use the equipment correctly. Do not use the inverter until you have a full knowledge of the equipment, safety information and instructions. In this Instruction Manual, the safety instruction levels are classified into "WARNING" and "CAUTION".

⚠WARNING Incorrect handling may cause hazardous conditions, resulting in death or severe injury.

⚠CAUTION Incorrect handling may cause hazardous conditions, resulting in medium or slight injury, or may cause only material damage.

The **⚠CAUTION** level may even lead to a serious consequence according to conditions. Both instruction levels must be followed because these are important to personal safety.

1.Electric Shock Prevention

⚠WARNING

- While power is ON or when the inverter is running, do not open the front cover. Otherwise you may get an electric shock.
- Do not run the inverter with the front cover or wiring cover removed. Otherwise you may access the exposed high-voltage terminals or the charging part of the circuitry and get an electric shock.
- Even if power is OFF, do not remove the front cover except for wiring or periodic inspection. You may accidentally touch the charged inverter circuits and get an electric shock.
- Before wiring, inspection or switching EMC filter ON/OFF connector, power must be switched OFF. To confirm that, LED indication of the operation panel must be checked. (It must be OFF.) Any person who is involved in wiring, inspection or switching EMC filter ON/OFF connector shall wait for at least 10 minutes after the power supply has been switched OFF and check that there are no residual voltage using a tester or the like. The capacitor is charged with high voltage for some time after power OFF, and it is dangerous.
- This inverter must be earthed (grounded). Earthing (grounding) must conform to the requirements of national and local safety regulations and electrical code (NEC section 250, IEC 536 class 1 and other applicable standards). A neutral-point earthed (grounded) power supply for 400V class inverter in compliance with EN standard must be used.
- Any person who is involved in wiring or inspection of this equipment shall be fully competent to do the work.
- The inverter must be installed before wiring. Otherwise you may get an electric shock or be injured.
- Setting dial and key operations must be performed with dry hands to prevent an electric shock. Otherwise you may get an electric shock.
- Do not subject the cables to scratches, excessive stress, heavy loads or pinching. Otherwise you may get an electric shock.
- Do not replace the cooling fan while power is ON. It is dangerous to replace the cooling fan while power is ON.
- Do not touch the printed circuit board or handle the cables with wet hands. Otherwise you may get an electric shock.
- When measuring the main circuit capacitor capacity (*Pr. 259 Main circuit capacitor life measuring* = "1"), the DC voltage is applied to the motor for 1s at powering OFF. Never touch the motor terminal, etc. right after powering OFF to prevent an electric shock.
- IPM motor is a synchronous motor with high-performance magnets embedded in the rotor. Motor terminals hold high-voltage while the motor is running even after the inverter power is turned OFF. Before wiring or inspection, the motor must be confirmed to be stopped. When the motor is driven by the load in applications such as fan and blower, a low-voltage manual contactor must be connected at the inverter's output side, and wiring and inspection must be performed while the contactor is open. Otherwise you may get an electric shock.

2. Fire Prevention ⚠CAUTION

- Inverter must be installed on a nonflammable wall without holes (so that nobody touches the inverter heatsink on the rear side, etc.). Mounting it to or near flammable material can cause a fire.
- If the inverter has become faulty, the inverter power must be switched OFF. A continuous flow of large current could cause a fire.
- Do not connect a resistor directly to the DC terminals P/+ and N/-. Doing so could cause a fire.

3. Injury Prevention ⚠CAUTION

- The voltage applied to each terminal must be the ones specified in the Instruction Manual. Otherwise burst, damage, etc. may occur.
- The cables must be connected to the correct terminals. Otherwise burst, damage, etc. may occur.
- Polarity must be correct. Otherwise burst, damage, etc. may occur.
- While power is ON or for some time after power-OFF, do not touch the inverter since the inverter will be extremely hot. Doing so can cause burns.

4. Additional Instructions

Also the following points must be noted to prevent an accidental failure, injury, electric shock, etc.

(1) Transportation and installation

⚠CAUTION

- The product must be transported in correct method that corresponds to the weight. Failure to do so may lead to injuries.
- Do not stack the boxes containing inverters higher than the number recommended.
- The product must be installed to the position where withstands the weight of the product according to the information in the Instruction Manual.
- Do not install or operate the inverter if it is damaged or has parts missing. This can result in breakdowns.
- When carrying the inverter, do not hold it by the front cover or setting dial; it may fall off or fail.
- Do not stand or rest heavy objects on the product.
- The inverter mounting orientation must be correct.
- Foreign conductive objects must be prevented from entering the inverter. That includes screws and metal fragments or other flammable substance such as oil.
- As the inverter is a precision instrument, do not drop or subject it to impact.
- The inverter must be used under the following environment: Otherwise the inverter may be damaged.

Environment	Surrounding air temperature	-10°C to +50°C (non-freezing)
	Ambient humidity	90% RH or less (non-condensing)
	Storage temperature	-20°C to +65°C *1
	Atmosphere	Indoors (free from corrosive gas, flammable gas, oil mist, dust and dirt)
	Altitude, vibration	Maximum 1000m above sea level for standard operation. 5.9m/s^2 *2 or less at 10 to 55Hz (directions of X, Y, Z axes)

*1 Temperature applicable for a short time, e.g. in transit.
*2 2.9m/s^2 or less for the 185K or higher.

(2) Wiring ⚠**CAUTION**

- Do not install a power factor correction capacitor, surge suppressor or capacitor type filter on the inverter output side. These devices on the inverter output side may be overheated or burn out.
- The connection orientation of the output cables U, V, W to the motor affects the rotation direction of the motor.
- IPM motor terminals (U, V, W) hold high-voltage while the IPM motor is running even after the power is turned OFF. Before wiring, the IPM motor must be confirmed to be stopped. Otherwise you may get an electric shock.
- Never connect an IPM motor to the commercial power supply. Applying the commercial power supply to input terminals (U,V, W) of an IPM motor will burn the IPM motor. The IPM motor must be connected with the output terminals (U, V, W) of the inverter.

(3) Test operation and adjustment

⚠**CAUTION**

- Before starting operation, each parameter must be confirmed and adjusted. A failure to do so may cause some machines to make unexpected motions.

(4) Operation ⚠**WARNING**

- The IPM motor capacity must be same with the inverter capacity. (The 0.75K inverter can be used with a one-rank lower MM-EF motor.)
- Do not use multiple IPM motors with one inverter.
- Any person must stay away from the equipment when the retry function is set as it will restart suddenly after trip.
- Since pressing STOP RESET key may not stop output depending on the function setting status, separate circuit and switch that make an emergency stop (power OFF, mechanical brake operation for emergency stop, etc.) must be provided.
- OFF status of the start signal must be confirmed before resetting the inverter fault. Resetting inverter alarm with the start signal ON restarts the motor suddenly.
- Do not use an IPM motor in an application where a motor is driven by its load and runs at a speed higher than the maximum motor speed.
- A dedicated IPM motor must be used under IPM motor control. Do not use a synchronous motor, induction motor, or synchronous induction motor under IPM motor control.
- The inverter must be used for three-phase induction motors or the dedicated IPM motor.
  Connection of any other electrical equipment to the inverter output may damage the equipment.
- Do not modify the equipment.
- Do not perform parts removal which is not instructed in this manual. Doing so may lead to fault or damage of the inverter.

⚠**CAUTION**

- The electronic thermal relay function does not guarantee protection of the motor from overheating. It is recommended to install both an external thermal and PTC thermistor for overheat protection.
- Do not use a magnetic contactor on the inverter input for frequent starting/stopping of the inverter. Otherwise the life of the inverter decreases.
- The effect of electromagnetic interference must be reduced by using a noise filter or by other means. Otherwise nearby electronic equipment may be affected.
- Appropriate measures must be taken to suppress harmonics. Otherwise power supply harmonics from the inverter may heat/ damage the power factor correction capacitor and generator.
- When driving a 400V class motor by the inverter, the motor must be an insulation-enhanced motor or measures must be taken to suppress surge voltage. Surge voltage attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor.
- When parameter clear or all parameter clear is performed, the required parameters must be set again before starting operations because all parameters return to the initial value.
- The inverter can be easily set for high-speed operation. Before changing its setting, the performances of the motor and machine must be fully examined.
- Stop status cannot be hold by the inverter's brake function. In addition to the inverter's brake function, a holding device must be installed to ensure safety.
- Before running an inverter which had been stored for a long period, inspection and test operation must be performed.
- For prevention of damage due to static electricity, nearby metal must be touched before touching this product to eliminate static electricity from your body.
- Do not connect an IPM motor under the general-purpose motor control settings (initial settings). Do not use a general-purpose motor under the IPM motor control settings. Doing so will cause a failure.
- In the system with an IPM motor, the inverter power must be turned ON before closing the contacts of the contactor at the output side.

(5) Emergency stop ⚠**CAUTION**

- A safety backup such as an emergency brake must be provided to prevent hazardous condition to the machine and equipment in case of inverter failure.
- When the breaker on the inverter input side trips, the wiring must be checked for fault (short circuit), and internal parts of the inverter for a damage, etc. The cause of the trip must be identified and removed before turning ON the power of the breaker.
- When any protective function is activated, appropriate corrective action must be taken, and the inverter must be reset before resuming operation.

(6) Maintenance, inspection and parts replacement

⚠**CAUTION**

- Do not carry out a megger (insulation resistance) test on the control circuit of the inverter. It will cause a failure.

(7) Disposing of the inverter

⚠**CAUTION**

- The inverter must be treated as industrial waste.

General instructions

Many of the diagrams and drawings in this Instruction Manual show the inverter without a cover or partially open for explanation. Never operate the inverter in this manner. The cover must be always reinstalled and the instruction in this Instruction Manual must be followed when operating the inverter.
For more details on a dedicated IPM motor, refer to the Instruction Manual of the dedicated IPM motor.

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<Abbreviations>

DU .... Operation panel (FR-DU07)
PU.. Operation panel (FR-DU07) and parameter unit (FR-PU04/FR-PU07)
Inverter .... Mitsubishi inverter FR-F700P series
FR-F700P .... Mitsubishi inverter FR-F700P series
Pr. .... Parameter Number (Number assigned to function)
PU operation........................... Operation using the PU (FR-DU07/FR-PU04/FR-PU07).
External operation .... Operation using the control circuit signals
Combined operation .... Combined operation using the PU (FR-DU07/FR-PU04/FR-PU07) and external operation.
General-purpose motor .... Three-phase induction motor
Mitsubishi standard motor ..... SF-JR
Mitsubishi constant-torque motor. SF-HRCA
Dedicated IPM motor.............. High-efficiency IPM motor MM-EF (1800r/min specification)
Premium high-efficiency IPM motor MM-EFS (1500r/min specification)

The following marks are used to indicate the controls as below.
(Parameters without any mark are valid for all controls.)

Mark	Control method	Applied motor (control)
V/F	V/F control	Three-phase induction motor (general-purpose motor control)
S MFVC	Simple magnetic flux vector control	
IPM	IPM motor control	Dedicated IPM motor (IPM motor control)

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- DeviceNet™ is a registered trademark of ODVA (Open DeviceNet Vender Association, Inc.).
- Other company and product names herein are the trademarks and registered trademarks of their respective owners.

1 OUTLINE

This chapter describes the basic "OUTLINE" for use of this product.
Always read the instructions before using the equipment.

1.1 Product checking and parts identification

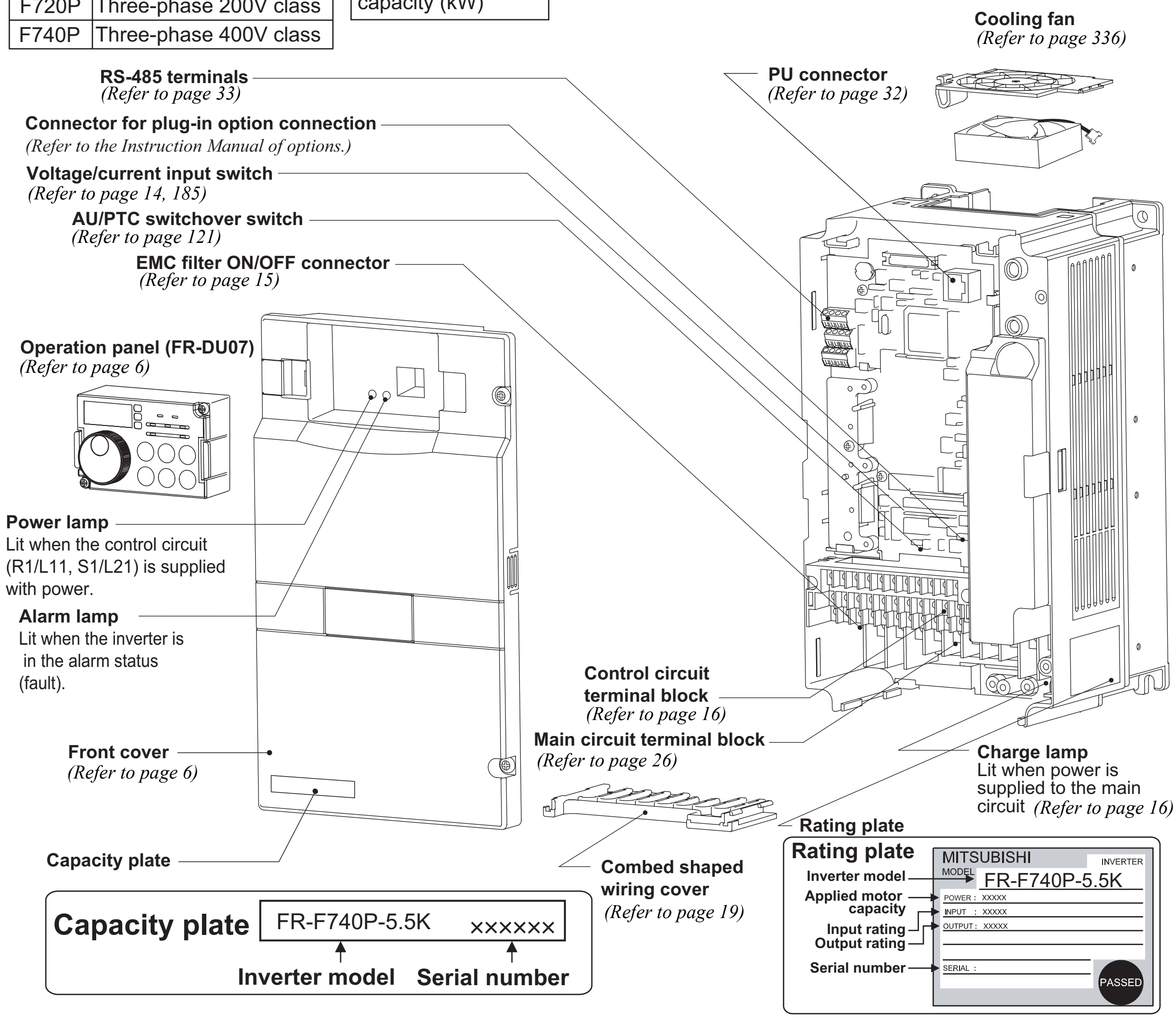
Unpack the inverter and check the capacity plate on the front cover and the rating plate on the inverter side face to ensure that the product agrees with your order and the inverter is intact.

- **Inverter Model**

FR - F740P - 5.5 K

Symbol	Voltage Class
F720P	Three-phase 200V class
F740P	Three-phase 400V class

Represents inverter capacity (kW)

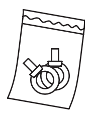


- **Accessory**
  - **Fan cover fixing screws (30K or lower)**
    (Refer to the Instruction Manual (Basic))

	Capacity	Screw Size (mm)	Quantity
200V	2.2K to 5.5K	M3 × 35	1
	7.5K to 15K	M4 × 40	2
	18.5K to 30K	M4 × 50	1
400V	3.7K, 5.5K	M3 × 35	1
	7.5K to 18.5K	M4 × 40	2
	22K, 30K	M4 × 50	1

- **DC reactor supplied (75K or higher)**
- **Eyebolt for hanging the inverter (37K to 315K)**

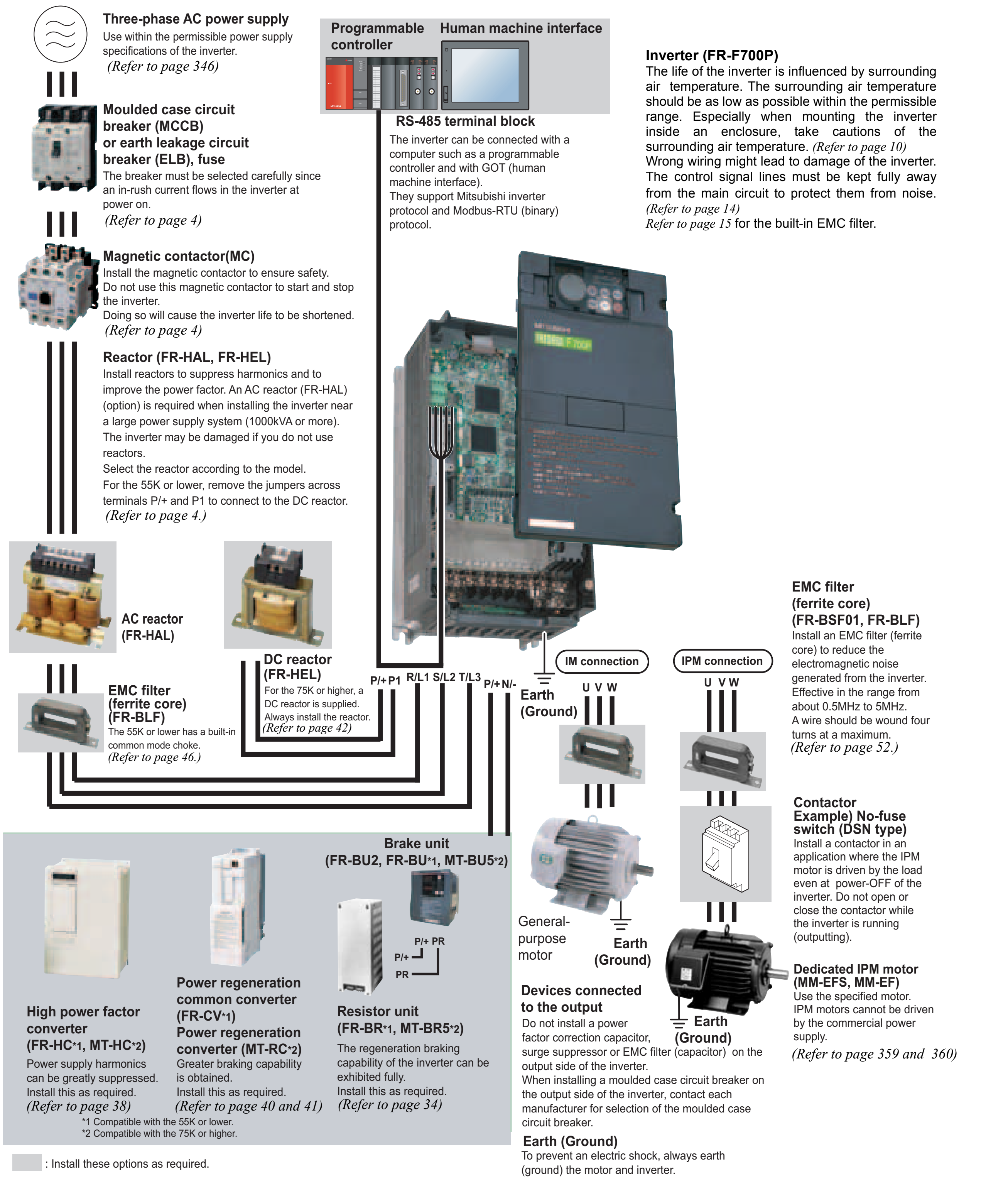
Capacity	Eyebolt Size	Quantity
37K	M8	2
45K to 160K	M10	2
185K to 315K	M12	2



REMARKS
- For removal and reinstallation of covers, *refer to page 6.*
- For how to find the SERIAL number, *refer to page 378.*

Harmonic suppression guideline
All models of General-purpose inverters used by specific consumers are covered by "Harmonic suppression guideline for consumers who receive high voltage or special high voltage". (*For further details, refer to page 49.)*

1.2 Inverter and peripheral devices



CAUTION

- Do not install a power factor correction capacitor, surge suppressor or capacitor type filter on the inverter output side. This will cause the inverter to trip or the capacitor, and surge suppressor to be damaged. If any of the above devices are connected, immediately remove them.
- Electromagnetic wave interference
  The input/output (main circuit) of the inverter includes high frequency components, which may interfere with the communication devices (such as AM radios) used near the inverter. In this case, set the EMC filter valid to minimize interference.
  (Refer to page 15.)
- Refer to the instruction manual of each option and peripheral devices for details of peripheral devices.
- An IPM motor cannot be driven by the commercial power supply.

1.2.1 Peripheral devices

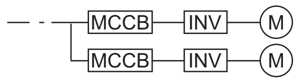
Check the inverter model of the inverter you purchased. Appropriate peripheral devices must be selected according to the capacity. Refer to the following list and prepare appropriate peripheral devices:

200V class

Motor Output (kW) *1	Applicable Inverter Model	Moulded Case Circuit Breaker (MCCB) *2 or Earth Leakage Circuit Breaker (ELB) (NF or NV type)		Input Side Magnetic Contactor*3	
		Power factor improving (AC or DC) reactor			
		Without	With	Without	With
0.75	FR-F720P-0.75K	10A	10A	S-N10	S-N10
1.5	FR-F720P-1.5K	15A	15A	S-N10	S-N10
2.2	FR-F720P-2.2K	20A	15A	S-N10	S-N10
3.7	FR-F720P-3.7K	30A	30A	S-N20, S-N21	S-N10
5.5	FR-F720P-5.5K	50A	40A	S-N25	S-N20, S-N21
7.5	FR-F720P-7.5K	60A	50A	S-N25	S-N25
11	FR-F720P-11K	75A	75A	S-N35	S-N35
15	FR-F720P-15K	125A	100A	S-N50	S-N50
18.5	FR-F720P-18.5K	150A	125A	S-N65	S-N50
22	FR-F720P-22K	175A	150A	S-N80	S-N65
30	FR-F720P-30K	225A	175A	S-N95	S-N80
37	FR-F720P-37K	250A	225A	S-N150	S-N125
45	FR-F720P-45K	300A	300A	S-N180	S-N150
55	FR-F720P-55K	400A	350A	S-N220	S-N180
75	FR-F720P-75K	—	400A	—	S-N300
90	FR-F720P-90K	—	400A	—	S-N300
110	FR-F720P-110K	—	500A	—	S-N400

*1 Selections for use of the Mitsubishi 4-pole standard motor with power supply voltage of 200VAC 50Hz.

*2 Select the MCCB according to the power supply capacity.
Install one MCCB per inverter.
For using commercial-power supply operation, select a breaker with capacity which allows the motor to be directly power supplied.
For installation in the United States, Class RK5, Class J, Class CC, Class L, Class T or any faster acting fuses or UL 489 Molded Case Circuit Breaker (MCCB) must be provided, in accordance with the National Electrical Code and any applicable local codes.
For installation in Canada, Class RK5, Class J, Class CC, Class L, Class T or any faster acting fuses or UL 489 Molded Case Circuit Breaker (MCCB) must be provided, in accordance with the Canada Electrical Code and any applicable provincial codes. *(Refer to the Instruction Manual (basic).)*



*3 Magnetic contactor is selected based on the AC-1 class. The electrical durability of magnetic contactor is 500,000 times. When the magnetic contactor is used for emergency stop during motor driving, the electrical durability is 25 times.
When using the MC for emergency stop during motor driving or using on the motor side during commercial-power supply operation, select the MC with class AC-3 rated current for the motor rated current.

CAUTION

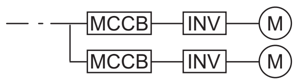
- When the inverter capacity is larger than the motor capacity, select an MCCB and a magnetic contactor according to the inverter model, and select cable and reactor according to the motor output.
- When the breaker on the inverter primary side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter, etc. Identify the cause of the trip, then remove the cause and power ON the breaker.

400V class

Motor Output (kW) *1	Applicable Inverter Model	Moulded Case Circuit Breaker (MCCB) *2 or Earth Leakage Circuit Breaker (ELB) (NF or NV type)		Input Side Magnetic Contactor*3	
		Power factor improving (AC or DC) reactor			
		Without	With	Without	With
0.75	FR-F740P-0.75K	5A	5A	S-N10	S-N10
1.5	FR-F740P-1.5K	10A	10A	S-N10	S-N10
2.2	FR-F740P-2.2K	10A	10A	S-N10	S-N10
3.7	FR-F740P-3.7K	20A	15A	S-N10	S-N10
5.5	FR-F740P-5.5K	30A	20A	S-N20, S-N21	S-N11, S-N12
7.5	FR-F740P-7.5K	30A	30A	S-N20, S-N21	S-N20, S-N21
11	FR-F740P-11K	50A	40A	S-N20, S-N21	S-N20, S-N21
15	FR-F740P-15K	60A	50A	S-N25	S-N20, S-N21
18.5	FR-F740P-18.5K	75A	60A	S-N25	S-N25
22	FR-F740P-22K	100A	75A	S-N35	S-N25
30	FR-F740P-30K	125A	100A	S-N50	S-N50
37	FR-F740P-37K	150A	125A	S-N65	S-N50
45	FR-F740P-45K	175A	150A	S-N80	S-N65
55	FR-F740P-55K	200A	175A	S-N80	S-N80
75	FR-F740P-75K	—	225A	—	S-N95
90	FR-F740P-90K	—	225A	—	S-N150
110	FR-F740P-110K	—	225A	—	S-N180
132	FR-F740P-132K	—	400A	—	S-N220
150	FR-F740P-160K	—	400A	—	S-N300
160	FR-F740P-160K	—	400A	—	S-N300
185	FR-F740P-185K	—	400A	—	S-N300
220	FR-F740P-220K	—	500A	—	S-N400
250	FR-F740P-250K	—	600A	—	S-N600
280	FR-F740P-280K	—	600A	—	S-N600
315	FR-F740P-315K	—	700A	—	S-N600
355	FR-F740P-355K	—	800A	—	S-N600
400	FR-F740P-400K	—	900A	—	S-N800
450	FR-F740P-450K	—	1000A	—	1000A Rated product
500	FR-F740P-500K	—	1200A	—	1000A Rated product
560	FR-F740P-560K	—	1500A	—	1200A Rated product

*1 Selections for use of the Mitsubishi 4-pole standard motor with power supply voltage of 400VAC 50Hz.

*2 Select the MCCB according to the power supply capacity.
Install one MCCB per inverter.
For using commercial-power supply operation, select a breaker with capacity which allows the motor to be directly power supplied.
For installation in the United States, Class RK5, Class J, Class CC, Class L, Class T or any faster acting fuses or UL 489 Molded Case Circuit Breaker (MCCB) must be provided, in accordance with the National Electrical Code and any applicable local codes.
For installation in Canada, Class RK5, Class J, Class CC, Class L, Class T or any faster acting fuses or UL 489 Molded Case Circuit Breaker (MCCB) must be provided, in accordance with the Canada Electrical Code and any applicable provincial codes. *(Refer to the Instruction Manual (basic).)*



*3 Magnetic contactor is selected based on the AC-1 class. The electrical durability of magnetic contactor is 500,000 times. When the magnetic contactor is used for emergency stop during motor driving, the electrical durability is 25 times.
When using the MC for emergency stop during motor driving or using on the motor side during commercial-power supply operation, select the MC with class AC-3 rated current for the motor rated current.

CAUTION

- When the inverter capacity is larger than the motor capacity, select an MCCB and a magnetic contactor according to the inverter model, and select cable and reactor according to the motor output.
- When the breaker on the inverter primary side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter, etc. Identify the cause of the trip, then remove the cause and power ON the breaker.

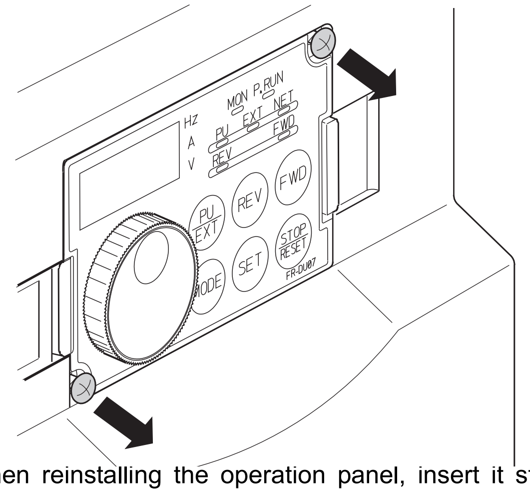
1

OUTLINE

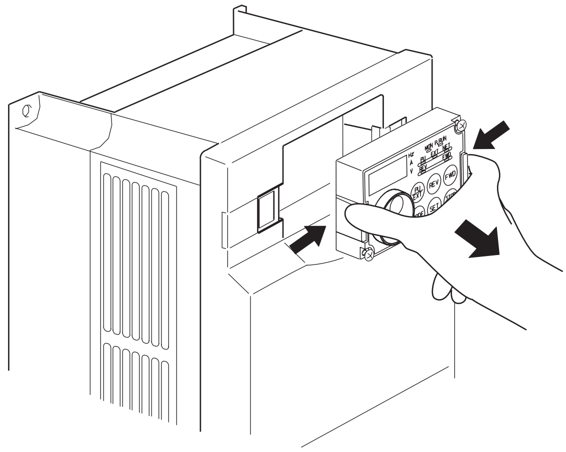
1.3 Method of removal and reinstallation of the front cover

•Removal of the operation panel

1) Loosen the two screws on the operation panel. (These screws cannot be removed.)



2) Push the left and right hooks of the operation panel and pull the operation panel toward you to remove.

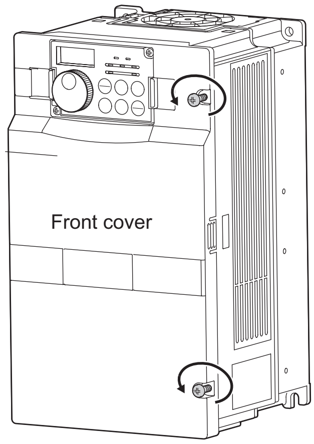


When reinstalling the operation panel, insert it straight to reinstall securely and tighten the fixed screws of the operation panel.

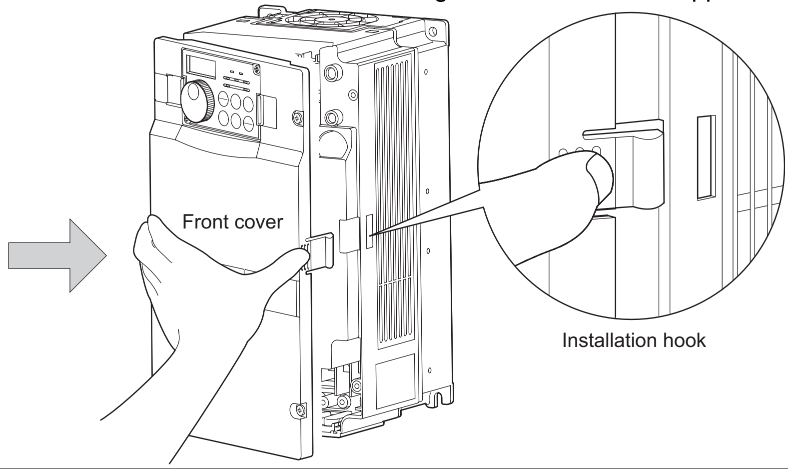
FR-F720P-30K or lower, FR-F740P-30K or lower

•Removal

1) Loosen the installation screws of the front cover.

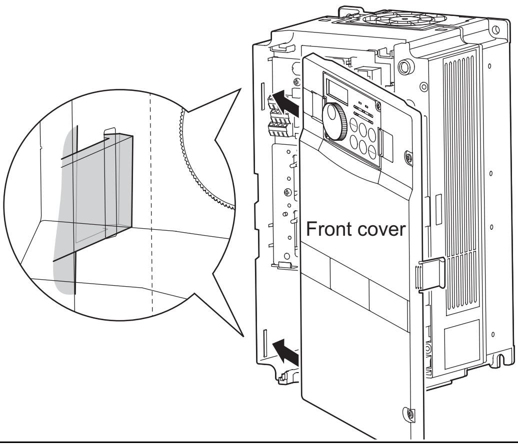


2) Pull the front cover toward you to remove by pushing an installation hook using left fixed hooks as supports.

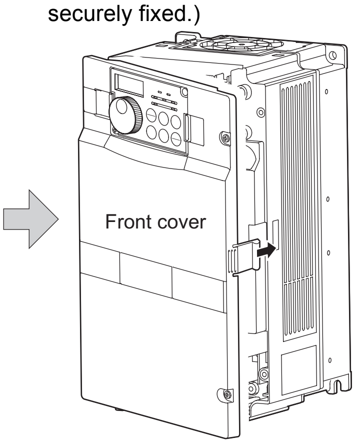


•Reinstallation

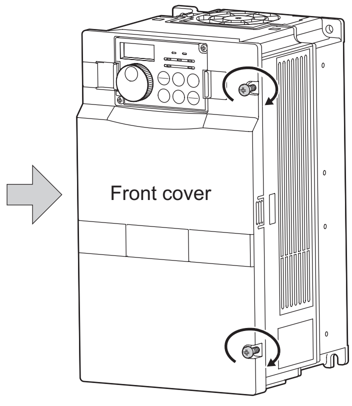
1) Insert the two fixed hooks on the left side of the front cover into the sockets of the inverter.



2) Using the fixed hooks as supports, securely press the front cover against the inverter. (Although installation can be done with the operation panel mounted, make sure that a connector is securely fixed.)



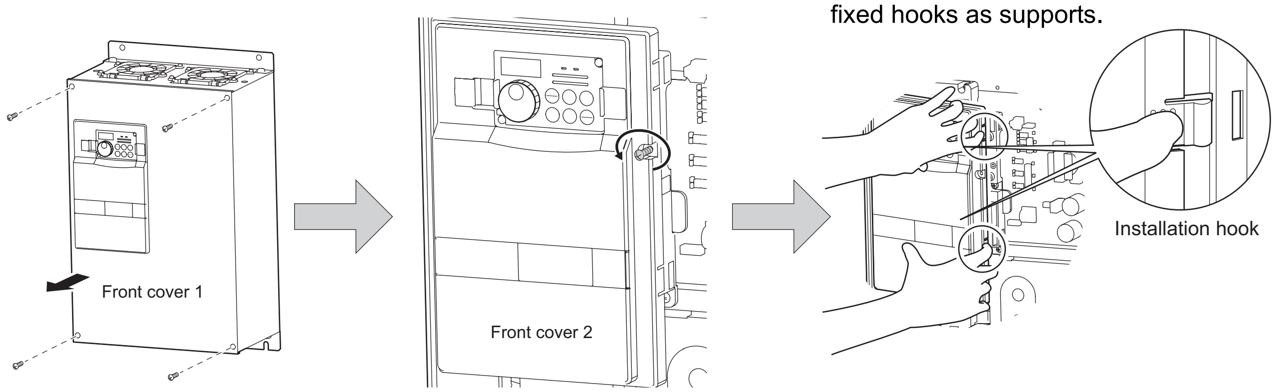
3) Tighten the installation screws and fix the front cover.



FR-F720P-37K or higher, FR-F740P-37K or higher

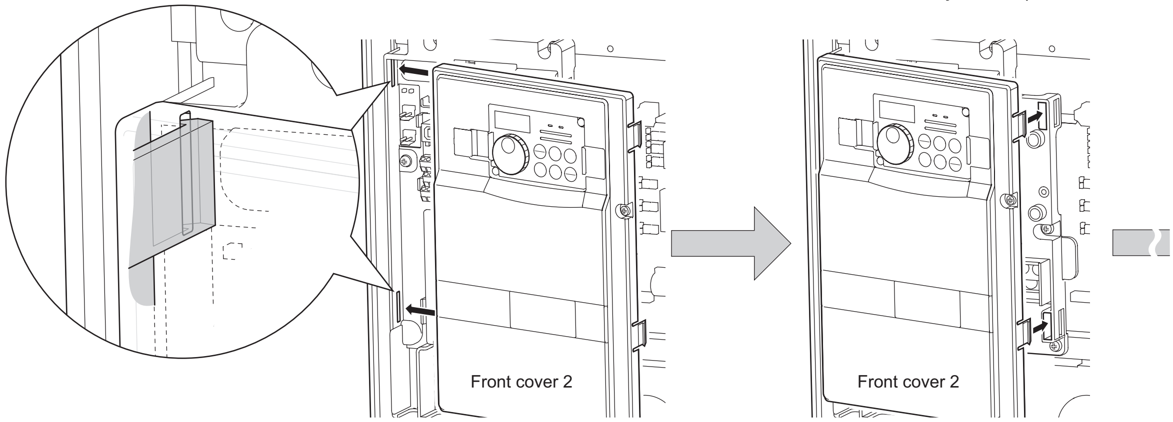
•Removal

1) Remove installation screws on the front cover 1 to remove the front cover 1.
2) Loosen the installation screws of the front cover 2.
3) Pull the front cover 2 toward you to remove by pushing an installation hook on the right side using left fixed hooks as supports.

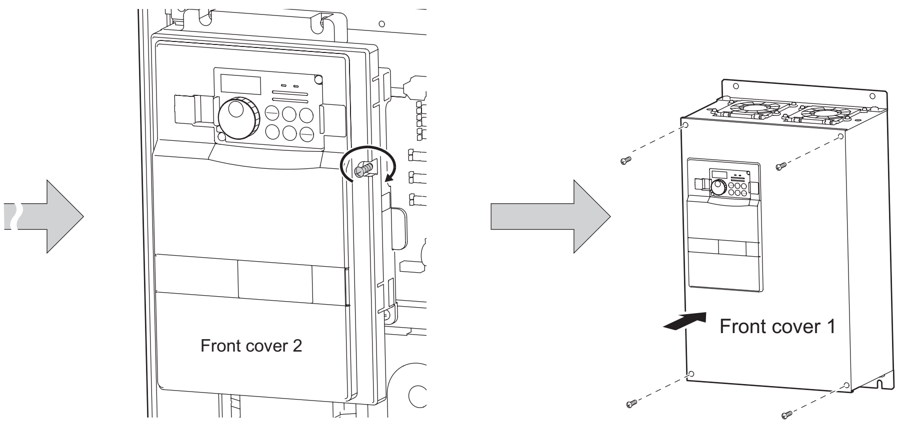


•Reinstallation

1) Insert the two fixed hooks on the left side of the front cover 2 into the sockets of the inverter.
2) Using the fixed hooks as supports, securely press the front cover 2 against the inverter. (Although installation can be done with the operation panel mounted, make sure that a connector is securely fixed.)



3) Fix the front cover 2 with the installation screws.
4) Fix the front cover 1 with the installation screws.



REMARKS

· For the FR-F740P-185K or higher, the front cover 1 is separated into two parts.

CAUTION

· Fully make sure that the front cover has been reinstalled securely. Always tighten the installation screws of the front cover.
· The same serial number is printed on the capacity plate of the front cover and the rating plate of the inverter. Before reinstalling the front cover, check the serial numbers to ensure that the cover removed is reinstalled to the inverter from where it was removed.

1.4 Installation of the inverter and enclosure design

When an inverter enclosure is to be designed and manufactured, heat generated by contained equipment, etc., the environment of an operating place, and others must be fully considered to determine the enclosure structure, size and equipment layout. The inverter unit uses many semiconductor devices. To ensure higher reliability and long period of operation, operate the inverter in the ambient environment that completely satisfies the equipment specifications.

1.4.1 Inverter installation environment

As the inverter installation environment should satisfy the standard specifications indicated in the following table, operation in any place that does not meet these conditions not only deteriorates the performance and life of the inverter, but also causes a failure. Refer to the following points and take adequate measures.

Environmental standard specifications of inverter

Item	Description
Surrounding air temperature	-10 to +50°C (non-freezing)
Ambient humidity	90% RH maximum (non-condensing)
Atmosphere	Free from corrosive and explosive gases, dust and dirt
Maximum Altitude	1,000m or less
Vibration	5.9m/s^2 or less *1 at 10 to 55Hz (directions of X, Y, Z axes)

*1 2.9m/s^2 or less for the 185K or higher.

(1) Temperature

The permissible surrounding air temperature of the inverter is between -10°C and +50°C. Always operate the inverter within this temperature range. Operation outside this range will considerably shorten the service lives of the semiconductors, parts, capacitors and others. Take the following measures so that the surrounding air temperature of the inverter falls within the specified range.

1) Measures against high temperature
- Use a forced ventilation system or similar cooling system. *(Refer to page 10.)*
- Install the enclosure in an air-conditioned electrical chamber.
- Block direct sunlight.
- Provide a shield or similar plate to avoid direct exposure to the radiated heat and wind of a heat source.
- Ventilate the area around the enclosure well.

2) Measures against low temperature
- Provide a space heater in the enclosure.
- Do not power OFF the inverter. (Keep the start signal of the inverter OFF.)

3) Sudden temperature changes
- Select an installation place where temperature does not change suddenly.
- Avoid installing the inverter near the air outlet of an air conditioner.
- If temperature changes are caused by opening/closing of a door, install the inverter away from the door.

(2) Humidity

Normally operate the inverter within the 45 to 90% range of the ambient humidity. Too high humidity will pose problems of reduced insulation and metal corrosion. On the other hand, too low humidity may produce a spatial electrical breakdown. The insulation distance specified in JEM1103 "Control Equipment Insulator" is defined as humidity 45 to 85%.

1) Measures against high humidity
- Make the enclosure enclosed, and provide it with a hygroscopic agent.
- Take dry air into the enclosure from outside.
- Provide a space heater in the enclosure.

2) Measures against low humidity
What is important in fitting or inspection of the unit in this status is to discharge your body (static electricity) beforehand and keep your body from contact with the parts and patterns, besides blowing air of proper humidity into the enclosure from outside.

3) Measures against condensation
Condensation may occur if frequent operation stops change the in-enclosure temperature suddenly or if the outside-air temperature changes suddenly.
Condensation causes such faults as reduced insulation and corrosion.
- Take the measures against high humidity in 1).
- Do not power off the inverter. (Keep the start signal of the inverter OFF.)

(3) Dust, dirt, oil mist

Dust and dirt will cause such faults as poor contact of contact points, reduced insulation or reduced cooling effect due to moisture absorption of accumulated dust and dirt, and in-enclosure temperature rise due to clogged filter.
In the atmosphere where conductive powder floats, dust and dirt will cause such faults as malfunction, deteriorated insulation and short circuit in a short time.
Since oil mist will cause similar conditions, it is necessary to take adequate measures.

Countermeasures
- Place in a totally enclosed enclosure.
  Take measures if the in-enclosure temperature rises. *(Refer to page 10.)*
- Purge air.
  Pump clean air from outside to make the in-enclosure pressure higher than the outside-air pressure.

(4) Corrosive gas, salt damage

If the inverter is exposed to corrosive gas or to salt near a beach, the printed board patterns and parts will corrode or the relays and switches will result in poor contact.
In such places, take the measures given in Section (3).

(5) Explosive, flammable gases

As the inverter is non-explosion proof, it must be contained in an explosion proof enclosure.
In places where explosion may be caused by explosive gas, dust or dirt, an enclosure cannot be used unless it structurally complies with the guidelines and has passed the specified tests. This makes the enclosure itself expensive (including the test charges).
The best way is to avoid installation in such places and install the inverter in a non-hazardous place.

(6) Highland

Use the inverter at the altitude of within 1000m.
If it is used at a higher place, it is likely that thin air will reduce the cooling effect and low air pressure will deteriorate dielectric strength.

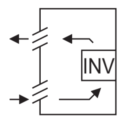
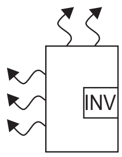
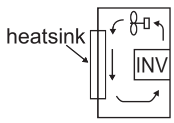
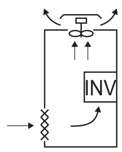
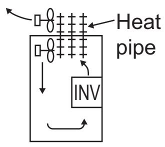
(7) Vibration, impact

The vibration resistance of the inverter is up to $5.9m/s^2$ ($2.9m/s^2$ for the 185K or higher) at 10 to 55Hz frequency (directions of X, Y, Z axes) and 1mm amplitude.
Vibration or impact, if less than the specified value, applied for a long time may make the mechanism loose or cause poor contact to the connectors.
Especially when impact is imposed repeatedly, caution must be taken as the part pins are likely to break.

Countermeasures
- Provide the enclosure with rubber vibration isolators.
- Strengthen the structure to prevent the enclosure from resonance.
- Install the enclosure away from sources of vibration.

1.4.2 Cooling system for inverter enclosure

From the enclosure that contains the inverter, the heat of the inverter and other equipment (transformers, lamps, resistors, etc.) and the incoming heat such as direct sunlight must be dissipated to keep the in-enclosure temperature lower than the permissible temperatures of the in-enclosure equipment including the inverter.
The cooling systems are classified as follows in terms of the cooling calculation method.
1) Cooling by natural heat dissipation from the enclosure surface (Totally enclosed type)
2) Cooling by heat sink (Aluminum fin, etc.)
3) Cooling by ventilation (Forced ventilation type, pipe ventilation type)
4) Cooling by heat exchanger or cooler (Heat pipe, cooler, etc.)

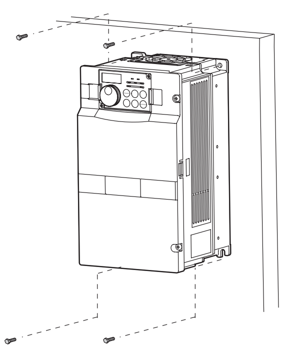
Cooling System		Enclosure Structure	Comment
Natural cooling	Natural ventilation (Enclosed, open type)		Low in cost and generally used, but the enclosure size increases as the inverter capacity increases. For relatively small capacities.
	Natural ventilation (Totally enclosed type)		Being a totally enclosed type, the most appropriate for hostile environment having dust, dirt, oil mist, etc. The enclosure size increases depending on the inverter capacity.
Forced cooling	Heatsink cooling		Having restrictions on the heatsink mounting position and area, and designed for relative small capacities.
	Forced ventilation		For general indoor installation. Appropriate for enclosure downsizing and cost reduction, and often used.
	Heat pipe		Totally enclosed type for enclosure downsizing.

1.4.3 Inverter placement

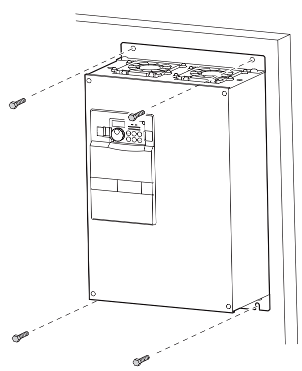
(1) Installation of the inverter

Installation on the enclosure

30K or lower



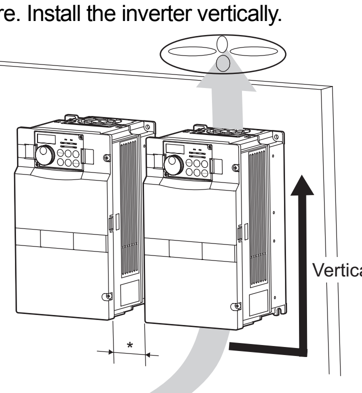
37K or higher



Fix six positions for the FR-F740P-185K to 400K and fix eight positions for the FR-F740P-450K to 560K.

CAUTION

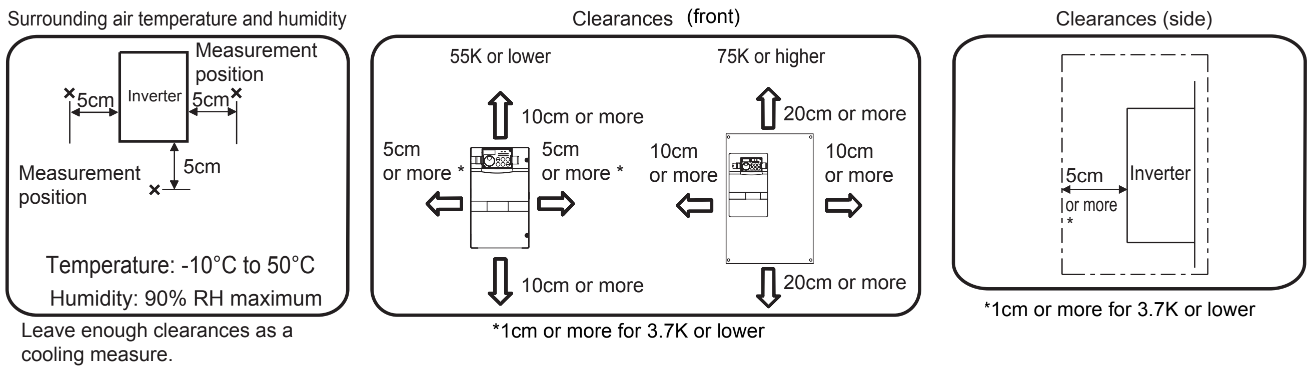
When encasing multiple inverters, install them in parallel as a cooling measure. Install the inverter vertically.



*Refer to the clearances on the next page.

(2) Clearances around the inverter

To ensure ease of heat dissipation and maintenance, leave at least the shown clearances around the inverter. At least the following clearances are required under the inverter as a wiring space, and above the inverter as a heat dissipation space.



REMARKS

- For replacing the cooling fan of the FR-F740P-185K or higher, 30cm of space is necessary in front of the inverter. Refer to *page 336* for fan replacement.

(3) Inverter mounting orientation

Mount the inverter on a wall as specified. Do not mount it horizontally or any other way.

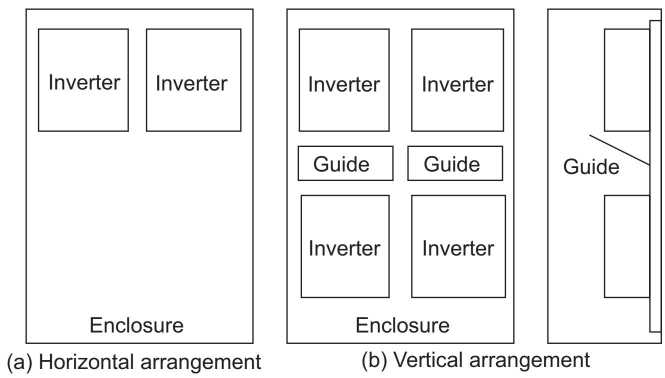
(4) Above the inverter

Heat is blown up from inside the inverter by the small fan built in the unit. Any equipment placed above the inverter should be heat resistant.

(5) Arrangement of multiple inverters

When multiple inverters are placed in the same enclosure, generally arrange them horizontally as shown in the right figure (a). When it is inevitable to arrange them vertically to minimize space, take such measures as to provide guides since heat from the bottom inverters can increase the temperatures in the top inverters, causing inverter failures.

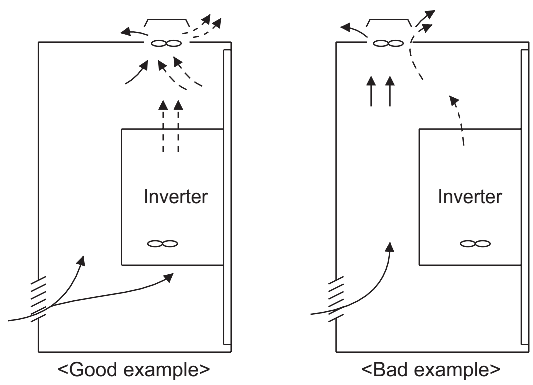
When mounting multiple inverters, fully take caution not to make the surrounding air temperature of the inverter higher than the permissible value by providing ventilation and increasing the enclosure size.



Arrangement of multiple inverters

(6) Placement of ventilation fan and inverter

Heat generated in the inverter is blown up from the bottom of the unit as warm air by the cooling fan. When installing a ventilation fan for that heat, determine the place of ventilation fan installation after fully considering an air flow. (Air passes through areas of low resistance. Make an airway and airflow plates to expose the inverter to cool air.)



Placement of ventilation fan and inverter

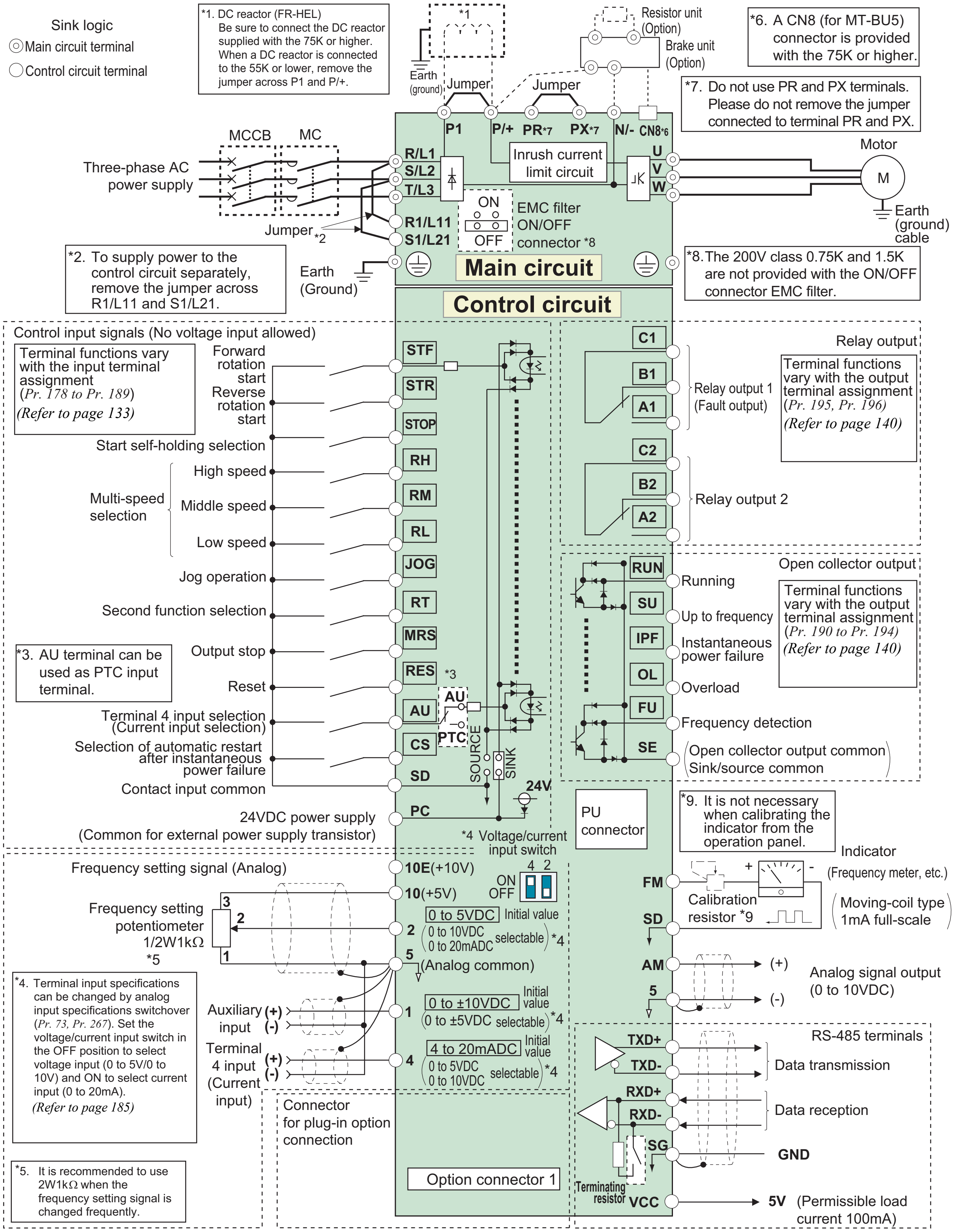
MEMO

2 WIRING

This chapter explains the basic "WIRING" for use of this product.
Always read the instructions before using the equipment.

2.1 Wiring

2.1.1 Terminal connection diagram

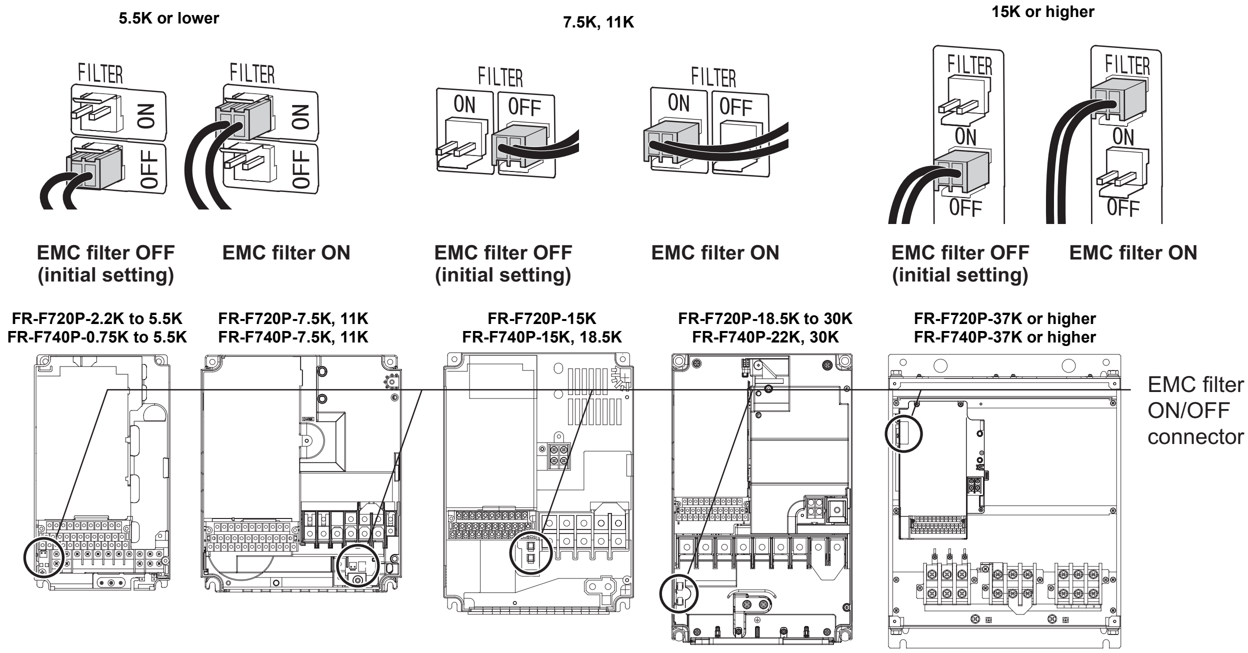


CAUTION

- To prevent a malfunction due to noise, keep the signal cables more than 10cm away from the power cables. Also separate the main circuit wire of the input side and the output side.
- After wiring, wire offcuts must not be left in the inverter.
  Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean.
  When drilling mounting holes in an enclosure etc. take care not to allow chips and other foreign matter to enter the inverter.
- Set the voltage/current input switch correctly. Operation with a wrong setting may cause a fault, failure or malfunction.

2.1.2 EMC filter

This inverter is equipped with a built-in EMC filter (capacitive filter) and common mode choke.
The EMC filter is effective for reduction of air-propagated noise on the input side of the inverter.
The EMC filter is factory-set to disable (OFF). To enable it, fit the EMC filter ON/OFF connector to the ON position.
The input side common mode choke, built-in the 55K or lower inverter, is always valid regardless of ON/OFF of the EMC filter ON/OFF connector.

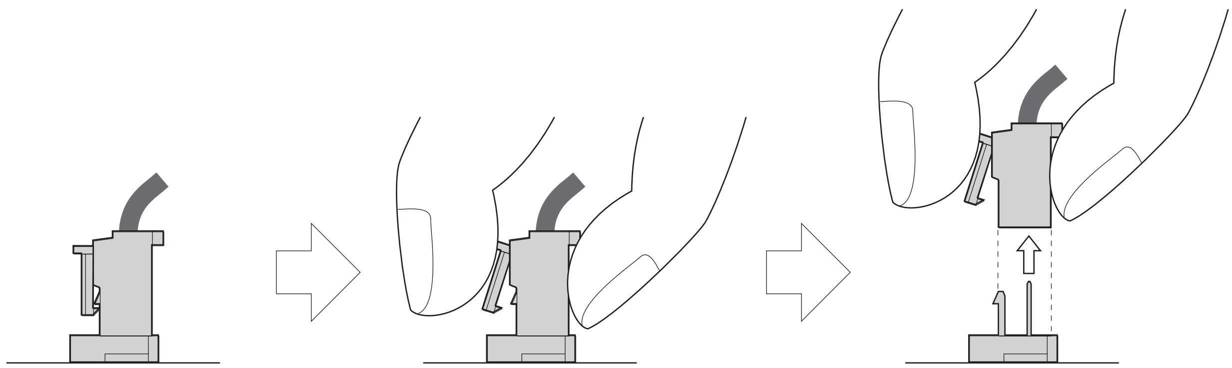


The FR-F720P-0.75K and 1.5K are not provided with the EMC filter ON/OFF connector. (Always ON)

<How to disconnect the connector>

(1) Before removing a front cover, check to make sure that the indication of the inverter operation panel is OFF, wait for at least 10 minutes after the power supply has been switched OFF, and check that there are no residual voltage using a tester or the like. (For the front cover removal method, refer to *page 6.*)

(2) When disconnecting the connector, push the fixing tab and pull the connector straight without pulling the cable or forcibly pulling the connector with the tab fixed. When installing the connector, also engage the fixing tab securely. If it is difficult to disconnect the connector, use a pair of long-nose pliers, etc.



EMC filter ON/OFF connector (Side view)

Disengage connector fixing tab.

With tab disengaged, pull up connector straight.

CAUTION

· Fit the connector to either ON or OFF.
· Enabling (turning ON) the EMC filter increases leakage current. *(Refer to page 45)*

⚠ WARNING

⚠ While power is ON or when the inverter is running, do not open the front cover. Otherwise you may get an electric shock.

2.2 Main circuit terminal specifications

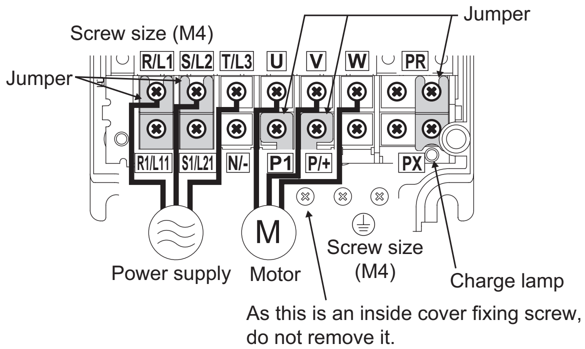
2.2.1 Specification of main circuit terminal

<table>
<tr><th>Terminal Symbol</th><th>Terminal Name</th><th>Description</th><th>Refer to Page</th></tr>
<tr><td>R/L1,
S/L2,
T/L3</td><td>AC power input</td><td>Connect to the commercial power supply.
Keep these terminals open when using the high power factor converter (FR-HC, MT-HC) or power regeneration common converter (FR-CV).</td><td>16</td></tr>
<tr><td>U, V, W</td><td>Inverter output</td><td>Connect a three-phase squirrel-cage motor or dedicated IPM motor.</td><td>16</td></tr>
<tr><td>R1/L11,
S1/L21</td><td>Power supply for control circuit</td><td>Connected to the AC power supply terminals R/L1 and S/L2. To retain the fault display and fault output or when using the high power factor converter (FR-HC, MT-HC) or power regeneration common converter (FR-CV), remove the jumpers from terminals R/L1 and R1/L11, and S/L2 and S1/L21, and apply external power to these terminals.
The power capacity necessary when separate power is supplied from R1/L11 and S1/L21 differs according to the inverter capacity.
<table>
<tr><th></th><th>15K or lower</th><th>18.5K</th><th>22K or higher</th></tr>
<tr><td>200V class</td><td>60VA</td><td>80VA</td><td>80VA</td></tr>
<tr><td>400V class</td><td>60VA</td><td>60VA</td><td>80VA</td></tr>
</table></td><td>24</td></tr>
<tr><td>P/+, N/-</td><td>Brake unit connection</td><td>Connect the brake unit (FR-BU2, FR-BU, BU and MT-BU5), power regeneration common converter (FR-CV), high power factor converter (FR-HC and MT-HC) or power regeneration converter (MT-RC).</td><td>34</td></tr>
<tr><td>P/+, P1</td><td>DC reactor connection</td><td>For the 55K or lower, remove the jumper across terminals P/+ and P1, and connect the DC reactor. (Be sure to connect the DC reactor supplied with the 75K or higher.)
When a DC reactor is not connected, the jumper across terminals P/+ and P1 should not be removed.</td><td>42</td></tr>
<tr><td>PR, PX</td><td colspan="2">Please do not remove or use terminals PR and PX or the jumper connected.</td><td>—</td></tr>
<tr><td>⏚</td><td>Earth (ground)</td><td>For earthing (grounding) the inverter chassis. Must be earthed (grounded).</td><td>22</td></tr>
</table>

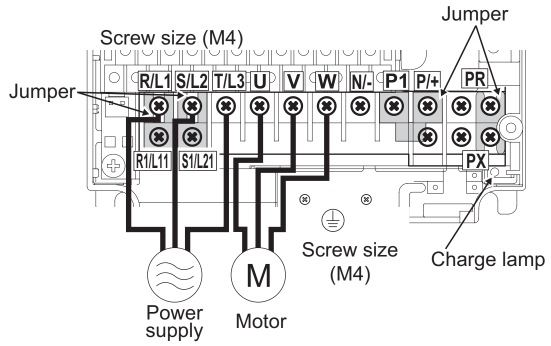
2.2.2 Terminal arrangement of the main circuit terminal, power supply and the motor wiring

200V class

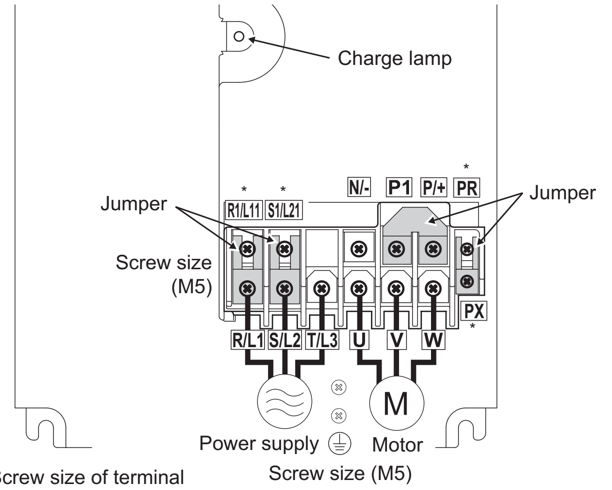
FR-F720P-0.75K, 1.5K



FR-F720P-2.2K to 5.5K

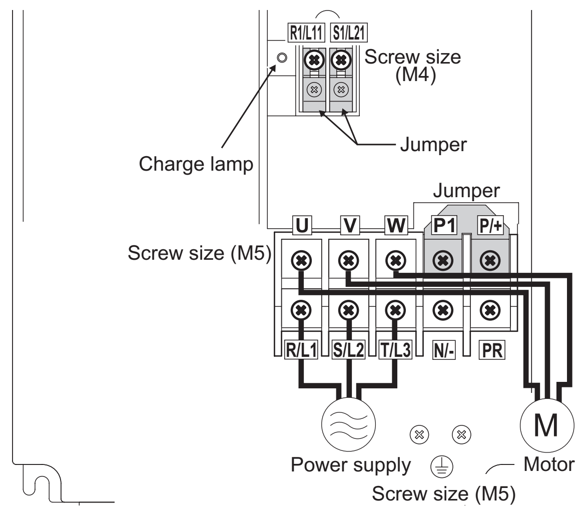


FR-F720P-7.5K, 11K

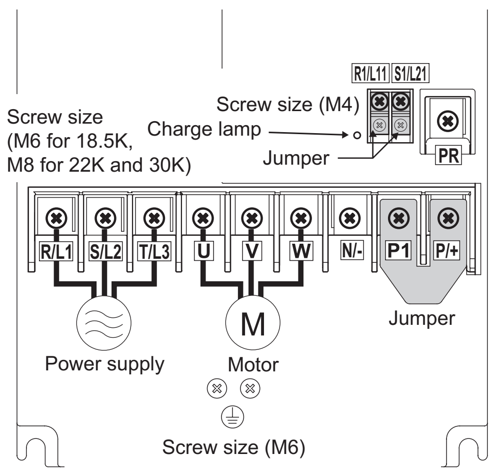


* Screw size of terminal R1/L11, S1/L21, PR and PX is M4.

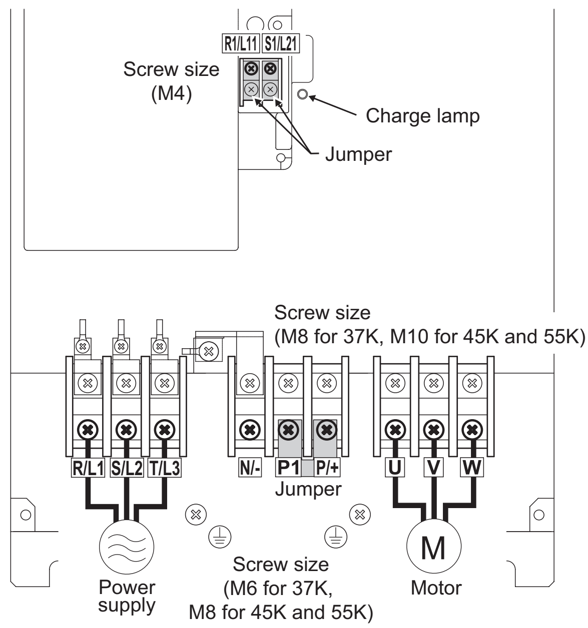
FR-F720P-15K



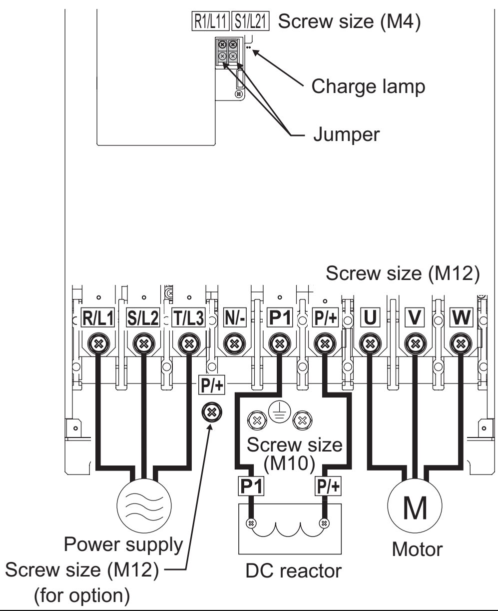
FR-F720P-18.5K to 30K



FR-F720P-37K to 55K



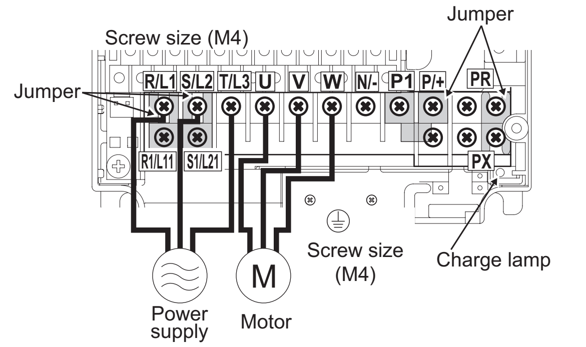
FR-F720P-75K to 110K



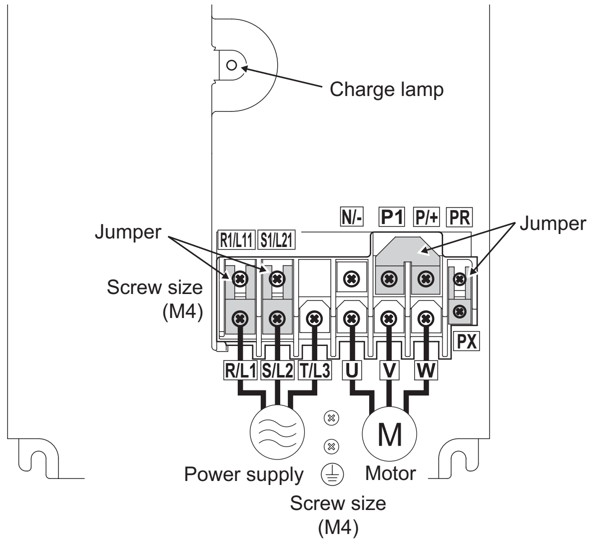
2
WIRING

400V class

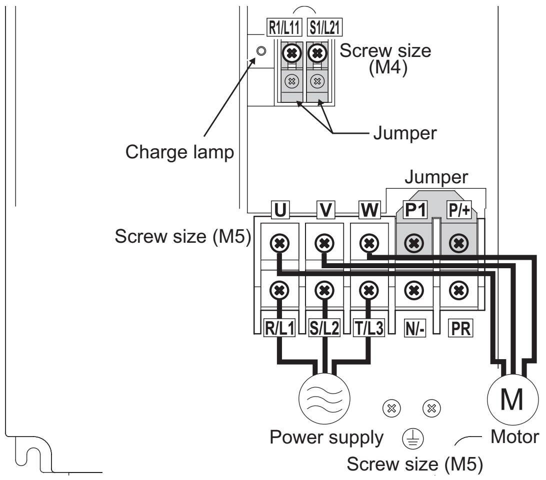
FR-F740P-0.75K to 5.5K



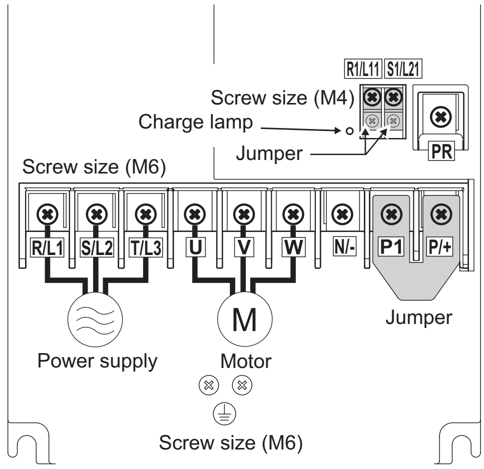
FR-F740P-7.5K, 11K



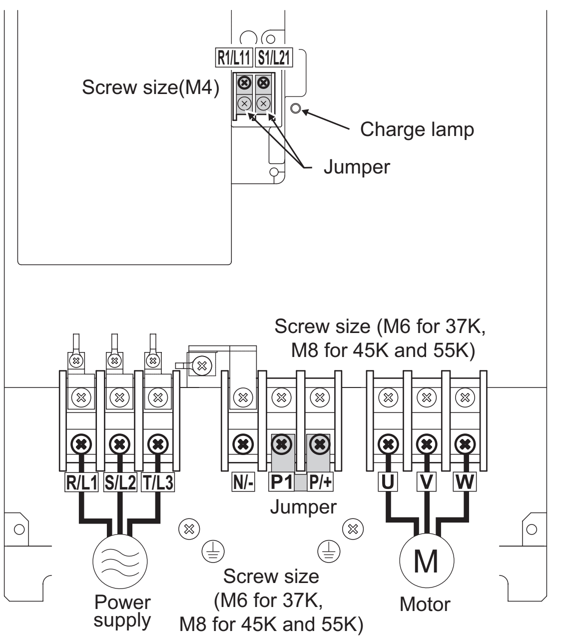
FR-F740P-15K, 18.5K



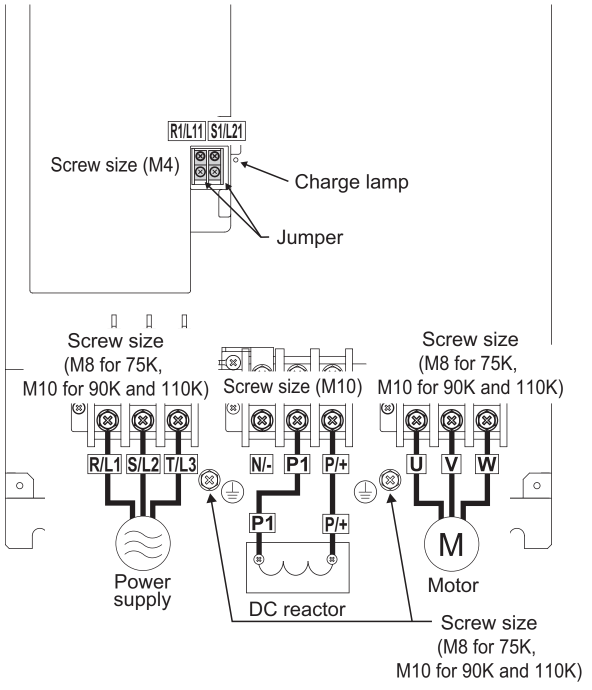
FR-F740P-22K, 30K

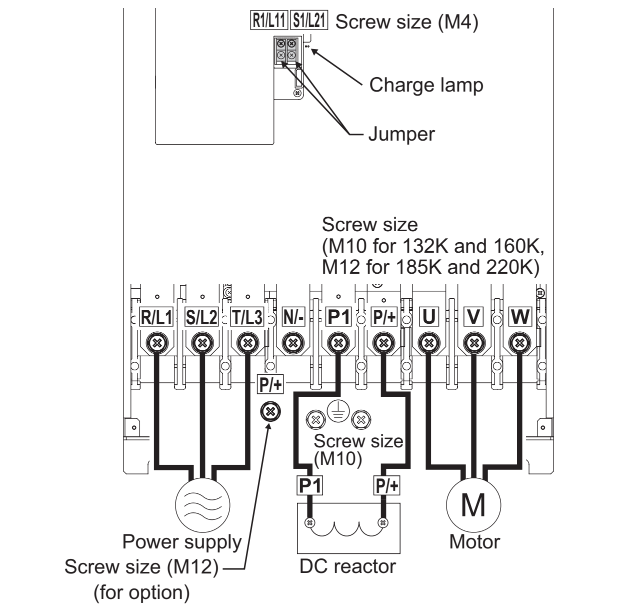


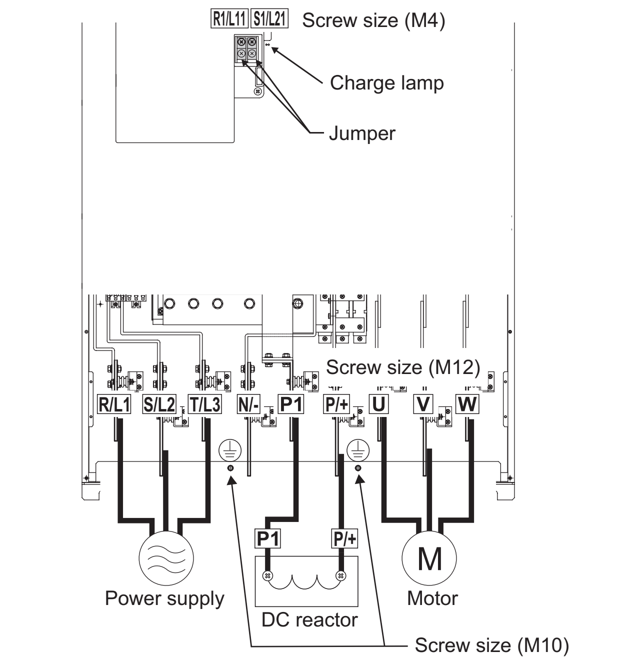
FR-F740P-37K to 55K



FR-F740P-75K to 110K

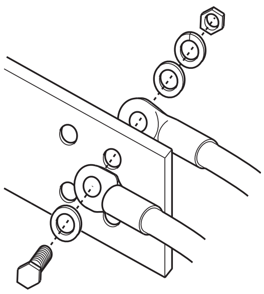






CAUTION

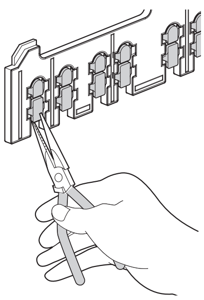
- The power supply cables must be connected to R/L1, S/L2, T/L3. (Phase sequence needs not to be matched.) Never connect the power cable to the U, V, W of the inverter. Doing so will damage the inverter.
- Connect the motor to U, V, W. At this time, turning ON the forward rotation switch (signal) rotates the motor in the counterclockwise direction when viewed from the motor shaft.
- When wiring the inverter main circuit conductor of the 250K or higher, tighten a nut from the right side of the conductor. When wiring two wires, place wires on both sides of the conductor. (Refer to the drawing below.) For wiring, use bolts (nuts) provided with the inverter.

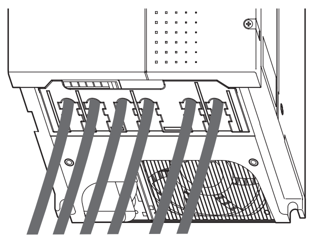


- Handling of the wiring cover
  (FR-F720P-18.5K, 22K, FR-F740P-22K, 30K)
  For the hook of the wiring cover, cut off the necessary parts using a pair of long-nose pliers etc.

CAUTION

Cut off the same number of lugs as wires. If parts where no wire is put through has been cut off (10mm or more), protective structure (JEM1030) becomes an open type (IP00).





2

WIRING

2.2.3 Cables and wiring length

(1) Applicable cable size

Select the recommended cable size to ensure that a voltage drop will be 2% or less.

If the wiring distance is long between the inverter and motor, a main circuit cable voltage drop will cause the motor torque to decrease especially at the output of a low frequency.

The following table indicates a selection example for the wiring length of 20m.

200V class (when input power supply is 220V)

Applicable Inverter Model	Terminal Screw Size *4	Tightening Torque N·m	Crimping Terminal		Cable Sizes								
					HIV, etc. (mm^2) *1				AWG/MCM *2		PVC, etc. (mm^2) *3		
			R/L1, S/L2, T/L3	U, V, W	R/L1, S/L2, T/L3	U, V, W	P/+, P1	Earthing cable	R/L1, S/L2, T/L3	U, V, W	R/L1, S/L2, T/L3	U, V, W	Earthing cable
FR-F720P-0.75K to 2.2K	M4	1.5	2-4	2-4	2	2	2	2	14	14	2.5	2.5	2.5
FR-F720P-3.7K	M4	1.5	5.5-4	5.5-4	3.5	3.5	3.5	3.5	12	12	4	4	4
FR-F720P-5.5K	M4	1.5	5.5-4	5.5-4	5.5	5.5	5.5	5.5	10	10	6	6	6
FR-F720P-7.5K	M5	2.5	14-5	8-5	14	8	14	5.5	6	8	16	10	16
FR-F720P-11K	M5	2.5	14-5	14-5	14	14	14	14	6	6	16	16	16
FR-F720P-15K	M5	2.5	22-5	22-5	22	22	22	14	4	6 (*5)	25	25	16
FR-F720P-18.5K	M6	4.4	38-6	38-6	38	38	38	22	2	2	35	35	25
FR-F720P-22K	M8 (M6)	7.8	38-8	38-8	38	38	38	22	2	2	35	35	25
FR-F720P-30K	M8 (M6)	7.8	60-8	60-8	60	60	60	22	1/0	1/0	50	50	25
FR-F720P-37K	M8 (M6)	7.8	80-8	80-8	80	80	80	22	3/0	3/0	70	70	35
FR-F720P-45K	M10 (M8)	14.7	100-10	100-10	100	100	100	38	4/0	4/0	95	95	50
FR-F720P-55K	M10 (M8)	14.7	100-10	100-10	100	100	100	38	4/0	4/0	95	95	50
FR-F720P-75K	M12 (M10)	24.5	150-12	150-12	125	125	150	38	250	250	—	—	—
FR-F720P-90K	M12 (M10)	24.5	150-12	150-12	150	150	2×100	38	2×4/0	2×4/0	—	—	—
FR-F720P-110K	M12 (M10)	24.5	100-12	100-12	2×100	2×100	2×100	38	2×4/0	2×4/0	—	—	—

*1 The cable size is that of the cable (HIV cable (600V class 2 vinyl-insulated cable) etc.) with continuous maximum permissible temperature of 75°C. Assumes that the surrounding air temperature is 50°C or less and the wiring distance is 20m or less.

*2 The recommended cable size is that of the cable (THHW cable) with continuous maximum permissible temperature of 75°C. Assumes that the surrounding air temperature is 40°C or less and the wiring distance is 20m or less.
(Selection example for use mainly in the United States.)

*3 For the 15K or lower, the recommended cable size is that of the cable (PVC cable) with continuous maximum permissible temperature of 70°C. Assumes that the surrounding air temperature is 40°C or less and the wiring distance is 20m or less.
For the 18.5K or higher, the recommended cable size is that of the cable (XLPE cable) with continuous maximum permissible temperature of 90°C. Assumes that the surrounding air temperature is 40°C or less and wiring is performed in an enclosure.
(Selection example for use mainly in Europe.)

*4 The terminal screw size indicates the terminal size for R/L1, S/L2, T/L3, U, V, W, and a screw for earthing (grounding).
A screw for earthing (grounding) of the 22K or higher is indicated in ( ).

*5 When connecting the option unit to P/+, P1, N/-, use THHN cables for the option and terminals R/L1, S/L2, T/L3, U, V, W.

400V class (when input power supply is 440V)

Applicable Inverter Model	Terminal Screw Size *4	Tightening Torque N·m	Crimping (Compression) Terminal		Cable Sizes								
					HIV, etc. (mm^2) *1				AWG/MCM *2		PVC, etc. (mm^2) *3		
			R/L1, S/L2, T/L3	U, V, W	R/L1, S/L2, T/L3	U, V, W	P/+, P1	Earthing cable	R/L1, S/L2, T/L3	U, V, W	R/L1, S/L2, T/L3	U, V, W	Earthing cable
FR-F740P-0.75K to 3.7K	M4	1.5	2-4	2-4	2	2	2	2	14	14	2.5	2.5	2.5
FR-F740P-5.5K	M4	1.5	2-4	2-4	2	2	3.5	3.5	12	14	2.5	2.5	4
FR-F740P-7.5K	M4	1.5	5.5-4	5.5-4	3.5	3.5	3.5	3.5	12	12	4	4	4
FR-F740P-11K	M4	1.5	5.5-4	5.5-4	5.5	5.5	5.5	8	10	10	6	6	10
FR-F740P-15K	M5	2.5	8-5	8-5	8	8	8	8	8	8	10	10	10
FR-F740P-18.5K	M5	2.5	14-5	8-5	14	8	14	14	6	8	16	10	16
FR-F740P-22K	M6	4.4	14-6	14-6	14	14	22	14	6	6	16	16	16
FR-F740P-30K	M6	4.4	22-6	22-6	22	22	22	14	4	4	25	25	16
FR-F740P-37K	M6	4.4	22-6	22-6	22	22	22	14	4	4	25	25	16
FR-F740P-45K	M8	7.8	38-8	38-8	38	38	38	22	1	2	50	50	25
FR-F740P-55K	M8	7.8	60-8	60-8	60	60	60	22	1/0	1/0	50	50	25
FR-F740P-75K	M8	7.8	60-8	60-8	60	60	60	38	1/0	1/0	50	50	25
FR-F740P-90K	M10	14.7	60-10	60-10	60	60	80	38	3/0	3/0	50	50	25
FR-F740P-110K	M10	14.7	80-10	80-10	80	80	100	38	3/0	3/0	70	70	35
FR-F740P-132K	M10	14.7	100-10	100-10	100	100	100	38	4/0	4/0	95	95	50
FR-F740P-160K	M10	14.7	150-10	150-10	125	125	150	38	250	250	120	120	70
FR-F740P-185K	M12 (M10)	24.5	150-12	150-12	150	150	2×100	38	300	300	150	150	95
FR-F740P-220K	M12 (M10)	24.5	100-12	100-12	2×100	2×100	2×100	38	2×4/0	2×4/0	2×95	2×95	95
FR-F740P-250K	M12 (M10)	46	100-12	100-12	2×100	2×100	2×125	38	2×4/0	2×4/0	2×95	2×95	95
FR-F740P-280K	M12 (M10)	46	150-12	150-12	2×125	2×125	2×125	38	2×250	2×250	2×120	2×120	120
FR-F740P-315K	M12 (M10)	46	150-12	150-12	2×150	2×150	2×150	60	2×300	2×300	2×150	2×150	150
FR-F740P-355K	M12 (M10)	46	200-12	200-12	2×200	2×200	2×200	60	2×350	2×350	2×185	2×185	2×95
FR-F740P-400K	M12 (M10)	46	C2-200	C2-200	2×200	2×200	2×200	60	2×400	2×400	2×185	2×185	2×95
FR-F740P-450K	M12 (M10)	46	C2-250	C2-250	2×250	2×250	2×250	60	2×500	2×500	2×240	2×240	2×120
FR-F740P-500K	M12 (M10)	46	C2-250	C2-250	2×250	2×250	3×200	100	2×500	2×500	2×240	2×240	2×120
FR-F740P-560K	M12 (M10)	46	C2-200	C2-200	3×200	3×200	3×200	100	3×350	3×350	3×185	3×185	2×150

*1 For the FR-F740P-55K or lower, the recommended cable size is that of the cable (e.g. HIV cable (600V class 2 vinyl-insulated cable)) with continuous maximum permissible temperature of 75°C. Assumes that the surrounding air temperature is 50°C or less and the wiring distance is 20m or less.
For the FR-F740P-75K or higher, the recommended cable size is that of the cable (e.g. LMFC (heat resistant flexible cross-linked polyethylene insulated cable)) with continuous maximum permissible temperature of 90°C. Assumes that the surrounding air temperature is 50°C or less and wiring is performed in an enclosure.

*2 For the FR-F740P-45K or lower, the recommended cable size is that of the cable (THHW cable) with continuous maximum permissible temperature of 75°C. Assumes that the surrounding air temperature is 40°C or less and the wiring distance is 20m or less.
For the FR-F740P-55K or higher, the recommended cable size is that of the cable (THHN cable) with continuous maximum permissible temperature of 90°C. Assumes that the surrounding air temperature is 40°C or less and wiring is performed in an enclosure.
(Selection example for use mainly in the United States.)

*3 For the FR-F740P-45K or lower, the recommended cable size is that of the cable (PVC cable) with continuous maximum permissible temperature of 70°C. Assumes that the surrounding air temperature is 40°C or less and the wiring distance is 20m or less.
For the FR-F740P-55K or higher, the recommended cable size is that of the cable (XLPE cable) with continuous maximum permissible temperature of 90°C. Assumes that the surrounding air temperature is 40°C or less and wiring is performed in an enclosure.
(Selection example for use mainly in the Europe.)

*4 The terminal screw size indicates the terminal size for R/L1, S/L2, T/L3, U, V, W, and a screw for earthing (grounding).
A screw for earthing (grounding) of the 185K or higher is indicated in ( ).

The line voltage drop can be calculated by the following formula:

$$\text{Line voltage drop [V]} = \frac{\sqrt{3} \times \text{wire resistance[m}\Omega\text{/m]} \times \text{wiring distance[m]} \times \text{current[A]}}{1000}$$

Use a larger diameter cable when the wiring distance is long or when it is desired to decrease the voltage drop (torque reduction) in the low speed range.

CAUTION

- Tighten the terminal screw to the specified torque.
  A screw that has been tighten too loosely can cause a short circuit or malfunction.
  A screw that has been tighten too tightly can cause a short circuit or malfunction due to the unit breakage.
- Use crimping terminals with insulation sleeve to wire the power supply and motor.

(2) Notes on earthing (grounding)

- Always earth (ground) the motor and inverter.

1)Purpose of earthing (grounding)

Generally, an electrical apparatus has an earth (ground) terminal, which must be connected to the ground before use.

An electrical circuit is usually insulated by an insulating material and encased. However, it is impossible to manufacture an insulating material that can shut off a leakage current completely, and actually, a slight current flow into the case. The purpose of earthing (grounding) the case of an electrical apparatus is to prevent operator from getting an electric shock from this leakage current when touching it.

To avoid the influence of external noises, this earthing (grounding) is important to audio equipment, sensors, computers and other apparatuses that handle low-level signals or operate very fast.

2)Earthing (grounding) methods and earthing (grounding) work

As described previously, earthing (grounding) is roughly classified into an electrical shock prevention type and a noise-affected malfunction prevention type. Therefore, these two types should be discriminated clearly, and the following work must be done to prevent the leakage current having the inverter's high frequency components from entering the malfunction prevention type earthing (grounding):

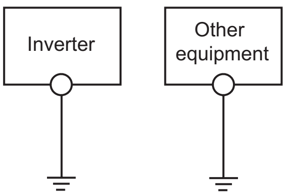
(a) If possible, use (I) independent earthing (grounding) in figure below for the inverter. If independent earthing (grounding) is not available, use (II) joint earthing (grounding) in the figure below which the inverter is connected with the other equipment at an earthing (grounding) point.
The (III) common earthing (grounding) as in the figure below, which inverter shares a common earth (ground) cable with the other equipment, must be avoided.
A leakage current including many high frequency components flows in the earth (ground) cables of the inverter and inverter-driven motor. Therefore, use the independent earthing (grounding) and separated the earthing (grounding) cable of the inverter from equipments sensitive to EMI.
In a high building, it may be effective to use the EMI prevention type earthing (grounding) connecting to an iron structure frame, and electric shock prevention type earthing (grounding) with the independent earthing (grounding) together.

(b) This inverter must be earthed (grounded). Earthing (Grounding) must conform to the requirements of national and local safety regulations and electrical code (NEC section 250, IEC 536 class 1 and other applicable standards).
A neutral-point earthed (grounded power supply for 400V class inverter in compliance with EN standard must be used.

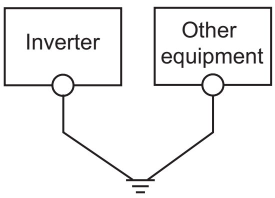
(c) Use the thickest possible earth (ground) cable. The earth (ground) cable should be of not less than the size indicated in the above table on the previous page.

(d) The earthing (grounding) point should be as near as possible to the inverter, and the earthing (grounding) wire length should be as short as possible.

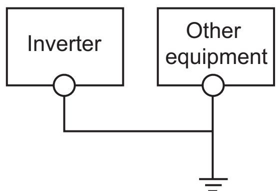
(e) Run the earth (ground) cable as far away as possible from the I/O wiring of equipment sensitive to noises and run them in parallel in the minimum distance.



(I) Independent earthing.......Best



(II) Joint earthing.......Good



(III) Joint earthing.......Not allowed

To be compliant with the EU Directive (Low Voltage Directive), refer to *the Instruction Manual (Basic)*.

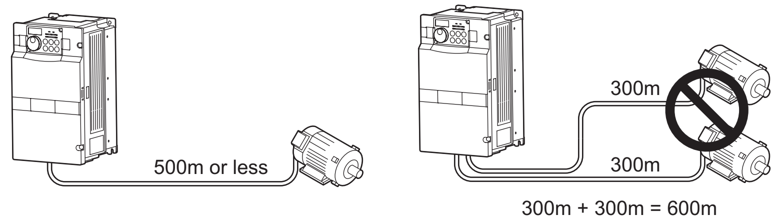
(3) Total wiring length

●Under general-purpose motor control

Connect one or more general-purpose motors within the total wiring length shown in the following table.

Pr. 72 PWM frequency selection Setting (carrier frequency)	0.75K	1.5K	2.2K or Higher
2 (2kHz) or lower	300m	500m	500m
3 (3kHz) or higher	200m	300m	500m

Total wiring length when using a general-purpose motor (2.2K or higher)



When driving a 400V class motor by the inverter, surge voltages attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor. Take the following measures 1) or 2) in this case.
Refer to *page 53* for measures against deteriorated insulation.

1) Use a "400V class inverter-driven insulation-enhanced motor" and set frequency in *Pr. 72 PWM frequency selection* according to wiring length.

	Wiring Length		
	50m or less	50m to 100m	exceeding 100m
Pr. 72 PWM frequency selection Setting (carrier frequency)	14.5kHz or lower	9kHz or lower	4kHz or lower

2) Connect the surge voltage suppression filter (FR-ASF-H/FR-BMF-H) to the 55K or lower and the sine wave filter (MT-BSL/BSC) to the 75K or higher on the inverter output side.

●Under IPM motor control

Connect an IPM motor within the total wiring length of 100m.
Use one dedicated IPM motor for one inverter. Multiple IPM motors cannot be connected to an inverter.
To drive a 400V-class motor with an inverter under IPM control, set *Pr.72 PWM frequency selection* according to the wiring length as shown below.

Applied inverter	Wiring Length	
	50m or less	50m to 100m
FR-F740P-0.75K to 1.5K	0(2kHz) to 15(14kHz)	5(2kHz) or lower
Other	0(2kHz) to 15(14kHz)	9(6kHz) or lower

CAUTION

- Especially for long-distance wiring, the inverter may be affected by a charging current caused by the stray capacitances of the wiring, leading to a malfunction of the overcurrent protective function or fast response current limit function or a malfunction or fault of the equipment connected on the inverter output side. If fast-response current limit function malfunctions, disable this function. (For *Pr.156 Stall prevention operation selection, refer to page 91*.)
- For details of *Pr. 72 PWM frequency selection , refer to page 182*. (When using an optional sine wave filter (MT-BSL/BSC) for the 75K or higher, set "25" in *Pr.72* (2.5kHz). (Sine wave filter can be only used with a general-purpose motor.)
- The surge voltage suppression filter (FR-ASF-H/FR-BMF-H) option and sine wave filter (MT-BSL/BSC) cannot be used under IPM motor control, so do not connect them.
- For explanation of surge voltage suppression filter (FR-ASF-H/FR-BMF-H) and sine wave filter (MT-BSL/BSC), refer to the manual of each option.

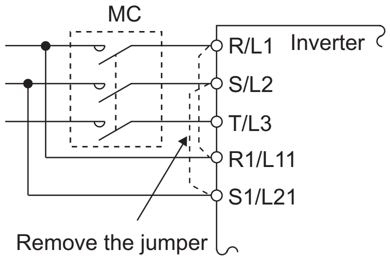
(4) Cable size of the control circuit power supply (terminal R1/L11, S1/L21)

· Terminal Screw Size: M4
· Cable size: 0.75mm^2 to 2mm^2
· Tightening torque: 1.5N·m

2
WIRING

2.2.4 When connecting the control circuit and the main circuit separately to the power supply

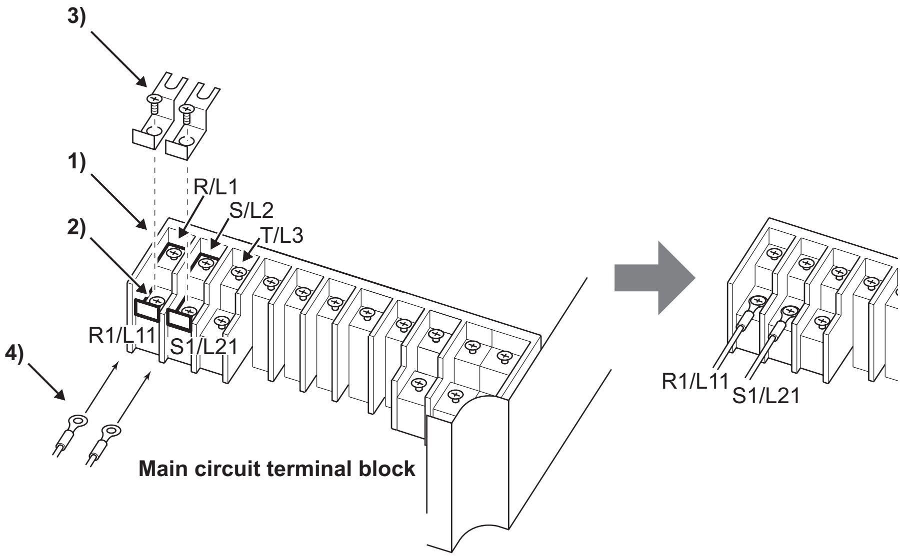
<Connection diagram>



When fault occurs, opening of the electromagnetic contactor (MC) on the inverter power supply side results in power loss in the control circuit, disabling the fault output signal retention. Terminals R1/L11 and S1/L21 are provided for when retention of a fault signal is required. In this case, connect the power supply terminals R1/L11 and S1/L21 of the control circuit to the primary side of the MC.
Do not connect the power cable to incorrect terminals. Doing so may damage the inverter.

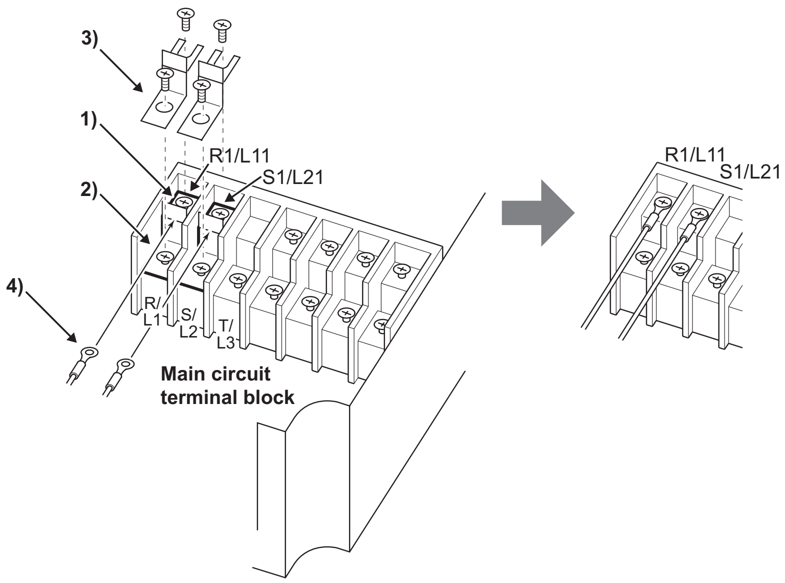
- **FR-F720P-0.75K to 5.5K, FR-F740P-0.75K to 5.5K**

1) Loosen the upper screws.
2) Remove the lower screws.
3) Remove the jumper
4) Connect the separate power supply cable for the control circuit to the lower terminals (R1/L11, S1/L21).



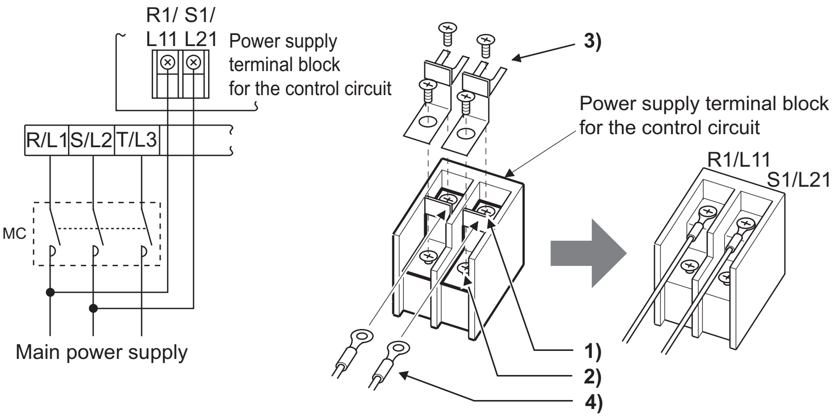
- **FR-F720P-7.5K, 11K, FR-F740P-7.5K, 11K**

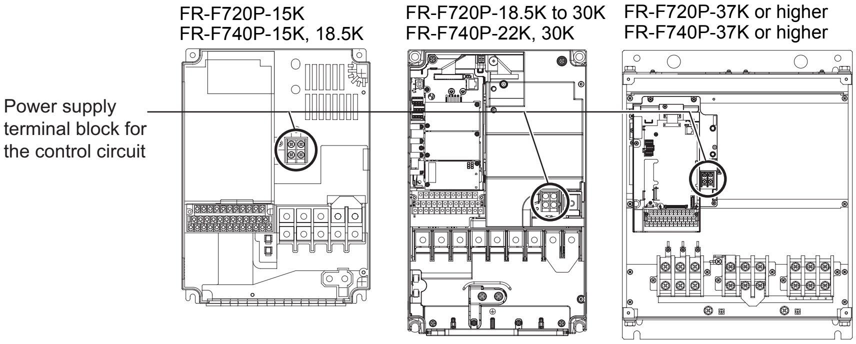
1) Remove the upper screws.
2) Remove the lower screws.
3) Remove the jumper.
4) Connect the separate power supply cable for the control circuit to the upper terminals (R1/L11, S1/L21).



- **FR-F720P-15K, FR-F740P-15K or higher**

1) Remove the upper screws.
2) Remove the lower screws.
3) Pull the jumper toward you to remove.
4) Connect the separate power supply cable for the control circuit to the upper terminals (R1/L11, S1/L21).





CAUTION

- Be sure to use the inverter with the jumpers across terminals R/L1 and R1/L11, and S/L2 and S1/L21 removed when supplying power from other sources. The inverter may be damaged if you do not remove the jumper.
- The voltage should be the same as that of the main control circuit when the control circuit power is supplied from other than the primary side of the MC.
- The power capacity necessary when separate power is supplied from R1/L11 and S1/L21 differs according to the inverter capacity.

	15K or lower	18.5K	22K or higher
200V class	60VA	80VA	80VA
400V class	60VA	60VA	80VA

- If the main circuit power is switched OFF (for 0.1s or more) then ON again, the inverter resets and a fault output will not be held.

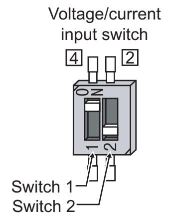
2.3 Control circuit specifications

2.3.1 Control circuit terminals

[ ] indicates that terminal functions can be selected using *Pr. 178 to Pr. 196 (I/O terminal function selection) (Refer to page 133.)*

(1) Input signals

Type	Terminal Symbol	Terminal Name	Description		Rated Specifications	Refer to Page
Contact input	STF	Forward rotation start	Turn ON the STF signal to start forward rotation and turn it OFF to stop.	When the STF and STR signals are turned ON simultaneously, the stop command is given.	Input resistance 4.7kΩ Voltage at opening: 21 to 27VDC Contacts at short-circuited: 4 to 6mADC	133
	STR	Reverse rotation start	Turn ON the STR signal to start reverse rotation and turn it OFF to stop.			
	STOP	Start self-holding selection	Turn ON the STOP signal to self-hold the start signal.			133
	RH, RM, RL	Multi-speed selection	Multi-speed can be selected according to the combination of RH, RM and RL signals.			133
	JOG	Jog mode selection	Turn ON the JOG signal to select Jog operation (initial setting) and turn ON the start signal (STF or STR) to start Jog operation.			133
	RT	Second function selection	Turn ON the RT signal to select second function. When the second function such as "second torque boost" and "second V/F (base frequency)" are set, turning ON the RT signal selects these functions.			133
	MRS	Output stop	Turn ON the MRS signal (20ms or more) to stop the inverter output. Use to shut off the inverter output when stopping the motor by electromagnetic brake.			133
	RES	Reset	Use to reset fault output provided when fault occurs. Turn ON the RES signal for more than 0.1s, then turn it OFF. In the initial status, reset is set always-enabled. By setting *Pr.75*, reset can be set enabled only at fault occurrence. Inverter recovers about 1s after the reset is released.			133
	AU	Terminal 4 input selection	Terminal 4 is valid only when the AU signal is turned ON. (The frequency setting signal can be set between 0 and 20mADC.) Turning the AU signal ON makes terminal 2 (voltage input) invalid.			185
		PTC input	AU terminal is used as PTC input terminal (thermal protection of the motor). When using it as PTC input terminal, set the AU/PTC switch to PTC.			121
	CS	Selection of automatic restart after instantaneous power failure	When the CS signal is left ON, the inverter restarts automatically at power restoration. Note that restart setting is necessary for this operation. In the initial setting, a restart is disabled. *(Refer to Pr. 57 Restart coasting time page 162)*			133
	SD	Contact input common (sink) (initial setting)	Common terminal for contact input terminal (sink logic) and terminal FM.		——	—
		External transistor common (source)	Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the source logic to avoid malfunction by undesirable currents.			
		24VDC power supply common	Common output terminal for 24VDC 0.1A power supply (PC terminal). Isolated from terminals 5 and SE.			
	PC	External transistor common (sink) (initial setting)	Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the sink logic to avoid malfunction by undesirable currents.		Power supply voltage range 19.2 to 28.8VDC Permissible load current 100mA	30
		Contact input common (source)	Common terminal for contact input terminal (source logic).			
		24VDC power supply	Can be used as 24VDC 0.1A power supply.			

Type	Terminal Symbol	Terminal Name	Description	Rated Specifications	Refer to Page
Frequency setting	10E	Frequency setting power supply	When connecting the frequency setting potentiometer at an initial status, connect it to terminal 10. Change the input specifications of terminal 2 when connecting it to terminal 10E. *(Refer to Pr. 73 Analog input selection inpage 191.)*	10VDC±0.4V Permissible load current 10mA	185
	10			5.2VDC±0.2V Permissible load current 10mA	185
	2	Frequency setting (voltage)	Inputting 0 to 5VDC (or 0 to 10V, 0 to 20mA) provides the maximum output frequency at 5V (10V, 20mA) and makes input and output proportional. Use *Pr. 73* to switch from among input 0 to 5VDC (initial setting), 0 to 10VDC, and 0 to 20mA. Set the voltage/current input switch in the ON position to select current input (0 to 20mA).*1	Voltage input: Input resistance 10kΩ ± 1kΩ Maximum permissible voltage 20VDC Current input: Input resistance 245Ω ± 5Ω Maximum permissible current 30mA	185
	4	Frequency setting (current)	Inputting 4 to 20mADC (or 0 to 5V, 0 to 10V) provides the maximum output frequency at 20mA (5V, 10V) makes input and output proportional. This input signal is valid only when the AU signal is ON (terminal 2 input is invalid). Use *Pr. 267* to switch from among input 4 to 20mA (initial setting), 0 to 5VDC, and 0 to 10VDC. Set the voltage/current input switch in the OFF position to select voltage input (0 to 5V/0 to 10V).*1		185
	1	Frequency setting auxiliary	Inputting 0 to ±5 VDC or 0 to ±10VDC adds this signal to terminal 2 or 4 frequency setting signal. Use *Pr.73* to switch between the input 0 to ±5VDC and 0 to ±10VDC (initial setting).	Input resistance 10kΩ ± 1kΩ Maximum permissible voltage ± 20VDC	185
	5	Frequency setting common	Common terminal for frequency setting signal (terminal 2, 1 or 4) and analog output terminal AM. Do not earth (ground).	——	185

*1 Set *Pr. 73*, *Pr. 267*, and a voltage/current input switch correctly, then input an analog signal in accordance with the setting.
Applying a voltage signal with voltage/current input switch ON (current input is selected) or a current signal with switch OFF (voltage input is selected) could cause component damage of the inverter or analog circuit of signal output devices. *(For details, refer to page 185.)*

2

WIRING

(2) Output signals

Type	Terminal Symbol	Terminal Name	Description		Rated Specifications	Refer to Page
Relay	A1, B1, C1	Relay output 1 (Fault output)	1 changeover contact output indicates that the inverter's protective function has activated and the output stopped. Fault: No conduction between B and C (conduction between A and C) Normal: Conduction between B and C (No conduction between A and C)		Contact capacity: 230VAC 0.3A (Power factor=0.4) 30VDC 0.3A	140
	A2, B2, C2	Relay output 2	1 changeover contact output			140
Open collector	RUN	Inverter running	Switched low when the inverter output frequency is equal to or higher than the starting frequency (initial value 0.5Hz). Switched high during stop or DC injection brake operation.		Permissible load 24VDC (27VDC maximum) 0.1A (A voltage drop is 3.4V maximum when the signal is ON.) Low is when the open collector output transistor is ON (conducts). High is when the transistor is OFF (does not conduct).	140
	SU	Up to frequency	Switched low when the output frequency reaches within the range of ±10% (initial value) of the set frequency. Switched high during acceleration/deceleration and at a stop.	Alarm code (4bit) output		140
	OL	Overload warning	Switched low when stall prevention is activated by the stall prevention function. Switched high when stall prevention is cancelled.			140
	IPF	Instantaneous power failure	Switched low when an instantaneous power failure and under voltage protections are activated.			140
	FU	Frequency detection	Switched low when the inverter output frequency is equal to or higher than the preset detected frequency and high when less than the preset detected frequency.			140
	SE	Open collector output common	Common terminal for terminals RUN, SU, OL, IPF, FU		———	—
Pulse	FM	For meter	Select one e.g. output frequency from monitor items. (Not output during inverter reset.) The output signal is proportional to the magnitude of the corresponding monitoring item. To set a full-scale value for monitoring the output frequency and the output current, set *Pr.56* and *Pr.158*.	Output item: Output frequency (initial setting)	Permissible load current 2mA 1440 pulse/s at 60Hz (general-purpose motor control) 1440 pulse/s at 90Hz (IPM motor control with 30K or lower) 1440 pulse/s at 120Hz (IPM motor control with 37K or higher)	157
Analog	AM	Analog signal output		Output item: Output frequency (initial setting)	Output signal 0 to 10VDC Permissible load current 1mA (load impedance 10kΩ or more) Resolution 8 bit	157

(3) Communication

Type	Terminal Symbol		Terminal Name	Description	Refer to Page
RS-485	—		PU connector	With the PU connector, communication can be established through RS-485. (for connection on a 1:1 basis only) Conforming standard : EIA-485 (RS-485) Transmission format : Multidrop link Communication speed : 4800 to 38400bps Overall length : 500m	224
	RS-485 terminals	TXD+	Inverter transmission terminal	With the RS-485 terminals, communication can be established through RS-485. Conforming standard : EIA-485 (RS-485) Transmission format : Multidrop link Communication speed : 300 to 38400bps Overall length : 500m	226
		TXD-			
		RXD+	Inverter reception terminal		
		RXD-			
		SG	Earth (Ground)		

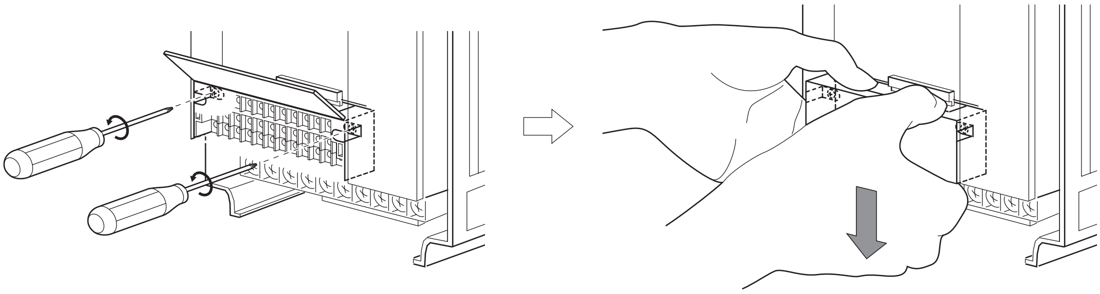
2.3.2 Changing the control logic

The input signals are set to sink logic (SINK) when shipped from the factory.

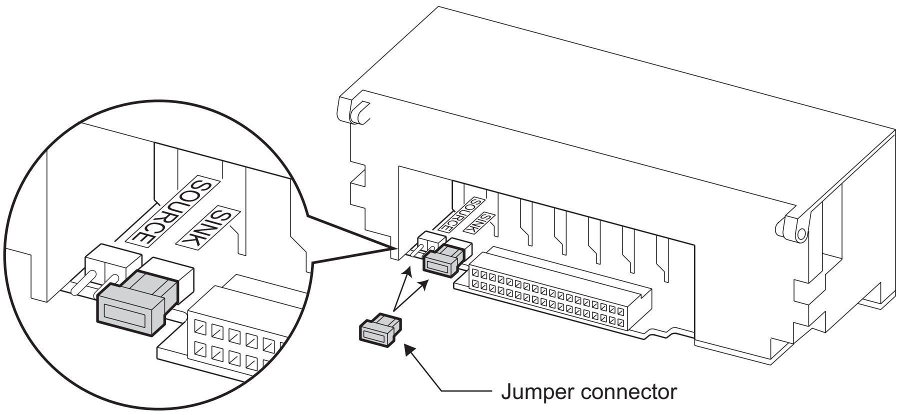
To change the control logic, the jumper connector on the back of the control circuit terminal block must be moved to the other position.

(The output signals may be used in either the sink or source logic independently of the jumper connector position.)

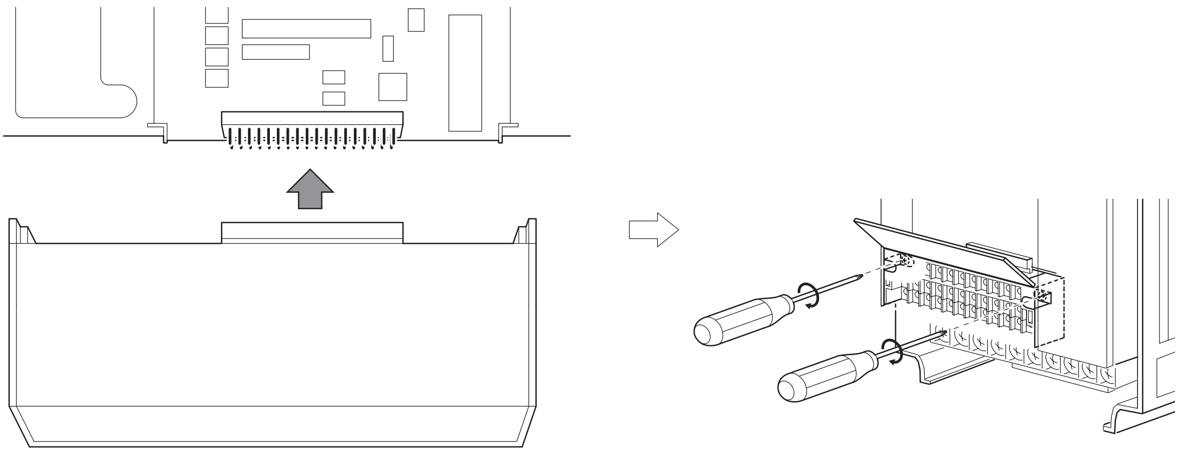
1) Loosen the two installation screws in both ends of the control circuit terminal block. (These screws cannot be removed.)
   Pull down the terminal block from behind the control circuit terminals.



2) Change the jumper connector set to the sink logic (SINK) on the rear panel of the control circuit terminal block to source logic (SOURCE).



3) Using care not to bend the pins of the inverter's control circuit connector, reinstall the control circuit terminal block and fix it with the mounting screws.



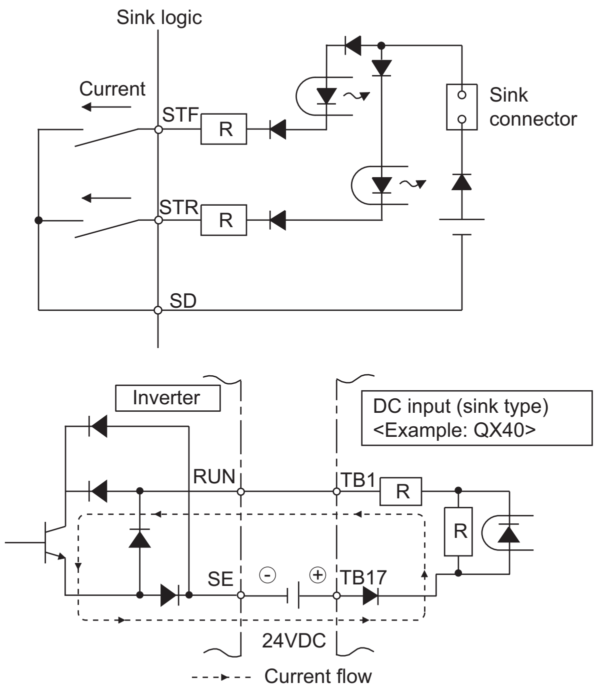
CAUTION

1. Make sure that the control circuit connector is fitted correctly.
2. While power is on, never disconnect the control circuit terminal block.

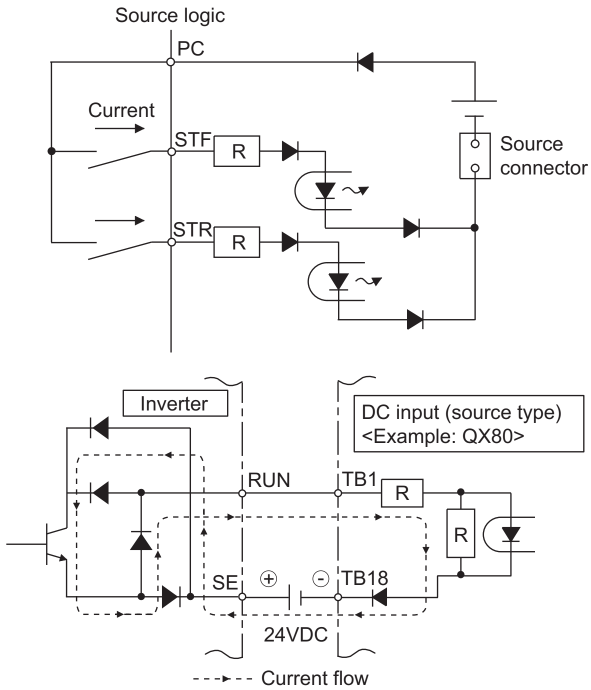
4) Sink logic and source logic

- In sink logic, a signal switches ON when a current flows from the corresponding signal input terminal.
  Terminal SD is common to the contact input signals. Terminal SE is common to the open collector output signals.
- In source logic, a signal switches ON when a current flows into the corresponding signal input terminal.
  Terminal PC is common to the contact input signals. Terminal SE is common to the open collector output signals.

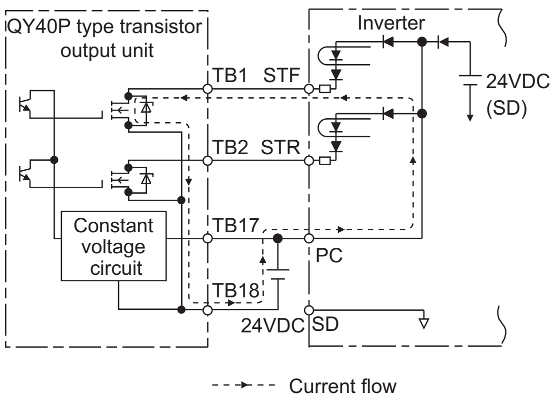
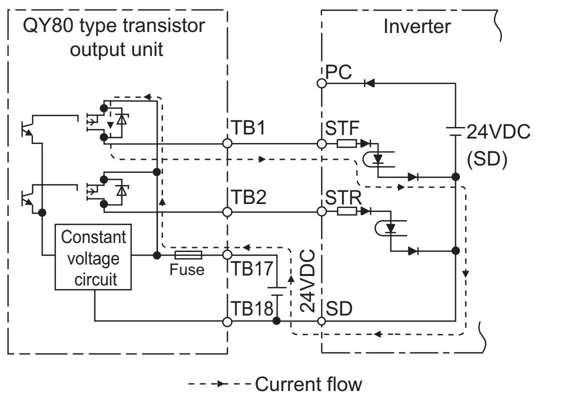
●Current flow concerning the input/output signal when sink logic is selected



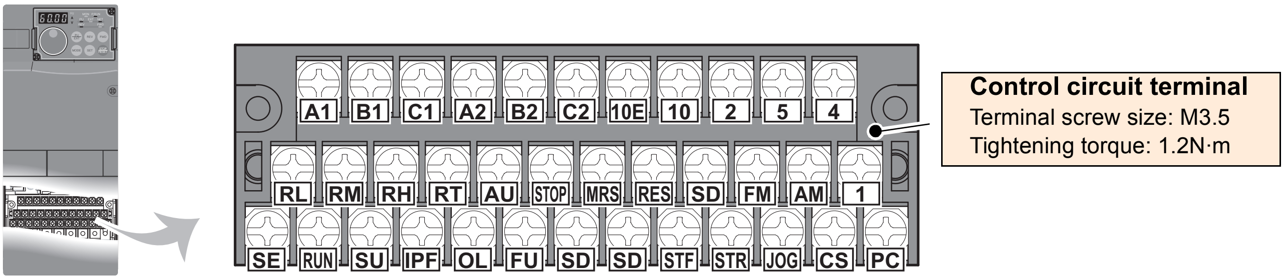
●Current flow concerning the input/output signal when source logic is selected



- When using an external power supply for transistor output

· Sink logic type Use terminal PC as a common terminal, and perform wiring as shown below. (Do not connect terminal SD of the inverter with terminal 0V of the external power supply. When using terminals PC and SD as a 24VDC power supply, do not install a power supply in parallel in the outside of the inverter. Doing so may cause a malfunction due to undesirable current.) 	· Source logic type Use terminal SD as a common terminal, and perform wiring as shown below. (Do not connect terminal PC of the inverter with terminal +24V of the external power supply. When using terminals PC and SD as a 24VDC power supply, do not install an external power supply in parallel with the inverter. Doing so may cause a malfunction in the inverter due to undesirable currents.) 

2.3.3 Control circuit terminal layout



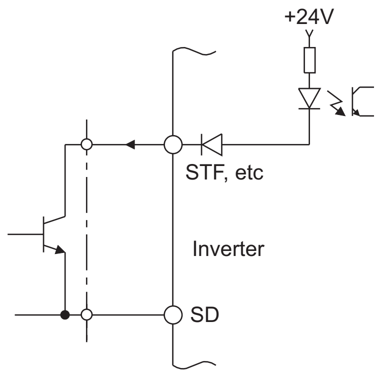
(1) Common terminals of the control circuit (SD, 5, SE)

Terminals SD, 5, and SE are all common terminals (0V) for I/O signals and are isolated from each other. Do not earth(ground) these terminals.
Avoid connecting the terminal SD and 5 and the terminal SE and 5.
Terminal SD is a common terminal for the contact input terminals (STF, STR, STOP, RH, RM, RL, JOG, RT, MRS, RES, AU, CS) and frequency output signal (FM).
The open collector circuit is isolated from the internal control circuit by photocoupler.
Terminal 5 is a common terminal for frequency setting signal (terminal 2, 1 or 4) and analog output terminal AM.
It should be protected from external noise using a shielded or twisted cable.
Terminal SE is a common terminal for the open collector output terminal (RUN, SU, OL, IPF, FU).
The contact input circuit is isolated from the internal control circuit by photocoupler.

(2) Signal inputs by contactless switches

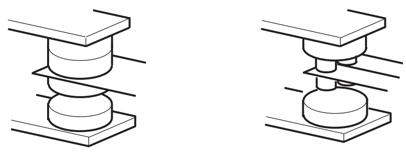
The contacted input terminals of the inverter (STF, STR, STOP, RH, RM, RL, JOG, RT, MRS, RES, AU, CS) can be controlled using a transistor instead of a contacted switch as shown on the right.

External signal input using transistor



2.3.4 Wiring instructions

1) It is recommended to use the cables of 0.75mm^2 gauge for connection to the control circuit terminals.
   If the cable gauge used is 1.25mm^2 or more, the front cover may be lifted when there are many cables running or the cables are run improperly, resulting in an operation panel contact fault.
2) The maximum wiring length should be 30m (200m for terminal FM).
3) Use two or more parallel micro-signal contacts or twin contacts to prevent a contact faults when using contact inputs since the control circuit input signals are micro-currents.



Micro signal contacts   Twin contacts

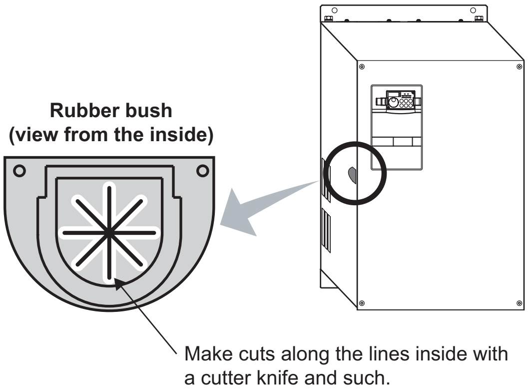
4) Use shielded or twisted cables for connection to the control circuit terminals and run them away from the main and power circuits (including the 200V relay sequence circuit).
5) Do not apply a voltage to the contact input terminals (e.g. STF) of the control circuit.
6) Always apply a voltage to the fault output terminals (A, B, C) via a relay coil, lamp, etc.

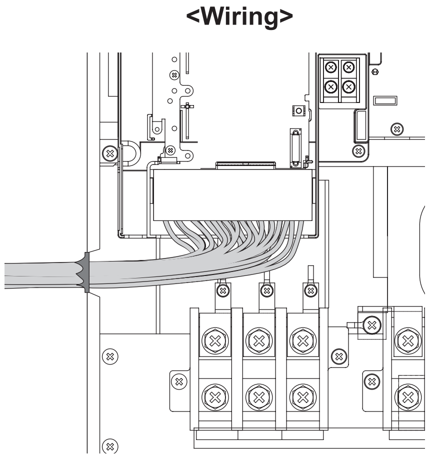
2

WIRING

● Wiring of the control circuit of the 75K or higher

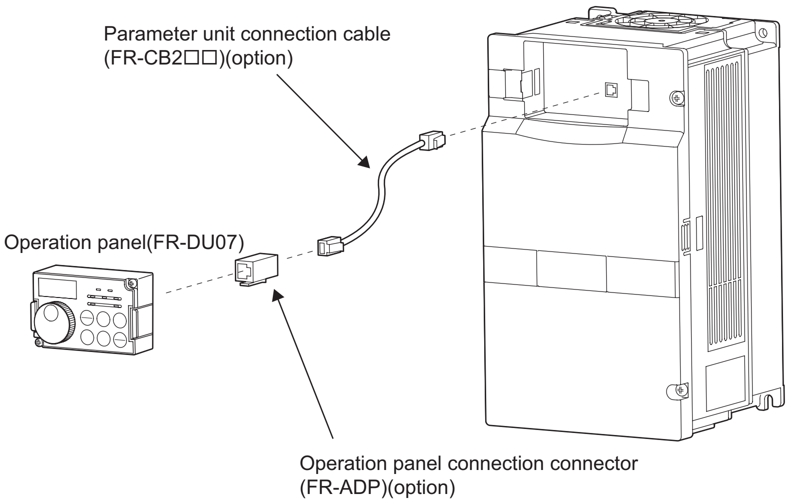
For wiring of the control circuit of the 75K or higher, separate away from wiring of the main circuit.
Make cuts in rubber bush of the inverter side and lead wires.





2.3.5 Mounting the operation panel (FR-DU07) on the enclosure surface

Having an operation panel on the enclosure surface is convenient. With a connection cable, you can mount the operation panel (FR-DU07) to the enclosure surface, and connect it to the inverter.
Use the option FR-CB2□□, or the following connector and cable available on the market.
Securely insert one end of connection cable into the PU connector of the inverter and the other end into the connection connector of the operation panel (FR-DU07) along the guides until the stoppers are fixed.

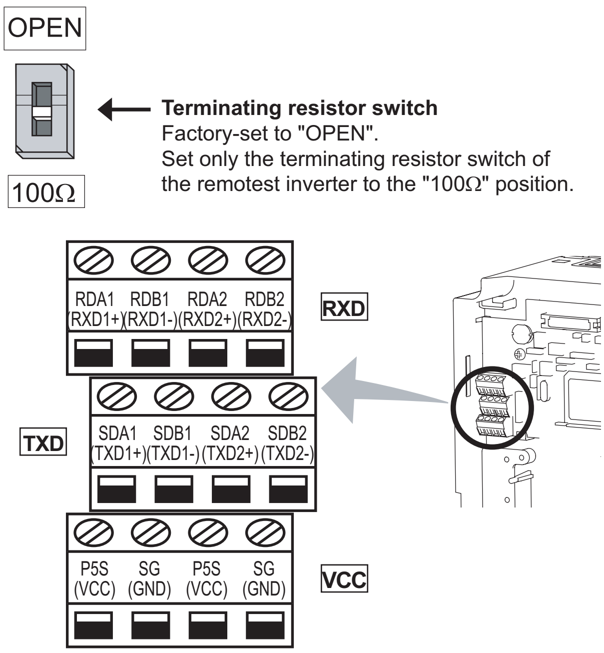


CAUTION

Do not connect the cable to a LAN port of a personal computer, to a fax modem socket, or to a telephone connector. Doing so may damage the inverter and the connected device due to the differences in the electric specifications.

2.3.6 RS-485 terminal block

- Conforming standard: EIA-485(RS-485)
- Transmission format: Multidrop link
- Communication speed: MAX 38400bps
- Overall length: 500m
- Connection cable:Twisted pair cable
  (4 pairs)



2.3.7 Communication operation

Using the PU connector or RS-485 terminal, you can perform communication operation from a personal computer etc. When the PU connector is connected with a personal, FA or other computer by a communication cable, a user program can run and monitor the inverter or read and write to parameters.
For the Mitsubishi inverter protocol (computer link operation), communication can be performed with the PU connector and RS-485 terminal.
For the Modbus-RTU protocol, communication can be performed with the RS-485 terminal.
For further details, *refer to page 224*.

2

WIRING

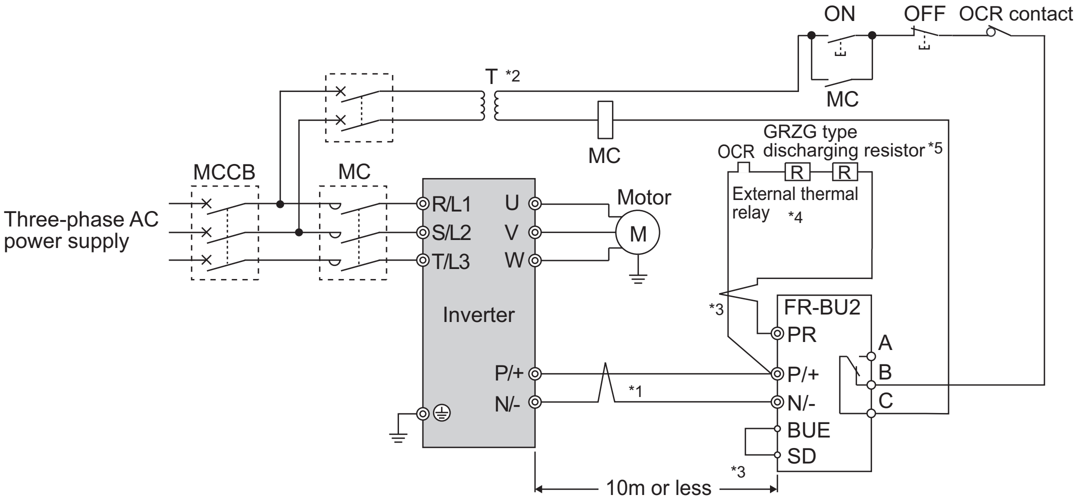
2.4 Connection of stand-alone option units

The inverter accepts a variety of stand-alone option units as required.
Incorrect connection will cause inverter damage or accident. Connect and operate the option unit carefully in accordance with the corresponding option unit manual.

2.4.1 Connection of the brake unit (FR-BU2)

Connect the brake unit (FR-BU2) as shown below to improve the braking capability at deceleration.

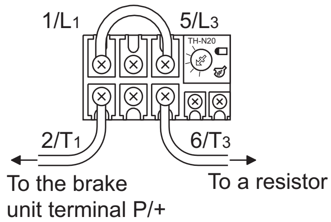
(1) Connection example with the GRZG type discharging resistor



*1 Connect the inverter terminals (P/+, N/-) and brake unit (FR-BU2) terminals so that their terminal names match with each other. (Incorrect connection will damage the inverter and brake unit.)
*2 When the power supply is 400V class, install a step-down transformer.
*3 Keep a wiring distance of within 5m between the inverter, brake unit (FR-BU2) and discharging resistor. Even when the wiring is twisted, the cable length must not exceed 10m. When twisting, twist at least 5 times per meter.
The brake unit may be damaged if cables are not twisted when the wiring length is 5m or more or the wiring length exceeds 10m or more even if cables are twisted.
*4 It is recommended to install an external thermal relay to prevent overheat of discharging resistors.
*5 Refer to FR-BU2 manual for connection method of discharging resistor.

<Recommended external thermal relay>

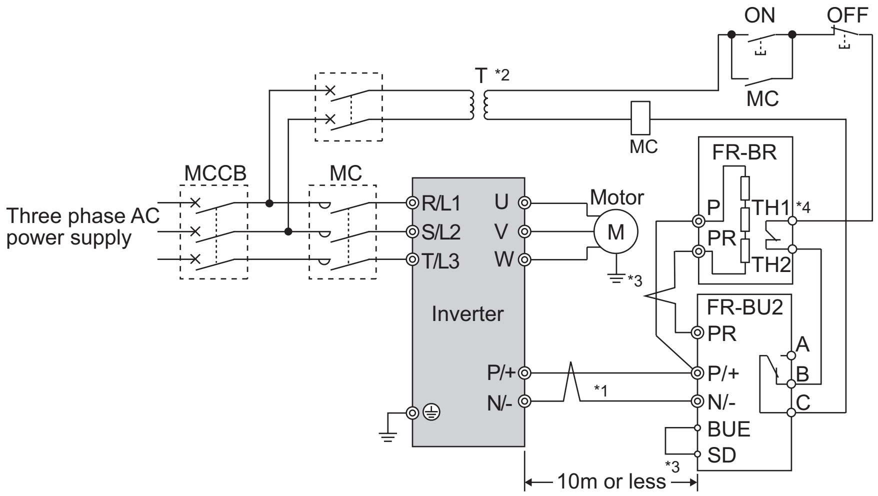
Brake Unit	Discharging Resistor	Recommended External Thermal Relay
FR-BU2-1.5K	GZG 300W-50Ω (one)	TH-N20CXHZ 1.3A
FR-BU2-3.7K	GRZG 200-10Ω (three in series)	TH-N20CXHZ 3.6A
FR-BU2-7.5K	GRZG 300-5Ω (four in series)	TH-N20CXHZ 6.6A
FR-BU2-15K	GRZG 400-2Ω (six in series)	TH-N20CXHZ 11A
FR-BU2-H7.5K	GRZG 200-10Ω (six in series)	TH-N20CXHZ 3.6A
FR-BU2-H15K	GRZG 300-5Ω (eight in series)	TH-N20CXHZ 6.6A
FR-BU2-H30K	GRZG 400-2Ω (twelve in series)	TH-N20CXHZ 11A



CAUTION

- Set "1" in *Pr. 0 Brake mode selection* of the FR-BU2 to use GRZG type discharging resistor.
- Do not remove a jumper across terminal P/+ and P1 except when connecting a DC reactor.

(2) FR-BR-(H) connection example with resistor unit



*1 Connect the inverter terminals (P/+, N/-) and brake unit (FR-BU2) terminals so that their terminal names match with each other. (Incorrect connection will damage the inverter and brake unit.)
*2 When the power supply is 400V class, install a step-down transformer.
*3 The wiring distance between the inverter, brake unit (FR-BU) and resistor unit (FR-BR) should be within 5m. Even when the wiring is twisted, the cable length must not exceed 10m.
*4 The contact between TH1 and TH2 is closed in the normal status and is open at a fault.

CAUTION

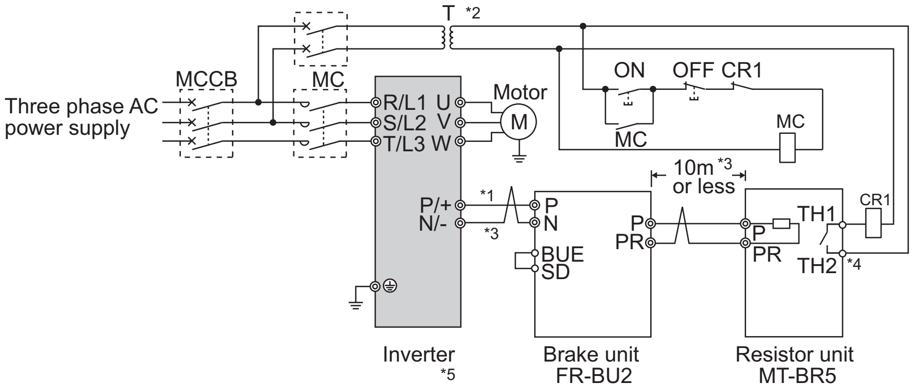
· Do not remove a jumper across terminal P/+ and P1 except when connecting a DC reactor.

(3) Connection example with MT-BR5 type resistor unit

After making sure that the wiring is correct, set the following parameters:

· *Pr. 30 Regenerative function selection* = "1"
· *Pr. 70 Special regenerative brake duty* = "0 (initial value)"

Set *Pr. 0 Brake mode selection* = "2" in the brake unit FR-BU2.



*1 Connect the inverter terminals (P/+, N/-) and brake unit (FR-BU2) terminals so that their terminal names match with each other. (Incorrect connection will damage the inverter and brake unit.)
*2 When the power supply is 400V class, install a step-down transformer.
*3 The wiring distance between the inverter, brake unit (FR-BU2) and resistor unit (MT-BR5) should be within 5m. If twisted wires are used, the distance should be within 10m.
*4 The contact between TH1 and TH2 is open in the normal status and is closed at a fault.
*5 CN8 connector used with the MT-BU5 type brake unit is not used.

CAUTION

· The stall prevention (overvoltage), oL, does not occur while *Pr. 30 Regenerative function selection* = "1" and *Pr. 70 Special regenerative brake duty* = "0% (initial setting)."

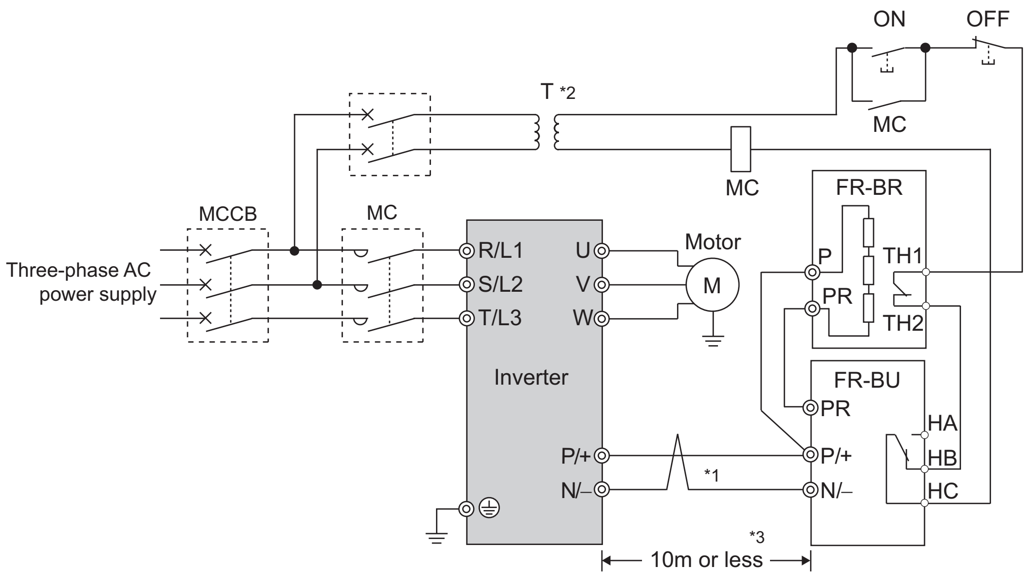
♦ Parameters referred to ♦

Pr.30 Regenerative function selection ☞ *Refer to page 125*
Pr.70 Special regenerative brake duty ☞ *Refer to page 125*

2.4.2 Connection of the brake unit (FR-BU/MT-BU5)

When connecting the brake unit (FR-BU(H)/MT-BU5) to improve the brake capability at deceleration, make connection as shown below.

(1) Connection with the FR-BU (55K or lower)



*1 Connect the inverter terminals (P/+, N/-) and brake unit (FR-BU (H)) terminals so that their terminal signals match with each other. (Incorrect connection will damage the inverter.)

*2 When the power supply is 400V class, install a step-down transformer.

*3 The wiring distance between the inverter, brake unit (FR-BU) and resistor unit (FR-BR) should be within 5m. If twisted wires are used, the distance should be within 10m.

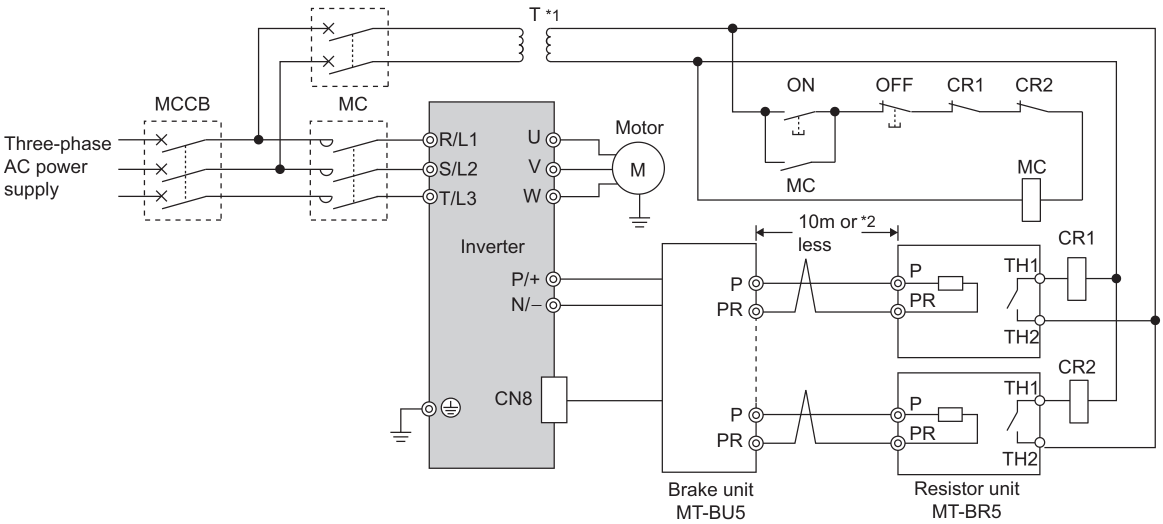
CAUTION

- If the transistors in the brake unit should become faulty, the resistor can be unusually hot, causing a fire. Therefore, install a magnetic contactor on the inverter's input side to configure a circuit so that a current is shut off in case of fault.
- Do not remove a jumper across terminal P/+ and P1 except when connecting a DC reactor.

(2) Connection with the MT-BU5 (75K or higher)

After making sure that the wiring is correct, set the following parameters:

- *Pr. 30 Regenerative function selection* = "1"
- *Pr. 70 Special regenerative brake duty* = "10%"



*1 When the power supply is 400V class, install a step-down transformer.

*2 The wiring length between the resistor unit and brake resistor should be 10m maximum when wires are twisted and 5m maximum when wires are not twisted.

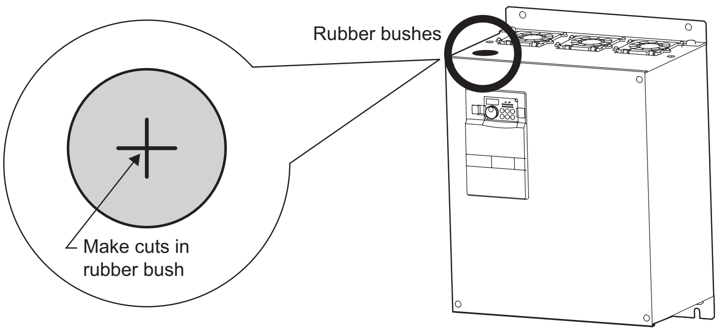
CAUTION

- Install the brake unit in a place where a cooling air reaches the brake unit heatsink and within a distance of the cable supplied with the brake unit reaches the inverter.
- For wiring of the brake unit and inverter, use an accessory cable supplied with the brake unit. Connect the main circuit cable to the inverter terminals P/+ and N/- and connect the control circuit cable to the CN8 connector inside by making cuts in the rubber bush at the top of the inverter for leading the cable.
- The brake unit which uses multiple resistor units has terminals equal to the number of resistor units. Connect one resistor unit to one pair of terminal (P, PR).

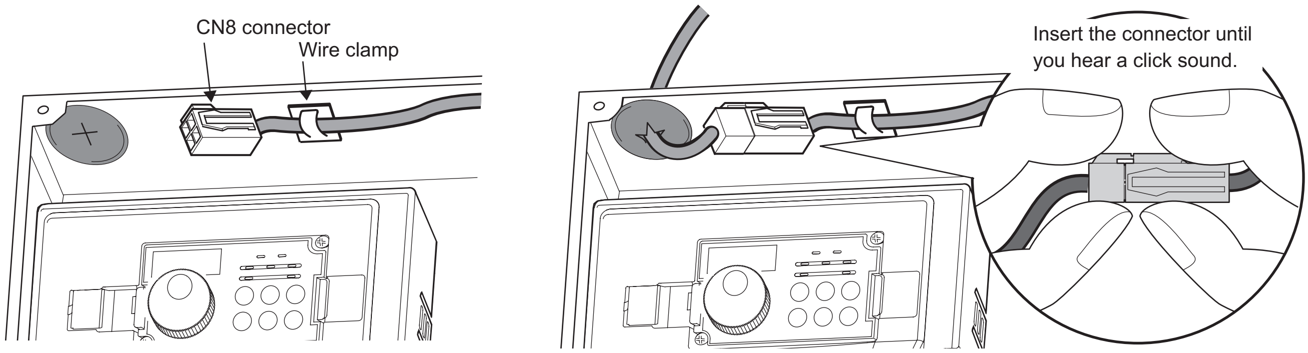
<Inserting the CN8 connector>

Make cuts in rubber bush of the upper portion of the inverter and lead a cable.

1) Make cuts in the rubber bush for leading the CN8 connector cable with a nipper or cutter knife.



2) Insert a connector on the MT-BU5 side through a rubber bush to connect to a connector on the inverter side.



CAUTION

Clamp the CN8 connector cable on the inverter side with a wire clamp securely.

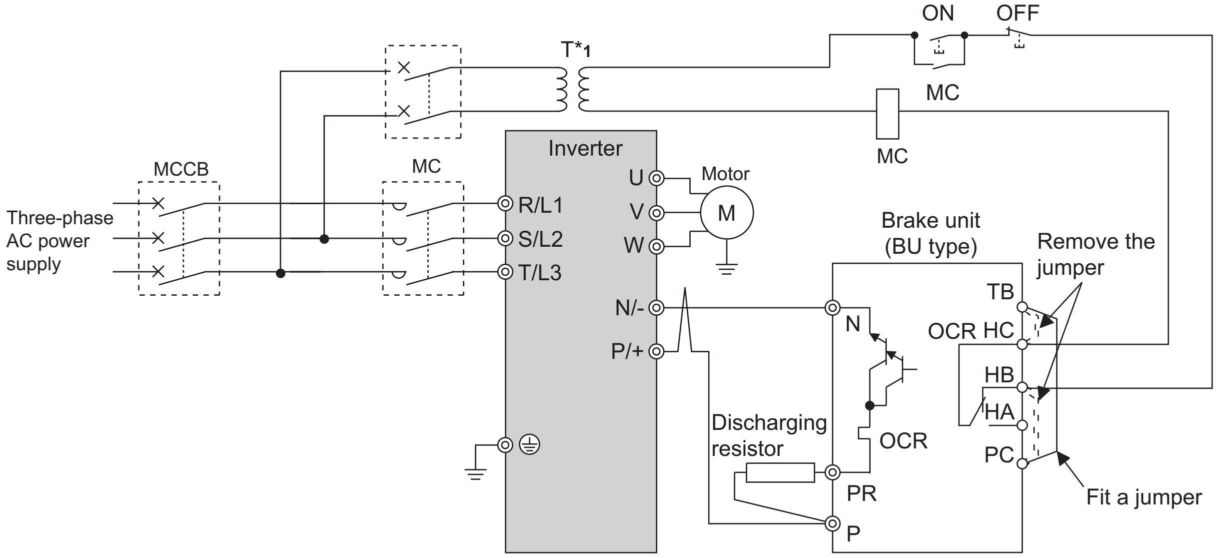
♦ Parameters referred to ♦

Pr.30 Regenerative function selection ☞ *Refer to page 125*
Pr.70 Special regenerative brake duty ☞ *Refer to page 125*

2 WIRING

2.4.3 Connection of the brake unit (BU type)

Connect the brake unit (BU type) correctly as shown below. Incorrect connection will damage the inverter. Remove the jumper across terminals HB and PC and terminals TB and HC of the brake unit and fit it to across terminals PC and TB.



*1 When the power supply is 400V class, install a step-down transformer.

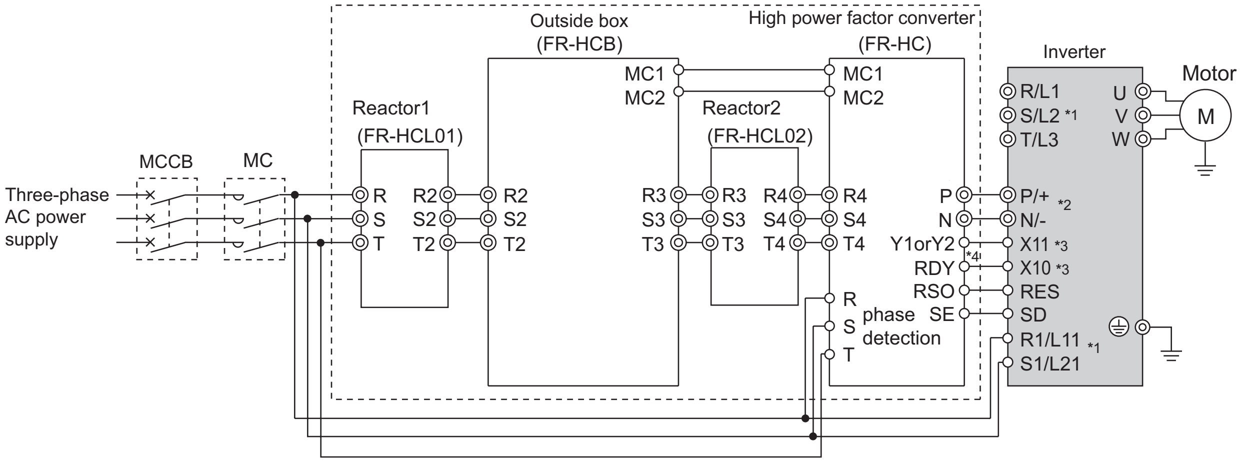
CAUTION

- The wiring distance between the inverter, brake unit and discharging resistor should be within 2m. If twisted wires are used, the distance should be within 5m.
- If the transistors in the brake unit should become faulty, the resistor can be unusually hot, causing a fire. Therefore, install a magnetic contactor on the inverter's power supply side to shut off a current in case of fault.
- Do not remove a jumper across terminal P/+ and P1 except when connecting a DC reactor.

2.4.4 Connection of the high power factor converter (FR-HC/MT-HC)

When connecting the high power factor converter (FR-HC/MT-HC) to suppress power harmonics, perform wiring securely as shown below. Incorrect connection will damage the high power factor converter and inverter.
After making sure that the wiring is correct, set "2" in *Pr. 30 Regenerative function selection*. (*Refer to page 125*.)

(1) Connection with the FR-HC (55K or lower)



*1 Remove the jumpers across the inverter terminals R/L1 and R1/L11 and terminals S/L2 and S1/L21, and connect the control circuit power supply to the R1/L11 and S1/L21 terminals. Do not connect anything to the power input terminals R/L1, S/L2, and T/L3. Incorrect connection will damage the inverter. (E.OPT (option fault) will occur. (*Refer to page 318.*))

*2 Do not insert the MCCB between terminals P/+ and N/- (P/+ and P/+, N/- and N/-). Opposite polarity of terminals N/-, P/+ will damage the inverter.

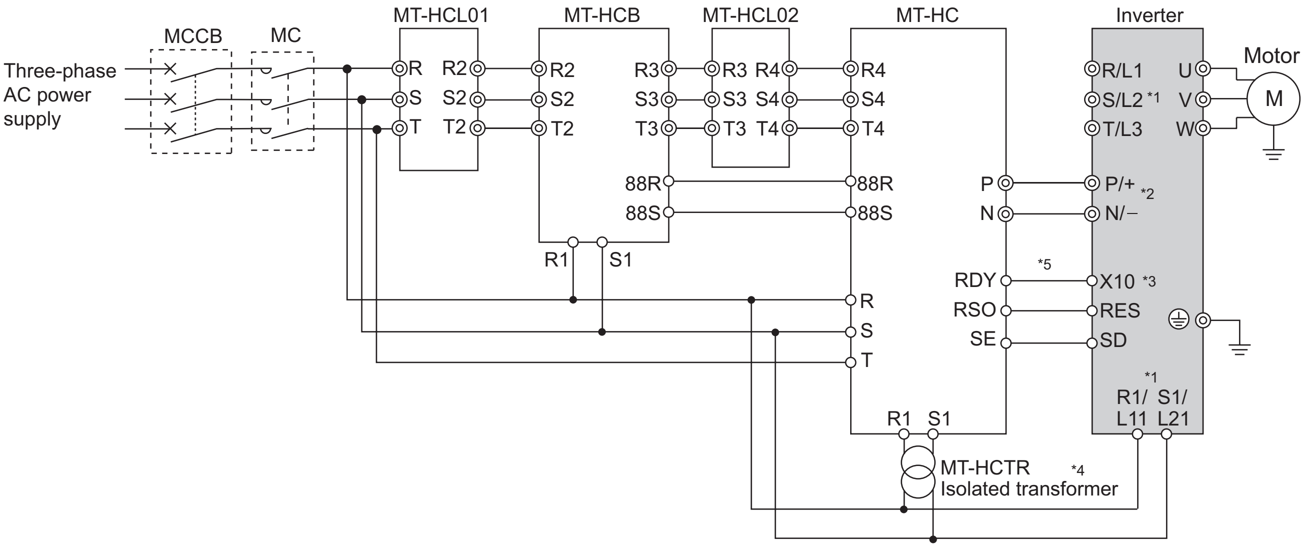
*3 Use *Pr. 178 to Pr. 189 (input terminal function selection)* to assign the terminals used for the X10 (X11) signal. (*Refer to page 133.*)
For communication where the start command is sent only once, e.g. RS-485 communication operation, use the X11 signal when making setting to hold the mode at occurrence of an instantaneous power failure. (*Refer to page 125.*)

*4 Be sure to connect terminal RDY of the FR-HC to the X10 signal or MRS signal assigned terminal of the inverter, and connect terminal SE of the FR-HC to terminal SD of the inverter. Without proper connecting, FR-HC will be damaged.

CAUTION

- The voltage phases of terminals R/L1, S/L2, T/L3 and terminals R4, S4, T4 must be matched.
- Use sink logic (initial setting) when the FR-HC is connected. The FR-HC cannot be connected when source logic is selected.
- Do not connect a DC reactor to the inverter when FR-HC is connected.
- Do not remove a jumper across terminal P/+ and P1.

(2) Connection with the MT-HC (75K or higher)



*1 Remove the jumper across terminals R and R1, S and S1 of the inverter, and connect the control circuit power supply to the R1 and S1 terminals. Do not connect anything to the power input terminals R/L1, S/L2, and T/L3. Incorrect connection will damage the inverter. (E.OPT (option fault) will occur. (*Refer to page 318.*)

*2 Do not insert the MCCB between terminals P/+ and N/- (P/+ and P/+, N/- and N/-). Opposite polarity of terminals N, P will damage the inverter.

*3 Use *Pr. 178 to Pr. 189 (input terminal function selection)* to assign the terminals used for the X10 (X11) signal. (*Refer to page 133.)* For communication where the start command is sent only once, e.g. RS-485 communication operation, use the X11 signal when making setting to hold the mode at occurrence of an instantaneous power failure. *(Refer to page 125.)*

*4 Connect the power supply to terminals R1 and S1 of the MT-HC via an isolated transformer.

*5 Be sure to connect terminal RDY of the MT-HC to the X10 signal or MRS signal assigned terminal of the inverter, and connect terminal SE of the MT-HC to terminal SD of the inverter. Without proper connecting, MT-HC will be damaged.

CAUTION

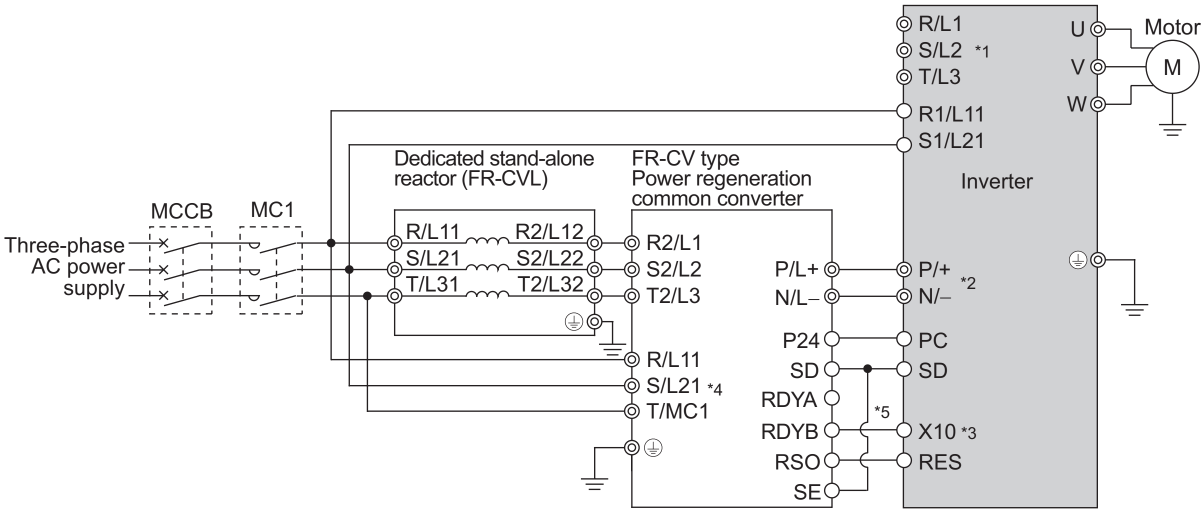
· The voltage phases of terminals R/L1, S/L2, T/L3 and terminals R4, S4, T4 must be matched.
· Use sink logic (initial setting) when the MT-HC is connected. The MT-HC cannot be connected when source logic is selected.
· When connecting the inverter to the MT-HC, do not connect the DC reactor provided to the inverter.

♦ Parameters referred to ♦

Pr.30 Regenerative function selection ☞ Refer to page 125

2.4.5 Connection of the power regeneration common converter (FR-CV) (55K or lower)

When connecting the power regeneration common converter (FR-CV), make connection so that the inverter terminals (P/+, N/-) and the terminal symbols of the power regeneration common converter (FR-CV) are the same.
After making sure that the wiring is correct, set "2" in *Pr. 30 Regenerative function selection*. *(Refer to page 125.)*



*1 Remove the jumpers across terminals R/L1 and R1/L11 and terminals S/L2 and S1/L21 of the inverter, and connect the control circuit power supply across terminals R1/L11 and S1/L21. Do not connect anything to the power input terminals R/L1, S/L2, T/L3. Incorrect connection will damage the inverter. (E.OPT (option fault) will occur. *(Refer to page 318.)*)

*2 Do not insert the MCCB between the terminals P/+ and N/- (between P/L+ and P/+, between N/L- and N/-). Opposite polarity of terminals N/-, P/+ will damage the inverter.

*3 Assign the terminal for X10 signal using any of *Pr. 178 to Pr. 189 (input terminal function selection)*. *(Refer to page 133)*

*4 Be sure to connect the power supply and terminals R/L11, S/L21, T/MC1.
Operating the inverter without connecting them will damage the power regeneration common converter.

*5 Be sure to connect terminal RDYB of the FR-CV to the X10 signal or MRS signal assigned terminal of the inverter, and connect terminal SE of the FR-CV to terminal SD of the inverter. Without proper connecting, FR-CV will be damaged.

CAUTION

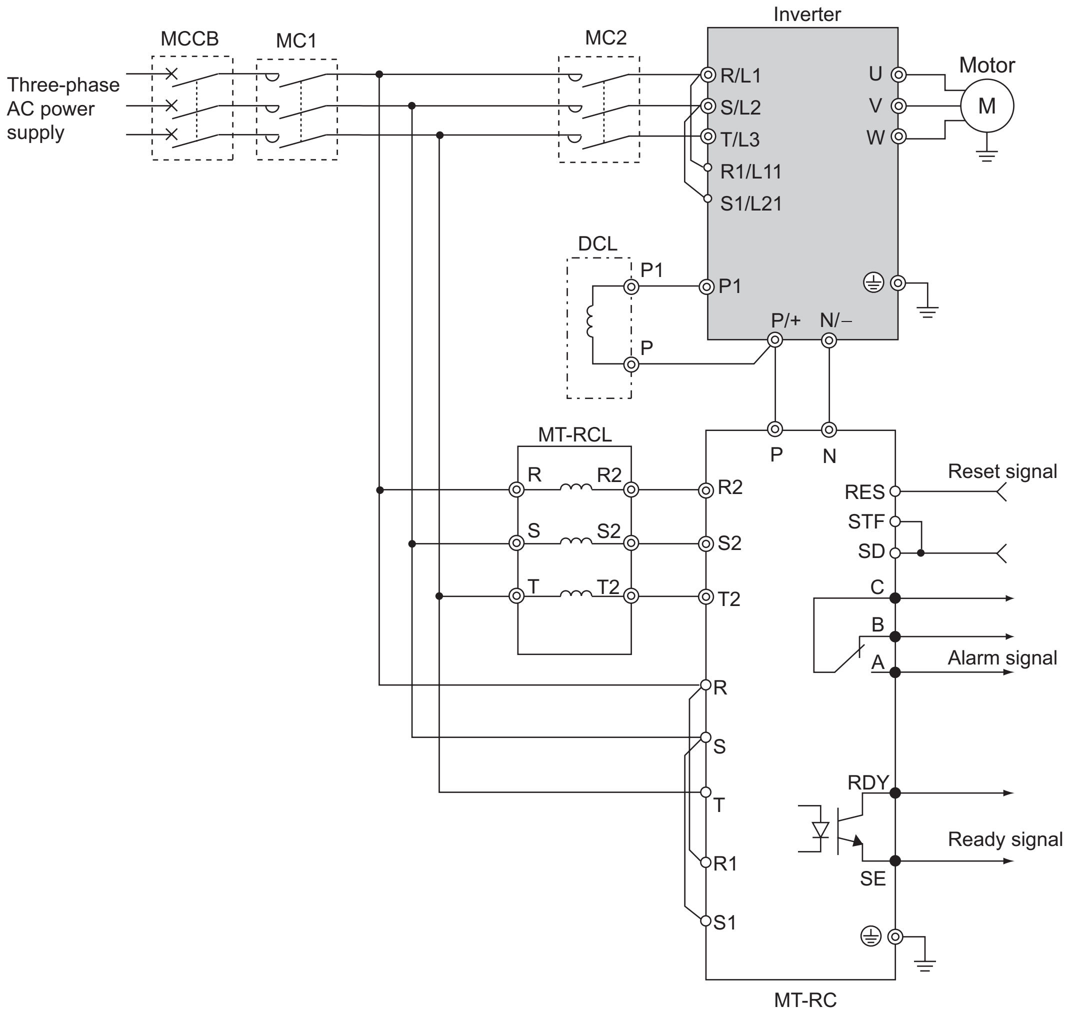
- The voltage phases of terminals R/L11, S/L21, T/MC1 and terminals R2/L1, S2/L2, T2/L3 must be matched.
- Use sink logic (initial setting) when the FR-CV is connected. The FR-CV cannot be connected when source logic is selected.
- Do not connect a DC reactor to the inverter when FR-CV is connected.
- Do not remove a jumper across terminal P/+ and P1.

♦ Parameters referred to ♦

Pr.30 Regenerative function selection ☞ Refer to page 125

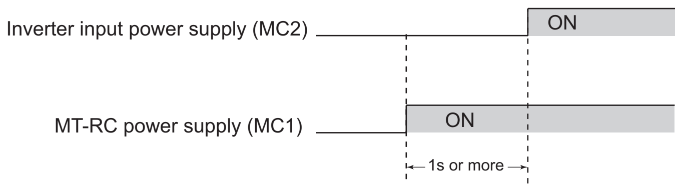
2.4.6 Connection of the power regeneration converter (MT-RC) (75K or higher)

When connecting a power regeneration converter (MT-RC), perform wiring securely as shown below. Incorrect connection will damage the regeneration converter and inverter. After connecting securely, set "1" in *Pr. 30 Regenerative function selection* and "0" in *Pr. 70 Special regenerative brake duty*.



CAUTION

- When using the FR-F700P series together with the MT-RC, install a magnetic contactor (MC) at the input side of the inverter so that power is supplied to the inverter after 1s or more has elapsed after powering ON the MT-RC. When power is supplied to the inverter prior to the MT-RC, the inverter and the MT-RC may be damaged or the MCCB may trip or be damaged.
- Refer to the MT-RC manual for precautions for connecting the power coordination reactor and others.

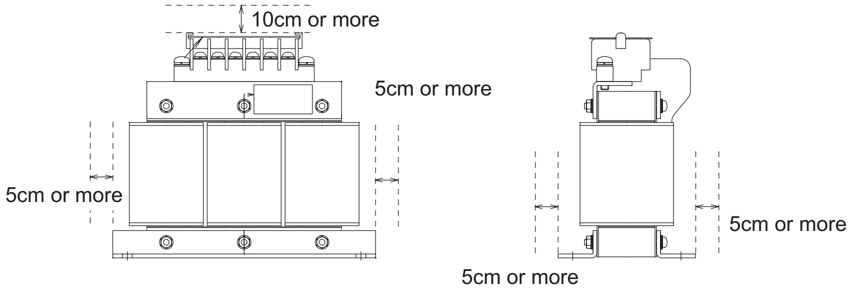


♦ Parameters referred to ♦

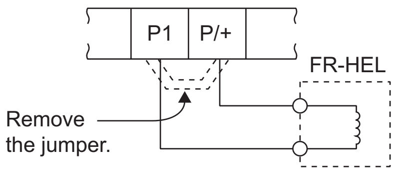
Pr.30 Regenerative function selection ☞ *Refer to page 125*
Pr.70 Special regenerative brake duty ☞ *Refer to page 125*

2.4.7 Connection of the power factor improving DC reactor (FR-HEL)

(1) Keep the surrounding air temperature within the permissible range (-10°C to +50°C). Keep enough clearance around the reactor because it heats up. (Take 10cm or more clearance on top and bottom and 5cm or more on left and right regardless of the installation direction.)



(2) When using the DC reactor (FR-HEL), connect it between terminals P1 and P/+.
For the 55K or lower, the jumper connected across terminals P1 and P/+ must be removed. Otherwise, the reactor will not exhibit its performance.
For the 75K or higher, a DC reactor is supplied. Always install the reactor.



CAUTION

- The wiring distance should be within 5m.
- The size of the cables used should be equal to or larger than that of the power supply cables (R/L1, S/L2, T/L3). *(Refer to page 20)*

3 PRECAUTIONS FOR USE OF THE INVERTER

This chapter explains the "PRECAUTIONS FOR USE OF THE INVERTER" for use of this product.
Always read the instructions before using the equipment.

3.1 EMC and leakage currents

3.1.1 Leakage currents and countermeasures

Capacitances exist between the inverter I/O cables, other cables and earth and in the motor, through which a leakage current flows. Since its value depends on the static capacitances, carrier frequency, etc., low acoustic noise operation at the increased carrier frequency of the inverter will increase the leakage current. Therefore, take the following measures. Select the earth leakage circuit breaker according to its rated sensitivity current, independently of the carrier frequency setting.

(1) To-earth (ground) leakage currents

Leakage currents may flow not only into the inverter's own line but also into the other lines through the earth (ground) cable, etc. These leakage currents may operate earth (ground) leakage circuit breakers and earth leakage relays unnecessarily.

- Suppression technique
  - If the carrier frequency setting is high, decrease the *Pr. 72 PWM frequency selection* setting. Note that motor noise increases.Selecting *Pr. 240 Soft-PWM operation selection* makes the sound inoffensive.
  - By using earth leakage circuit breakers designed for harmonic and surge suppression in the inverter's own line and other line, operation can be performed with the carrier frequency kept high (with low noise).
- To-earth (ground) leakage currents
  - Take caution as long wiring will increase the leakage current. Decreasing the carrier frequency of the inverter reduces the leakage current.
  - Increasing the motor capacity increases the leakage current. The leakage current of the 400V class is larger than that of the 200V class.

(2) Line-to-line leakage currents

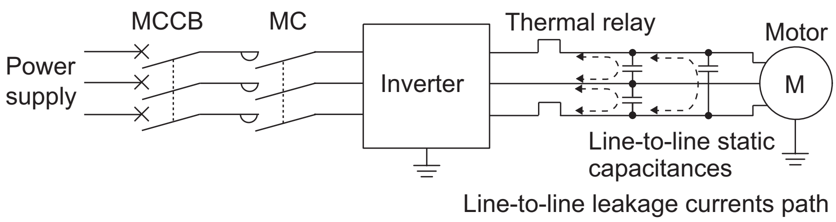
Harmonics of leakage currents flowing in static capacitances between the inverter output cables may operate the external thermal relay unnecessarily. When the wiring length is long (50m or more) for the 400V class small-capacity model (7.5K or lower), the external thermal relay is likely to operate unnecessarily because the ratio of the leakage current to the rated motor current increases.

- Line-to-line leakage current data example (200V class)

Motor Capacity (kW)	Rated Motor Current(A)	Leakage Currents(mA)	
		Wiring length 50m	Wiring length 100m
0.4	1.8	310	500
0.75	3.2	340	530
1.5	5.8	370	560
2.2	8.1	400	590
3.7	12.8	440	630
5.5	19.4	490	680
7.5	25.6	535	725

· Motor: SF-JR 4P
· Carrier frequency: 14.5kHz
· Used wire: $2mm^2$, 4cores Cabtyre cable

*The leakage currents of the 400V class are about twice as large.



Line-to-line leakage currents path

- Measures
  - Use *Pr. 9 Electronic thermal O/L relay*.
  - If the carrier frequency setting is high, decrease the *Pr. 72 PWM frequency selection* setting. Note that motor noise increases.Selecting *Pr. 240 Soft-PWM operation selection* makes the sound inoffensive. To ensure that the motor is protected against line-to-line leakage currents, it is recommended to use a temperature sensor to directly detect motor temperature.
- Installation and selection of moulded case circuit breaker

  Install a moulded case circuit breaker (MCCB) on the power receiving side to protect the wiring of the inverter input side. Select the MCCB according to the inverter input side power factor (which depends on the power supply voltage, output frequency and load). Especially for a completely electromagnetic MCCB, one of a slightly large capacity must be selected since its operation characteristic varies with harmonic currents. (Check it in the data of the corresponding breaker.) As an earth leakage circuit breaker, use the Mitsubishi earth leakage circuit breaker designed for harmonics and surge suppression.

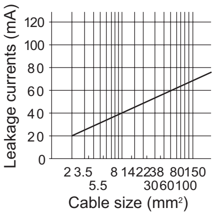
(3) Selection of rated sensitivity current of earth leakage circuit breaker

When using the earth leakage current breaker with the inverter circuit, select its rated sensitivity current as follows, independently of the PWM carrier frequency:

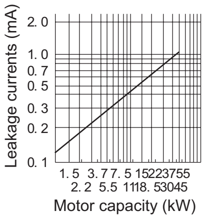
- Breaker designed for harmonic and surge suppression
  Rated sensitivity current:
  $I\Delta n \geq 10 \times (Ig1 + Ign + Igi + Ig2 + Igm)$
- Standard breaker
  Rated sensitivity current:
  $I\Delta n \geq 10 \times \{Ig1 + Ign + Igi + 3 \times (Ig2 + Igm)\}$

Ig1, Ig2: Leakage currents in wire path during commercial power supply operation
Ign: Leakage current of inverter input side noise filter
Igm: Leakage current of motor during commercial power supply operation
Igi: Leakage current of inverter unit

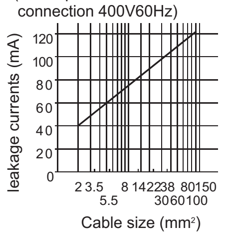
Example of leakage current of cable path per 1km during the commercial power supply operation when the CV cable is routed in metal conduit
(200V 60Hz)



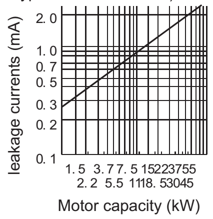
Leakage current example of three-phase induction motor during the commercial power supply operation
(200V 60Hz)



Example of leakage current per 1km during the commercial power supply operation when the CV cable is routed in metal conduit
(Three-phase three-wire delta connection 400V60Hz)

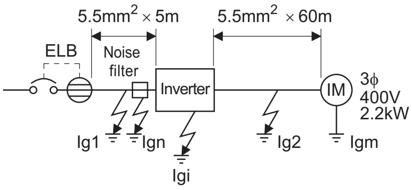


Leakage current example of three-phase induction motor during the commercial power supply operation
(Totally-enclosed fan-cooled type motor 400V60Hz)



For "人" connection, the amount of leakage current is appox.1/3 of the above value.

Example



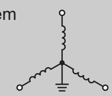
●Selection example (in the case of the left figure (400V class 人 connection))

	Breaker Designed for Harmonic and Surge Suppression	Standard Breaker
Leakage current Ig1 (mA)	$\frac{1}{3} \times 66 \times \frac{5m}{1000m} = 0.11$	
Leakage current Ign (mA)	0 (without noise filter)	
Leakage current Igi (mA)	1 (without EMC filter) Refer to the following table for the leakage current of the inverter*	
Leakage current Ig2 (mA)	$\frac{1}{3} \times 66 \times \frac{60m}{1000m} = 1.32$	
Motor leakage current Igm (mA)	0.36	
Total leakage current (mA)	2.79	6.15
Rated sensitivity current (mA)	30	100

* *Refer to page 15* for the presence/absence of the EMC filter.

●Inverter leakage current (with and without EMC filter)

Input power conditions
(200V class: 220V/60Hz, 400V class: 440V/60Hz, power supply unbalance within 3%)

	Voltage (V)	EMC Filter	
		ON (mA)	OFF (mA)
Phase grounding 	200	22(1)*	1
	400	30	1
Earthed-neutral system 	400	1	1

*For the FR-F720P-0.75K and 1.5K, the EMC filter is always valid.
The leakage current is 1mA.

CAUTION

- Install the earth leakage circuit breaker (ELB) on the input side of the inverter.
- In the 人 connection earthed-neutral system, the sensitivity current is blunt against an earth (ground) fault in the inverter output side. Earthing (Grounding) must conform to the requirements of national and local safety regulations and electrical codes. (NEC section 250, IEC 536 class 1 and other applicable standards)
- When the breaker is installed on the output side of the inverter, it may be unnecessarily operated by harmonics even if the effective value is less than the rating. In this case, do not install the breaker since the eddy current and hysteresis loss will increase, leading to temperature rise.
- The following models are standard breakers....BV-C1, BC-V, NVB, NV-L, NV-G2N, NV-G3NA and NV-2F earth leakage relay (except NV-ZHA), NV with AA neutral wire open-phase protection
  The other models are designed for harmonic and surge suppression....NV-C/NV-S/MN series, NV30-FA, NV50-FA, BV-C2, earth leakage alarm breaker (NF-Z), NV-ZHA, NV-H

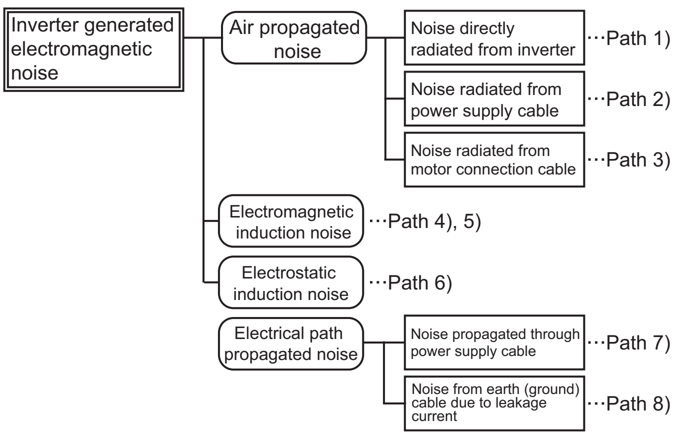
3.1.2 EMC measures

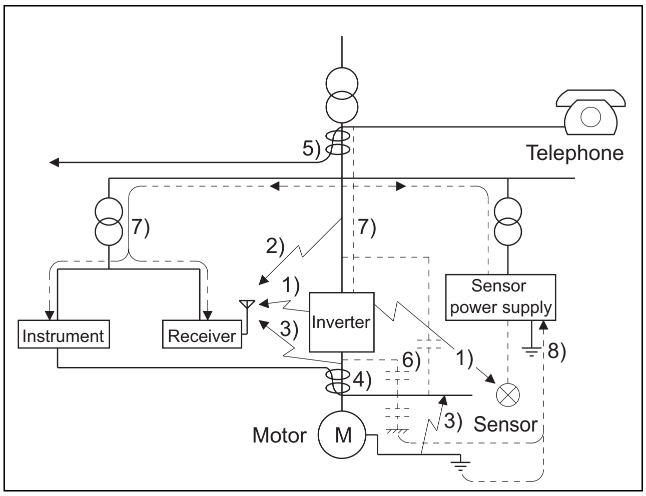
Some electromagnetic noises enter the inverter to malfunction it and others are radiated by the inverter to malfunction peripheral devices. Though the inverter is designed to have high immunity performance, it handles low-level signals, so it requires the following basic techniques. Also, since the inverter chops outputs at high carrier frequency, that could generate electromagnetic noises. If these electromagnetic noises cause peripheral devices to malfunction, EMI measures should be taken to suppress noises. These techniques differ slightly depending on EMI paths.

1) Basic techniques
- Do not run the power cables (I/O cables) and signal cables of the inverter in parallel with each other and do not bundle them.
- Use twisted pair shielded cables for the detector connection and control signal cables, and connect the sheathes of the shield cables to terminal SD.
- Earth (Ground) the inverter, motor, etc. at one point.

2) Techniques to reduce electromagnetic noises that enter and malfunction the inverter (Immunity measures)
When devices that generate many electromagnetic noises (which use magnetic contactors, magnetic brakes, many relays, for example) are installed near the inverter and the inverter may be malfunctioned by electromagnetic noises, the following measures must be taken:
- Provide surge suppressors for devices that generate many electromagnetic noises to suppress electromagnetic noises.
- Fit data line filters to signal cables.
- Earth (Ground) the shields of the detector connection and control signal cables with cable clamp metal.

3) Techniques to reduce electromagnetic noises that are radiated by the inverter to malfunction peripheral devices (EMI measures)
Inverter-generated electromagnetic noises are largely classified into those radiated by the cables connected to the inverter and inverter main circuits (I/O), those electromagnetically and electrostatically induced to the signal cables of the peripheral devices close to the main circuit power supply, and those transmitted through the power supply cables.



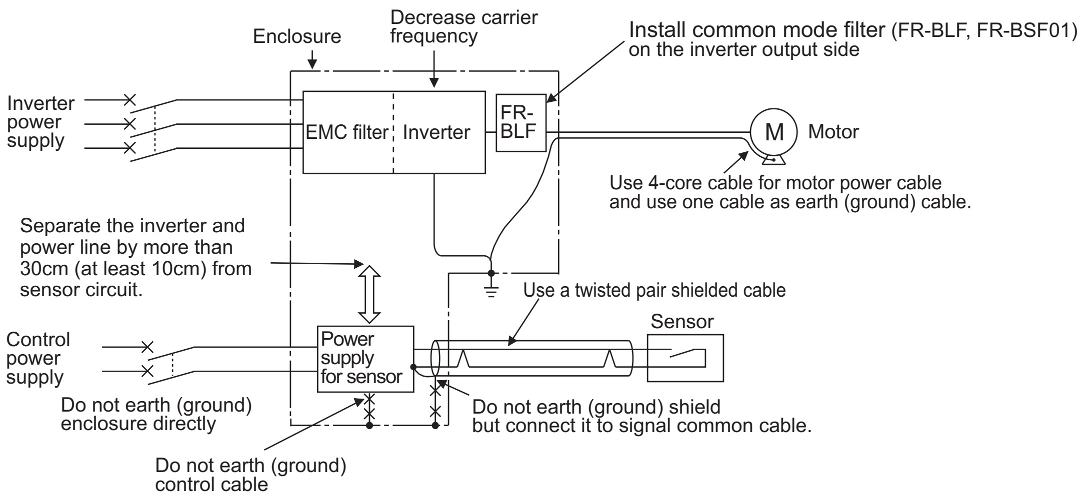


Propagation Path	Measures
1) 2) 3)	When devices that handle low-level signals and are liable to malfunction due to electromagnetic noises, e.g. instruments, receivers and sensors, are contained in the enclosure that contains the inverter or when their signal cables are run near the inverter, the devices may be malfunctioned by air-propagated electromagnetic noises. The following measures must be taken: (1) Install easily affected devices as far away as possible from the inverter. (2) Run easily affected signal cables as far away as possible from the inverter and its I/O cables. (3) Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them. (4) Set the EMC filter ON/OFF connector of the inverter to the ON position. *(Refer to page 15)* (5) Insert a common mode filters into I/O and capacitors between the input lines to suppress cable-radiated noises. (6) Use shield cables as signal cables and power cables and run them in individual metal conduits to produce further effects.
4) 5) 6)	When the signal cables are run in parallel with or bundled with the power cables, magnetic and static induction noises may be propagated to the signal cables to malfunction the devices and the following measures must be taken: (1) Install easily affected devices as far away as possible from the inverter. (2) Run easily affected signal cables as far away as possible from the I/O cables of the inverter. (3) Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them. (4) Use shield cables as signal cables and power cables and run them in individual metal conduits to produce further effects.
7)	When the power supplies of the peripheral devices are connected to the power supply of the inverter in the same line, inverter-generated noises may flow back through the power supply cables to malfunction the devices and the following measures must be taken: (1) Set the EMC filter ON/OFF connector of the inverter to the ON position. *(Refer to page 15)* (2) Install the common mode filter (FR-BLF, FR-BSF01) to the power cables (output cable) of the inverter.
8)	When a closed loop circuit is formed by connecting the peripheral device wiring to the inverter, leakage currents may flow through the earth (ground) cable of the inverter to malfunction the device. In such a case, disconnection of the earth (ground) cable of the device may cause the device to operate properly.

● Data line filter

Data line filter is effective as an EMC measure. Provide a data line filter for the detector cable, etc.

● EMC measures



REMARKS

•For compliance with the EU EMC Directive, refer to the ***Instruction Manual (Basic).***

PRECAUTIONS FOR USE OF THE INVERTER

3

3.1.3 Power supply harmonics

The inverter may generate power supply harmonics from its converter circuit to affect the power generator, power capacitor etc. Power supply harmonics are different from noise and leakage currents in source, frequency band and transmission path. Take the following countermeasure suppression techniques.

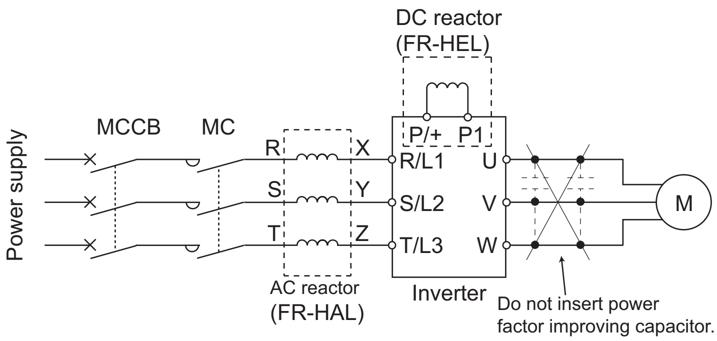
- The differences between harmonics and noises are indicated below:

Item	Harmonics	Noise
Frequency	Normally number 40 to 50 max. (3kHz or less)	High frequency (several 10kHz to 1GHz order)
Environment	To-electric channel, power impedance	To-space, distance, wiring path
Quantitative understanding	Theoretical calculation possible	Random occurrence, quantitative grasping difficult
Generated amount	Nearly proportional to load capacity	Depending on the current fluctuation ratio (larger as switching is faster)
Affected equipment immunity	Specified in standard per equipment	Different depending on maker's equipment specifications
Suppression example	Provide reactor.	Increase distance.

- **Measures**

The harmonic current generated from the inverter to the input side differs according to various conditions such as the wiring impedance, whether a reactor is used or not, and output frequency and output current on the load side.

For the output frequency and output current, we understand that they should be calculated in the conditions under the rated load at the maximum operating frequency.



CAUTION

The power factor improving capacitor and surge suppressor on the inverter output side may be overheated or damaged by the high frequency components of the inverter output. Also, since an excessive current flows in the inverter to activate overcurrent protection, do not provide a capacitor and surge suppressor on the inverter output side when the motor is driven by the inverter. For power factor improvement, install a reactor on the inverter input side or in the DC circuit.

3.1.4 Harmonic suppression guideline

Harmonic currents flow from the inverter to a power receiving point via a power transformer. The harmonic suppression guideline was established to protect other consumers from these outgoing harmonic currents.
The three-phase 200V input specifications 3.7kW or less are previously covered by "Harmonic suppression guideline for household appliances and general-purpose products" and other models are covered by "Harmonic suppression guideline for consumers who receive high voltage or special high voltage". However, the general-purpose inverter has been excluded from the target products covered by "Harmonic suppression guideline for household appliances and general-purpose products" in January 2004. Later, this guideline was repealed on September 6, 2004. All capacities of all models are now target products of "Harmonic suppression guideline for consumers who receive high voltage or special high voltage".

"Guideline for specific consumers"
This guideline sets forth the maximum values of harmonic currents outgoing from a high-voltage or especially high-voltage consumer who will install, add or renew harmonic generating equipment. If any of the maximum values is exceeded, this guideline requires that consumer to take certain suppression measures.

Table 1 Maximum Values of Outgoing Harmonic Currents per 1kW Contract Power

Received Power Voltage	5th	7th	11th	13th	17th	19th	23rd	Over 23rd
6.6kV	3.5	2.5	1.6	1.3	1.0	0.9	0.76	0.70
22kV	1.8	1.3	0.82	0.69	0.53	0.47	0.39	0.36
33kV	1.2	0.86	0.55	0.46	0.35	0.32	0.26	0.24

(1) Application of the harmonic suppression guideline for specific consumers

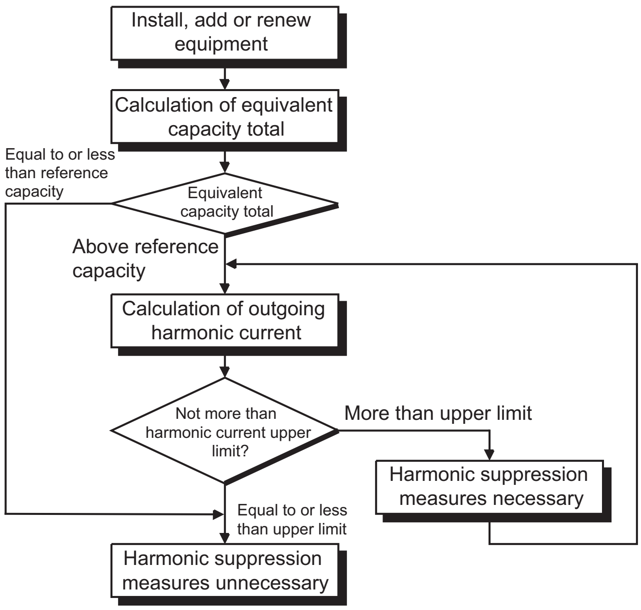


Table 2 Conversion factors for FR-F700P series

Class	Circuit Type		Conversion Factor (Ki)
3	Three-phase bridge (Capacitor smoothing)	Without reactor	K31 = 3.4
		With reactor (AC side)	K32 = 1.8
		With reactor (DC side)	K33 = 1.8
		With reactor (AC, DC sides)	K34 = 1.4
5	Self-exciting three-phase bridge	When high power factor converter is used	K5 = 0

Table 3 Equivalent Capacity Limits

Received Power Voltage	Reference Capacity
6.6kV	50kVA
22/33kV	300kVA
66kV or more	2000kVA

Table 4 Harmonic content (Values of the fundamental current is 100%)

Reactor	5th	7th	11th	13th	17th	19th	23rd	25th
Not used	65	41	8.5	7.7	4.3	3.1	2.6	1.8
Used (AC side)	38	14.5	7.4	3.4	3.2	1.9	1.7	1.3
Used (DC side)	30	13	8.4	5.0	4.7	3.2	3.0	2.2
Used (AC, DC sides)	28	9.1	7.2	4.1	3.2	2.4	1.6	1.4

1) Calculation of equivalent capacity P0 of harmonic generating equipment
The "equivalent capacity" is the capacity of a 6-pulse converter converted from the capacity of consumer's harmonic generating equipment and is calculated with the following equation.If the sum of equivalent capacities is higher than the limit in Table 3, harmonics must be calculated with the following procedure:

$P0 = \Sigma (Ki \times Pi)$ [kVA]
Ki: Conversion Factor(According to Table 2)
Pi: Rated capacity of harmonic generating equipment* [kVA]
i : Number indicating the conversion circuit type

* Rated capacity: Determined by the capacity of the applied motor and found in Table 5. It should be noted that the rated capacity used here is used to calculate generated harmonic amount and is different from the power supply capacity required for actual inverter drive.

2) Calculation of outgoing harmonic current
Outgoing harmonic current = fundamental wave current (value converted from received power voltage) × operation ratio × harmonic content
· Operation ratio: Operation ratio = actual load factor × operation time ratio during 30 minutes
· Harmonic content: Found in Table.

Table 5 Rated capacities and outgoing harmonic currents of inverter-driven motors

Applied Motor (kW)	Rated Current (A)		Fundamental Wave Current Converted from 6.6kV (mA)	Rated Capacity (kVA)	Outgoing Harmonic Current Converted from 6.6kV (mA) (No reactor, 100% operation ratio)							
	200V	400V			5th	7th	11th	13th	17th	19th	23rd	25th
0.75	2.74	1.37	83	0.97	53.95	34.03	7.055	6.391	3.569	2.573	2.158	1.494
1.5	5.5	2.75	167	1.95	108.6	68.47	14.20	12.86	7.181	5.177	4.342	3.006
2.2	7.93	3.96	240	2.81	156.0	98.40	20.40	18.48	10.32	7.440	6.240	4.320
3.7	13.0	6.50	394	4.61	257.1	161.5	33.49	30.34	16.94	12.21	10.24	7.092
5.5	19.1	9.55	579	6.77	376.1	237.4	49.22	44.58	24.90	17.95	15.05	10.42
7.5	25.6	12.8	776	9.07	504.4	318.2	65.96	59.75	33.37	24.06	20.18	13.97
11	36.9	18.5	1121	13.1	728.7	459.6	95.29	86.32	48.20	34.75	29.15	20.18
15	49.8	24.9	1509	17.6	980.9	618.7	128.3	116.2	64.89	46.78	39.24	27.16
18.5	61.4	30.7	1860	21.8	1209	762.6	158.1	143.2	79.98	57.66	48.36	33.48
22	73.1	36.6	2220	25.9	1443	910.2	188.7	170.9	95.46	68.82	57.72	39.96
30	98.0	49.0	2970	34.7	1931	1218	252.5	228.7	127.7	92.07	77.22	53.46
37	121	60.4	3660	42.8	2379	1501	311.1	281.8	157.4	113.5	95.16	65.88
45	147	73.5	4450	52.1	2893	1825	378.3	342.7	191.4	138.0	115.7	80.10
55	180	89.9	5450	63.7	3543	2235	463.3	419.7	234.4	169.0	141.7	98.10

Applied Motor (kW)	Rated Current (A)		Fundamental Wave Current Converted from 6.6kV (mA)	Rated Capacity (kVA)	Outgoing Harmonic Current Converted from 6.6kV (mA) (With DC reactor, 100% operation ratio)							
	200V	400V			5th	7th	11th	13th	17th	19th	23rd	25th
75	245	123	7455	87.2	2237	969	626	373	350	239	224	164
90	293	147	8909	104	2673	1158	748	445	419	285	267	196
110	357	179	10848	127	3254	1410	911	542	510	347	325	239
132	—	216	13091	153	3927	1702	1100	655	615	419	393	288
160	—	258	15636	183	4691	2033	1313	782	735	500	469	344
220	—	355	21515	252	6455	2797	1807	1076	1011	688	645	473
250	—	403	24424	286	7327	3175	2052	1221	1148	782	733	537
280	—	450	27273	319	8182	3545	2291	1364	1282	873	818	600
315	—	506	30667	359	9200	3987	2576	1533	1441	981	920	675
355	—	571	34606	405	10382	4499	2907	1730	1627	1107	1038	761
400	—	643	38970	456	11691	5066	3274	1949	1832	1247	1169	857
450	—	723	43818	512	13146	5696	3681	2191	2060	1402	1315	964
500	—	804	48727	570	14618	6335	4093	2436	2290	1559	1462	1072
560	—	900	54545	638	16364	7091	4582	2727	2564	1746	1636	1200

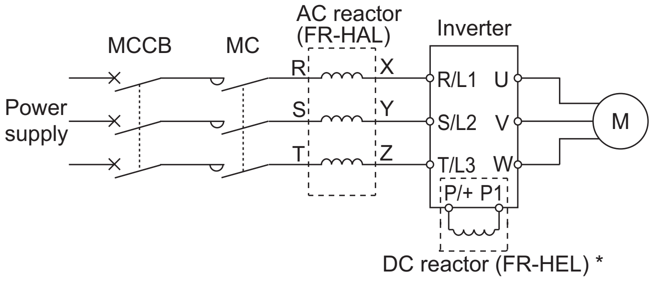
3) Harmonic suppression technique requirement
If the outgoing harmonic current is higher than the maximum value per 1kW (contract power) × contract power, a harmonic suppression technique is required.

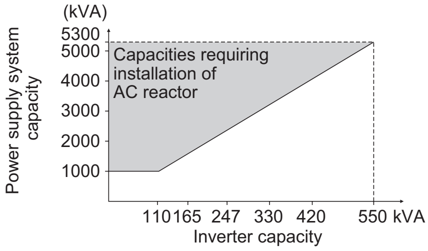
4) Harmonic suppression techniques

No.	Item	Description
1	Reactor installation (FR-HAL, FR-HEL)	Install an AC reactor (FR-HAL) on the AC side of the inverter or a DC reactor (FR-HEL) on its DC side or both to suppress outgoing harmonic currents.
2	High power factor converter (FR-HC, MT-HC)	The converter circuit is switched on-off to convert an input current waveform into a sine wave, suppressing harmonic currents substantially. The high power factor converter (FR-HC, MT-HC) is used with the standard accessory.
3	Installation of power factor improving capacitor	When used with a series reactor, the power factor improving capacitor has an effect of absorbing harmonic currents.
4	Transformer multi-phase operation	Use two transformers with a phase angle difference of 30° as in 人 - △, △ - △ combination to provide an effect corresponding to 12 pulses, reducing low-degree harmonic currents.
5	Passive filter (AC filter)	A capacitor and a reactor are used together to reduce impedances at specific frequencies, producing a great effect of absorbing harmonic currents.
6	Active filter	This filter detects the current of a circuit generating a harmonic current and generates a harmonic current equivalent to a difference between that current and a fundamental wave current to suppress a harmonic current at a detection point, providing a great effect of absorbing harmonic currents.

3.2 Installation of a reactor

When the inverter is connected near a large-capacity power transformer (1000kVA or more) or when a power capacitor is to be switched over, an excessive peak current may flow in the power input circuit, damaging the converter circuit. To prevent this, always install the AC reactor (FR-HAL)





When connecting the FR-HEL to the 55K or lower, remove the jumper across terminals P/+ and P1. For the 75K or higher, a DC reactor is supplied. Always install the reactor.

REMARKS

The wiring length between the FR-HEL and inverter should be 5m maximum and minimized. Use the same wire size as that of the power supply wire (R/L1, S/L2, T/L3). *(Refer to page 20)*

3.3 Power-OFF and magnetic contactor (MC)

(1) Inverter input side magnetic contactor (MC)

On the inverter input side, it is recommended to provide an MC for the following purposes.

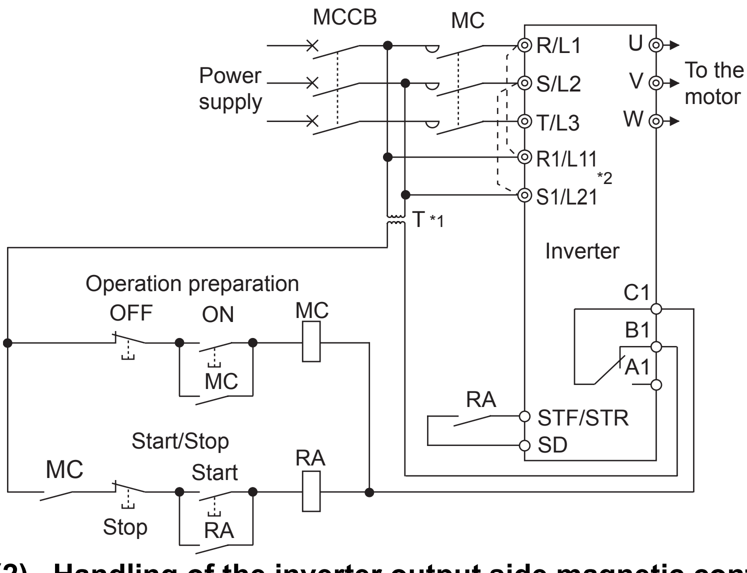
(Refer to *page 4* for selection.)

1) To release the inverter from the power supply when the fault occurs or when the drive is not functioning (e.g. emergency stop operation).
2) To prevent any accident due to an automatic restart at restoration of power after an inverter stop made by a power failure
3) To separate the inverter from the power supply to ensure safe maintenance and inspection work

The inverter's input side MC is used for the above purpose, select class JEM1038-AC3MC for the inverter input side current when making an emergency stop during normal operation.

REMARKS

Since repeated inrush current at power ON will shorten the life of the converter circuit (switching life is 100 million times (about 500,000 times for the 200V class 37K or higher)), frequent starts/stops must be avoided. Turn ON/OFF the inverter start controlling terminals (STF, STR) to run/stop the inverter.



• Inverter start/stop circuit example

As shown on the left, always use the start signal (ON or OFF of STF (STR) signal) to make a start or stop. *(Refer to page 138)*

*1 When the power supply is 400V class, install a step-down transformer.

*2 Connect the power supply terminals R1/L11, S1/L21 of the control circuit to the primary side of the MC to hold an alarm signal when the inverter's protective circuit is activated. At this time, remove jumpers across terminals R/L1 and R1/L11, and S/L2 and S1/L21. (Refer to *page 24* for removal of the jumper.)

(2) Handling of the inverter output side magnetic contactor

Switch the magnetic contactor between the inverter and general-purpose motor only when both the inverter and motor are at a stop. When the magnetic contactor is turned ON while the inverter is operating, overcurrent protection of the inverter and such will activate. When using a magnetic contactor to switch to a commercial power supply while using a general-purpose motor, it is recommended to use the bypass operation *Pr. 135 to Pr. 139*. *(Refer to page 274)*.

CAUTION

IPM motor is a synchronous motor with high-performance magnets embedded in the rotor. Motor terminals hold high-voltage while the motor is running even after the inverter power is turned OFF. Before wiring or inspection, the motor must be confirmed to be stopped. When the motor is driven by the load in applications such as fan and blower, a low-voltage manual contactor must be connected at the inverter's output side, and wiring and inspection must be performed while the contactor is open. Otherwise you may get an electric shock.

3.4 Inverter-driven 400V class motor

In the PWM type inverter, a surge voltage attributable to wiring constants is generated at the motor terminals. Especially for a 400V class motor, the surge voltage may deteriorate the insulation. When the 400V class motor is driven by the inverter, consider the following measures:

● Measures

Under general-purpose motor control
It is recommended to take either of the following measures:

(1) Rectifying the motor insulation and limiting the PWM carrier frequency according to the wiring length
For the 400V class motor, use an insulation-enhanced motor.
Specifically,
1)Specify the "400V class inverter-driven insulation-enhanced motor".
2)For the dedicated motor such as the constant-torque motor and low-vibration motor, use the "inverter-driven, dedicated motor".
3)Set *Pr. 72 PWM frequency selection* as indicated below according to the wiring length

	Wiring Length		
	50m or less	**50m to 100m**	**exceeding 100m**
Pr. 72 PWM frequency selection	15(14.5kHz) or less	9(9kHz) or less	4(4kHz) or less

(2) Suppressing the surge voltage on the inverter side
Connect the surge voltage suppression filter (FR-ASF-H/FR-BMF-H) to the 55K or lower and the sine wave filter (MT-BSL/BSC) to the 75K or higher on the inverter output side.

Under IPM motor control
Set *Pr.72 PWM frequency selection* according to the wiring length as shown below.

Applied inverter	Wiring Length	
	50m or less	**50m to 100m**
FR-F740P-0.75K to 1.5K	0(2kHz) to 15(14kHz)	5(2kHz) or less
Other	0(2kHz) to 15(14kHz)	9(6kHz) or less

CAUTION
- For details of *Pr. 72 PWM frequency selection , refer to page 182*. (When using an optional sine wave filter (MT-BSL/BSC) for the or more, set "25" in *Pr.72* (2.5kHz).)
- The surge voltage suppression filter (FR-ASF-H/FR-BMF-H) option and sine wave filter (MT-BSL/BSC) cannot be used under IPM motor control, so do not connect them.
- For explanation of surge voltage suppression filter (FR-ASF-H/FR-BMF-H) and sine wave filter (MT-BSL/BSC), refer to the manual of each option.

3.5 Precautions for use of the inverter

The FR-F700P series is a highly reliable product, but incorrect peripheral circuit making or operation/handling method may shorten the product life or damage the product.
Before starting operation, always recheck the following items.

(1) Use crimping terminals with insulation sleeve to wire the power supply and motor.

(2) Application of power to the output terminals (U, V, W) of the inverter will damage the inverter. Never perform such wiring.

(3) After wiring, wire offcuts must not be left in the inverter.
Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean. When drilling mounting holes in an enclosure etc., take care not to allow chips and other foreign matter to enter the inverter.

(4) Use cables of the size to make a voltage drop 2% or less.
If the wiring distance is long between the inverter and motor, a main circuit cable voltage drop will cause the motor torque to decrease especially at the output of a low frequency.
Refer to *page 20* for the recommended cable sizes.

(5) When using a general-purpose motor, the overall wiring length should be 500m or less.
When using an IPM motor, the overall wiring length should be 100m or less.
Especially for long distance wiring, the fast-response current limit function may decrease or the equipment connected to the output side may malfunction or become faulty under the influence of a charging current due to the stray capacity of the wiring. Therefore, note the overall wiring length. (*Refer to page 23*)

(6) Electromagnetic wave interference
The input/output (main circuit) of the inverter includes high frequency components, which may interfere with the communication devices (such as AM radios) used near the inverter. In this case, set the EMC filter valid to minimize interference. *(Refer to page 15)*

(7) Do not install a power factor correction capacitor, surge suppressor or capacitor type filter on the inverter output side.
This will cause the inverter to trip or the capacitor and surge suppressor to be damaged. If any of the above devices is installed, immediately remove it.

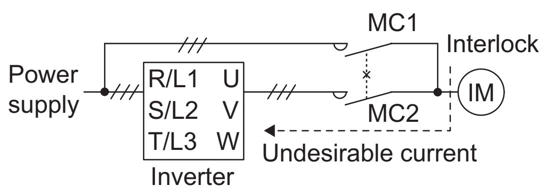
(8) For some short time after the power is switched OFF, a high voltage remains in the smoothing capacitor.
When accessing the inverter for inspection, wait for at least 10 minutes after the power supply has been switched OFF, and then make sure that the voltage across the main circuit terminals P/+ and N/- of the inverter is not more than 30VDC using a tester, etc.

(9) A short circuit or earth (ground) fault on the inverter output side may damage the inverter modules.
- Fully check the insulation resistance of the circuit prior to inverter operation since repeated short circuits caused by peripheral circuit inadequacy or an earth (ground) fault caused by wiring inadequacy or reduced motor insulation resistance may damage the inverter modules.
- Fully check the to-earth (ground) insulation and phase to phase insulation of the inverter output side before power-ON. Especially for an old motor or use in hostile atmosphere, securely check the motor insulation resistance etc.

(10) Do not use the inverter input side magnetic contactor to start/stop the inverter.
Since repeated inrush currents at power ON will shorten the life of the converter circuit (switching life is about 1,000,000 times), frequent starts and stops of the MC must be avoided.
Always use the start signal (ON/OFF of STF and STR signals) to start/stop the inverter. *(Refer to page 14)*

(11) Do not apply a voltage higher than the permissible voltage to the inverter I/O signal circuits.
Application of a voltage higher than the permissible voltage to the inverter I/O signal circuits or opposite polarity may damage the I/O devices. Especially check the wiring to prevent the speed setting potentiometer from being connected incorrectly to short terminals 10E and 5.

(12) When driving a general-purpose motor, provide electrical and mechanical interlocks for MC1 and MC2 which are used for bypass operation.
When the wiring is incorrect or if there is an electronic bypass circuit as shown on the right, the inverter will be damaged when the power supply is connected to the inverter U, V, W terminals due to arcs generated at the time of switch-over or chattering caused by a sequence error.



(13) If the machine must not be restarted when power is restored after a power failure, provide a magnetic contactor in the inverter's input side and also make up a sequence which will not switch on the start signal.
If the start signal (start switch) remains on after a power failure, the inverter will automatically restart as soon as the power is restored.

(14) Inverter input side magnetic contactor (MC)
On the inverter input side, connect a MC for the following purposes. (*Refer to page 4* for selection.)
1)To release the inverter from the power supply when a fault occurs or when the drive is not functioning (e.g. emergency stop operation). For example, MC avoids overheat or burnout of the brake resistor when heat capacity of the resistor is insufficient or brake regenerative transistor is damaged with short while connecting an optional brake resistor.
2)To prevent any accident due to an automatic restart at restoration of power after an inverter stop made by a power failure
3)To separate the inverter from the power supply to ensure safe maintenance and inspection work.
The inverter's input side MC is used for the above purpose, select class JEM1038-AC3 MC for the inverter input side current when making an emergency stop during normal operation.

(15) Handling of inverter output side magnetic contactor
Switch the magnetic contactor between the inverter and motor only when both the inverter and motor are at a stop. When the magnetic contactor is turned ON while the inverter is operating, overcurrent protection of the inverter and such will activate. When MC is provided for switching to the commercial power supply, for example, switch it ON/OFF after the inverter and motor have stopped.
IPM motor is a synchronous motor with high-performance magnets embedded in the rotor. Motor terminals hold high-voltage while the motor is running even after the inverter power is turned OFF. Before wiring or inspection, the motor must be confirmed to be stopped. When the motor is driven by the load in applications such as fan and blower, a low-voltage manual contactor must be connected at the inverter's output side, and wiring and inspection must be performed while the contactor is open. Otherwise you may get an electric shock.

(16) Countermeasures against inverter-generated EMI
If electromagnetic noise generated from the inverter causes frequency setting signal to fluctuate and motor rotation speed to be unstable when changing motor speed with analog signal, the following countermeasures are effective.
- Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them.
- Run signal cables as far away as possible from power cables (inverter I/O cables).
- Use shield cables as signal cables.
- Install a ferrite core on the signal cable (Example: ZCAT3035-1330 TDK).

(17) Instructions for overload operation
When performing an operation of frequent start/stop of the inverter, increase/decrease in the temperature of the transistor element of the inverter may repeat due to a continuous flow of large current, shortening the life from thermal fatigue. Since thermal fatigue is related to the amount of current, the life can be increased by reducing bound current, starting current, etc. Decreasing current may increase the life. However, decreasing current will result in insufficient torque and the motor may not start. A counter action for this is to raise the permissible current level by increasing the inverter capacity (up to 2 ranks) when using a general-purpose motor, and by increasing the inverter and IPM motor capacities when using an IPM motor.

(18) Make sure that the specifications and rating match the system requirements.

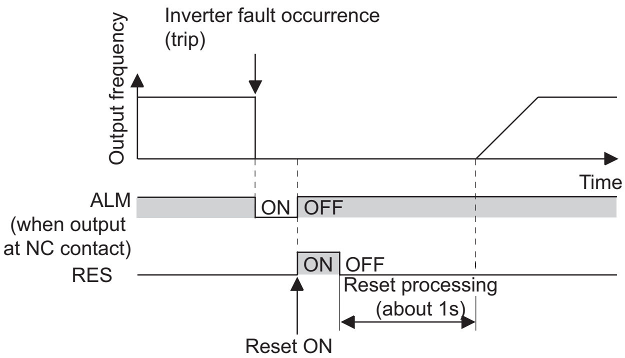
3.6 Failsafe of the system which uses the inverter

When a fault occurs, the inverter trips to output a fault signal. However, a fault output signal may not be output at an inverter fault occurrence when the detection circuit or output circuit fails, etc. Although Mitsubishi assures best quality products, provide an interlock which uses inverter status output signals to prevent accidents such as damage to machine when the inverter fails for some reason and at the same time consider the system configuration where failsafe from outside the inverter, without using the inverter, is enabled even if the inverter fails.

(1) Interlock method which uses the inverter status output signals
By combining the inverter status output signals to provide an interlock as shown below, an inverter alarm can be detected.

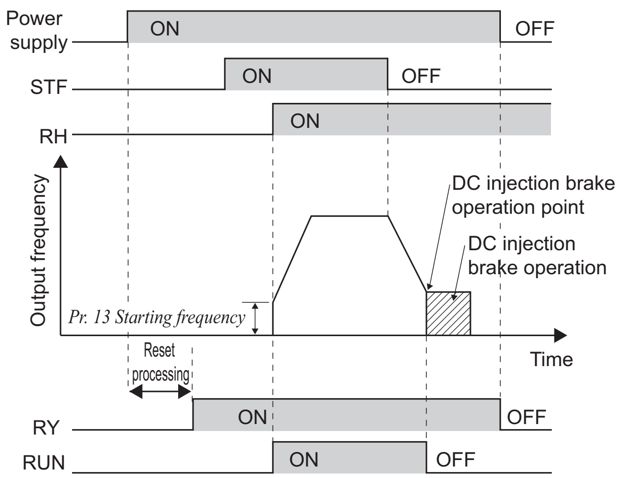
No.	Interlock Method	Check Method	Used Signals	Refer to Page
1)	Inverter protective function operation	Operation check of an alarm contact Circuit error detection by negative logic	Fault output signal ALM signal	140
2)	Inverter running status	Operation ready signal checks	Operation ready signal (RY signal)	140
3)	Inverter running status	Logic check of the start signal and running signal	Start signal (STF signal, STR signal) Running signal (RUN signal)	138, 140
4)	Inverter running status	Logic check of the start signal and output current	Start signal (STF signal, STR signal) Output current detection signal Y12 signal	138, 146

1) Checking by the output of the inverter fault signal
When the inverter's protective function activates and the inverter trips, the fault output signal (ALM signal) is output. (ALM signal is assigned to terminal A1B1C1 in the initial setting).
With this signal, you can check if the inverter is operating properly.
In addition, negative logic can be set (ON when the inverter is normal, OFF when the fault occurs).



2) Checking the inverter operating status by the inverter operation ready completion signal
Operation ready signal (RY signal) is output when the inverter power is ON and the inverter becomes operative.
Check if the RY signal is output after powering ON the inverter.

3) Checking the inverter operating status by the start signal input to the inverter and inverter running signal.
The inverter running signal (RUN signal) is output when the inverter is running (RUN signal is assigned to terminal RUN in the initial setting).
Check if RUN signal is output when inputting the start signal to the inverter (forward signal is STF signal and reverse signal is STR signal). For logic check, note that RUN signal is output for the period from the inverter decelerates until output to the motor is stopped, configure a sequence considering the inverter deceleration time



4) Checking the motor operating status by the start signal input to the inverter and inverter output current detection signal.
The output current detection signal (Y12 signal) is output when the inverter operates and currents flows in the motor. Check if Y12 signal is output when inputting the start signal to the inverter (forward signal is STF signal and reverse signal is STR signal). Note that the current level at which Y12 signal is output is set to 120% of the inverter rated current in the initial setting, it is necessary to adjust the level to around 20% using no load current of the motor as reference with *Pr.150 Output current detection level*.
For logic check, as same as the inverter running signal (RUN signal), the inverter outputs for the period from the inverter decelerates until output to the motor is stopped, configure a sequence considering the inverter deceleration time.

Output Signal	*Pr. 190 to Pr. 196* Setting	
	Positive logic	Negative logic
ALM	99	199
RY	11	111
RUN	0	100
Y12	12	112

- When using various signals, assign functions to *Pr. 190 to Pr. 196 (output terminal function selection)* referring to the table on the left.

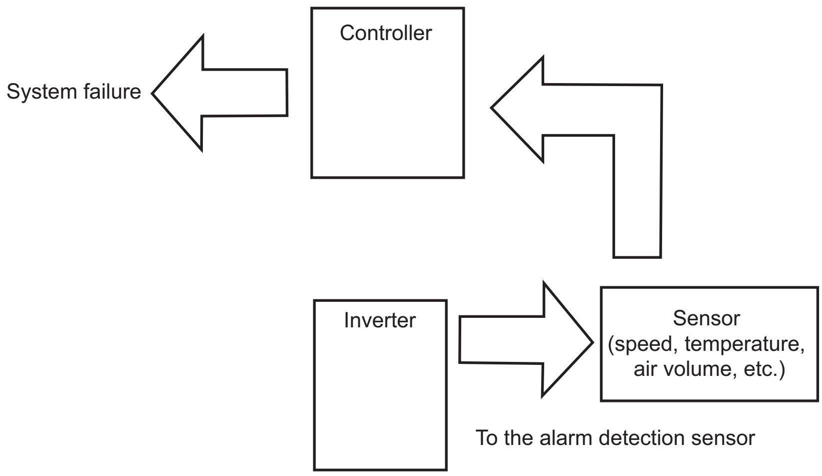
CAUTION

· Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

(2) Backup method outside the inverter
Even if the interlock is provided by the inverter status signal, enough failsafe is not ensured depending on the failure status of the inverter itself. For example, when the inverter CPU fails, even if the interlock is provided using the inverter fault signal, start signal and RUN signal, there is a case where a fault signal is not output and RUN signal is kept output even if an inverter fault occurs.
Provide a speed detector to detect the motor speed and current detector to detect the motor current and consider the backup system such as checking up as below according to the level of importance of the system.

1) Start signal and actual operation check
Check the motor running and motor current while the start signal is input to the inverter by comparing the start signal to the inverter and detected speed of the speed detector or detected current of the current detector. Note that the motor current runs as the motor is running for the period until the motor stops since the inverter starts decelerating even if the start signal turns off. For the logic check, configure a sequence considering the inverter deceleration time. In addition, it is recommended to check the three-phase current when using the current detector.

2) Command speed and actual operation check
Check if there is no gap between the actual speed and commanded speed by comparing the inverter speed command and detected speed of the speed detector.



MEMO

4 PARAMETERS

This chapter explains the "PARAMETERS" for use of this product.
Always read the instructions before using the equipment.

The following marks are used to indicate the controls as below.
(Parameters without any mark are valid for all controls.)

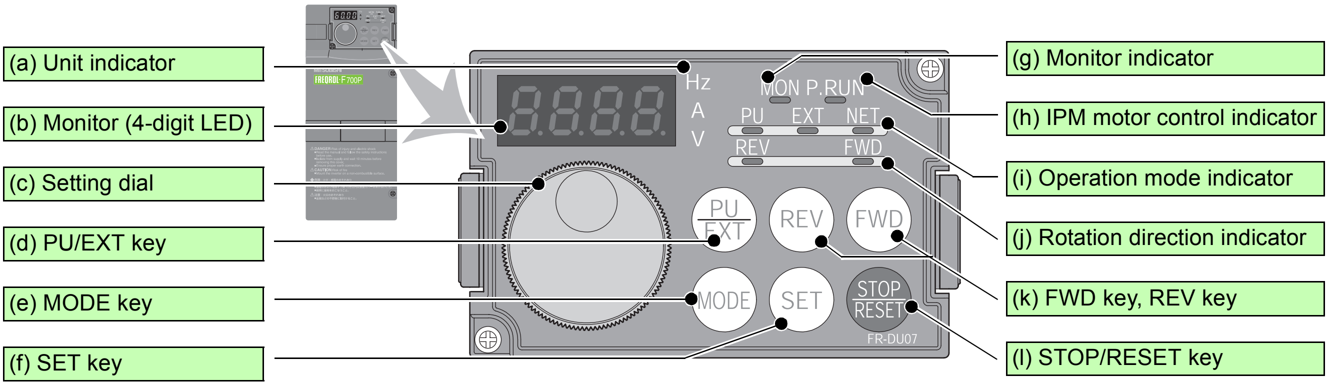
Mark	Control method	Applied motor (control)
V/F	V/F control	Three-phase induction motor (general-purpose motor control)
S MFVC	Simple magnetic flux vector control	
IPM	IPM motor control	Dedicated IPM motor (IPM motor control)

1
2
3
4
5
6
7

4.1 Operation panel (FR-DU07)

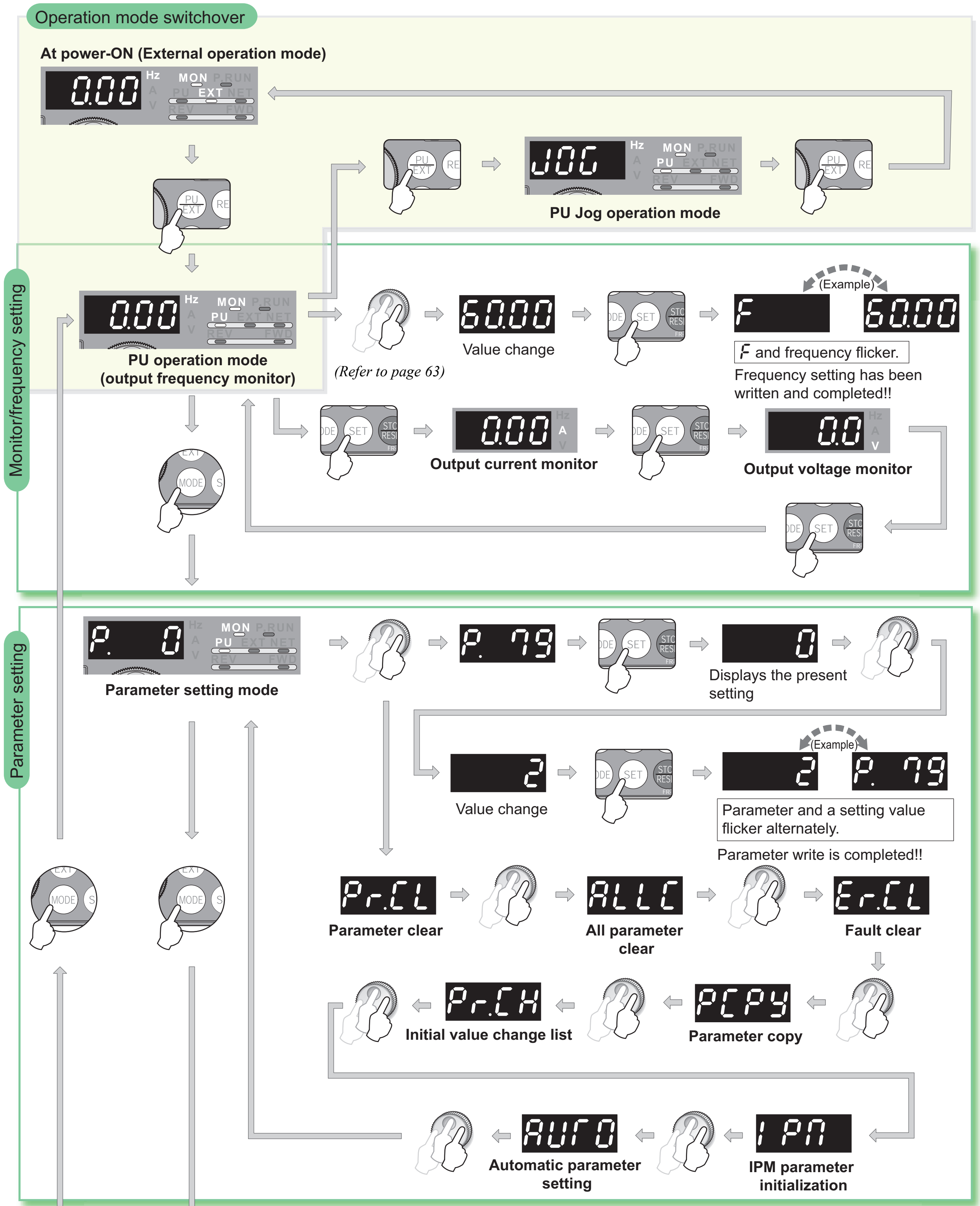
4.1.1 Component of the operation panel (FR-DU07)

To mount the operation panel (FR-DU07) on the enclosure surface, *refer to page 32*.



No.	Component	Name	Description
(a)	Hz A V	Unit indicator	Hz: Lit to indicate frequency. (Flickers when the set frequency monitor is displayed.) A: Lit to indicate current. V: Lit to indicate voltage.
(b)	8.8.8.8.	Monitor (4-digit LED)	Shows the frequency, parameter number, etc. (To monitor the output power, set frequency and other items, set *Pr.52*.)
(c)		Setting dial	The dial of the Mitsubishi inverters. The setting dial is used to change the frequency and parameter settings. Press the setting dial to perform the following operations: • To display a set frequency in the monitor mode • To display the present setting during calibration • To display a fault history number in the faults history mode
(d)	PU/EXT	PU/EXT key	Used to switch between the PU and External operation modes. To use the External operation mode (operation using a separately connected frequency setting potentiometer and start signal), press this key to light up the EXT indicator. (Press MODE simultaneously (0.5s), or change the *Pr.79* setting to change to the combined operation mode.) PU: PU operation mode EXT: External operation mode Used to cancel the PU stop also.
(e)	MODE	MODE key	Used to switch among different setting modes. Pressing PU/EXT simultaneously changes the operation mode. Holding this key for 2 seconds locks the operation. The key lock is invalid when *Pr.161*="0 (initial setting)." (*Refer to page* 295.)
(f)	SET	SET key	Used to enter a setting. If pressed during the operation, monitored item changes as the following: Output frequency → Output current → Output voltage* * Energy saving monitor is displayed when the energy saving monitor is set with *Pr. 52*.
(g)	MON	Monitor indicator	Lit to indicate the monitor mode.
(h)	P.RUN	IPM motor control indicator	Lit to indicate IPM motor control. Flickers to indicate IPM motor test operation.
(i)	PU EXT NET	Operation mode indicator	PU: Lit to indicate the PU operation mode. EXT: Lit to indicate the External operation mode. (EXT is lit at power-ON in the initial setting.) NET: Lit to indicate the Network operation mode. PU and EXT: Lit to indicate EXT/PU combined operation mode 1 and 2
(j)	REV FWD	Rotation direction indicator	FWD: Lit to indicate the forward rotation. REV: Lit to indicate the reverse rotation. Lit: When the forward/reverse operation is being performed. Flickers: When the frequency command is not given even if the forward/reverse command is given. When the frequency command is lower than the starting frequency. When the MRS signal is being input.
(k)	FWD REV	FWD key, REV key	FWD key: Used to give a start command in forward rotation. REV key: Used to give a start command in reverse rotation.
(l)	STOP RESET	STOP/RESET key	Used to stop operation commands. Used to reset a fault when the protective function (fault) is activated.

4.1.2 Basic operation (factory setting)



Faults history

E - - -

[Operation for displaying faults history]

The past eight faults can be displayed. *(Refer to page 304)*

(The latest fault is ended by ".".)

When no fault history exists, E 0 is displayed.

While a fault is displayed:

- The display shifts as follows by pressing SET : Output frequency at the fault → Output current → Output voltage → Energization time.
  (After Energization time, it goes back to a fault display.)
- Pressing the setting dial shows the fault history number.

4

PARAMETERS

4.1.3 Easy operation mode setting (easy setting mode)

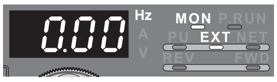
Setting of *Pr. 79 Operation mode selection* according to combination of the start command and speed command can be easily made.

Operation example

Start command by the external signal (STF/STR), frequency command by .

Operation — **Display**

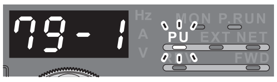
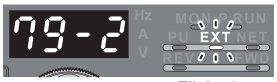
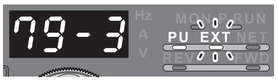
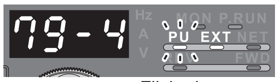
1. Screen at power-ON
   The monitor display appears.



2. Press PU/EXT and MODE for 0.5s.

3. Turn until 79 - 3 appears.
   (Refer to the table below for other settings)

Flickering

Operation Panel Indication	Operation Method	
	Start command	Frequency command
 Flickering	FWD, REV	*
 Flickering	External (STF, STR)	Analog voltage input
 Flickering	External (STF, STR)	*
 Flickering	FWD, REV	Analog voltage input

* To use as a potentiometer, refer to *page 297*.

4. Press SET to set.

Flicker ··· Parameter setting complete!!
The monitor display appears after 3s.

REMARKS

? Er 1 is displayed ... Why?
- *Pr. 79* is not registered in user group with "1" in *Pr. 160 User group read selection*.
- Parameter write is disabled with "1" set in *Pr. 77*.

? Er 2 is displayed ... Why?
- Setting cannot be changed during operation. Turn the start command (FWD or REV, STF or STR) OFF.

- If MODE is pressed before pressing SET, the easy setting mode is terminated and the display goes back to the monitor display. If the easy setting mode is terminated while *Pr.79* = "0 (initial setting)," the operation mode switches between the PU operation mode and the External operation mode. Check the operation mode.
- Reset can be made with STOP/RESET.
- The priorities of the frequency commands when *Pr. 79* = "3" are "Multi-speed operation (RL/RM/RH/REX) > PID control (X14) > terminal 4 analog input (AU) > digital input from the operation panel".

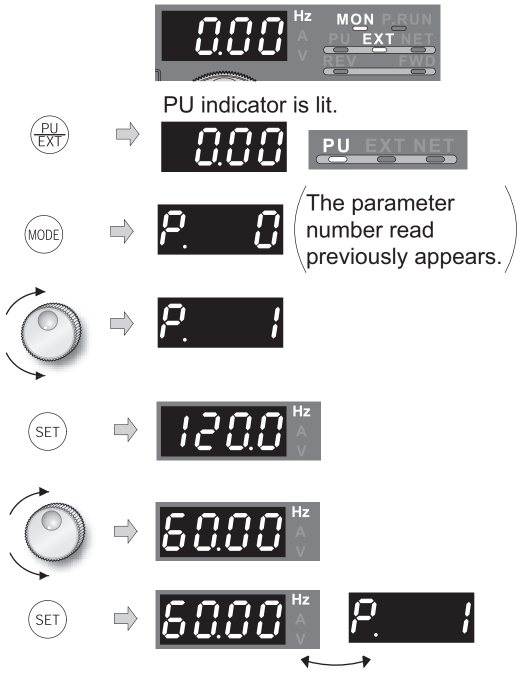
4.1.4 Changing the parameter setting value

Changing example | Change the *Pr. 1 Maximum frequency* .

Operation

1. Screen at power-ON
   The monitor display appears.
2. Press (PU/EXT) to choose the PU operation mode.
3. Press (MODE) to choose the parameter setting mode.
4. Turn (dial) until P. 1 (*Pr. 1*) appears.
5. Press (SET) to read the present set value.
   " 120.0 "(initial value) appears.
6. Turn (dial) to change it to the set value "60.00".
7. Press (SET) to set.

Display



Flicker ··· Parameter setting complete!!

· Turn (dial) to read another parameter.
· Press (SET) to show the setting again.
· Press (SET) twice to show the next parameter.
· Press (MODE) twice to return the monitor to frequency monitor.

? Er 1 to Er 4 appear ... Why?

Er 1 appears. ......Write disable error
Er 2 appears. ......Write error during operation
Er 3 appears. ......Calibration error
Er 4 appears. ......Mode designation error

For details refer to *page 310*.

REMARKS

· The number of digits displayed on the operation panel (FR-DU07) is four. Only the upper four digits of values can be displayed and set. If the values to be displayed have five digits or more including decimal places, the fifth or later numerals cannot be displayed nor set.

(Example) When *Pr.1*
When 60Hz is set, 60.00 is displayed.
When 120Hz is set, 120.0 is displayed. The second decimal places cannot be displayed nor set.

POINT

When *Pr.77 Parameter write selection* = "0 (initial setting)," the parameter setting change is only available while the inverter is stopped under the PU operation mode.
To enable the parameter setting change while the inverter is running or under the operation mode other than PU operation mode, change the *Pr.77* setting

4.1.5 Displaying the set frequency

Press the setting dial ( ) in the PU operation mode or in the External/PU combined operation mode 1 (*Pr.79* = "3") to show the set frequency.

4.2 Parameter list

4.2.1 Parameter list

In the initial setting, only the simple mode parameters are displayed.
Set *Pr. 160 User group read selection* as required.
To use the inverter under IPM motor control, *refer to page 77*.

Parameter	Name	Initial Value	Setting Range	Remarks
160	**User group read selection**	9999	9999	Only the simple mode parameters can be displayed.
			0	Simple mode and extended mode parameters can be displayed.
			1	Only the parameters registered in the user group can be displayed.

REMARKS

- The parameters marked ◎ are the simple mode parameters.
- The parameters marked with [shaded box] in the table allow their settings to be changed during operation even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.
- Refer to the appendix 2 *(page 368)* for instruction codes for communication and availability of parameter clear, all clear, and parameter copy of each parameter.
- Ver.UP ....Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
Basic functions	◎ 0	**Torque boost**	0 to 30%	0.1%	6/4/3/2/ 1.5/1% *1	87	
	◎ 1	**Maximum frequency**	0 to 120Hz	0.01Hz	120/60Hz *2	96	
	◎ 2	**Minimum frequency**	0 to 120Hz	0.01Hz	0Hz	96	
	◎ 3	**Base frequency**	0 to 400Hz	0.01Hz	60Hz	98	
	◎ 4	**Multi-speed setting (high speed)**	0 to 400Hz	0.01Hz	60Hz	102	
	◎ 5	**Multi-speed setting (middle speed)**	0 to 400Hz	0.01Hz	30Hz	102	
	◎ 6	**Multi-speed setting (low speed)**	0 to 400Hz	0.01Hz	10Hz	102	
	◎ 7	**Acceleration time**	0 to 3600/ 360s	0.1/0.01s	5s/15s *3	109	
	◎ 8	**Deceleration time**	0 to 3600/ 360s	0.1/0.01s	10s/30s *3	109	
	◎ 9	**Electronic thermal O/L relay**	0 to 500/0 to 3600A	0.01/0.1A	Rated inverter current	117	
DC injection brake	10	**DC injection brake operation frequency**	0 to 120Hz, 9999	0.01Hz	3Hz	123	
	11	**DC injection brake operation time**	0 to 10s	0.1s	0.5s	123	
	12	**DC injection brake operation voltage**	0 to 30%	0.1%	4/2/1% *4	123	
—	13	**Starting frequency**	0 to 60Hz	0.01Hz	0.5Hz	113	
—	14	**Load pattern selection**	0, 1	1	1	100	
Jog operation	15	**Jog frequency**	0 to 400Hz	0.01Hz	5Hz	104	
	16	**Jog acceleration/deceleration time**	0 to 3600/360s	0.1/0.01s	0.5s	104	
—	17 Ver.UP	**MRS input selection**	0, 2, 4	1	0	136	
—	18	**High speed maximum frequency**	120 to 400Hz	0.01Hz	120/60Hz *2	96	
—	19	**Base frequency voltage**	0 to 1000V, 8888, 9999	0.1V	9999	98	

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
Acceleration/ deceleration times	20	Acceleration/deceleration reference frequency	1 to 400Hz	0.01Hz	60Hz	109	
	21	Acceleration/deceleration time increments	0, 1	1	0	109	
Stall prevention	22	Stall prevention operation level	0 to 150%, 9999	0.1%	120%	91	
	23	Stall prevention operation level compensation factor at double speed	0 to 200%, 9999	0.1%	9999	91	
Multi-speed setting	24 to 27	Multi-speed setting (4 speed to 7 speed)	0 to 400Hz, 9999	0.01Hz	9999	102	
—	28	Multi-speed input compensation selection	0, 1	1	0	106	
—	29	Acceleration/deceleration pattern selection	0, 1, 2, 3, 6	1	0	115	
—	30	Regenerative function selection	0, 2, 10, 20/ 0, 1, 2, 10, 11, 20, 21 *2	1	0	125	
Frequency jump	31	Frequency jump 1A	0 to 400Hz, 9999	0.01Hz	9999	97	
	32	Frequency jump 1B	0 to 400Hz, 9999	0.01Hz	9999	97	
	33	Frequency jump 2A	0 to 400Hz, 9999	0.01Hz	9999	97	
	34	Frequency jump 2B	0 to 400Hz, 9999	0.01Hz	9999	97	
	35	Frequency jump 3A	0 to 400Hz, 9999	0.01Hz	9999	97	
	36	Frequency jump 3B	0 to 400Hz, 9999	0.01Hz	9999	97	
—	37	Speed display	0, 1 to 9998	1	0	150	
Frequency detection	41	Up-to-frequency sensitivity	0 to 100%	0.1%	10%	144	
	42	Output frequency detection	0 to 400Hz	0.01Hz	6Hz	144	
	43	Output frequency detection for reverse rotation	0 to 400Hz, 9999	0.01Hz	9999	144	
Second functions	44	Second acceleration/deceleration time	0 to 3600/360s	0.1/0.01s	5s	109	
	45	Second deceleration time	0 to 3600/360s, 9999	0.1/0.01s	9999	109	
	46	Second torque boost	0 to 30%, 9999	0.1%	9999	87	
	47	Second V/F (base frequency)	0 to 400Hz, 9999	0.01Hz	9999	98	
	48	Second stall prevention operation current	0 to 150%	0.1%	120%	91	
	49	Second stall prevention operation frequency	0 to 400Hz, 9999	0.01Hz	0Hz	91	
	50	Second output frequency detection	0 to 400Hz	0.01Hz	30Hz	144	
	51	Second electronic thermal O/L relay	0 to 500A, 9999/ 0 to 3600A, 9999 *2	0.01/0.1A *2	9999	117	
Monitor functions	52	DU/PU main display data selection	0, 5, 6, 8 to 14, 17, 20, 23 to 25, 50 to 57, 100	1	0	152	
	54	FM terminal function selection	1 to 3, 5, 6, 8 to 14, 17, 21, 24, 50, 52, 53	1	1	152	
	55	Frequency monitoring reference	0 to 400Hz	0.01Hz	60Hz	157	
	56	Current monitoring reference	0 to 500A/0 to 3600A *2	0.01/0.1A *2	Rated inverter current	157	

Parameter List

4

PARAMETERS

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
Automatic restart functions	57	Restart coasting time	0, 0.1 to 5s, 9999/ 0, 0.1 to 30s, 9999 *2	0.1s	9999	162	
	58	Restart cushion time	0 to 60s	0.1s	1s	162	
—	59	Remote function selection	0, 1, 2, 3, 11, 12, 13	1	0	106	
—	◎ 60	Energy saving control selection	0, 4, 9	1	0	176	
—	65	Retry selection	0 to 5	1	0	172	
—	66	Stall prevention operation reduction starting frequency	0 to 400Hz	0.01Hz	60Hz	91	
Retry	67	Number of retries at fault occurrence	0 to 10, 101 to 110	1	0	172	
	68	Retry waiting time	0 to 10s	0.1s	1s	172	
	69	Retry count display erase	0	1	0	172	
—	70	Special regenerative brake duty	0 to 10%	0.1%	0%	125	
—	71 Ver.UP	Applied motor	0, 1, 2, 20, 120, 210	1	0	122	
—	72	PWM frequency selection	0 to 15/0 to 6, 25 *2	1	2	182	
—	73	Analog input selection	0 to 7, 10 to 17	1	1	185	
—	74	Input filter time constant	0 to 8	1	1	192	
—	75	Reset selection/disconnected PU detection/PU stop selection	0 to 3, 14 to 17	1	14	198	
—	76	Fault code output selection	0, 1, 2	1	0	174	
—	77	Parameter write selection	0, 1, 2	1	0	200	
—	78	Reverse rotation prevention selection	0, 1, 2	1	0	201	
—	◎ 79	Operation mode selection	0, 1, 2, 3, 4, 6, 7	1	0	206	
Simple magnetic flux vector control IPM motor control	80	Motor capacity	0.4 to 55kW, 9999/ 0 to 3600kW, 9999 *2	0.01/0.1kW	9999	89	
	90	Motor constant (R1)	0 to 50Ω, 9999/ 0 to 400mΩ, 9999 *2	0.001Ω/ 0.01mΩ	9999	89	
Adjustable 5 points V/F	100	V/F1(first frequency)	0 to 400Hz, 9999	0.01Hz	9999	101	
	101	V/F1(first frequency voltage)	0 to 1000V	0.1V	0V	101	
	102	V/F2(second frequency)	0 to 400Hz, 9999	0.01Hz	9999	101	
	103	V/F2(second frequency voltage)	0 to 1000V	0.1V	0V	101	
	104	V/F3(third frequency)	0 to 400Hz, 9999	0.01Hz	9999	101	
	105	V/F3(third frequency voltage)	0 to 1000V	0.1V	0V	101	
	106	V/F4(fourth frequency)	0 to 400Hz, 9999	0.01Hz	9999	101	
	107	V/F4(fourth frequency voltage)	0 to 1000V	0.1V	0V	101	
	108	V/F5(fifth frequency)	0 to 400Hz, 9999	0.01Hz	9999	101	
	109	V/F5(fifth frequency voltage)	0 to 1000V	0.1V	0V	101	
PU connector communication	117	PU communication station number	0 to 31	1	0	229	
	118	PU communication speed	48, 96, 192, 384	1	192	229	
	119	PU communication stop bit length	0, 1, 10, 11	1	1	229	
	120	PU communication parity check	0, 1, 2	1	2	229	
	121	Number of PU communication retries	0 to 10, 9999	1	1	229	
	122	PU communication check time interval	0, 0.1 to 999.8s, 9999	0.1s	9999	229	
	123	PU communication waiting time setting	0 to 150ms, 9999	1	9999	229	
	124	PU communication CR/LF selection	0, 1, 2	1	1	229	

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
—	◎ 125	Terminal 2 frequency setting gain frequency	0 to 400Hz	0.01Hz	60Hz	193	
—	◎ 126	Terminal 4 frequency setting gain frequency	0 to 400Hz	0.01Hz	60Hz	193	
PID operation	127	PID control automatic switchover frequency	0 to 400Hz, 9999	0.01Hz	9999	261	
	128	PID action selection	10, 11, 20, 21, 50, 51, 60, 61, 110, 111, 120, 121	1	10	261	
	129	PID proportional band	0.1 to 1000%, 9999	0.1%	100%	261	
	130	PID integral time	0.1 to 3600s, 9999	0.1s	1s	261	
	131	PID upper limit	0 to 100%, 9999	0.1%	9999	261	
	132	PID lower limit	0 to 100%, 9999	0.1%	9999	261	
	133	PID action set point	0 to 100%, 9999	0.01%	9999	261	
	134	PID differential time	0.01 to 10.00s, 9999	0.01s	9999	261	
Bypass	135	Electronic bypass sequence selection	0, 1	1	0	274	
	136	MC switchover interlock time	0 to 100s	0.1s	1s	274	
	137	Start waiting time	0 to 100s	0.1s	0.5s	274	
	138	Bypass selection at a fault	0, 1	1	0	274	
	139	Automatic switchover frequency from inverter to bypass operation	0 to 60Hz, 9999	0.01Hz	9999	274	
Backlash measures	140	Backlash acceleration stopping frequency	0 to 400Hz	0.01Hz	1Hz	115	
	141	Backlash acceleration stopping time	0 to 360s	0.1s	0.5s	115	
	142	Backlash deceleration stopping frequency	0 to 400Hz	0.01Hz	1Hz	115	
	143	Backlash deceleration stopping time	0 to 360s	0.1s	0.5s	115	
—	144	Speed setting switchover	0, 2, 4, 6, 8, 10, 102, 104, 106, 108, 110	1	4	150	
PU	145	PU display language selection	0 to 7	1	0	295	
—	147	Acceleration/deceleration time switching frequency	0 to 400Hz, 9999	0.01Hz	9999	109	
Current detection	148	Stall prevention level at 0V input	0 to 150%	0.1%	120%	91	
	149	Stall prevention level at 10V input	0 to 150%	0.1%	150%	91	
	150	Output current detection level	0 to 150%	0.1%	120%	146	
	151	Output current detection signal delay time	0 to 10s	0.1s	0s	146	
	152	Zero current detection level	0 to 150%	0.1%	5%	146	
	153	Zero current detection time	0 to 10s	0.01s	0.5s	146	
—	154	Voltage reduction selection during stall prevention operation	0, 1	1	1	91	
—	155	RT signal function validity condition selection	0, 10	1	0	137	
—	156	Stall prevention operation selection	0 to 31, 100, 101	1	0	91	
—	157	OL signal output timer	0 to 25s, 9999	0.1s	0s	91	
—	158	AM terminal function selection	1 to 3, 5, 6, 8 to 14, 17, 21, 24, 50, 52, 53	1	1	152	
—	159	Automatic switchover frequency range from bypass to inverter operation	0 to 10Hz, 9999	0.01Hz	9999	274	

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
—	◎160	**User group read selection**	0, 1, 9999	1	9999	201	
—	161	**Frequency setting/key lock operation selection**	0, 1, 10, 11	1	0	295	
Automatic restart functions	162	**Automatic restart after instantaneous power failure selection**	0, 1, 10, 11	1	0	162	
	163	**First cushion time for restart**	0 to 20s	0.1s	0s	162	
	164	**First cushion voltage for restart**	0 to 100%	0.1%	0%	162	
	165	**Stall prevention operation level for restart**	0 to 150%	0.1%	120%	162	
Current detection	166	**Output current detection signal retention time**	0 to 10s, 9999	0.1s	0.1s	146	
	167	**Output current detection operation selection**	0, 1, 10, 11	1	0	146	
—	168	Parameter for manufacturer setting. Do not set.					
—	169						
Cumulative monitor clear	170	**Watt-hour meter clear**	0, 10, 9999	1	9999	152	
	171	**Operation hour meter clear**	0, 9999	1	9999	152	
User group	172	**User group registered display/batch clear**	9999, (0 to 16)	1	0	201	
	173	**User group registration**	0 to 999, 9999	1	9999	201	
	174	**User group clear**	0 to 999, 9999	1	9999	201	
Input terminal function assignment	178	**STF terminal function selection**	0 to 8, 10 to 12, 14, 16, 24, 25, 60, 62, 64 to 67, 70 to 72, 9999	1	60	133	
	179	**STR terminal function selection**	0 to 8, 10 to 12, 14, 16, 24, 25, 61, 62, 64 to 67, 70 to 72, 9999	1	61	133	
	180	**RL terminal function selection**	0 to 8, 10 to 12, 14, 16, 24, 25, 62, 64 to 67, 70 to 72, 9999	1	0	133	
	181	**RM terminal function selection**		1	1	133	
	182	**RH terminal function selection**		1	2	133	
	183	**RT terminal function selection**		1	3	133	
	184	**AU terminal function selection**	0 to 8, 10 to 12, 14, 16, 24, 25, 62 to 67, 70 to 72, 9999	1	4	133	
	185	**JOG terminal function selection**	0 to 8, 10 to 12, 14, 16, 24, 25, 62, 64 to 67, 70 to 72, 9999	1	5	133	
	186	**CS terminal function selection**		1	6	133	
	187	**MRS terminal function selection**		1	24	133	
	188	**STOP terminal function selection**		1	25	133	
	189	**RES terminal function selection**		1	62	133	

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
Output terminal function assignment	190	RUN terminal function selection	0 to 5, 7, 8, 10 to 19, 25, 26, 45 to 48, 57, 64, 67, 70, 79, 85, 90 to 96, 98, 99, 100 to 105, 107, 108, 110 to 116, 125, 126, 145 to 148, 157, 164, 167, 170, 179, 185, 190 to 196, 198, 199, 9999	1	0	140	
	191	SU terminal function selection		1	1	140	
	192	IPF terminal function selection		1	2	140	
	193	OL terminal function selection		1	3	140	
	194	FU terminal function selection		1	4	140	
	195	ABC1 terminal function selection	0 to 5, 7, 8, 10 to 19, 25, 26, 45 to 48, 57, 64, 67, 70, 79, 85, 90, 91, 94 to 96, 98, 99, 100 to 105, 107, 108, 110 to 116, 125, 126, 145 to 148, 157, 164, 167, 170, 179, 185, 190, 191, 194 to 196, 198, 199, 9999	1	99	140	
	196	ABC2 terminal function selection		1	9999	140	
Multi-speed setting	232 to 239	Multi-speed setting (8 speed to 15 speed)	0 to 400Hz, 9999	0.01Hz	9999	102	
—	240	Soft-PWM operation selection	0, 1	1	1	182	
—	241	Analog input display unit switchover	0, 1	1	0	193	
—	242	Terminal 1 added compensation amount (terminal 2)	0 to 100%	0.1%	100%	191	
—	243	Terminal 1 added compensation amount (terminal 4)	0 to 100%	0.1%	75%	191	
—	244	Cooling fan operation selection	0, 1	1	1	281	
Slip compensation	245	Rated slip	0 to 50%, 9999	0.01%	9999	90	
	246	Slip compensation time constant	0.01 to 10s	0.01s	0.5s	90	
	247	Constant-power range slip compensation selection	0, 9999	1	9999	90	
—	250	Stop selection	0 to 100s, 1000 to 1100s, 8888, 9999	0.1s	9999	130	
—	251	Output phase loss protection selection	0, 1	1	1	175	
Frequency compensation function	252	Override bias	0 to 200%	0.1%	50%	191	
	253	Override gain	0 to 200%	0.1%	150%	191	
Life check	255	Life alarm status display	(0 to 15)	1	0	282	
	256	Inrush current limit circuit life display	(0 to 100%)	1%	100%	282	
	257	Control circuit capacitor life display	(0 to 100%)	1%	100%	282	
	258	Main circuit capacitor life display	(0 to 100%)	1%	100%	282	
	259	Main circuit capacitor life measuring	0, 1	1	0	282	
—	260	PWM frequency automatic switchover	0, 1	1	1	182	

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
Power failure stop	261	Power failure stop selection	0, 1, 2, 21, 22	1	0	169	
	262	Subtracted frequency at deceleration start	0 to 20Hz	0.01Hz	3Hz	169	
	263	Subtraction starting frequency	0 to 400Hz, 9999	0.01Hz	60Hz	169	
	264	Power-failure deceleration time 1	0 to 3600/ 360s	0.1/0.01s	5s	169	
	265	Power-failure deceleration time 2	0 to 3600/ 360s, 9999	0.1/0.01s	9999	169	
	266	Power failure deceleration time switchover frequency	0 to 400Hz	0.01Hz	60Hz	169	
—	267	Terminal 4 input selection	0, 1, 2	1	0	185	
—	268	Monitor decimal digits selection	0, 1, 9999	1	9999	152	
—	269	Parameter for manufacturer setting. Do not set.					
Password function	296	Password lock level	0 to 6, 99, 101 to 106, 199, 9999	1	9999	203	
	297	Password lock/unlock	(0 to 5), 1000 to 9998, 9999	1	9999	203	
—	299	Rotation direction detection selection at restarting	0, 1, 9999	1	9999	162	
RS-485 communication	331	RS-485 communication station number	0 to 31(0 to 247)	1	0	229	
	332	RS-485 communication speed	3, 6, 12, 24, 48, 96, 192, 384	1	96	229	
	333	RS-485 communication stop bit length	0, 1, 10, 11	1	1	229	
	334	RS-485 communication parity check selection	0, 1, 2	1	2	229	
	335	RS-485 communication retry count	0 to 10, 9999	1	1	229	
	336	RS-485 communication check time interval	0 to 999.8s, 9999	0.1s	0s	229	
	337	RS-485 communication waiting time setting	0 to 150ms, 9999	1	9999	229	
	338	Communication operation command source	0, 1	1	0	219	
	339	Communication speed command source	0, 1, 2	1	0	219	
	340	Communication startup mode selection	0, 1, 2, 10, 12	1	0	218	
	341	RS-485 communication CR/LF selection	0, 1, 2	1	1	229	
	342	Communication EEPROM write selection	0, 1	1	0	230	
	343	Communication error count	—	1	0	247	
Remote output	495	Remote output selection	0, 1, 10, 11	1	0	148	
	496	Remote output data 1	0 to 4095	1	0	148	
	497	Remote output data 2	0 to 4095	1	0	148	
—	502 Ver.UP	Stop mode selection at communication error	0 to 3	1	0	231	
Maintenance	503	Maintenance timer	0 (1 to 9998)	1	0	285	
	504	Maintenance timer alarm output set time	0 to 9998, 9999	1	9999	285	
—	505	Speed setting reference	1 to 120Hz	0.01Hz	60	150	
—	522	Output stop frequency	0 to 400Hz, 9999	0.01Hz	9999	131	
—	539	Modbus-RTU communication check time interval	0 to 999.8s, 9999	0.1s	9999	247	

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
Communication	549	Protocol selection	0, 1	1	0	247	
	550	NET mode operation command source selection	0, 1, 9999	1	9999	219	
	551	PU mode operation command source selection	1, 2	1	2	219	
PID operation	553	PID deviation limit	0 to 100.0%, 9999	0.1%	9999	261	
	554	PID signal operation selection	0 to 3, 10 to 13	1	0	261	
Current average monitor	555	Current average time	0.1 to 1.0s	0.1s	1s	286	
	556	Data output mask time	0.0 to 20.0s	0.1s	0s	286	
	557	Current average value monitor signal output reference current	0 to 500A/0 to 3600A *2	0.01/0.1A *2	Rated inverter current	286	
—	563	Energization time carrying-over times	(0 to 65535)	1	0	152	
—	564	Operating time carrying-over times	(0 to 65535)	1	0	152	
—	571	Holding time at a start	0.0 to 10.0s, 9999	0.1s	9999	113	
PID control	575	Output interruption detection time	0 to 3600s, 9999	0.1s	1s	261	
	576	Output interruption detection level	0 to 400Hz	0.01Hz	0Hz	261	
	577	Output interruption cancel level	900 to 1100%	0.1%	1000%	261	
—	611	Acceleration time at a restart	0 to 3600s, 9999	0.1s	5/15s *2	162	
Speed smoothing control	653	Speed smoothing control	0 to 200%	0.1%	0	184	
	654	Speed smoothing cutoff frequency	0 to 120Hz	0.01Hz	20Hz	184	
—	665	Regeneration avoidance frequency gain	0 to 200%	0.1%	100	279	
—	779 Ver.UP	Operation frequency during communication error	0 to 400Hz, 9999	0.01Hz	9999	231	
—	791	Acceleration time in low-speed range	0 to 3600/360s, 9999	0.1/0.01s	9999	109	
—	792	Deceleration time in low-speed range	0 to 3600/360s, 9999	0.1/0.01s	9999	109	
—	799	Pulse increment setting for output power	0.1kWh, 1kWh, 10kWh, 100kWh, 1000kWh	0.1	1kWh	149	
—	800	Control method selection	9, 20	1	20	82	
Adjustment function	820	Speed control P gain 1	0 to 1000%	1%	25%	84	
	821	Speed control integral time 1	0 to 20s	0.001s	0.333s	84	
—	867	AM output filter	0 to 5s	0.01s	0.01s	157	
—	870	Speed detection hysteresis	0 to 5Hz	0.01Hz	0Hz	144	
—	872	Input phase loss protection selection	0, 1	1	0	175	
Regeneration avoidance function	882	Regeneration avoidance operation selection	0, 1, 2	1	0	279	
	883	Regeneration avoidance operation level	300 to 800V	0.1V	380V/ 760VDC *5	279	
	884	Regeneration avoidance at deceleration detection sensitivity	0 to 5	1	0	279	
	885 Ver.UP	Regeneration avoidance compensation frequency limit value	0 to 30Hz, 9999	0.01Hz	6Hz	279	
	886	Regeneration avoidance voltage gain	0 to 200%	0.1%	100%	279	

Parameter List

4

PARAMETERS

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
Free parameter	888	Free parameter 1	0 to 9999	1	9999	288	
	889	Free parameter 2	0 to 9999	1	9999	288	
Energy saving monitor	891	Cumulative power monitor digit shifted times	0 to 4, 9999	1	9999	177	
	892	Load factor	30 to 150%	0.1%	100%	177	
	893	Energy saving monitor reference (motor capacity)	0.1 to 55kW/ 0 to 3600kW *2	0.01/0.1kW *2	Rated inverter	177	
	894	Control selection during commercial power-supply operation	0, 1, 2, 3	1	0	177	
	895	Power saving rate reference value	0, 1, 9999	1	9999	177	
	896	Power unit cost	0 to 500, 9999	0.01	9999	177	
	897	Power saving monitor average time	0, 1 to 1000h, 9999	1h	9999	177	
	898	Power saving cumulative monitor clear	0, 1, 10, 9999	1	9999	177	
	899	Operation time rate (estimated value)	0 to 100%, 9999	0.1%	9999	177	
Calibration parameters	C0 (900) *6	FM terminal calibration	—	—	—	159	
	C1 (901) *6	AM terminal calibration	—	—	—	159	
	C2 (902) *6	Terminal 2 frequency setting bias frequency	0 to 400Hz	0.01Hz	0Hz	193	
	C3 (902) *6	Terminal 2 frequency setting bias	0 to 300%	0.1%	0%	193	
	125 (903) *6	Terminal 2 frequency setting gain frequency	0 to 400Hz	0.01Hz	60Hz	193	
	C4 (903) *6	Terminal 2 frequency setting gain	0 to 300%	0.1%	100%	193	
	C5 (904) *6	Terminal 4 frequency setting bias frequency	0 to 400Hz	0.01Hz	0Hz	193	
	C6 (904) *6	Terminal 4 frequency setting bias	0 to 300%	0.1%	20%	193	
	126 (905) *6	Terminal 4 frequency setting gain frequency	0 to 400Hz	0.01Hz	60Hz	193	
	C7 (905) *6	Terminal 4 frequency setting gain	0 to 300%	0.1%	100%	193	
PID operation	C42 (934) *6	PID display bias coefficient	0 to 500.00, 9999	0.01	9999	261	
	C43 (934) *6	PID display bias analog value	0 to 300.0%	0.1%	20%	261	
	C44 (935) *6	PID display gain coefficient	0 to 500.00, 9999	0.01	9999	261	
	C45 (935) *6	PID display gain analog value	0 to 300.0%	0.1%	100%	261	
—	989	Parameter copy alarm release	10/100	1	10/100	301	
PU	990	PU buzzer control	0, 1	1	1	298	
	991	PU contrast adjustment	0 to 63	1	58	298	
—	997 Ver.UP	Fault initiation	16 to 18, 32 to 34, 48, 49, 64, 80 to 82, 96, 97, 112, 128, 129, 144, 145, 160, 161, 176 to 179, 192 to 194, 196 to 199, 230, 241, 245 to 247, 253, 9999	1	9999	289	
—	998 Ver.UP	IPM parameter initialization	0, 1, 12, 101, 112	1	0	80	

Function	Parameters	Name	Setting Range	Minimum Setting Increments	Initial Value	Refer to Page	Customer Setting
—	◎ 999	**Automatic parameter setting**	10, 11, 20, 21, 30, 31, 9999	1	9999	290	
Clear parameter	Pr.CL	**Parameter clear**	0, 1	1	0	299	
	ALLC	**All parameter clear**	0, 1	1	0	300	
	Er.CL	**Faults history clear**	0, 1	1	0	304	
—	PCPY	**Parameter copy**	0, 1, 2, 3	1	0	301	
—	Pr.CH	**Initial value change list**	—	—	—	303	
—	IPM Ver.UP	**IPM parameter initialization**	0, 1, 12	1	0	80	
—	AUTO	**Automatic parameter setting**	—	—	—	290	

*1 Differ according to capacities. (6%:0.75K, 4%:1.5K to 3.7K, 3%:5.5K, 7.5K, 2%:11K to 37K, 1.5%:45K, 55K, 1%:75K or higher)
*2 Differ according to capacities. (55K or lower / 75K or higher)
*3 Differ according to capacities. (7.5K or lower / 11K or higher)
*4 Differ according to capacities. (4%:7.5K or lower, 2%:11K to 55K, 1%:75K or higher)
*5 Differ according to the voltage class. (200V class/400V class).
*6 The parameter number in parentheses is the one for use with the parameter unit (FR-PU04/FR-PU07).

4.3 IPM motor control IPM

Purpose	Parameter that must be Set		Refer to Page
To perform IPM parameter initialization	IPM parameter initialization	Pr.998	*80*
To perform IPM motor test	Control method selection	Pr.800	*82*
To adjust the gain for IPM motor control	Adjusting the speed control gain	Pr.820, Pr.821	*84*

Highly efficient motor control and highly accurate motor speed control can be performed by using the inverter with an IPM motor.
The motor speed is detected by the output voltage and current of the inverter. It does not require a speed detector such as an encoder. The inverter drives the IPM motor with the least required current when a load is applied in order to achieve the highest motor efficiency.

POINT

The following conditions must be met to perform IPM motor control.
- For the motor model, dedicated IPM motor (MM-EFS model or MM-EF model) must be used.
- The motor capacity must be equivalent to the inverter capacity. (The 0.75K inverter can be used with the 0.4kW MM-EF.)
- Single-motor operation (one motor run by one inverter) must be performed.
- The overall wiring length with the motor must be 100m or less.

4.3.1 Setting procedure of IPM motor control IPM

- This inverter is set for a general-purpose motor in the initial setting. Follow the following procedure to change the setting for the IPM motor control.

Perform IPM parameter initialization by selecting the parameter setting mode (IPM) on the operation panel.* *(Refer to page 79)*

↓

Set "1" or "12" in IPM (IPM parameter initialization) to select IPM motor control. *Refer to page 79* for the setting method.
Setting value "1": MM-EF
Setting value "12": MM-EFS
P.RUN on the operation panel (FR-DU07) is lit when IPM motor control is set.

Set parameters such as the acceleration/deceleration time and multi-speed setting.

↓

Set parameters such as the acceleration/deceleration time and multi-speed setting as required.

Set the operation command. *(Refer to page 122)*

↓

Select the start command and speed command.

Test run

* IPM parameter initialization is performed by setting *Pr. 998 IPM parameter initialization* or by selecting IPM (IPM parameter initialization) on the operation panel.
To change to the IPM motor control, perform IPM parameter initialization at first. If parameter initialization is performed after setting other parameters, some of those parameters will be initialized too. (*Refer to page 80* for the parameters that are initialized.)

REMARKS

- "Er1" appears if IPM parameter initialization is performed while *Pr.72* = "25."
- To use a 0.4kW MM-EF, set *Pr.80 Motor capacity* = "0.4" before setting IPM parameter initialization.

CAUTION

- For the setting range of a speed command under dedicated IPM motor (MM-EFS 1500r/min specification, MM-EF 1800r/min specification) controls, refer to the output frequency range in *Chapter 8.2 Common specifications (Refer to page 348)*.
- The selectable carrier frequencies under IPM motor control are 2k, 6k, 10k, and 14kHz.
- Constant-speed operation cannot be performed in the low-speed range lower than 150r/min (MM-EFS 1500r/min specification) or 180r/min (MM-EF 1800r/min specification). Generally, speed control can be performed in the range that satisfies the ratio, 1:10.
- During IPM motor control, the RUN signal is output about 100ms after turning ON the start command (STF, STR). The delay is due to the magnetic pole detection.
- The following operations and controls are disabled during IPM motor control: adjustable 5 points V/F, bypass sequence, energy saving operation, Optimum excitation control, and speed smoothing.
- The option surge voltage suppression filter (FR-ASF-H/FR-BMF-H) and sine wave filter (MT-BSL/BSC) cannot be used under IPM motor control, so do not connect them.
- When parameter copy is performed from a FR-F700P series inverter, which is set to use MM-EFS under IPM motor control, check that IPM motor control is selected on the operation panel (P.RUN is lit) after the copy. When parameters are copied to a FR-F700P series inverter, which is not compatible with MM-EFS, Simple magnetic flux vector control is selected instead of IPM motor control.

(1) IPM motor control setting by selecting the parameter setting mode on the operation panel (IPM)

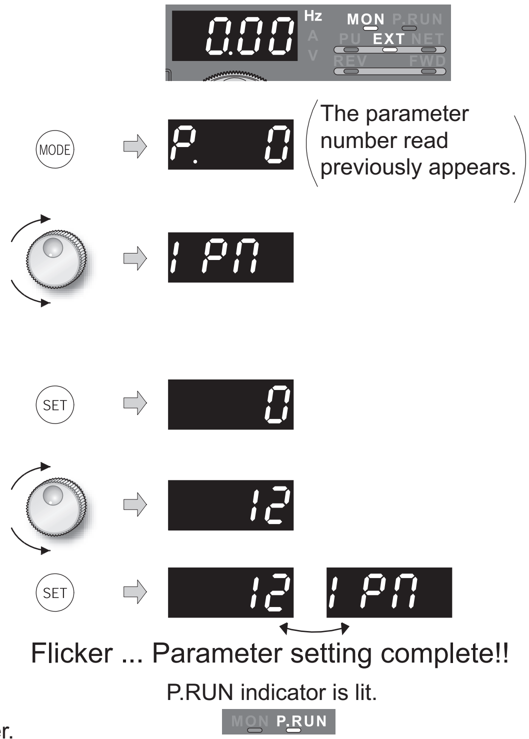
POINT

· The parameters required to drive an IPM motor are automatically changed as a batch. *(Refer to page 80.)*

Operation example	Initialize the parameter setting for a premium high-efficiency IPM motor (MM-EFS) by selecting the parameter setting mode on the operation panel.

Operation — **Display**

1. Screen at power-ON
   The monitor display appears.
2. Parameter setting mode
   Press (MODE) to choose the parameter setting mode.
3. Selecting the parameter
   Turn the setting dial until IPM (IPM parameter initialization) appears.
4. Displaying the setting
   Press (SET) to read the currently set value.
   "0" (initial value) appears.
5. Selecting the setting
   Turn the setting dial to change it to the set value "12".
6. Parameter setting
   Press (SET) to set.



· Turn the setting dial to read another parameter.

· Press (SET) to show the setting again.

· Press (SET) twice to show the automatic parameter setting (AUTO).

Setting	Description
0	Parameter settings for a general-purpose motor
1	Parameter settings for a high-efficiency IPM motor MM-EF (rotations per minute)
12	Parameter settings for a premium high-efficiency IPM motor MM-EFS (rotations per minute)

REMARKS

· Performing IPM parameter initialization by selecting the parameter setting mode on the operation panel automatically changes the *Pr. 998 IPM parameter initialization* setting.
· The parameter initialization sets the same capacity as the inverter capacity to *Pr. 80 Motor capacity*. To use a 0.4kW MM-EF, set *Pr. 80 Motor capacity* = "0.4" before performing IPM parameter initialization by selecting the parameter setting mode on the operation panel.
· The IPM parameter setting is displayed as "1, 12" in the parameter setting mode even if *Pr.998 IPM parameter initialization* = "101, 112."

(2) IPM motor control display and IPM motor control signal

P.RUN on the operation panel (FR-DU07) is lit and the IPM motor control signal (IPM) is output during IPM motor control. For the terminal to output the IPM motor control signal, assign the function by setting "57 (positive logic)" or "157 (negative logic)" to any of *Pr.190 to Pr.196 (Output terminal function selection)*.

♦ Parameters referred to ♦

Pr.60 Energy saving control selection ☞ *Refer to page 176*
Pr.72 PWM frequency selection ☞ *Refer to page 182*
Pr.100 to Pr.109 (Adjustable 5 points V/F) ☞ *Refer to page 101*
Pr.135 to Pr.139, Pr.159 Commercial power supply-inverter switchover function ☞ *Refer to page 274*
Pr.190 to Pr.196 (Output terminal function selection) ☞ *Refer to page 140*
Pr.653 Speed smoothing control ☞ *Refer to page 184*
Pr.654 Speed smoothing cutoff frequency ☞ *Refer to page 184*
Pr.800 Control method selection ☞ *Refer to page 82*

4.3.2 Initializing the parameters required to drive an IPM motor (Pr.998) IPM

- By performing IPM parameter initialization, IPM motor control is selected and the parameters, which are required to drive an IPM motor, are changed. Initial settings and setting ranges of the parameters are adjusted automatically to drive an IPM motor.
- Initialization is performed by setting *Pr.998 IPM parameter initialization* or by choosing the mode on the operation panel.

Parameter Number	Name	Initial value	Setting range	Description	
998 * Ver.UP	IPM parameter initialization	0	0	Parameter settings for a general-purpose motor (frequency)	Initial parameter settings required to drive a general-purpose motor are set.
			1	Parameter settings for a high-efficiency IPM motor MM-EF (rotations per minute)	Initial parameter settings required to drive an IPM motor are set.
			12	Parameter settings for a premium high-efficiency IPM motor MM-EFS (rotations per minute)	
			101	Parameter settings for a high-efficiency IPM motor MM-EF (frequency)	
			112	Parameter settings for a premium high-efficiency IPM motor MM-EFS (frequency)	

* This parameter allows its setting to be changed in any operation mode even if "0 (initial value)" is set in *Pr. 77 Parameter write selection*.

Ver.UP ....Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

(1) *IPM parameter initialization (Pr.998)*

- To use a 0.4kW MM-EF, set *Pr. 80 Motor capacity* = "0.4" before performing IPM parameter initialization. By performing IPM parameter initialization, initial settings required to drive an IPM motor can be set in parameters.
- When *Pr. 998* = "1 or 12," the monitor is displayed and the frequency is set using the motor rotations per minute.
  To use frequency to display or set, set *Pr. 998* = "101 or 112."
- Set *Pr. 998* = "0" to change the parameter settings from the settings required to drive an IPM motor to the settings required to drive a general-purpose motor.

Pr.998 Setting	Description	Operation in the parameter setting mode
0	Parameter settings for a general-purpose motor (frequency)	"IPM" ⇒ Write "0"
1	Parameter settings for a high-efficiency IPM motor MM-EF (rotations per minute)	"IPM" ⇒ Write "1"
12	Parameter settings for a premium high-efficiency IPM motor MM-EFS (rotations per minute)	"IPM" ⇒ Write "12"
101	Parameter settings for a high-efficiency IPM motor MM-EF (frequency)	Invalid
112	Parameter settings for a premium high-efficiency IPM motor MM-EFS (frequency)	Invalid

REMARKS

- Make sure to set *Pr. 998* before setting other parameters. If the *Pr. 998* setting is changed after setting other parameters, some of those parameters will be initialized too. (Refer to "(2) IPM parameter initialization list" for the parameters that are initialized.)
- To change back to the parameter settings required to drive a general-purpose motor, perform parameter clear or all parameter clear.
- If the setting of *Pr. 998 IPM parameter initialization* is changed from "1, 12 (rotations per minute)" to "101, 112 (frequency)," or from "101, 112" to "1, 12," all the target parameters are initialized.
  The purpose of *Pr. 998* is not to change the display units. Use *Pr. 144 Speed setting switchover* to change the display units between rotations per minute and frequency. *Pr. 144* enables switching of display units between rotations per minute and frequency without initializing the parameter settings.
  Example) Changing the *Pr. 144* setting between "6" and "106" switches the display units between frequency and rotations per minute.

(2) IPM parameter initialization list

By selecting IPM motor control from the parameter setting mode or with *Pr.998 IPM parameter initialization*, the parameter settings in the following table change to the settings required to drive an IPM motor. The changed settings differ according to the IPM motor specification (capacity). Refer to the IPM motor specification list shown below.
Performing parameter clear or all parameter clear sets back the parameter settings to the settings required to drive a general-purpose motor.

Parameter	Name	Setting			Setting increments	
		General-purpose motor	IPM motor (rotations per minute)	IPM motor (frequency)		
	Pr.998	0 (Initial setting)	1 (MM-EF), 12 (MM-EFS)	101 (MM-EF), 112 (MM-EFS)	1, 12	0, 101, 112
1	Maximum frequency	120/60Hz *3	Maximum motor rotations per minute	Maximum motor frequency	1r/min	0.01Hz
4	Multi-speed setting (high speed)	60Hz	Rated motor rotations per minute	Rated motor frequency	1r/min	0.01Hz
9	Electronic thermal O/L relay	Rated inverter current	Rated motor current		0.01A/0.1A *3	
13	Starting frequency	0.5Hz	Minimum rotations per minute	Minimum frequency	1r/min	0.01Hz
15	Jog frequency	5Hz	Minimum rotations per minute	Minimum frequency	1r/min	0.01Hz
18	High speed maximum frequency	120/60Hz *3	Maximum motor rotations per minute	Maximum motor frequency	1r/min	0.01Hz
20	Acceleration/deceleration reference frequency	60Hz	Rated motor rotations per minute	Rated motor frequency	1r/min	0.01Hz
22	Stall prevention operation level	120%	Short-time motor torque		0.1%	
37	Speed display	0	0		1	
55	Frequency monitoring reference	60Hz	Rated motor rotations per minute	Rated motor frequency	1r/min	0.01Hz
56	Current monitoring reference	Rated inverter current	Rated motor current		0.01A/0.1A *3	
71 Ver.UP	Applied motor	0	120 (when *Pr.998* = "1 or 101") 210 (when *Pr.998* = "12 or 112")		1	
80	Motor capacity	9999	Inverter capacity *2		0.01kW/0.1kW *3	
125 (903)	Terminal 2 frequency setting gain frequency	60Hz	Rated motor rotations per minute	Rated motor frequency	1r/min	0.01Hz
126 (905)	Terminal 4 frequency setting gain frequency	60Hz	Rated motor rotations per minute	Rated motor frequency	1r/min	0.01Hz
144	Speed setting switchover	4	Number of motor poles + 100	Number of motor poles	1	
240	Soft-PWM operation selection	1	0		1	
260	PWM frequency automatic switchover	1	1		1	
263	Subtraction starting frequency	60Hz	Rated motor rotations per minute	Rated motor frequency	1r/min	0.01Hz
266	Power failure deceleration time switchover frequency	60Hz	Rated motor rotations per minute	Rated motor frequency	1r/min	0.01Hz
390 *1	% setting reference frequency	60Hz	Rated motor frequency		0.01Hz	
505	Speed setting reference	60Hz	Rated motor frequency		0.01Hz	
557	Current average value monitor signal output reference current	Rated inverter current	Rated motor current		0.01A/0.1A *3	
870	Speed detection hysteresis	0Hz	Speed detection hysteresis rotations per minute	Speed detection hysteresis frequency	1r/min	0.01Hz
885	Regeneration avoidance compensation frequency limit value	6Hz	Minimum rotations per minute	Minimum frequency	1r/min	0.01Hz
893 Ver.UP	Energy saving monitor reference (motor capacity)	Rated inverter capacity	Motor capacity *(Pr. 80)*		0.01kW/0.1kW *3	

*1 This parameter can be set when FR-A7NL is mounted.
*2 When *Pr.80 Motor capacity* ≠ "9999," the *Pr.80 Motor capacity* setting is not changed by IPM parameter initialization. IPM parameter initialization is performed by setting *Pr.998 IPM parameter initialization* or the parameter setting mode on the operation panel.
*3 Initial values differ according to the inverter capacity. (55K or lower/75K or higher)

Ver.UP .... Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

REMARKS

If IPM parameter initialization is performed in rotations per minute (*Pr. 998* = "1" or "12"), the parameters not listed in the table above are also set and displayed in rotations per minute.

4

PARAMETERS

[IPM motor specification list]

	MM-EF (30kW or lower)	MM-EF (37kW to 75kW)	MM-EF (90kW or higher)	MM-EFS (15kW or lower)	MM-EFS (18.5kW to 55kW)
Rated motor frequency (rotations per minute)	90Hz (1800r/min)	120Hz (1800r/min)	120Hz (1800r/min)	75Hz (1500r/min)	100Hz (1500r/min)
Maximum motor frequency (rotations per minute)	135Hz (2700r/min)	180Hz (2700r/min)	160Hz (2400r/min)	112.5Hz (2250r/min)	150Hz (2250r/min)
Number of motor poles	6	8	8	6	8
Short-time motor torque	120%	120%	120%	120%	120%
Minimum frequency (rotations per minute)	9Hz (180r/min)	12Hz (180r/min)	12Hz (180r/min)	7.5Hz (150r/min)	10Hz (150r/min)
Speed detection hysteresis frequency (rotations per minute)	0.5Hz (10r/min)	0.5Hz (8r/min)	0.5Hz (8r/min)	0.5Hz (10r/min)	0.5Hz (8r/min)

(3) IPM motor control dedicated parameter

The following parameters are activated only under IPM motor control.
See the reference pages for details.

Parameter number	Name	Description	Refer to Page
791	Acceleration time in low-speed range	Acceleration time in the low-speed range ("rated motor frequency/10" or lower) is set.	109
792	Deceleration time in low-speed range	Deceleration time in the low-speed range ("rated motor frequency/10" or lower) is set.	109
800	Control method selection	IPM motor test operation is selected.	82
820	Speed control P gain 1	The proportional gain during speed control is set. (Setting this parameter higher improves the trackability for speed command changes. It also reduces the speed fluctuation due to a load fluctuation.)	84
821	Speed control integral time 1	The integral time during speed control is set. (Setting this parameter shortens the return time to the original speed when the speed fluctuates due to a load fluctuation.)	84

4.3.3 IPM motor test operation (Pr.800) IPM

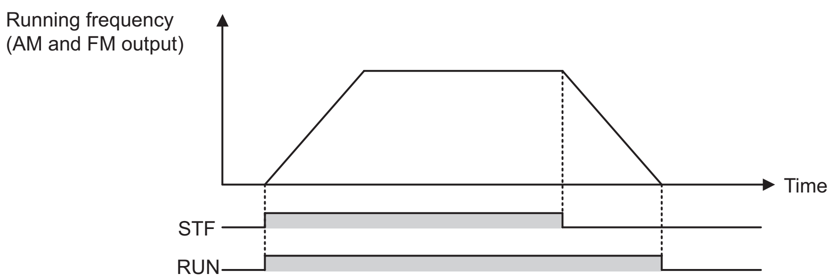
Without connecting an IPM motor, the frequency movement can be checked by the monitor or analog signal output. Two types of operation can be selected using this parameter: an actual operation by connecting an IPM motor, or a test operation without connecting an IPM motor to simulate a virtual operation.

Parameter Number	Name	Initial value	Setting range	Operation
800	Control method selection	20	9	IPM motor test operation (Motor is not driven even if it is connected.)
			20	Normal operation (Motor can be driven.)

The above parameters can be set when *Pr.160 User group read selection* = "0." *(Refer to page 201)*

(1) Test operation

- To activate the IPM motor test operation, set *Pr.998 IPM parameter initialization* , change the control to IPM motor control, then set *Pr.800 Control method selection* = "9."
  Perform a test operation by giving a frequency and a start command under each of PU/External/Network operation mode.
- P.RUN on the operation panel (FR-DU07) flickers during the IPM motor test operation.



REMARKS

- In the test operation, current is not detected and voltage is not output. Related monitor displays of the output current and voltage show "0."

(2) Valid/invalid statuses of I/O terminal functions during the test operation

1)*Input terminal function selection (Pr.178 to Pr.189)*
All assignable functions are valid.

2)*Output terminal function selection (Pr. 190 to Pr. 196)*
Some functions have restrictions. For details, refer to the table below.

○: Valid, ×: Not output as there is no output current

Signal name	Function	
RUN	Inverter running	○
SU	Up to frequency	○
IPF	Instantaneous power failure/undervoltage	○
OL	Overload alarm	×
FU	Output frequency detection	○
FU2	Second output frequency detection	○
RBP	Regenerative brake pre-alarm	○
THP	Electronic thermal O/L relay pre-alarm	×
PU	PU operation mode	○
RY	Inverter operation ready	○
Y12	Output current detection	○
Y13	Zero current detection	○
FDN	PID lower limit	○
FUP	PID upper limit	○
RL	PID forward/reverse rotation output	○
FAN	Fan fault output	○
FIN	Heatsink overheat pre-alarm	○
RUN3	Inverter running and start command is on	○

Signal name	Function	
Y46	During deceleration at occurrence of power failure	○
PID	During PID control activated	○
Y48	PID deviation limit	○
IPM	IPM motor control	○
Y64	During retry	○
SLEEP	PID output interruption	○
Y79	Pulse train output of output power	×
Y85	DC feeding	○
Y90	Life alarm	○
Y91	Fault output 3 (power-off signal)	○
Y92	Energy saving average value updated timing	○
Y93	Current average value monitor signal	○
ALM2	Fault output 2	○
Y95	Maintenance timer signal	○
REM	Remote output	○
LF	Alarm output	○
ALM	Fault output	○
9999	No function	—

(3) Valid/invalid statuses of monitor outputs during the test operation

○: Valid, ×: Invalid (always displays 0)
△: Displays accumulated value before the test, —: Not monitored

Monitoring items	DU/PU monitor display	AM/FM output
Output frequency	○	○
Output current	×	×
Output voltage	×	×
Fault display	○	—
Frequency setting value	○	○
Running speed	○	○
Converter output voltage	○	○
Regenerative brake duty	○	○
Electronic thermal relay load factor	× *2	× *2
Output current peak value	× *2	× *2
Converter output voltage peak value	○	○
Input power	×	×
Output power	×	×
Load meter	×	×
Cumulative energization time	○	—
Reference voltage output	—	○
Actual operation time	○	—

Monitoring items	DU/PU monitor display	AM/FM output
Motor load factor	×	×
Cumulative power	△	—
Energy saving effect	×	×
Cumulative saving energy	△	—
PID set point	○	○
PID measured value	○	○
PID deviation	○	—
Input terminal status	○	—
Output terminal status	○	—
Option input terminal status	○	—
Option output terminal status	○	—

*1 Monitor output is valid or invalid depending on the monitor type (operation panel display, parameter unit display, or terminal FM/AM). For details, *refer to page 152*.

*2 When the operation is switched to the test operation, "0" is displayed. When IPM motor control is selected again after a test operation, the output current peak value and the electronic thermal relay load factor from the last operation are displayed.

♦ Parameters referred to ♦

Pr.52 DU/PU main display data selection ☞Refer to page 152
Pr.178 to Pr.189 (Input terminal function assignment) ☞Refer to page 133
Pr. 190 to Pr. 196 (Output terminal function selection) ☞Refer to page 140

4

PARAMETERS

4.3.4 Adjusting the speed control gain (Pr.820, Pr.821) IPM

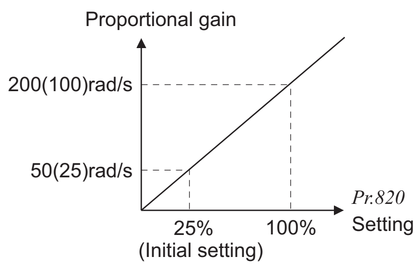
Manual adjustment of gain is useful to exhibit the optimum performance of the machine or to improve unfavorable conditions such as vibration and acoustic noise during the operation with high load inertia or gear backlashes.

Parameter Number	Name	Initial value	Setting range	Operation
820	Speed control P gain 1	25%	0 to 1000%	The proportional gain during speed control is set. (Setting this parameter higher improves the trackability for speed command changes. It also reduces the speed fluctuation due to a load fluctuation.)
821	Speed control integral time 1	0.333s	0 to 20s	The integral time during speed control is set. (Setting this parameter lower shortens the return time to the original speed when the speed fluctuates due to a load fluctuation.)

The above parameters can be set when *Pr.160 User group read selection* = "0." *(Refer to page 201)*

(1) Adjusting the speed control gain manually

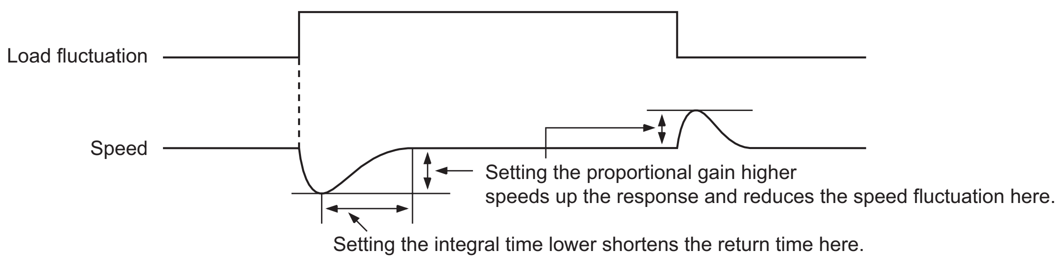
· The speed control gain can be adjusted for the conditions such as abnormal machine vibration, acoustic noise, slow response, and overshoot.



* The values for 75K or higher are indicated in parenthesis.

· *Pr.820 Speed control P gain 1* = "25% (initial setting)" is equivalent to 50rad/s (speed response of a single motor). (Half the value for 75K or higher.) Setting this parameter higher speeds up the response, but setting this too high causes vibration and acoustic noise.
· Setting *Pr.821 Speed control integral time 1* lower shortens the return time to the original speed at a speed fluctuation, but setting it too low causes overshoot.

· Actual speed gain is calculated as below when load inertia is applied.



$$\text{Actual speed gain} = \text{Speed gain of a single motor} \times \frac{JM}{JM+JL}$$

JM: Motor inertia
JL: Load inertia converted as the motor axis inertia

· Adjust in the following procedure:
  1) Change the *Pr.820* setting while checking the conditions.
  2) If it can not be adjusted well, change *Pr.821* setting, and perform 1) again.

No.	Movement/condition	Adjustment method	
1	Load inertia is too high.	Set *Pr.820 and Pr.821* higher.	
		Pr.820	If acceleration is slow, raise the setting by 10%s and set a value that satisfies the following condition: The setting immediately before vibration/ noise starts occurring × 0.8 to 0.9
		Pr.821	If overshoots occur, raise the setting by double the setting and set a value that satisfies the following condition: The setting where overshoots stop occurring × 0.8 to 0.9
2	Vibration or acoustic noise is generated from machines.	Set *Pr.820* lower and *Pr.821* higher.	
		Pr.820	Lower the setting by 10%s and set a value that satisfies the following condition: The setting immediately before vibration/noise starts occurring × 0.8 to 0.9
		Pr.821	If overshoots occur, raise the setting by double the setting and set a value that satisfies the following condition: The setting where overshoots stop occurring × 0.8 to 0.9
3	Response is slow.	Set *Pr.820* higher.	
		Pr.820	If acceleration is slow, raise the setting by 5%s and set a value that satisfies the following condition: The setting immediately before vibration/noise starts occurring × 0.8 to 0.9
4	Return time (response time) is long.	Set *Pr.821* lower.	
		Lower *Pr.821* by half the current setting and set a value that satisfies the following condition: The setting immediately before overshoots or unstable movements stop occurring × 0.8 to 0.9	
5	Overshoots or unstable movements occur.	Set *Pr.821* higher.	
		Raise *Pr.821* by double the current setting and set a value that satisfies the following condition: The setting immediately before overshoots or unstable movements stop occurring × 0.8 to 0.9	

(2) Troubleshooting

	Condition	Possible cause	Countermeasure
1	Motor does not run at the correct speed. (Command speed and actual speed differ.)	(1) Speed command from the controller is different from the actual speed. The speed command is affected by noise. (2) The command speed and the speed recognized by the inverter are different.	(1) Check that the speed command sent from the controller is correct. Lower *Pr.72 PWM frequency selection*. (2) Adjust bias and gain *(Pr.125, Pr.126, C2 to C7)* of the speed command again.
2	The speed does not accelerate to the command speed.	(1) Torque shortage Stall prevention operation is activated. (2) Only P (proportion) control is performed.	(1) -1 Raise the stall prevention operation level. *(Refer to page 91.)* (1) -2 Capacity shortage (2) Speed deviation occurs under P (proportional) control when the load is heavy. Select PI control.
3	Motor speed fluctuates.	(1) Speed command varies. (2) Torque shortage (3) Speed control gain is not suitable for the machine. (Resonance occurs.)	(1) -1 Check that the speed command sent from the controller is correct. (Take EMC measures.) (1) -2 Lower *Pr.72 PWM frequency selection*. (2) Raise the stall prevention operation level. *(Refer to page 91.)* (3) Adjust *Pr.820 and Pr.821 (Refer to page 84.)*
4	Hunting (vibration or acoustic noise) occurs in the motor or the machine.	(1) Speed control gain is too high. (2) Motor wiring is incorrect.	(1) Set *Pr.820* lower and *Pr.821* higher. (2) Check the wiring.

	Condition	Possible cause	Countermeasure
5	Acceleration/deceleration time is different from the setting.	(1) Torque shortage (2) Load inertia is too high.	(1) Raise the stall prevention operation level. *(Refer to page 91.)* (2) Set acceleration/deceleration time suitable for the load.
6	Machine movement is unstable.	(1) Speed control gain is not suitable for the machine. (2) Response is slow because of the inverter's acceleration/ deceleration time setting.	(1) Adjust *Pr.820 and Pr.821 (Refer to page 84.)* (2) Set the optimum acceleration/deceleration time.
7	Rotation ripple occurs during the low-speed operation.	(1) High carrier frequency is affecting the motor rotation. (2) Speed control gain is too low.	(1) Lower *Pr.72 PWM frequency selection*. (2) Raise *Pr.820 Speed control P gain 1*.

4.4 Adjustment of the output torque (current) of the motor

Purpose	Parameter that must be Set		Refer to Page
Set starting torque manually	**Manual torque boost**	**Pr. 0, Pr. 46**	87
Automatically control output current according to load	**Simple magnetic flux vector control**	**Pr. 80, Pr. 90**	89
Compensate for motor slip to secure low-speed torque	**Slip compensation**	**Pr. 245 to Pr. 247**	90
Limit output current to prevent inverter trip	**Stall prevention operation**	**Pr. 22, Pr. 23, Pr. 66, Pr. 154, Pr. 156, Pr. 157**	91

4.4.1 *Manual torque boost (Pr. 0, Pr. 46)* V/F

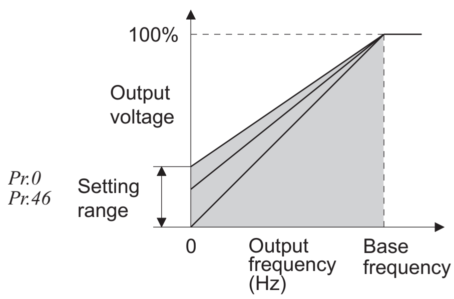
You can compensate for a voltage drop in the low-frequency range to improve motor torque reduction in the low-speed range.
- Motor torque in the low-frequency range can be adjusted to the load to increase the starting motor torque.
- The starting torque boost can be changed by switching terminals.

<table>
<tr><th>Parameter Number</th><th>Name</th><th colspan="2">Initial Value</th><th>Setting Range</th><th>Description</th></tr>
<tr><td rowspan="6">0</td><td rowspan="6">Torque boost</td><td>0.75K</td><td>6%</td><td rowspan="6">0 to 30%</td><td rowspan="6">Set the output voltage at 0Hz as %.</td></tr>
<tr><td>1.5K to 3.7K</td><td>4%</td></tr>
<tr><td>5.5K, 7.5K</td><td>3%</td></tr>
<tr><td>11K to 37K</td><td>2%</td></tr>
<tr><td>45K, 55K</td><td>1.5%</td></tr>
<tr><td>75K or higher</td><td>1%</td></tr>
<tr><td rowspan="2">46 *1</td><td rowspan="2">Second torque boost</td><td colspan="2" rowspan="2">9999</td><td>0 to 30%</td><td>Set the torque boost value when the RT signal is on.</td></tr>
<tr><td>9999</td><td>Without second torque boost</td></tr>
</table>

*1 They can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*

(1) Starting torque adjustment

- On the assumption that *Pr. 19 Base frequency voltage* is 100%, set the output voltage at 0Hz in % in *Pr. 0* (*Pr. 46*).
- Adjust the parameter little by little (about 0.5%), and check the motor status each time. If the setting is too large, the motor will overheat. The guideline is about 10% at the greatest.



(2) Set multiple torque boost (RT signal, *Pr. 46*)

- Use the second torque boost when changing the torque boost according to application or when using multiple motors by switching between them by one inverter.
- *Pr. 46 Second torque boost* is valid when the RT signal turns ON.

REMARKS
- The RT signal acts as the second function selection signal and makes the other second functions valid. *(Refer to page 136)*
- The RT signal is assigned to the RT terminal in the default setting. By setting "3" to any of *Pr. 178 to Pr. 189 (Input terminal function selection)*, you can assign the RT signal to the other terminal.

CAUTION

- Increase the setting when the distance between the inverter and motor is long or when motor torque is insufficient in the low-speed range. If the setting is too large, an overcurrent trip may occur.
- The *Pr. 0* and *Pr. 46* settings are valid only when V/F control is selected.
- When using the inverter dedicated motor (constant-torque motor) with the 5.5K or 7.5K, set the torque boost value to 2%. If the initial set *Pr. 71* value is changed to the setting for use with a constant-torque motor, the *Pr. 0* setting changes to the corresponding value in above.
- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 3 Base frequency, Pr. 19 Base frequency voltage ☞ *Refer to page 98*
Pr. 71 Applied motor ☞ *Refer to page 122*
Pr. 80 Motor capacity ☞ *Refer to page 89*
Pr. 178 to Pr. 189 (Input terminal function selection) ☞ *Refer to page 133*

4.4.2 Simple magnetic flux vector control (Pr.80, Pr.90) S MFVC

Providing optimum excitation to the motor can also produce high torque in a low-speed range.
(Simple magnetic flux vector control)

Parameter Number	Name	Initial Value	Setting Range		Description
80	**Motor capacity**	9999	55K or lower	0.4 to 55kW	Set the capacity of the motor used to select Simple magnetic flux vector control.
			75K or higher	0 to 3600kW	
			9999		V/F control is performed
90	**Motor constant (R1)**	9999	55K or lower	0 to 50Ω	Used to set the motor primary resistance value. (Normally setting is not necessary.)
			75K or higher	0 to 400mΩ	
			9999		Use the Mitsubishi motor (SF-JR, SF-HRCA) constants

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

POINT

- The number of motor poles should be any of 2, 4 and 6 poles.
- Single-motor operation (One motor for one inverter)
- The wiring length from inverter to motor should be within 30m

(1) Automatically control optimum torque *(Pr.80)*

- When Simple magnetic flux vector control is not used, set "9999" (initial value) in *Pr.80*.
- Set the used motor capacity (equal to or one rank higher than the inverter capacity).

REMARKS

When using a constant-torque motor, set *Pr. 71 Applied motor* to "1" (constant-torque motor).

CAUTION

- When Simple magnetic flux vector control is selected, the rated motor frequency is set in *Pr. 3* and the rated motor voltage is set in *Pr. 19*. The base frequency voltage is handled as 200V class : 200V, 400V class : 400V when "9999" or "8888" is set in *Pr. 19* .
- Adjustable 5 points V/F, energy saving operation mode, Optimum excitation control function only under V/F control. They do not function for Simple magnetic flux vector control.

(2) Set the motor constant *(Pr.90)*

- Normally setting is not necessary. When you need more torque under Simple magnetic flux vector control for other manufacturer's motor, set the motor primary resistance value (R1) for 人connection. When the setting value is "9999" (initial value), the motor constant is based on the Mitsubishi motor constant (SF-JR, SF-HRCA).

♦ Parameters referred to ♦

Pr. 3 Base frequency, Pr. 19 Base frequency voltage ☞ *Refer to page 98*
Pr. 60 Energy saving control selection ☞ *Refer to page 176*
Pr. 71 Applied motor ☞ *Refer to page 122*
Pr. 77 Parameter write selection ☞ *Refer to page 200*

4.4.3 Slip compensation (Pr. 245 to Pr. 247) V/F S MFVC

The inverter output current may be used to assume motor slip to keep the motor speed constant.

Parameter Number	Name	Initial Value	Setting Range	Description
245	**Rated slip**	9999	0.01 to 50%	Used to set the rated motor slip.
			0, 9999	No slip compensation
246	**Slip compensation time constant**	0.5s	0.01 to 10s	Used to set the slip compensation response time. When the value is made smaller, response will be faster. However, as load inertia is greater, a regenerative overvoltage (E.OV□) fault is more liable to occur.
247	**Constant-power range slip compensation selection**	9999	0	Slip compensation is not made in the constant power range (frequency range above the frequency set in *Pr. 3*)
			9999	Slip compensation is made in the constant power range.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

· Slip compensation is validated when the motor rated slip calculated by the following formula is set in *Pr. 245*. Slip compensation is not used when *Pr. 245* = "0" or "9999".

$$\textbf{Rated slip} = \frac{\textbf{Synchronous speed at base frequency - rated speed}}{\textbf{Synchronous speed at base frequency}} \times \textbf{100[\%]}$$

REMARKS

When performing slip compensation, the output frequency may become greater than the set frequency. Set the *Pr. 1 Maximum frequency* value a little higher than the set frequency.

♦ **Parameters referred to** ♦

Pr. 1 Maximum frequency ☞ *Refer to page 96*
Pr. 3 Base frequency ☞ *Refer to page 98*

4.4.4 Stall prevention operation (Pr. 22, Pr. 23, Pr. 48, Pr. 49, Pr. 66, Pr. 148, Pr. 149, Pr. 154, Pr. 156, Pr. 157)

This function monitors the output current and automatically changes the output frequency to prevent the inverter from coming to trip due to overcurrent, overvoltage, etc. It can also limit stall prevention and fast-response current limit operation during acceleration/deceleration, driving or regeneration.

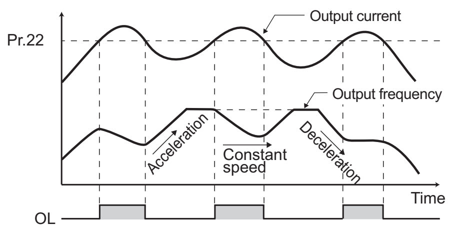
- Stall prevention
  If the output current exceeds the stall prevention operation level, the output frequency of the inverter is automatically varied to reduce the output current.
  Also the second stall prevention function can restrict the output frequency range in which the stall prevention function is valid.
- Fast-response current limit
  If the current exceeds the limit value, the output of the inverter is shut off to prevent an overcurrent.

Parameter Number	Name	Initial Value	Setting Range	Description
22 *1	Stall prevention operation level	120% *2	0	Stall prevention operation selection becomes invalid.
			0.1 to 150%	Set the current value at which stall prevention operation will be started.
			9999	Analog variable
23 V/F S MFVC	Stall prevention operation level compensation factor at double speed	9999	0 to 200%	The stall operation level can be reduced when operating at a high speed above the rated frequency.
			9999	Constant according to *Pr. 22*
48	Second stall prevention operation current	120%	0	Second stall prevention operation invalid
			0.1 to 150%	The second stall prevention operation level can be set.
49	Second stall prevention operation frequency	0Hz	0	Second stall prevention operation invalid
			0.01 to 400Hz	Set the frequency at which stall prevention operation of *Pr. 48* is started.
			9999	*Pr. 48* is valid when the RT signal is ON.
66 V/F S MFVC	Stall prevention operation reduction starting frequency	60Hz	0 to 400Hz	Set the frequency at which the stall operation level starts being reduced.
148	Stall prevention level at 0V input	120%	0 to 150%	Stall prevention operation level can be changed by the analog signal input to terminal 1.
149	Stall prevention level at 10V input	150%	0 to 150%	
154 V/F S MFVC	Voltage reduction selection during stall prevention operation	1	0	With voltage reduction — You can select whether to use output voltage reduction during stall prevention operation or not.
			1	Without voltage reduction
156	Stall prevention operation selection	0	0 to 31, 100, 101	You can select whether stall prevention operation and fast-response current limit operation will be performed or not.
157	OL signal output timer	0s	0 to 25s	Set the output start time of the OL signal output when stall prevention is activated.
			9999	Without the OL signal output

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

*1 This parameters allow its setting to be changed during operation in any operation mode even if "0 (initial value) or 1" is set in *Pr. 77 Parameter write selection*.

*2 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*



Stall prevention operation example

(1) Setting of stall prevention operation level *(Pr. 22)*

- For *Pr.22*, set the output current level where the stall prevention is activated. Set the output current level in ratio to the inverter rated current (rated IPM motor current under IPM motor control). Normally set 120% (initial value).
- Stall prevention operation stops acceleration (makes deceleration) during acceleration, makes deceleration during constant speed, and stops deceleration during deceleration.
- When stall prevention operation is performed, the OL signal is output.

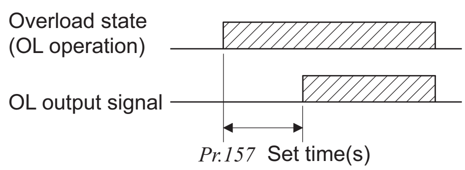
CAUTION

- If an overload status lasts long, an inverter trip (e.g. electronic thermal relay function (E.THM)) may occur.
- When *Pr. 156* has been set to activate the fast-response current limit (initial setting), the *Pr. 22* setting should not be higher than 140%. The torque will not be developed by doing so. (Under V/F control or Simple magnetic flux vector control)

(2) Stall prevention operation signal output and output timing adjustment (OL signal, *Pr. 157*)

- When the output current exceeds the stall prevention operation level and stall prevention is activated, the stall prevention operation signal (OL signal) turns ON for longer than 100ms. When the output current falls to or below the stall prevention operation level, the output signal turns OFF.
- Use *Pr. 157 OL signal output timer* to set whether the OL signal is output immediately or after a preset period of time.
- This operation is also performed when the regeneration avoidance function oL (overvoltage stall) is executed.

Pr. 157 Setting	Description
0 (initial value)	Output immediately.
0.1 to 25	Output after the set time (s) has elapsed.
9999	Not output.



REMARKS

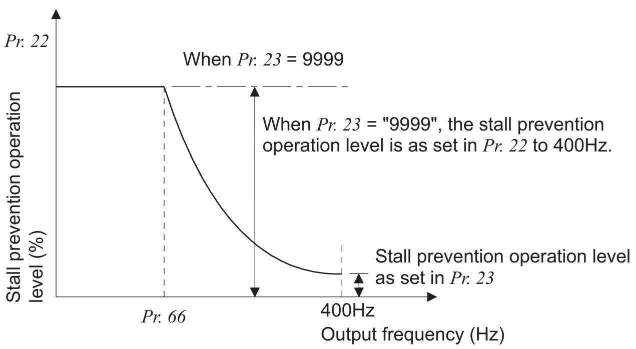
- The OL signal is assigned to the terminal OL in the initial setting. The OL signal can also be assigned to the other terminal by setting "3 (positive logic) or 103 (negative logic)" to any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

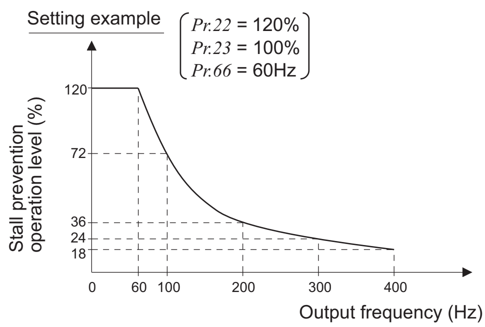
CAUTION

- If the frequency has fallen to 0.5Hz by stall prevention operation and remains for 3s, a fault (E.OLT) appears to shutoff the inverter output.
- Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

(3) Setting of stall prevention operation in high frequency range *(Pr. 22, Pr. 23, Pr. 66)*

V/F S MFVC





- During high-speed operation above the rated motor frequency, acceleration may not be made because the motor current does not increase. If operation is performed in a high frequency range, the current at motor lockup becomes smaller than the rated output current of the inverter, and the protective function (OL) is not executed if the motor is at a stop.
  To improve the operating characteristics of the motor in this case, the stall prevention level can be reduced in the high frequency range. This function is effective for performing operation up to the high-speed range on a centrifugal separator etc. Normally, set 60Hz in *Pr. 66* and 100% in *Pr. 23*.
- Formula for stall prevention operation level

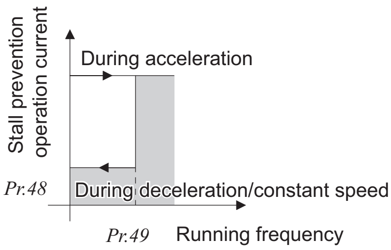
$$\text{Stall prevention operation level in high frequency range (\%)} = A + B \times \left[\frac{Pr.\,22 - A}{Pr.\,22 - B}\right] \times \left[\frac{Pr.\,23 - 100}{100}\right]$$

$$\text{However, } A = \frac{Pr.\,66(\text{Hz}) \times Pr.\,22(\%)}{\text{Output frequency (H)}},\quad B = \frac{Pr.\,66(\text{Hz}) \times Pr.\,22(\%)}{400\text{Hz}}$$

- When *Pr. 23 Stall prevention operation level compensation factor at double speed* = "9999" (initial value), the stall prevention operation level is kept constant at the *Pr. 22* setting up to 400Hz.

(4) Set multiple stall prevention operation levels *(Pr. 48, Pr. 49)*

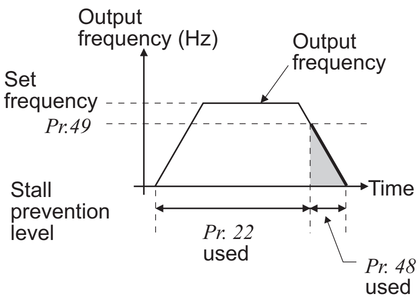
- Setting "9999" in *Pr. 49 Second stall prevention operation frequency* and turning the RT signal ON make *Pr. 48 Second stall prevention operation current* valid.
- In *Pr. 48*, you can set the stall prevention operation level at the output frequency from 0Hz to that set in *Pr. 49*. During acceleration, however, the operation level is as set in *Pr. 22*.
- This function can also be used for stop-on-contact or similar operation by decreasing the *Pr. 48* setting to weaken the deceleration torque (stopping torque).

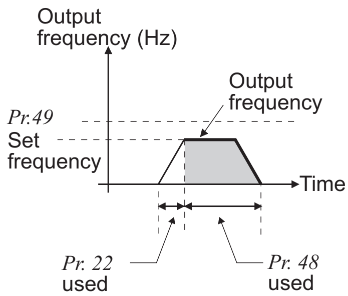


Pr. 49 Setting	Operation
0(initial value)	The second stall prevention operation is not performed.
0.01Hz to 400Hz	If the output frequency is equal to or less than the frequency set in *Pr. 49*, the second stall prevention function activates. (during constant speed or deceleration)*1
9999 *2	The second stall prevention function is performed according to the RT signal. RT signal ON ... Stall level *Pr. 48* RT signal OFF ... Stall level *Pr. 22*

*1 The smaller setting of the stall prevention operation levels set in *Pr. 22* and *Pr. 48* has a higher priority.

*2 When *Pr. 22* = "9999" (Stall prevention operation level analog input), the stall prevention operation level also switches from the analog input (terminal 1 input) to the stall prevention operation level of *Pr. 48* when the RT signal turns ON.
(The second stall prevention operation level cannot be input in an analog form.)





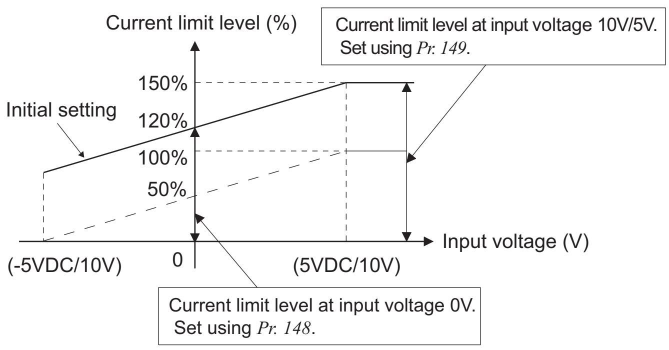
REMARKS

- When *Pr. 49* ≠ "9999" (level changed according to frequency) and *Pr. 48* = "0%", the stall prevention operation level is 0% at or higher than the frequency set in *Pr. 49*.
- In the initial setting, the RT signal is assigned to the RT terminal. By setting "3" to any of *Pr. 178 to Pr. 189 (input terminal function selection)*, you can assign the RT signal to the other terminal.

CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.
- The RT signal acts as the second function selection signal and makes the other second functions valid. *(Refer to page 137)*

(5) Stall prevention operation level setting by terminal 1 (analog variable) *(Pr. 148, Pr. 149)*



- Set *Pr. 22 Stall prevention operation level* to "9999".
  Input 0 to 5V (or 0 to 10V) to terminal 1.
  Select 5V or 10V using *Pr. 73 Analog input selection*. When *Pr. 73* = "1" (initial value), 0 to ±10V is input.
- Set the current limit level at the input voltage of 0V in *Pr. 148 Stall prevention level at 0V input.*
- Set the current limit level at the input voltage of 10V or 5V in *Pr. 149 Stall prevention level at 10V input*

REMARKS

- The fast-response current limit level cannot be set.
- When *Pr. 22* = 9999 (analog variable), functions other than the terminal 1 (auxiliary input, override function, PID control) are not executed.

(6) To further prevent a trip (*Pr. 154*) V/F S MFVC

- When *Pr. 154* is set to "0", the output voltage reduces during stall prevention operation. By making setting to reduce the output voltage, an overcurrent trip can further become difficult to occur.
- Use this function where a torque decrease will not pose a problem.

Pr. 154 Setting	Description
0	Output voltage reduced
1 (initial value)	Output voltage not reduced

(7) Limit the stall prevention operation and fast-response current limit operation according to the operating status (*Pr. 156*)

- Refer to the following table and select whether fast-response current limit operation will be performed or not and the operation to be performed at OL signal output.

Pr. 156 Setting	Fast-response Current Limit *4 ○: Activated ●: Not activated	Stall Prevention Operation Selection ○:Activated ●:Not activated			OL Signal Output ○:Operation continued ●:Operation not continued *1
		Acceleration	Constant speed	Deceleration	
0 (initial value)	○	○	○	○	○
1	●	○	○	○	○
2	○	●	○	○	○
3	●	●	○	○	○
4	○	○	●	○	○
5	●	○	●	○	○
6	○	●	●	○	○
7	●	●	●	○	○
8	○	○	○	●	○
9	●	○	○	●	○
10	○	●	○	●	○
11	●	●	○	●	○
12	○	○	●	●	○
13	●	○	●	●	○
14	○	●	●	●	○
15	●	●	●	●	— *2
100 *3 Driving	○	○	○	○	○
100 *3 Regeneration	●	●	●	●	— *2

Pr. 156 Setting	Fast-response Current Limit *4 ○:Activated ●: Not activated	Stall Prevention Operation Selection ○:Activated ●:Not activated			OL Signal Output ○:Operation continued ●:Operation not continued *1
		Acceleration	Constant speed	Deceleration	
16	○	○	○	○	●
17	●	○	○	○	●
18	○	●	○	○	●
19	●	●	○	○	●
20	○	○	●	○	●
21	●	○	●	○	●
22	○	●	●	○	●
23	●	●	●	○	●
24	○	○	○	○	●
25	●	○	○	●	●
26	○	●	○	●	●
27	●	●	○	●	●
28	○	○	●	●	●
29	●	○	●	●	●
30	○	●	●	●	●
31	●	●	●	●	— *2
101 *3 Driving	●	○	○	○	○
101 *3 Regeneration	●	●	●	●	— *2

*1 When "Operation not continued at signal output" is selected, the " E.OLT " fault code (stopped by stall prevention) is displayed and operation stopped.
*2 Since both fast-response current limit and stall prevention are not activated, OL signal and E.OLT are not output.
*3 The settings "100" and "101" allow operations to be performed in the driving and regeneration modes, respectively. The setting "101" disables the fast-response current limit in the driving mode.
*4 The fast-response current limit operation is disabled under IPM motor control.

CAUTION

- When the load is heavy, the elevator is predetermined, or the acceleration/deceleration time is short, stall prevention is activated and acceleration/deceleration may not be made according to the preset acceleration/deceleration time. Set *Pr. 156* and stall prevention operation level to the optimum values.
- In vertical lift applications, make setting so that the fast-response current limit is not activated. Torque may not be produced, causing a drop due to gravity.

⚠ CAUTION

⚠ Do not set a small value as the stall prevention operation current.
Otherwise, torque generated will reduce.

⚠ Always perform test operation.
Stall prevention operation during acceleration may increase the acceleration time.
Stall prevention operation performed during constant speed may cause sudden speed changes.
Stall prevention operation during deceleration may increase the deceleration time, increasing the deceleration distance.

♦ Parameters referred to ♦

· *Pr. 73 Analog input selection ☞ Refer to page 185*
· *Pr. 178 to Pr. 189 (Input terminal function selection) ☞ Refer to page 133*
· *Pr. 190 to Pr. 196 (output terminal function selection) ☞ Refer to page 140*

4

PARAMETERS

4.5 Limiting the output frequency

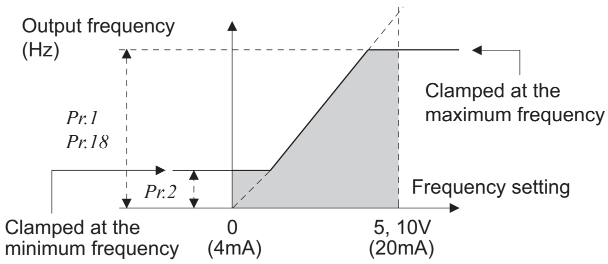
Purpose	Parameter that must be Set		Refer to Page
Set upper limit and lower limit of output frequency	**Maximum/minimum frequency**	**Pr. 1, Pr. 2, Pr. 18**	96
Perform operation by avoiding mechanical resonance points	**Frequency jump**	**Pr. 31 to Pr. 36**	97

4.5.1 Maximum/minimum frequency (Pr. 1, Pr. 2, Pr. 18)

You can limit the motor speed. Clamp the upper and lower limits of the output frequency.

Parameter Number	Name	Initial Value		Setting Range	Description
1	**Maximum frequency**	55K or lower	120Hz *2	0 to 120Hz	Set the upper limit of the output frequency.
		75K or higher	60Hz *2		
2	**Minimum frequency**	0Hz		0 to 120Hz	Set the lower limit of the output frequency.
18 *1	**High speed maximum frequency**	55K or lower	120Hz *2	120 to 400Hz *3	Set when performing the operation at 120Hz or higher.
		75K or higher	60Hz *2		

*1 The parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
*2 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*
*3 Even if a value higher than the maximum motor frequency *(Refer to page 81)* is set in *Pr. 18* under IPM motor control, the high speed maximum frequency is limited to the maximum motor frequency.



(1) Set maximum frequency

· Set the upper limit of the output frequency in *Pr. 1 Maximum frequency*. If the value of the frequency command entered is higher than the setting, the output frequency is clamped at the maximum frequency.
· To operate with a frequency higher than 120Hz under V/F control or Simple magnetic flux vector control, set the upper limit for the output frequency in *Pr. 18 High speed maximum frequency*. (When *Pr. 18* is set, *Pr. 1* automatically switches to the frequency of *Pr. 18*. When *Pr. 18* is set, *Pr. 18* automatically switches to the frequency of *Pr. 1*.)

REMARKS

· To operate with a frequency higher than 60Hz (rated IPM motor frequency under IPM motor control *(Refer to page 81)*) using frequency-setting analog signals, change the *Pr.125 (Pr.126)* (frequency setting gain) setting. Changing only *Pr.1* and *Pr.18* does not allow the operation with a frequency higher than 60Hz (rated IPM motor frequency under IPM motor control. *(Refer to page 81)*
· Under IPM motor control, the estimated output frequency (rotations per minute) is used to limit the frequency. Therefore, a value equal to or higher than the upper limit frequency may be displayed in the monitor.

(2) Set minimum frequency

- Use *Pr. 2 Minimum frequency* to set the lower limit of the output frequency.
- The output frequency is clamped by the *Pr. 2* setting even the set frequency is lower than the *Pr. 2* setting (The frequency will not decrease to the *Pr. 2* setting.)

REMARKS

- When *Pr. 15 Jog frequency* is equal to or less than *Pr. 2*, the *Pr. 15* setting has precedence over the *Pr. 2* setting.
- When stall prevention is activated to decrease the output frequency, the output frequency may drop to *Pr. 2* or below.
- Under IPM motor control, the estimated output frequency (rotations per minute) is used to limit the frequency. Therefore, the value displayed in the monitor may reach the lower limit frequency or lower.

⚠ CAUTION

⚠ If the *Pr. 2* setting is higher than the *Pr. 13 Starting frequency* value, note that the motor will run at the set frequency according to the acceleration time setting by simply switching the start signal ON, without entry of the command frequency.

♦ Parameters referred to ♦

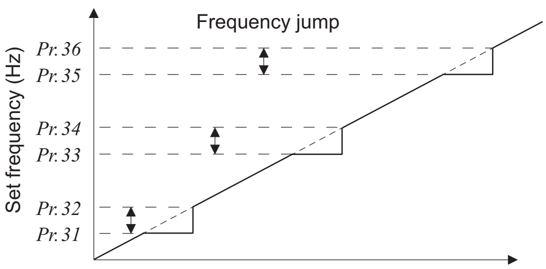
Pr. 13 Starting frequency ☞ *Refer to page 113*
Pr. 15 Jog frequency ☞ *Refer to page 104*
Pr. 125 Terminal 2 frequency setting gain frequency, Pr. 126 Terminal 4 frequency setting gain frequency ☞ *Refer to page 193*

4.5.2 Avoiding mechanical resonance points (Frequency jump) (Pr. 31 to Pr. 36)

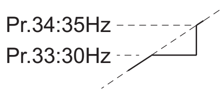
When it is desired to avoid resonance attributable to the natural frequency of a mechanical system, these parameters allow resonant frequencies to be jumped.

Parameter Number	Name	Initial Value	Setting Range	Description
31	**Frequency jump 1A**	9999	0 to 400Hz, 9999	1A to 1B, 2A to 2B, 3A to 3B is frequency jumps 9999: Function invalid
32	**Frequency jump 1B**	9999	0 to 400Hz, 9999	
33	**Frequency jump 2A**	9999	0 to 400Hz, 9999	
34	**Frequency jump 2B**	9999	0 to 400Hz, 9999	
35	**Frequency jump 3A**	9999	0 to 400Hz, 9999	
36	**Frequency jump 3B**	9999	0 to 400Hz, 9999	

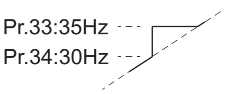
The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*



- Up to three areas may be set, with the jump frequencies set to either the top or bottom point of each area.
- The settings of frequency jumps 1A, 2A, 3A are jump points, and operation is performed at these frequencies in the jump areas.



Example 1 To fix the frequency to 30Hz in the range 30Hz to 35Hz, set 35Hz in *Pr. 34* and 30Hz in *Pr. 33*.



Example 2 To jump the frequency to 35Hz in the range 30Hz to 35Hz, set 35Hz in *Pr. 33* and 30Hz in *Pr. 34*.

CAUTION

- During acceleration/deceleration, the running frequency within the set area is valid.

4.6 V/F pattern

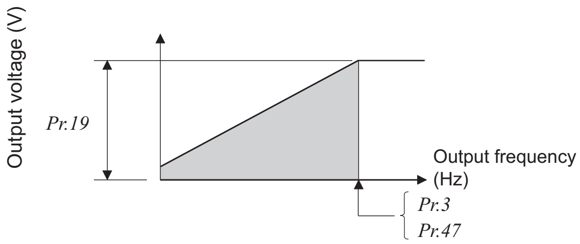
Purpose	Parameter that must be Set		Refer to Page
Set motor ratings	**Base frequency, base frequency voltage**	**Pr. 3, Pr. 19, Pr. 47**	98
Select a V/F pattern according to applications	**Load pattern selection**	**Pr. 14**	100
Use special motor	**Adjustable 5 points V/F**	**Pr. 71, Pr. 100 to Pr. 109**	101

4.6.1 Base frequency, voltage (Pr. 3, Pr. 19, Pr. 47) V/F S MFVC

Used to adjust the inverter outputs (voltage, frequency) to the motor rating.

Parameter Number	Name	Initial Value	Setting Range	Description
3	**Base frequency**	60Hz	0 to 400Hz	Set the frequency when the motor rated torque is generated. (50Hz/60Hz)
19 *	**Base frequency voltage**	9999	0 to 1000V	Set the base voltage.
			8888	95% of power supply voltage
			9999	Same as power supply voltage
47 *	**Second V/F (base frequency)**	9999	0 to 400Hz	Set the base frequency when the RT signal is ON.
			9999	Second V/F invalid

* The parameters can be set when *Pr. 160 User group read selection* = "0" *(Refer to page 201)*



(1) Setting of base frequency *(Pr. 3)*

- When operating a standard motor, generally set the rated frequency of the motor to *Pr. 3 Base frequency*. When running the motor using bypass operation, set *Pr. 3* to the same value as the power supply frequency.
- If the frequency given on the motor rating plate is "50Hz" only, always set to "50Hz". Leaving the base frequency unchanged from "60Hz" may make the voltage too low and the torque insufficient. It may result in an inverter trip due to overload. Caution must be taken especially when *Pr. 14 Load pattern selection* = "1" (variable torque load).
- When using the Mitsubishi constant-torque motor, set *Pr. 3* to 60Hz.

(2) Set multiple base frequencies *(Pr. 47)*

- When you want to change the base frequency when switching two motors with one inverter, use the *Pr. 47 Second V/F (base frequency)*.
- *Pr. 47 Second V/F (base frequency)* is valid when the RT signal is ON.

REMARKS

- The RT signal acts as the second function selection signal and makes the other second functions valid. *(Refer to page 137)*
- In the initial setting, the RT signal is assigned to the RT terminal. By setting "3" to any of *Pr. 178 to Pr. 189 (Input terminal function selection)*, you can assign the RT signal to the other terminal.

(3) Base frequency voltage setting *(Pr. 19)*

· Use *Pr. 19 Base frequency voltage* to set the base voltage (e.g. rated motor voltage).
· If the setting is equal to or less than the power supply voltage, the maximum output voltage of the inverter is as set in *Pr. 19*.
· *Pr. 19* can be utilized in the following cases.
  (a) When regeneration frequency is high (e.g. continuous regeneration)
  During regeneration, the output voltage becomes higher than the reference and may cause an overcurrent trip (E.OC□) due to an increased motor current.
  (b) When power supply voltage variation is large
  When the power supply voltage exceeds the rated voltage of the motor, speed variation or motor overheat may be caused by excessive torque or increased motor current.

CAUTION

· When *Pr. 71 Applied motor* is set to "2" (adjustable 5 points V/F characteristic), the *Pr. 47* setting becomes invalid. In addition, you cannot set "8888" or "9999" in *Pr. 19*.
· Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

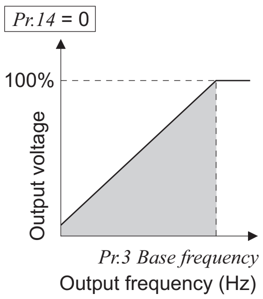
Pr. 14 Load pattern selection ☞ *Refer to page 100*
Pr. 29 Acceleration/deceleration pattern selection ☞ *Refer to page 115*
Pr. 71 Applied motor ☞ *Refer to page 122*
Pr. 80 Motor capacity ☞ *Refer to page 89*
Pr. 178 to Pr. 189 (input terminal function selection) ☞ *Refer to page 133*

4.6.2 Load pattern selection (Pr. 14) V/F

You can select the optimum output characteristic (V/F characteristic) for the application and load characteristics.

Parameter Number	Name	Initial Value	Setting Range	Description
14	**Load pattern selection**	1	0	For constant-torque load
			1	For variable-torque loads

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

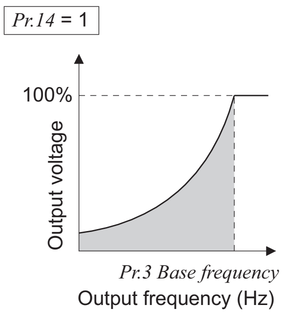


(1) For constant-torque load (setting "0")

· At or less than the base frequency voltage, the output voltage varies linearly with the output frequency.
· Set this value when driving the load whose load torque is constant if the speed varies, e.g. conveyor, cart or roll drive.

POINT

If the load is a fan or pump, select "For rated torque load (setting "0")" in any of the following cases.
· When a blower of large moment of inertia (J) is accelerated in a short time
· For constant-torque load such as rotary pump or gear pump
· When load torque increases at low speed, e.g. screw pump



(2) For variable-torque load (setting "1", initial value)

· At or less than the base frequency voltage, the output voltage varies with the output frequency in a square curve.
· Set this value when driving the load whose load torque varies in proportion to the square of the speed, e.g. fan or pump.

♦ Parameters referred to ♦

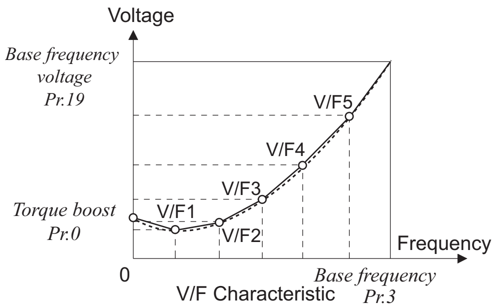
Pr. 3 Base frequency ☞ *Refer to page 98*

4.6.3 Adjustable 5 points V/F (Pr. 71, Pr. 100 to Pr. 109) V/F

Create a dedicated V/F pattern for V/F (frequency voltage/frequency) control by setting unique V/F characteristics at start-up and up to the base frequency/voltage point.
The torque pattern that is optimum for the machine's characteristic can be set.

Parameter Number	Name	Initial Value	Setting Range	Description
71	**Applied motor**	0	0, 1, 2, 20, 120, 210	Set "2" for adjustable 5 points V/F control.
100	**V/F1(first frequency)**	9999	0 to 400Hz, 9999	Set each points (frequency, voltage) of V/F pattern. 9999: No V/F setting
101	**V/F1(first frequency voltage)**	0V	0 to 1000V	
102	**V/F2(second frequency)**	9999	0 to 400Hz, 9999	
103	**V/F2(second frequency voltage)**	0V	0 to 1000V	
104	**V/F3(third frequency)**	9999	0 to 400Hz, 9999	
105	**V/F3(third frequency voltage)**	0V	0 to 1000V	
106	**V/F4(fourth frequency)**	9999	0 to 400Hz, 9999	
107	**V/F4(fourth frequency voltage)**	0V	0 to 1000V	
108	**V/F5(fifth frequency)**	9999	0 to 400Hz, 9999	
109	**V/F5(fifth frequency voltage)**	0V	0 to 1000V	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*



V/F Characteristic

- Any V/F characteristic can be provided by presetting the parameters of *V/F1 (first frequency voltage/first frequency) to V/F5*.
- For a machine of large static friction coefficient and small dynamic static friction coefficient, for example, set a V/F pattern that will increase the voltage only in a low-speed range since such a machine requires large torque at a start.

(Setting procedure)

1) Set the rated motor current in *Pr. 19 Base frequency voltage*. (No function at the setting of "9999" (initial value) or "8888".)
2) Set *Pr. 71 Applied motor* to "2" (Adjustable 5 points V/F characteristic).
3) Set the frequency and voltage you want to set in *Pr. 100 to Pr. 109*.

⚠ CAUTION

⚠ Make sure to set this parameter correctly according to the motor used.
Incorrect setting may cause the motor to overheat and burn.

CAUTION

- Adjustable 5 points V/F characteristics are available only under V/F control or Optimum excitation control. These are not available under Simple magnetic flux vector control or IPM motor control.
- When *Pr. 19 Base frequency voltage* = "8888" or "9999", *Pr. 71* cannot be set to "2". To set *Pr. 71* to "2", set the rated voltage value in *Pr. 19*.
- When the frequency values at each point are the same, a write disable error (Er1) appears.
- Set the points (frequencies, voltages) of *Pr. 100 to Pr. 109* within the ranges of *Pr. 3 Base frequency* and *Pr. 19 Base frequency voltage*.
- When "2" is set in *Pr. 71*, *Pr. 47 Second V/F (base frequency)* will not function.
- When *Pr. 71* is set to "2", the electronic thermal relay function makes calculation as a standard motor.

REMARKS

- A greater energy saving effect can be expected by combining *Pr. 60 Energy saving control selection* and adjustable 5 points V/F.
- For the 5.5K and 7.5K, the *Pr.0 Torque boost* and *Pr.12 DC injection brake operation voltage* settings are automatically changed according to the *Pr. 71* setting.

Pr. 71	Standard Motor Setting 0, 2, 20, 120	Constant-torque Motor Setting 1
Pr. 0	3%	2%
Pr. 12	4%	2%

♦ Parameters referred to ♦

- *Pr. 3 Base frequency, Pr. 19 Base frequency voltage* ☞ *Refer to page 98*
- *Pr. 12 DC injection brake operation voltage* ☞ *Refer to page 123*
- *Pr. 47 Second V/F (base frequency)* ☞ *Refer to page 98*
- *Pr. 60 Energy saving control selection* ☞ *Refer to page 176*
- *Pr. 71 Applied motor* ☞ *Refer to page 122*
- *Pr. 80 Motor capacity, Pr. 90 Motor constant (R1)* ☞ *Refer to page 89*

4.7 Frequency setting by external terminals

Purpose	Parameter that must be Set		Refer to Page
Make frequency setting by combination of terminals	**Multi-speed operation**	**Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239**	102
Perform jog operation	**Jog operation**	**Pr. 15, Pr. 16**	104
Added compensation for multi-speed setting and remote setting	**Multi-speed input compensation selection**	**Pr. 28**	106
Infinitely variable speed setting by terminals	**Remote setting function**	**Pr. 59**	106

4.7.1 Multi-speed setting operation (Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239)

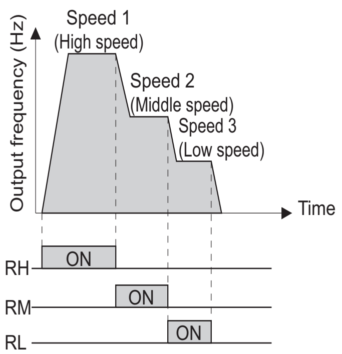
Can be used to change the preset speed in the parameter with the contact terminals.
Any speed can be selected by simply turning ON/OFF the contact signals (RH, RM, RL, REX signals).

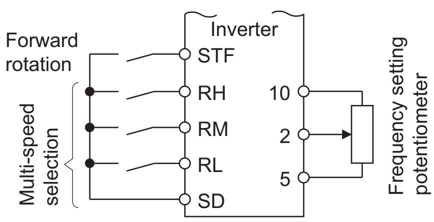
Parameter Number	Name	Initial Value	Setting Range	Description
4	**Multi-speed setting (high speed)**	60Hz *2	0 to 400Hz	Set the frequency when RH turns ON.
5	**Multi-speed setting (middle speed)**	30Hz	0 to 400Hz	Set the frequency when RM turns ON.
6	**Multi-speed setting (low speed)**	10Hz	0 to 400Hz	Set the frequency when RL turns ON.
24 *1	**Multi-speed setting (speed 4)**	9999	0 to 400Hz, 9999	Frequency from speed 4 to speed 15 can be set according to the combination of the RH, RM, RL and REX signals. 9999: not selected
25 *1	**Multi-speed setting (speed 5)**	9999	0 to 400Hz, 9999	
26 *1	**Multi-speed setting (speed 6)**	9999	0 to 400Hz, 9999	
27 *1	**Multi-speed setting (speed 7)**	9999	0 to 400Hz, 9999	
232 *1	**Multi-speed setting (speed 8)**	9999	0 to 400Hz, 9999	
233 *1	**Multi-speed setting (speed 9)**	9999	0 to 400Hz, 9999	
234 *1	**Multi-speed setting (speed 10)**	9999	0 to 400Hz, 9999	
235 *1	**Multi-speed setting (speed 11)**	9999	0 to 400Hz, 9999	
236 *1	**Multi-speed setting (speed 12)**	9999	0 to 400Hz, 9999	
237 *1	**Multi-speed setting (speed 13)**	9999	0 to 400Hz, 9999	
238 *1	**Multi-speed setting (speed 14)**	9999	0 to 400Hz, 9999	
239 *1	**Multi-speed setting (speed 15)**	9999	0 to 400Hz, 9999	

The above parameters allow their settings to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection.*
*1 The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
*2 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*

(1) Multi-speed setting *(Pr. 4 to Pr. 6)*

· Operation is performed at the frequency set in *Pr. 4* when the RH signal turns ON, *Pr. 5* when the RM signal turns ON, and *Pr. 6* when the RL signal turns ON.





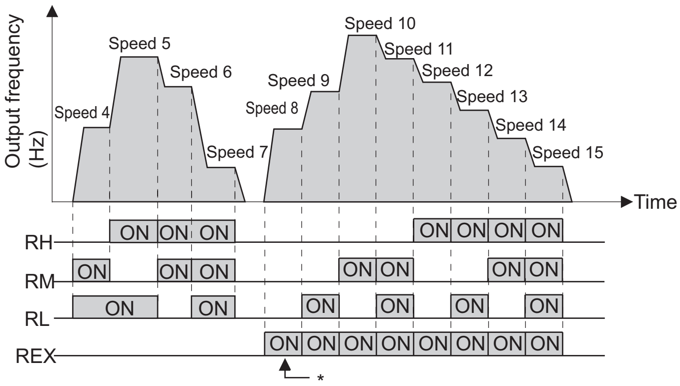
Multi-Speed Operation Connection Example

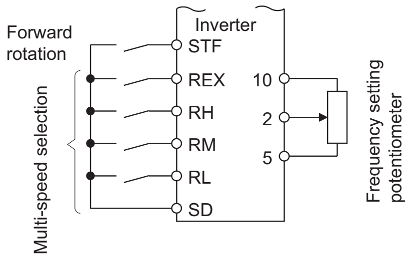
REMARKS

· In the initial setting, if two or three speeds are simultaneously selected, priority is given to the set frequency of the lower signal. For example, when the RH and RM signals turn ON, the RM signal *(Pr. 5)* has a higher priority.
· The RH, RM, RL signals are assigned to the terminal RH, RM, RL in the initial setting. By setting "0 (RL)", "1 (RM)", "2 (RH)" in any of *Pr.178 to Pr.189 (input terminal function assignment)*, you can assign the signals to other terminals.

(2) Multi-speed setting higher than speed 4 *(Pr. 24 to Pr. 27, Pr. 232 to Pr. 239)*

- Frequency from speed 4 to speed 15 can be set according to the combination of the RH, RM, RL and REX signals. Set the running frequencies in *Pr. 24 to Pr. 27, Pr. 232 to Pr. 239*. (In the initial value setting, speed 4 to speed 15 are invalid.)
- For the terminal used for REX signal input, set "8" in any of *Pr. 178 to Pr. 186* to assign the function.





Multi-Speed Operation Connection Example

* When "9999" is set in *Pr.232 Multi-speed setting (speed 8)*, operation is performed at frequency set in *Pr.6* when RH, RM and RL are turned OFF and REX is turned ON.

REMARKS

- The priorities of the frequency commands by the external signals are "jog operation > multi-speed operation > terminal 4 analog input > terminal 2 analog input". (Refer to *page 185* for the frequency command by analog input)
- Valid in External operation mode or PU/external combined operation mode (*Pr. 79* = "3" or "4").
- Multi-speed parameters can also be set in the PU or External operation mode.
- *Pr. 24 to Pr. 27* and *Pr. 232 to Pr. 239* settings have no priority between them.
- When a value other than "0" is set in *Pr. 59 Remote function selection*, the RH, RM and RL signals are used as the remote setting signals and the multi-speed setting becomes invalid.
- When making analog input compensation, set "1" in *Pr. 28 Multi-speed input compensation selection*.

CAUTION

- The RH, RM, RL, REX signals can be assigned to the input terminal using any of *Pr. 178 to Pr. 189 (input terminal function selection)*. Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 1 Maximum frequency, Pr. 2 Minimum frequency ☞ *Refer to page 96*
Pr. 15 Jog frequency ☞ *Refer to page 104*
Pr. 28 Multi-speed input compensation selection ☞ *Refer to page 106*
Pr. 59 Remote function selection ☞ *Refer to page 106*
Pr. 178 to Pr. 189 (input terminal function selection) ☞ *Refer to page 133*

4.7.2 Jog operation (Pr. 15, Pr. 16)

You can set the frequency and acceleration/deceleration time for jog operation. Jog operation can be performed from either the outside or PU.
Can be used for conveyor positioning, test operation, etc.

Parameter Number	Name	Initial Value	Setting Range	Description
15	**Jog frequency**	5Hz *1	0 to 400Hz	Set the frequency for jog operation.
16	**Jog acceleration/ deceleration time**	0.5s	0 to 3600/360s *2	Set the acceleration/deceleration time for jog operation. As the acceleration/deceleration time set the time taken to reach the frequency set in *Pr. 20 Acceleration/deceleration reference frequency*. (Initial value is 60Hz *1) The acceleration and deceleration times cannot be set separately.

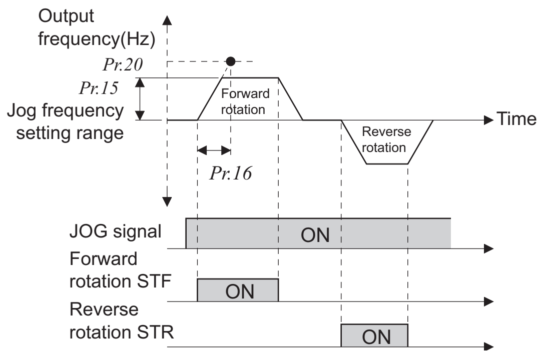
The above parameters are displayed as simple mode parameters only when the parameter unit (FR-PU04/FR-PU07) is connected. When the operation panel (FR-DU07) is connected, the above parameters can be set only when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

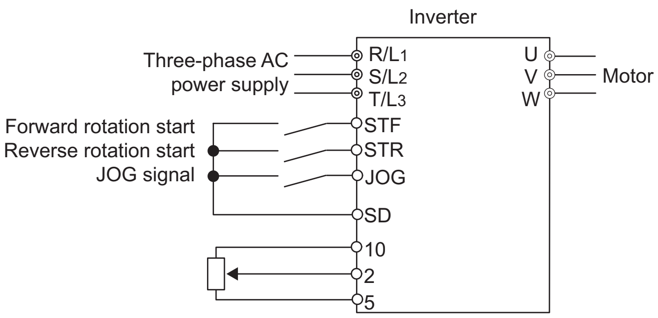
*1 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*

*2 When the setting of *Pr. 21 Acceleration/deceleration time increments* is "0" (initial value), the setting range is "0 to 3600s" and the setting increments are "0.1s", and when the setting is "1", the setting range is "0 to 360s" and the setting increments are "0.01s"

(1) Jog operation from outside

· When the JOG signal is ON, a start and stop are available by the start signal (STF, STR). (The JOG signal is assigned to the terminal JOG in the initial setting)

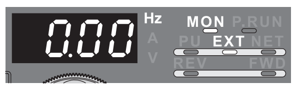




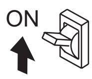
Connection diagram for external jog operation

Operation — **Indication**

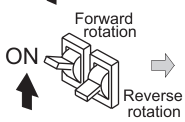
1. Screen at power-ON
   - Confirm that the External operation mode is selected. ([EXT] lit)
     If not lit, press (PU/EXT) to change to the External [EXT] operation mode.
     If the operation mode still does not change, set *Pr. 79* to change to the External operation mode.

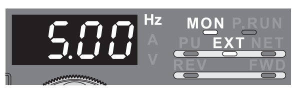


2. Turn the JOG switch ON.



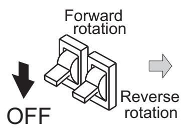
3. Turn the start switch (STF or STR) ON.
   - The motor rotates while start switch (STF or STR) is ON.
   - Rotates at 5Hz. (Initial value of *Pr. 15*)

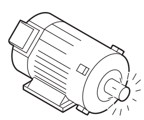




Rotates while ON

4. Turn the start switch (STF or STR) OFF.





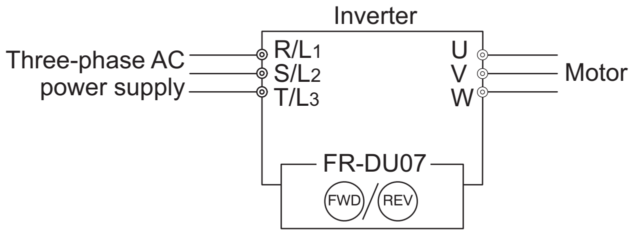
Stop

REMARKS

· When you want to change the running frequency, change *Pr. 15 Jog frequency* . (initial value "5Hz")
· When you want to change the acceleration/deceleration time, change *Pr. 16 Jog acceleration/deceleration time* . (initial value "0.5"s)

(2) Jog operation from PU

· Set the PU (FR-DU07/FR-PU04/FR-PU07) to the jog operation mode. Operation is performed only while the start button is pressed.

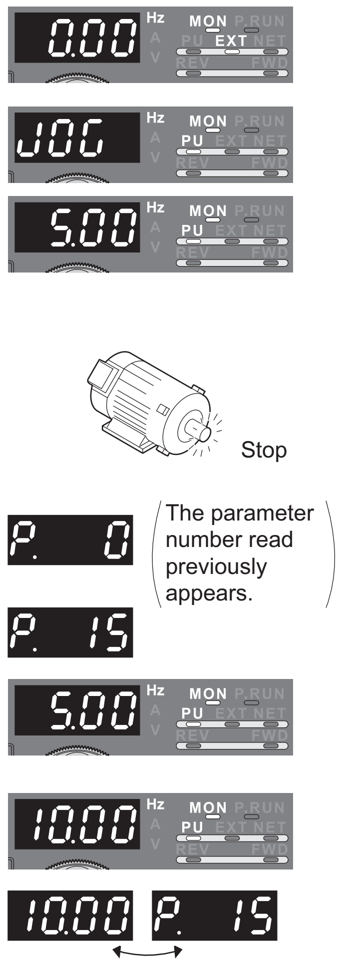


Operation / **Indication**

1. Confirmation of the RUN indicator and operation mode indicator
   - ●The monitor mode should have been selected.
   - ●The inverter should be at a stop.
2. Press PU/EXT to choose the PU JOG operation mode.
3. Press FWD (or REV). — Hold down.
   - ●While FWD (or REV) is pressed, the motor rotates.
   - ●Rotates at 5Hz. (initial value of Pr. 15)
4. Release FWD (or REV). — Release — Stop

[When changing the frequency of PU JOG operation]

5. Press MODE to choose the parameter setting mode. (The parameter number read previously appears.)
6. Turn the dial until *Pr. 15 Jog frequency* appears.
7. Press SET to show the present set value. (5Hz)
8. Turn the dial to set the value to "10.00". (10Hz)
9. Press SET to set.
10. Perform the operations in steps 1 to 4. The motor rotates at 10Hz.



Flicker · · · Parameter setting complete!!

CAUTION

- The *Pr. 15* setting should be equal to or higher than the *Pr. 13 Starting frequency* setting.
- The JOG signal can be assigned to the input terminal using any of *Pr. 178 to Pr. 189 (input terminal function selection)*. Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.
- During jog operation, the second acceleration/deceleration via the RT signal cannot be selected. (The other second functions are valid. *(Refer to page 136)*)
- When *Pr. 79 Operation mode selection* = "4", push FWD/REV of the PU (FR-DU07/FR-PU04/FR-PU07) to make a start or push STOP/RESET to make a stop.
- This function is invalid when *Pr. 79* = "3".

♦ Parameters referred to ♦

- *Pr. 13 Starting frequency* ☞ *Refer to page 113*
- *Pr. 20 Acceleration/deceleration reference frequency, Pr. 21 Acceleration/deceleration time increments* ☞ *Refer to page 109*
- *Pr. 79 Operation mode selection* ☞ *Refer to page 206*
- *Pr. 178 to Pr. 189 (input terminal function selection)* ☞ *Refer to page 133*

4

PARAMETERS

4.7.3 Input compensation of multi-speed and remote setting (Pr. 28)

By inputting the frequency setting compensation signal (terminal 1, 2), the speed (frequency) can be compensated for relative to the multi-speed setting or the speed setting by remote setting function.

Parameter Number	Name	Initial Value	Setting Range	Description
28	**Multi-speed input compensation selection**	0	0	Without compensation
			1	With compensation

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

REMARKS

· Select the compensation input voltage (0 to ±5V, 0 to ±10V) and used terminal (terminal 1, 2) using *Pr. 73 Analog input selection*.

♦ Parameters referred to ♦

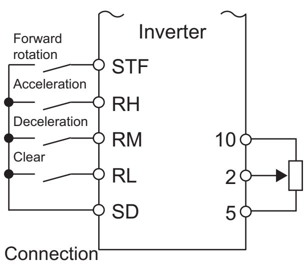
Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239 (multi-speed operation) ☞ *Refer to page 102*
Pr. 73 Analog input selection ☞ *Refer to page 185*
Pr. 59 Remote function selection ☞ *Refer to page 106*

4.7.4 Remote setting function (Pr. 59)

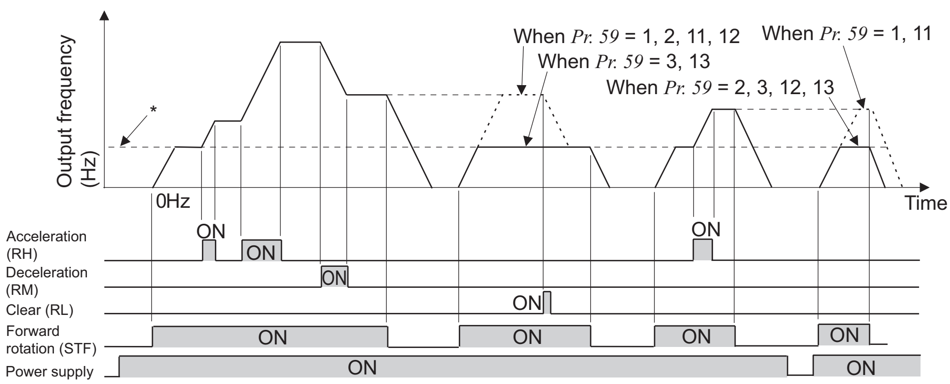
- Even if the operation panel is located away from the enclosure, you can use contact signals to perform continuous variable-speed operation, without using analog signals.
- By simply setting this parameter, you can use the acceleration, deceleration and setting clear functions of the motorized speed setter (FR-FK).

Parameter Number	Name	Initial Value	Setting Range	Description		
				RH, RM, RL Signal Function	Frequency Setting Storage Function	Deceleration to the Frequency Lower Than the Set Frequency
59	**Remote function selection**	0	0	Multi-speed setting	—	—
			1	Remote setting	Used	Disabled
			2	Remote setting	Not used	Disabled
			3	Remote setting	Not used (Turning STF/STR OFF clears remotely-set frequency.)	Disabled
			11	Remote setting	Used	Enabled
			12	Remote setting	Not used	Enabled
			13	Remote setting	Not used (Turning STF/STR OFF clears remotely-set frequency.)	Enabled

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*



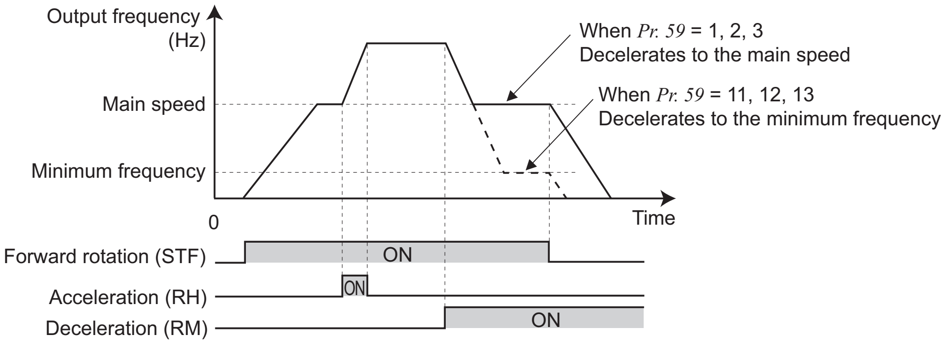
Connection diagram for remote setting



* External operation frequency (other than multi-speed) or PU running frequency

(1) Remote setting function

- Use *Pr. 59* to select whether to use the remote setting function or not and whether to use the frequency setting storage function in the remote setting mode or not.
  When *Pr. 59* setting is any of "1 to 3, 11 to 13" (remote setting function valid), the functions of the RH, RM and RL signals are changed to acceleration (RH), deceleration (RM) and clear (RL).
- When the remote function is used, the output frequency of the inverter can be compensated for as follows:
  External operation... Frequency set with RH and RM operation + external operation frequency other than multi-speed (PU operation frequency when *Pr.79* = "3" (external, PU combined)) and terminal 4 input
  (When making analog input compensation, set "1" to *Pr. 28 Multi-speed input compensation selection*.
  When *Pr. 28* is set to "0" and acceleration/deceleration is made to reach the set frequency of the analog voltage input (terminal 2 or terminal 4) by RH/RM, the auxiliary input by terminal 1 becomes invalid.)
  PU operation .... Frequency set by RH/RM operation + PU running frequency
- By setting *Pr. 59* = "11 to 13", the speed can be decelerated to the frequency lower than the main speed (set by the external operation frequency (except multi-speed setting) or PU operation frequency).



(2) Frequency setting storage

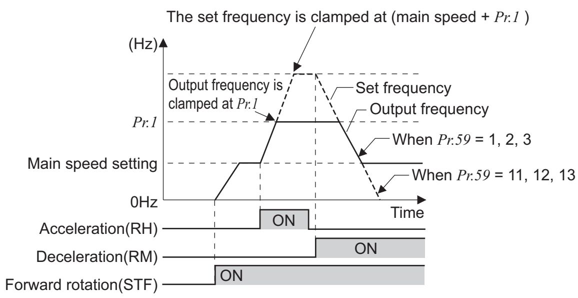
- The frequency setting storage function stores the remotely-set frequency (frequency set by RH/RM operation) into the memory (EEPROM). When power is switched OFF once, then ON, operation is resumed with the remotely set frequency. (*Pr. 59* =1, 11)

<Frequency setting storage conditions>

- The frequency when the start signal (STF or STR) turns OFF
- Remotely-set frequency is stored every minute after turning OFF (ON) the RH (acceleration) and RM (deceleration) signals together. (The frequency is overwritten if the latest frequency is different from the previous frequency when comparing the two. The state of the RL signal does not affect writing.)

CAUTION

- The range of frequency change by RH (acceleration) and RM (deceleration) is 0 to maximum frequency (*Pr. 1 or Pr. 18* setting). Note that the maximum value of set frequency is (main speed + maximum frequency).



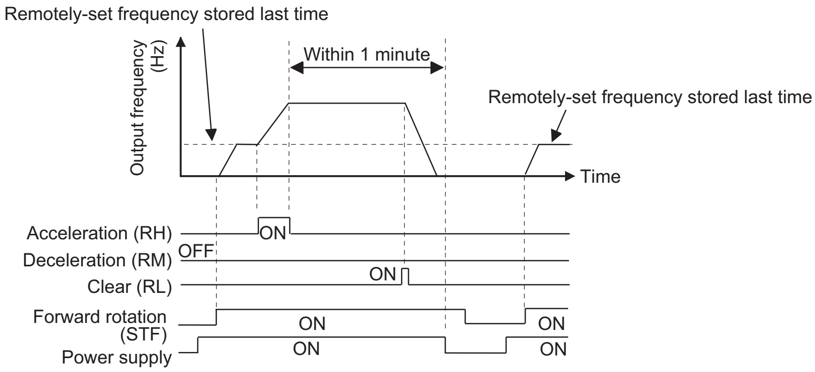
- When the acceleration or deceleration signal switches ON, acceleration/deceleration time is as set in *Pr. 44 Second acceleration/deceleration time* and *Pr. 45 Second deceleration time*. Note that when the time set in *Pr. 7* or *Pr. 8* is longer than the time set in *Pr. 44* or *Pr. 45*, the acceleration/deceleration time is as set in *Pr. 7* or *Pr. 8*. (when RT signal is OFF)
  When the RT signal is ON, acceleration/deceleration is made in the time set to *Pr. 44 Second acceleration/deceleration time* and *Pr. 45 Second deceleration time*, regardless of the Pr. 7 or Pr. 8 setting.
- Even if the start signal (STF or STR) is OFF, turning ON the acceleration (RH) or deceleration (RM) signal changes the preset frequency.
- When switching the start signal from ON to OFF, or changing frequency by the RH or RM signal frequently, set the frequency setting value storage function (write to EEPROM) invalid (*Pr. 59* ="2, 3, 12, 13"). If set valid (*Pr. 59* ="1, 11"), frequency is written to EEPROM frequently, and this will shorten the life of the EEPROM.
- The RH, RM, RL signals can be assigned to the input terminal using any of *Pr. 178 to Pr. 189 (input terminal function selection)*. Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.
- This parameter can be also used for the Network operation mode.

REMARKS

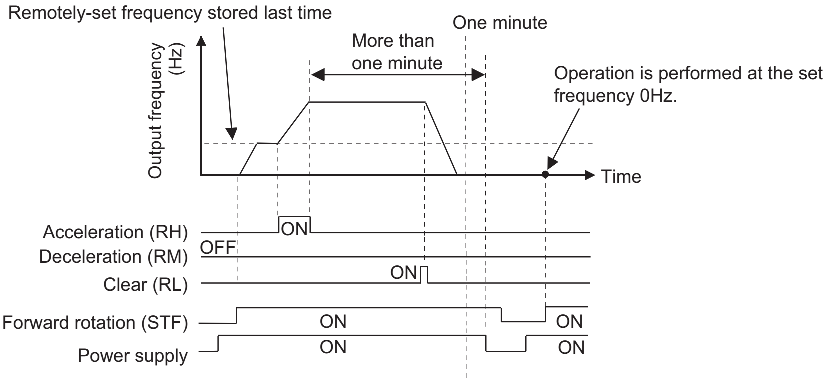
During jog operation or PID control operation, the remote setting function is invalid.

Setting frequency is "0"

- Even when the remotely-set frequency is cleared by turning on the RL (clear) signal after turn OFF (ON) of both the RH and RM signals, the inverter operates at the remotely-set frequency stored in the last operation if power is reapplied before one minute has elapsed since turn OFF (ON) of both the RH and RM signals



- When the remotely-set frequency is cleared by turning on the RL (clear) signal after turn OFF (ON) of both the RH and RM signals, the inverter operates at the frequency in the remotely-set frequency cleared state if power is reapplied after one minute has elapsed since turn OFF (ON) of both the RH and RM signals.



⚠ CAUTION

⚠ When selecting this function, re-set the maximum frequency according to the machine.

♦ Parameters referred to ♦

Pr. 1 Maximum frequency, Pr. 18 High speed maximum frequency ☞ *Refer to page 96*
Pr. 7 Acceleration time, Pr. 8 Deceleration time, Pr. 44 Second acceleration/deceleration time, Pr. 45 Second deceleration time. ☞ *Refer to page 109*
Pr. 28 Multi-speed input compensation selection ☞ *Refer to page 106*
Pr. 178 to Pr. 189 (input terminal function selection) ☞ *Refer to page 133*

4.8 Setting of acceleration/deceleration time and acceleration/deceleration pattern

Purpose	Parameter that must be set		Refer to page
Motor acceleration/deceleration time setting	**Acceleration/deceleration times**	**Pr.7, Pr.8, Pr.20, Pr.21, Pr.44, Pr.45, Pr. 147, Pr.791, Pr.792**	109
Starting frequency	**Starting frequency and start-time hold**	**Pr.13, Pr.571**	113
Set acceleration/deceleration pattern suitable for application	**Acceleration/deceleration pattern and backlash measures**	**Pr.29, Pr.140 to Pr.143**	115

4.8.1 Setting of the acceleration and deceleration time (Pr.7, Pr.8, Pr.20, Pr.21, Pr.44, Pr.45, Pr.147, Pr.791, Pr.792)

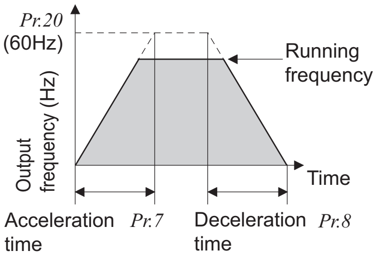
Used to set motor acceleration/deceleration time.
Set a larger value for a slower speed increase/decrease or a smaller value for a faster speed increase/decrease.
For the acceleration time at automatic restart after instantaneous power failure, refer to *Pr. 611 Acceleration time at a restart (refer to page 162)*.

Parameter Number	Name	Initial Value		Setting Range	Description	
7	**Acceleration time**	7.5K or lower	5s	0 to 3600/ 360s *2	Set the motor acceleration time.	
		11K or higher	15s			
8	**Deceleration time**	7.5K or lower	10s	0 to 3600/ 360s *2	Set the motor deceleration time.	
		11K or higher	30s			
20 *1	**Acceleration/ deceleration reference frequency**	60Hz *3		1 to 400Hz	Set the frequency that will be the basis of acceleration/deceleration time. As acceleration/deceleration time, set the frequency change time from stop to *Pr. 20*.	
21 *1	**Acceleration/ deceleration time increments**	0		0	Increments: 0.1s Range: 0 to 3600s	Increments and setting range of acceleration/ deceleration time setting can be changed.
				1	Increments: 0.01s Range: 0 to 360s	
44 *1	**Second acceleration/ deceleration time**	5s		0 to 3600/360s *2	Set the acceleration/deceleration time when the RT signal is on.	
45 *1	**Second deceleration time**	9999		0 to 3600/360s *2	Set the deceleration time when the RT signal is on.	
				9999	Acceleration time = deceleration time	
147 *1	**Acceleration/ deceleration time switching frequency**	9999		0 to 400Hz	The frequency where the acceleration/ deceleration time switches to the time set in *Pr.44* and *Pr.45*.	
				9999	No function	
791 IPM	**Acceleration time in low-speed range**	9999		0 to 3600/360s	Acceleration time in the low-speed range (rated motor frequency/10 or lower) is set.	
				9999	The acceleration time set in *Pr.7* is applied.	
792 IPM	**Deceleration time in low-speed range**	9999		0 to 3600/360s	Deceleration time in the low-speed range (rated motor frequency/10 or lower) is set.	
				9999	The deceleration time set in *Pr.8* is applied.	

*1 The parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
*2 Depends on the *Pr. 21 Acceleration/deceleration time increments* setting. The initial value for the setting range is "0 to 3600s" and the setting increments is "0.1s".
*3 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*

POINT

Setting *Pr.999 Automatic parameter setting* to "30" or "31" changes the setting increments of acceleration/deceleration time. *(Refer to page 290)*



(1) Acceleration time setting *(Pr.7, Pr.20)*

· Use *Pr. 7 Acceleration time* to set the acceleration time required to reach *Pr. 20 Acceleration/deceleration reference frequency* from 0Hz.
· Set the acceleration time according to the following formula.

$$\text{Acceleration time setting} = \frac{Pr.20}{\text{Maximum operating frequency} - Pr.13^{*}} \times \text{Acceleration time from stop to maximum operating frequency}$$

* The output starts at 0Hz under IPM motor control. Calculate with 0Hz.

Example) How to find the setting value for *Pr.7* when increasing the output frequency to the maximum frequency of 50Hz in 10s with *Pr.20* = 60Hz (initial setting) and *Pr.13* = 0.5Hz.

$$Pr.7 = \frac{60\text{Hz}}{50\text{Hz} - 0.5\text{Hz}} \times 10\text{s} \fallingdotseq 12.1\text{s}$$

(2) Deceleration time setting *(Pr.8, Pr.20)*

· Use *Pr. 8 Deceleration time* to set the deceleration time required to reach 0Hz from *Pr. 20 Acceleration/deceleration reference frequency*.
· Set the deceleration time according to the following formula.

$$\text{Deceleration time setting} = \frac{Pr.20}{\text{Maximum operating frequency} - Pr.10^{*}} \times \text{Deceleration time from maximum operating frequency to stop.}$$

* DC injection brake is not applied until the frequency drops to 0Hz regardless of the *Pr.10* setting under IPM motor control. Under IPM motor control, calculate as *Pr.10* ="0."

Example) How to find the setting value for *Pr.8* when decreasing the output frequency from the maximum frequency of 50Hz in 10s with *Pr.20* = 120Hz and *Pr.10* = 3Hz.

$$Pr.8 = \frac{120\text{Hz}}{50\text{Hz} - 3\text{Hz}} \times 10\text{s} \fallingdotseq 25.5\text{s}$$

(3) Change the setting range and increments of the acceleration/deceleration time *(Pr.21)*

· Use *Pr. 21* to set the acceleration/deceleration time and minimum setting range.
Setting "0" (initial value)......................0 to 3600s (minimum setting increments 0.1s)
Setting "1"...0 to 360s (minimum setting increments 0.01s)

CAUTION

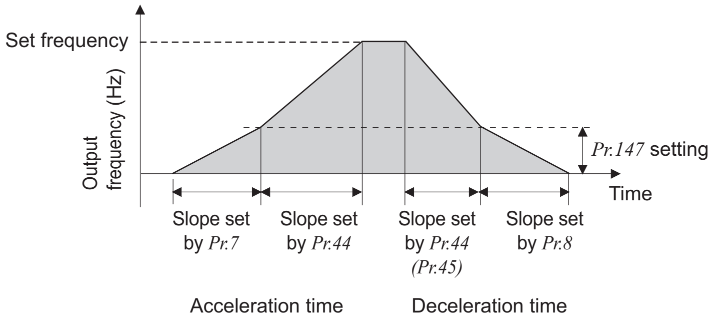
· Changing the *Pr. 21* setting changes the acceleration/deceleration time setting *(Pr. 7, Pr. 8, Pr. 16, Pr. 44, Pr. 45, Pr. 791, Pr. 792)*. (The *Pr. 611 Acceleration time at a restart* setting is not affected.)
<Example>
When *Pr. 21* = "0", setting "5.0" s in *Pr. 7* and "1" in *Pr. 21* automatically changes the *Pr. 7* setting to "0.5" s.

(4) Setting multiple acceleration/deceleration time (RT signal, *Pr.44, Pr.45, Pr. 147*)

- The *Pr.44* and *Pr.45* settings become valid when the RT signal turns ON or the output frequency reaches the value of *Pr.147* setting or higher.
- When "9999" is set in *Pr. 45*, the deceleration time becomes equal to the acceleration time *(Pr. 44)*.
- Acceleration/deceleration time changes when the RT signal turns ON or the output frequency reaches the *Pr.147* setting or higher.

Pr.147 setting	Acceleration/deceleration time	Description
9999 (initial value)	*Pr.7, Pr.8*	Acceleration/deceleration time is not automatically changed.
0.00Hz	*Pr.44, Pr.45*	Second acceleration/deceleration time is applied from the start.
0.01Hz ≤ *Pr.147* ≤ set frequency	Output frequency < *Pr.147*: *Pr.7, Pr.8* *Pr.147* ≤ output frequency: *Pr.44, Pr.45*	Acceleration/deceleration time is automatically changed. *
Set frequency < *Pr.147*	*Pr.7, Pr.8*	Not changed as the frequency has not reached the switchover frequency.

* Even if the output frequency is lower than the *Pr.147* setting, the acceleration/deceleration time is changed to the second acceleration/deceleration time by the RT signal.



CAUTION

- When the S-pattern acceleration/deceleration A is set *(refer to page 115)* under V/F control and Simple magnetic flux vector control, acceleration/deceleration time is the time to reach *Pr. 3 Base frequency*. When the S-pattern acceleration/deceleration A is set under IPM motor control, acceleration/deceleration time is the time to reach the rated motor frequency *(Refer to page 81)*.
- Acceleration/deceleration time formula when the set frequency is the base frequency or higher

$$t = \frac{4}{9} \times \frac{T}{(Pr.3)^2} \times f^2 + \frac{5}{9}T$$

T: Acceleration/deceleration time setting value(s)
f : Set frequency(Hz)

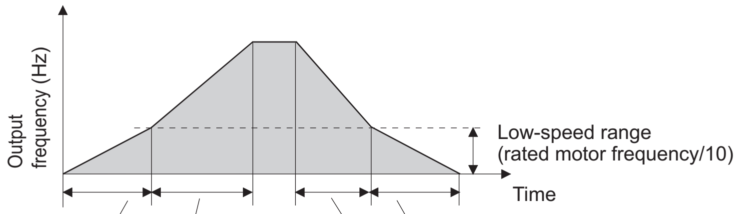
- Guideline for acceleration/deceleration time when *Pr. 3 Base frequency* = 60Hz (0Hz to set frequency)

Acceleration/deceleration time (s) \ Frequency setting (Hz)	60	120	200	400
5	5	12	27	102
15	15	35	82	305

- The RT signal can be assigned to the input terminal using any of *Pr. 178 to Pr. 189 (Input terminal function selection)*. Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

(5) Setting the acceleration/deceleration time in the low-speed range *(Pr.791, Pr.792)* IPM

If torque is required in the low-speed range (rated motor frequency *(Refer to page 81)*/10), set the *Pr.791 Acceleration time in low-speed range* and *Pr.792 Deceleration time in low-speed range* settings higher than the *Pr.7 Acceleration time* and *Pr.8 Deceleration time* settings so that the slow acceleration/deceleration is performed in the low-speed range.



REMARKS

- The RT signal acts as the second function selection signal and makes the other second function valid. *(Refer to page 137)*
- The RT signal is assigned to the RT terminal in the default setting. By setting "3" to any of *Pr. 178 to Pr. 189 (Input terminal function selection)*, you can assign the RT signal to the other terminal.
- If the *Pr. 20* setting is changed, the *Pr. 125 and Pr. 126 (frequency setting signal gain frequency)* settings do not change. Set *Pr. 125 and Pr. 126* to adjust the gains.
- When the *Pr. 7, Pr. 8, Pr. 44 and Pr. 45* settings are 0.03s or less, the acceleration/deceleration time is 0.04s. At that time, set *Pr. 20* to "120Hz" or less.
- Set *Pr.791* higher than *Pr.7*, and *Pr.792* higher than *Pr.8*. If set as *Pr.791* < *Pr.7*, the operation is performed as *Pr.791* = *Pr.7*. If set as *Pr.792* < *Pr.8*, the operation is performed as *Pr.792* = *Pr.8*.
- If the acceleration/deceleration time is set, the actual motor acceleration/deceleration time cannot be made shorter than the shortest acceleration/deceleration time determined by the mechanical system J (moment of inertia) and motor torque.

♦ Parameters referred to ♦

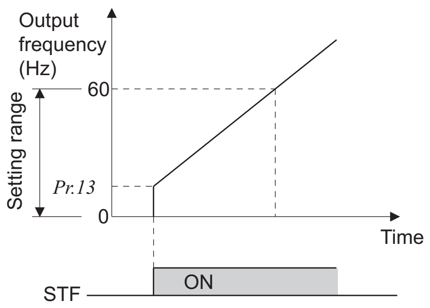
Pr. 3 Base frequency ☞ *Refer to page 98*
Pr. 10 DC injection brake operation frequency ☞ *Refer to page 123*
Pr. 29 Acceleration/deceleration pattern selection ☞ *Refer to page 115*
Pr. 125, Pr. 126 (Frequency setting gain frequency) ☞ *Refer to page 193*
Pr. 178 to Pr.189 (Input terminal function selection) ☞ *Refer to page 133*
Pr. 999 Automatic parameter setting ☞ *Refer to page 290*

4.8.2 Starting frequency and start-time hold function (Pr.13, Pr.571) V/F S MFVC

You can set the starting frequency and hold the set starting frequency for a certain period of time.
Set these functions when you need the starting torque or want to smooth motor drive at a start.

Parameter Number	Name	Initial Value	Setting Range	Description
13	**Starting frequency**	0.5Hz	0 to 60Hz	Frequency at start can be set in the range of 0 to 60Hz. You can set the starting frequency at which the start signal is turned ON.
571 V/F S MFVC	**Holding time at a start**	9999	0.0 to 10.0s	Set the holding time of *Pr. 13 Starting frequency*.
			9999	Holding function at a start is invalid

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

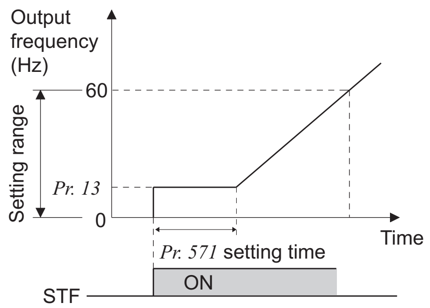


(1) Starting frequency setting *(Pr.13)*

· Frequency at start can be set in the range 0 to 60Hz.
· You can set the starting frequency at which the start signal is turned ON.

CAUTION

The inverter will not start if the frequency setting signal is less than the value set in *Pr. 13*.
For example, when 5Hz is set in *Pr. 13*, the motor will not start running until the frequency setting signal reaches 5Hz.



(2) Start-time hold function *(Pr.571)*

· This function holds the output frequency set in *Pr. 13 Starting frequency* during the period set in *Pr. 571*.
· This function performs initial excitation to smooth the motor drive at a start.

REMARKS

When *Pr. 13* = "0Hz", the starting frequency is held at 0.01Hz.

CAUTION

· When the start signal was turned OFF during start-time hold, deceleration is started at that point.
· At switching between forward rotation and reverse rotation, the starting frequency is valid but the start-time hold function is invalid.

⚠ CAUTION

⚠ Note that when *Pr. 13* is set to any value lower than *Pr. 2 Minimum frequency*, simply turning ON the start signal will run the motor at the preset frequency even if the command frequency is not input.

♦ Parameters referred to ♦

Pr.2 Minimum frequency ☞ *Refer to page 96*

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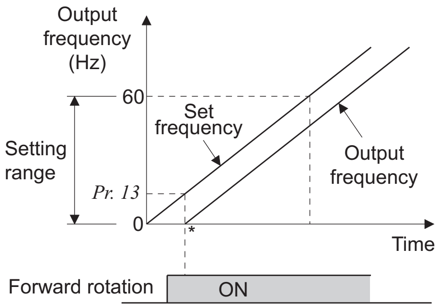
4.8.3 Minimum motor rotation frequency (Pr.13) IPM

Set the frequency where the motor starts running.
Set the deadband in the low-speed range to eliminate noise and offset deviation when setting a frequency with analog input.

Parameter Number	Name	Initial value	Setting range	Description
13	**Starting frequency**	Minimum frequency/ Minimum rotations per minute *	0 to 60Hz	The frequency where the motor starts running can be set in the range of 0 to 60Hz.

The above parameters can be set when *Pr.160 User group read selection* = "0." *(Refer to page 201.)*
* The value after the IPM parameter initialization. *(Refer to page 80)*



* Output from 0.01Hz

· The frequency where the IPM motor starts running can be set in the range of 0 to 60Hz.
· While the frequency command is less than the *Pr. 13 Starting frequency* setting, the IPM motor is stopped.
When the frequency command reaches the set frequency or higher, the IPM motor accelerates according to the *Pr. 7 Acceleration time setting.*

REMARKS

Under general-purpose motor control (under V/F control and Simple magnetic flux vector control), the inverter starts output at the frequency set in *Pr.13* at start, but in IPM motor control, the inverter always starts output from 0.01Hz.

CAUTION

The inverter output does not start when the frequency-setting signal is less than *Pr.13*.
For example, while *Pr.13* = 20Hz, the inverter output starts when the frequency setting signal reaches 20Hz.

⚠ CAUTION

⚠ Note that when *Pr. 13* is set to any value lower than *Pr. 2 Minimum frequency*, simply turning ON the start signal will run the motor at the preset frequency even if the command frequency is not input.

♦ Parameters referred to ♦

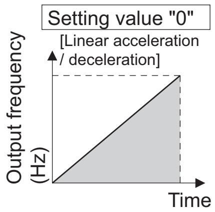
Pr.2 Minimum frequency ☞ *Refer to page 96*
Pr.7 Acceleration time ☞ *Refer to page 115*
IPM motor control ☞ *Refer to page 77*

4.8.4 Acceleration/deceleration pattern (Pr.29, Pr.140 to Pr.143)

You can set the acceleration/deceleration pattern suitable for application.
You can also set the backlash measures that stop acceleration/deceleration once at the parameter-set frequency and time during acceleration/deceleration.

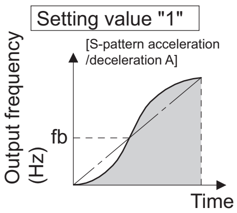
Parameter Number	Name	Initial Value	Setting Range	Description
29	**Acceleration/deceleration pattern selection**	0	0	Linear acceleration/ deceleration
			1	S-pattern acceleration/deceleration A
			2	S-pattern acceleration/deceleration B
			3	Backlash measures
			6	Variable-torque acceleration/deceleration
140	**Backlash acceleration stopping frequency**	1Hz	0 to 400Hz	Set the stopping frequency and time for backlash measures. Valid when *Pr. 29* = 3
141	**Backlash acceleration stopping time**	0.5s	0 to 360s	
142	**Backlash deceleration stopping frequency**	1Hz	0 to 400Hz	
143	**Backlash deceleration stopping time**	0.5s	0 to 360s	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*



(1) Linear acceleration/ deceleration (*Pr. 29* = "0", initial value)

· When the frequency is changed for acceleration, deceleration, etc. in inverter operation, the output frequency is changed linearly (linear acceleration/ deceleration) to reach the set frequency without straining the motor and inverter. Linear acceleration/deceleration has a uniform frequency/time slope.



(2) S-pattern acceleration/deceleration A (*Pr. 29* = "1")

· For machine tool spindle applications, etc.
Used when acceleration/deceleration must be made in a short time to a high-speed range of not lower than the base frequency. In this acceleration/ deceleration pattern, *Pr. 3 Base frequency** (fb) is the inflection point of the S pattern and you can set the acceleration/deceleration time appropriate for motor torque reduction in a constant-power operation range of base frequency (fb) or higher.

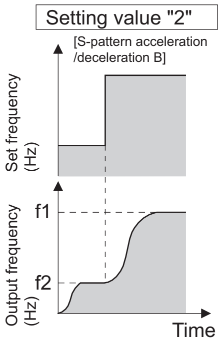
* Rated motor frequency under IPM motor control *(refer to page 81)*.

CAUTION

· For the acceleration/deceleration time of the S-pattern acceleration/deceleration A, set the time to reach *Pr.3 Base frequency* (rated IPM motor frequency under IPM motor control *(refer to page 81)*) but not the time to reach *Pr.20 Acceleration/ deceleration reference frequency*.

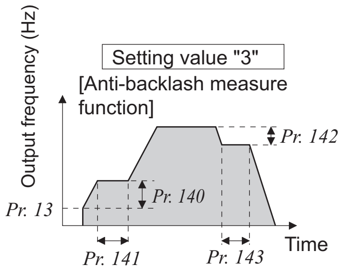
4

PARAMETERS



(3) S-pattern acceleration/deceleration B (*Pr. 29* = "2")

· For prevention of load shifting in conveyor and other applications. Since acceleration/deceleration is always made in an S shape from current frequency (f2) to target frequency (f1), this function eases shock produced at acceleration/deceleration and is effective for load collapse prevention, etc.



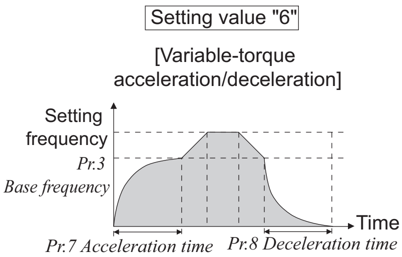
(4) Backlash measures (*Pr. 29* = "3", *Pr. 140 to Pr. 143*)

· What is backlash?
Reduction gears have an engagement gap and have a dead zone between forward rotation and reverse rotation. This dead zone is called backlash, and this gap disables a mechanical system from following motor rotation.
More specifically, a motor shaft develops excessive torque when the direction of rotation changes or when constant-speed operation shifts to deceleration, resulting in a sudden motor current increase or regenerative status.

· To avoid backlash, acceleration/deceleration is temporarily stopped.
Set the acceleration/deceleration stopping frequency and time in *Pr. 140 to Pr. 143*.

CAUTION

Setting the backlash measures increases the acceleration/deceleration time by the stopping time.



(5) Variable-torque acceleration/deceleration (*Pr.29* = "6")

V/F S MFVC

· This function is useful for variable-torque load such as a fan and blower to accelerate/decelerate in short time.
In areas where output frequency > base frequency, the speed accelerates/decelerates linearly.

CAUTION

· As the acceleration/deceleration time of variable-torque acceleration/deceleration, set the time taken to reach *Pr. 3 Base frequency*, not *Pr. 20 Acceleration/deceleration reference frequency*.

REMARKS

· When the base frequency is not 45 to 65Hz, the speed accelerates/decelerates linearly even though *Pr. 29* = "6".
· Variable-torque acceleration/deceleration overrides *Pr. 14* = "1" setting (for variable-torque load). Thus, when *Pr. 14* = "1" while variable-torque acceleration/deceleration is valid, inverter operates as *Pr. 14* = "0" (for constant-torque load).

♦ Parameters referred to ♦

Pr. 3 Base frequency ☞ *Refer to page 98*
Pr. 7 Acceleration time, Pr. 8 Deceleration time, Pr. 20 Acceleration/deceleration reference frequency ☞ *Refer to page 109*
Pr. 14 Load pattern selection ☞ *Refer to page 100*

4.9 Selection and protection of a motor

Purpose	Parameter that must be Set		Refer to page
Motor protection from overheat	**Electronic thermal O/L relay**	**Pr. 9, Pr. 51**	117
Use the constant-torque motor	**Applied motor**	**Pr. 71**	122

4.9.1 Motor protection from overheat (Electronic thermal relay function) (Pr. 9, Pr. 51)

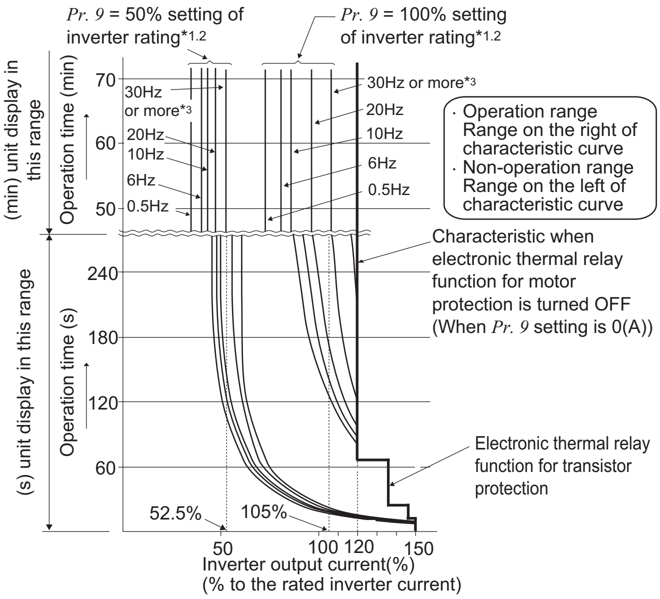
Set the current of the electronic thermal O/L relay to protect the motor from overheat. This feature provides the optimum protective characteristics, including reduced motor cooling capability, at low speed.

Parameter Number	Name	Initial Value	Setting Range		Description
9	**Electronic thermal O/L relay**	Rated inverter current *2	55K or lower	0 to 500A	Set the rated motor current.
			75K or higher	0 to 3600A	
51 *1 V/F S MFVC	**Second electronic thermal O/L relay** *3	9999	55K or lower	0 to 500A	Valid when the RT signal is ON. Set the rated motor current.
			75K or higher	0 to 3600A	
			9999		Second electronic thermal O/L relay invalid

*1 The parameters can be set when *Pr. 160 User group read selection* = "0" *(Refer to page 201)*
*2 Performing IPM parameter initialization automatically sets the rated current of the IPM motor. *(Refer to page 80)*
*3 When parameter is read using the FR-PU04, a parameter name different from an actual parameter is displayed.

(1) Electronic thermal relay function operation characteristic (THM) V/F S MFVC

[Electronic thermal relay function operation characteristic (E.THM)]



This function detects the overload (overheat) of the motor and the inverter trips. (The operation characteristic is shown on the left)

- Set the rated current [A] of the motor in *Pr. 9*. (If the motor has both 50Hz and 60Hz rating and the *Pr.3 Base frequency* is set to 60 Hz, set the 1.1 times of the 60Hz rated motor current.)
- Set "0" in *Pr. 9* when you do not want to activate the electronic thermal relay function, e.g. when using an external thermal relay with the motor. (Note that the output transistor protection of the inverter functions (E.THT).)
- When using the Mitsubishi constant-torque motor
  1) Set "1" in *Pr. 71*. (This provides a 100% continuous torque characteristic in the low-speed range.)
  2) Set the rated current of the motor in *Pr. 9*.

*1 When 50% of the inverter rated output current (current value) is set in *Pr. 9*
*2 The % value denotes the percentage to the rated inverter current. It is not the percentage to the rated motor current.
*3 When you set the electronic thermal relay function dedicated to the Mitsubishi constant-torque motor, this characteristic curve applies to operation at 6Hz or higher.

CAUTION

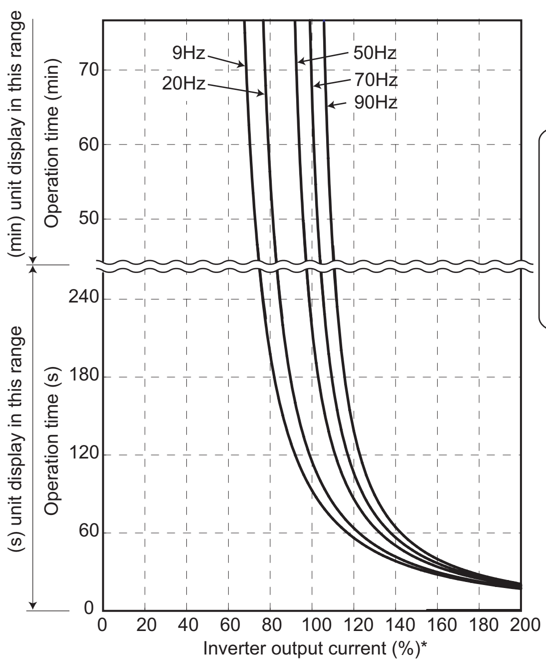
- Protective function by electronic thermal relay function is reset by inverter power reset and reset signal input. Avoid unnecessary reset and power-OFF.
- Install an external thermal relay (OCR) between the inverter and motor for the operation of several motors or of a multi-pole motor with one inverter. To select a setting for an external thermal relay, consider the line-to-line leakage current in addition to the current indicated on the motor's rating plate. (For more information on leakage current, *refer to page 44*.) The cooling effect of the motor drops during low-speed operation. Use a thermal protector or a motor with built-in thermistor.
- When the difference between the inverter and motor capacities is large and the setting is small, the protective characteristics of the electronic thermal relay function will be deteriorated. In this case, use an external thermal relay.

(2) Electronic thermal relay of IPM motor control *(Pr.9)* IPM

This function detects the overload (overheat) of the motor and trips the inverter by stopping the operation of the transistor at the inverter output side. (The operation characteristic is shown below.)

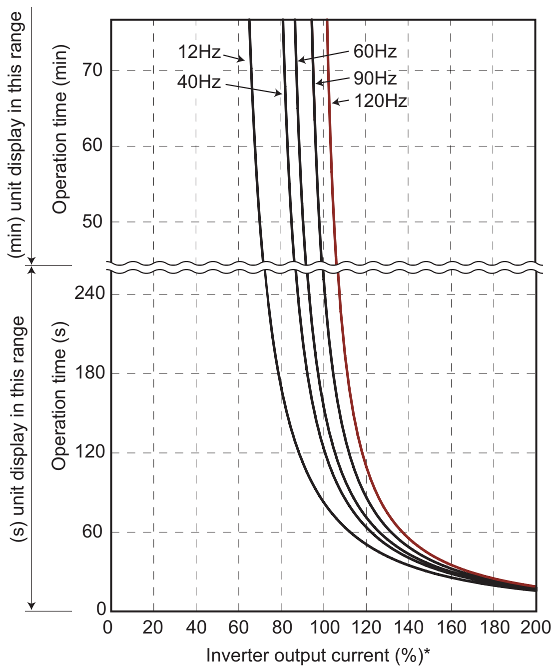
- Set the rated current [A] of the motor in *Pr.9*.
  Performing IPM parameter initialization automatically sets the rated current of the IPM motor. *(Refer to page 81)*
- Set "0" in *Pr.9* when you do not want to activate the electronic thermal relay function. An example for this case is when using an external thermal relay for the motor. (Note that the output transistor protection of the motor is activated. (E.THT))

· 30K or lower



· Operation range
Range on the right of characteristic curve
· Non-operation range
Range on the left of characteristic curve

· 37K or higher



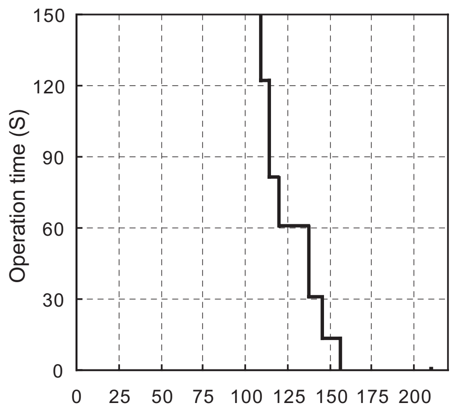
* The % value denotes the percentage to the rated motor current.

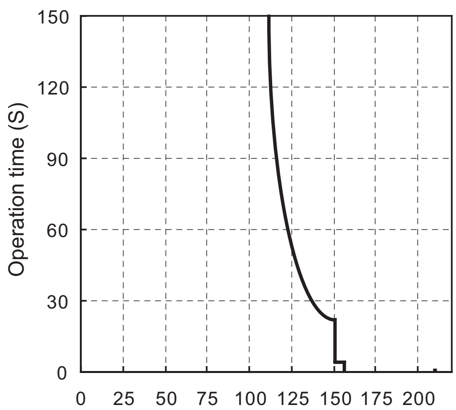
CAUTION

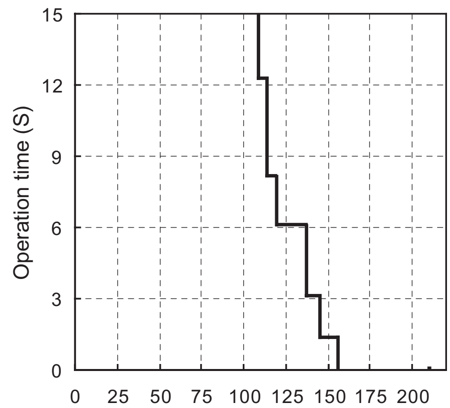
- Protective function by electronic thermal relay function is reset by inverter power reset and reset signal input. Avoid unnecessary reset and power-OFF.

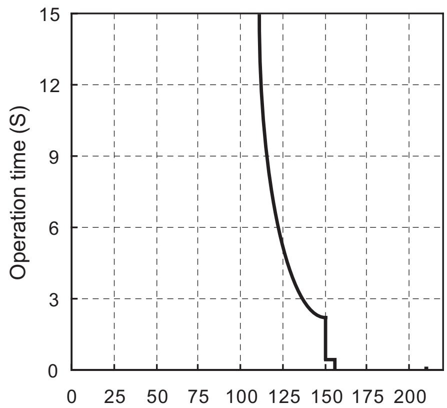
(3) Electronic thermal relay function operation characteristic (THT)

Electronic thermal relay function (transistor protection thermal) operation characteristics of the inverter when the ratio of the motor current to the inverter rated current is presented as transverse is shown. Transverse is calculated as follows: (motor current [A]/inverter rated current [A]) × 100 [%].

<table>
<tr><th rowspan="2">Optimum Conditions</th><th colspan="2">Inverter Capacity</th></tr>
<tr><th>55K or lower</th><th>75K or higher</th></tr>
<tr><td>Running frequency : 1Hz or higher
Carrier frequency: 2kHz</td><td>

Ratio of the motor current
to the rated inverter current (%)</td><td>

Ratio of the motor current
to the rated inverter current (%)</td></tr>
<tr><td>Running frequency : 1Hz or less
Carrier frequency: 2kHz</td><td>

Ratio of the motor current
to the rated inverter current (%)</td><td>

Ratio of the motor current
to the rated inverter current (%)</td></tr>
</table>

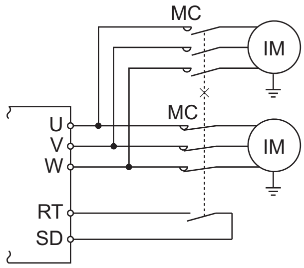
CAUTION

- Protective function by electronic thermal relay function is reset by inverter power reset and reset signal input. Avoid unnecessary reset and power-OFF.
- The operation time of the transistor protection thermal relay shortens when the *Pr. 72 PWM frequency selection* setting increases

(4) Set multiple electronic thermal relay functions *(Pr. 51)* V/F S MFVC

Use this function when rotating two motors of different rated currents individually by a single inverter. (When rotating two motors together, use external thermal relays.)

- Set the rated current of the second motor in *Pr. 51*.
- When the RT signal is ON, thermal protection is provided based on the *Pr. 51* setting.

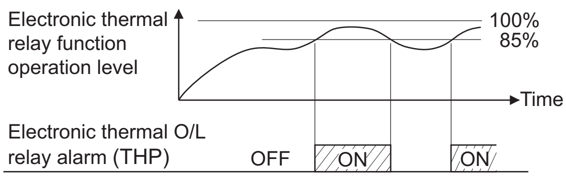


REMARKS

- The RT signal acts as the second function selection signal and makes the other second functions valid. *(Refer to page 136)*
- The RT signal is assigned to the RT terminal in the initial setting. By setting "3" in any of *Pr. 178 to Pr. 189 (input terminal function selection)*, you can assign the RT signal to the other terminal.

(5) Electronic thermal relay function plealarm (TH) and alarm signal (THP signal)

100%: Electronic thermal relay function alarm operation value

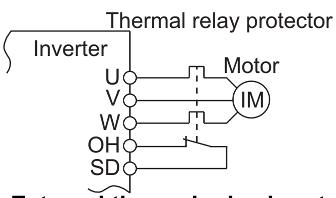


- The alarm signal (THP) is output and electronic thermal relay function prealarm (TH) is displayed when the electronic thermal value reaches 85% of the level set in *Pr. 9* or *Pr. 51*. If it reaches 100% of the *Pr. 9 Electronic thermal O/L relay* setting, an electronic thermal relay protection (E.THM/E.THT) activates.
- The inverter does not trip even when the alarm signal (THP) is output.
- For the terminal used for the THP signal output, assign the function by setting "8" (positive logic) or "108" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

CAUTION

- Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

(6) External thermal relay input (OH signal)



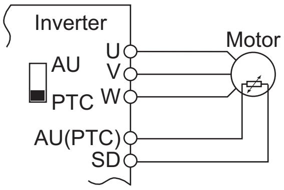
External thermal relay input connection example

- To protect the motor against overheat, use the OH signal when using an external thermal relay or the built-in thermal protector of the motor.
- When the thermal relay operates, the inverter trips and outputs the fault signal (E.OHT).
- For the terminal used for OH signal input, assign the function by setting "7" in any of *Pr. 178 to Pr. 189 (input terminal function selection)*

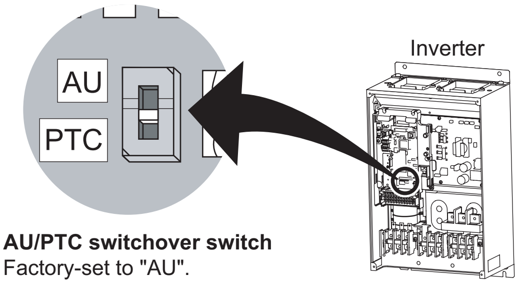
CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

(7) PTC thermistor input (PTC signal)



PTC thermistor input connection example



AU/PTC switchover switch
Factory-set to "AU".
Set to the "PTC" position to validate the PTC signal input.

Built-in PTC thermistor of the motor can be input to the PTC signal (AU terminal).

· For the terminal used for PTC signal input, assign the function by setting "63" in *Pr. 184 AU terminal function selection* and also set the AU/PTC switchover switch to the PTC terminal function. (The initial setting is the AU terminal function.)

· If a motor overheat state is detected for more than 10s according to the input from the PTC thermistor, the inverter shuts off the output and outputs the PTC thermal fault signal (E.PTC).

· The input specifications of the PTC thermistor are shown on the right.

Motor Temperature	PTC Thermistor Resistance Value (Ω)
Normal	0 to 500
Boundary	500 to 4k
Overheat	4k or higher

CAUTION

· When the PTC signal was not assigned to *Pr. 184* and the AU/PTC switchover switch was set to the PTC terminal function, the function assigned to the AU terminal is always off. Reversely, when the PTC signal was assigned to *Pr. 184* and the AU/PTC switchover switch was set to the AU terminal function, a PTC thermal error (E.PTC) occurs since the function is always in a motor overheat state.

· When you want to input a current, assign the AU signal to the other signal.

· Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 71 Applied motor ☞ *Refer to page 122*
Pr. 72 PWM frequency selection ☞ *Refer to page 182*
Pr. 178 to Pr. 189 (Input terminal function selection) ☞ *Refer to page 133*
Pr. 190 to Pr. 196 (Output terminal function selection) ☞ *Refer to page 140*
Specifications of the AU terminal ☞ *Refer to page 26*

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4.9.2 Applied motor (Pr. 71)

Setting of the used motor selects the thermal characteristic appropriate for the motor.
Setting is necessary when using a constant-torque motor or IPM motor. Thermal characteristic of the electronic thermal relay function suitable for the motor is set.

Parameter Number	Name	Initial Value	Setting Range	Description
71 Ver.UP	**Applied motor**	0*	0, 1, 2, 20, 120, 210	Selecting the standard motor or constant-torque motor or IPM motor sets the corresponding motor thermal characteristic.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
* Performing IPM parameter initialization changes the settings. *(Refer to page 80)*
Ver.UP ....Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

Refer to the following list and set this parameter according to the motor used.

Pr. 71 Setting	Thermal Characteristic of the Electronic Thermal Relay Function	Motor (○ : used motor)			
		Standard (SF-JR, etc.)	Constant-torque (SF-HRCA, etc.)	IPM (MM-EF)	IPM (MM-EFS)
0 (initial value)	Thermal characteristics of a standard motor	○			
1	Thermal characteristics of the Mitsubishi constant-torque motor		○		
2	Thermal characteristics of a standard motor Adjustable 5 points V/F *(Refer to page 101)*	○			
20	Mitsubishi standard motor SF-JR 4P(1.5kW or lower)	○			
120*	High-efficiency IPM motor (MM-EFS) *(Refer to page 80)*			○	
210*	Premium high-efficiency IPM motor MM-EFS *(Refer to page 80)*				○

* The setting automatically changes to "120 or 210" when IPM parameter initialization is performed. *(Refer to page 80)*

REMARKS

· For the 5.5K and 7.5K, the *Pr. 0 Torque boost* and *Pr. 12 DC injection brake operation voltage* settings are automatically changed according to the *Pr. 71* setting as follows.

Pr. 71	Standard Motor Setting 0, 2, 20, 120, 210	Constant-torque Motor Setting 1
Pr. 0	3%	2%
Pr. 12	4%	2%

· With *Pr. 71* = "210" setting, *Pr. 80 Motor capacity* can be set only in the range of 0.75K to 55K.

⚠ CAUTION

⚠ Make sure to set this parameter correctly according to the motor used.
Incorrect setting may cause the motor to overheat and burn.

♦ Parameters referred to ♦

Pr. 0 Torque boost ☞ *Refer to page 87*
Pr. 12 DC injection brake operation voltage ☞ *Refer to page 123*
Pr. 100 to Pr. 109 (Adjustable 5 points V/F) ☞ *Refer to page 101*
IPM motor control ☞ *Refer to page 77*

4.10 Motor brake and stop operation

Purpose	Parameter that must be set		Refer to Page
Motor braking torque adjustment	**DC injection brake of general-purpose motor control**	**Pr. 10 to Pr. 12**	123
Motor braking torque adjustment	**DC injection brake of IPM motor control**	**Pr. 10, Pr. 11**	124
Improve the motor braking torque with an option	**Selection of a regenerative brake**	**Pr. 30, Pr. 70**	125
Performing operation by DC current input	**DC current feeding mode**	**Pr. 30**	125
Coast the motor to a stop	**Selection of motor stopping method**	**Pr. 250**	130
	Output stop function	**Pr. 522**	131

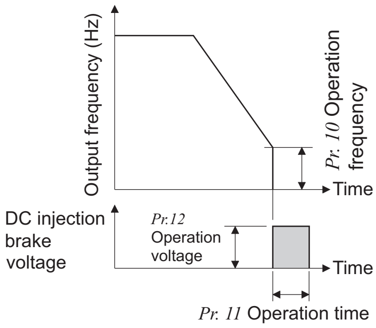
4.10.1 DC injection brake of general-purpose motor control (Pr. 10 to Pr. 12)

V/F S MFVC

The DC injection brake can be operated at a motor stop to adjust the stop timing and braking torque.
In DC injection brake operation, DC voltage is directly applied to the motor to prevent the motor shaft from rotating when a motor decelerates to stop.
The motor will not return to the original position if the motor shaft rotates due to external force.

Parameter Number	Name	Initial Value		Setting Range	Description
10	**DC injection brake operation frequency**	3Hz		0 to 120Hz	Set the operation frequency of the DC injection brake.
				9999	Operated at *Pr. 13* or less.
11	**DC injection brake operation time**	0.5s		0	DC injection brake disabled
				0.1 to 10s	Set the operation time of the DC injection brake.
12 V/F S MFVC	**DC injection brake operation voltage**	7.5K or lower	4%	0 to 30%	Set the DC injection brake voltage (torque). When "0" is set, DC injection brake is disabled.
		11K to 55K	2%		
		75K or higher	1%		

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*



(1) Operation frequency setting *(Pr. 10)*

- When the frequency at which the DC injection brake will be operated is set to *Pr. 10*, the DC voltage is applied to the motor upon reaching to the set frequency during deceleration.
- At the *Pr. 10* setting of "9999", the DC injection brake is operated when deceleration is made to the frequency set in *Pr. 13 Starting frequency*.

(2) Operation time setting *(Pr. 11)*

- In *Pr. 11*, set the time of the DC injection brake.
- When *Pr. 11* = "0s", the DC injection brake is disabled. (At a stop, the motor coasts.)
- When the motor does not stop due to large load moment (J), increasing the setting produces an effect.

(3) Operation voltage (torque) setting *(Pr. 12)*

- Use *Pr. 12* to set the percentage to the power supply voltage.
- When *Pr. 12* = "0%", the DC injection brake is disabled. (At a stop, the motor coasts.)
- When using the constant-torque motor (SF-JRCA) and energy saving motor (SF-HR, SF-HRCA), change the *Pr. 12* setting as follows.
  SF-JRCA: 3.7K or lower ...4%, 5.5K to 55K...2%
  SF-HR, SF-HRCA: 3.7K or lower...4%, 5.5K and 7.5K...3%, 11K to 55K...2% (30K...1.5%)

REMARKS

- For the 5.5K and 7.5K, when the *Pr. 12* setting is as below, changing the *Pr. 71 Applied motor* setting changes the *Pr. 12* setting automatically, it is not necessary to change the *Pr. 12* setting.
  (a) When *Pr. 12* is 4% (initial value)
  The *Pr. 12* setting is automatically changed to 2% if the *Pr. 71* value is changed from the value selecting the standard motor (0, 2, 120, 210) to the value selecting the constant motor (1).
  (b) When *Pr. 12* is 2%
  The *Pr. 12* setting is automatically changed to 4% if the *Pr. 71* value is changed from the value selecting the constant motor (1) to the value selecting the standard motor (0, 2, 120, 210).
- Even if the *Pr. 12* setting is increased, braking torque is limited so that the output current is within the rated inverter current.

⚠ CAUTION

⚠ As stop holding torque is not produced, install a mechanical brake.

♦ **Parameters referred to** ♦

Pr. 13 Starting frequency ☞ *Refer to page 113*
Pr. 71 Applied motor ☞ *Refer to page 122*
Pr. 178 to Pr. 189 (Input terminal function selection) ☞ *Refer to page 133*

4.10.2 DC injection brake of IPM motor control (Pr.10, Pr.11) IPM

At a motor stop, DC injection brake operates to apply braking torque to the motor.

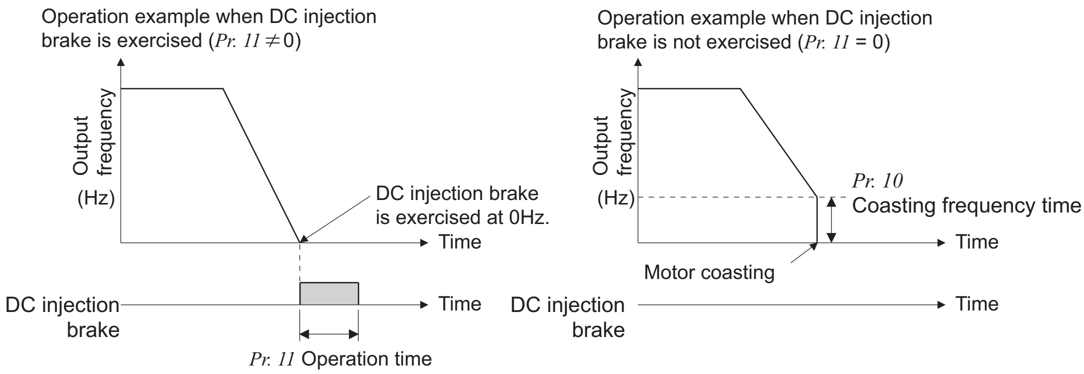
Parameter Number	Name	Initial Value	Setting Range	Description
10	DC injection brake operation frequency	3Hz	0 to 120Hz	Set the frequency at which the motor coasts.
			9999	Operate when the output frequency becomes less than or equal to *Pr. 13 Starting frequency*.
11	DC injection brake operation time	0.5s	0	DC injection brake disabled
			0.1 to 10s	Set the operation time of the DC injection brake.

(1) Coasting frequency setting *(Pr.10)*

- When frequency at which coasting starts is set in *Pr.10*, output is shutoff when this frequency is reached during deceleration and motor starts coasting. (This function is valid when *Pr. 11* = "0s")
- When *Pr.11*≠"0," *Pr.10* is always set to 0Hz.

(2) Operation time setting *(Pr.11)*

- In *Pr. 11*, set the time of the DC injection brake.
- When *Pr. 11* = "0", the DC injection brake is disabled. (At a stop, the motor coasts.)
- When the motor does not stop due to large load moment (J), increasing the setting produces an effect.



⚠ CAUTION

⚠ As stop holding torque is not produced, install a mechanical brake.
⚠ An IPM motor is a motor with interior permanent magnets. High voltage is generated at motor terminals while the motor is running. Do not touch motor terminals and other parts until the motor stops to prevent an electric shock.

♦ **Parameters Referred to** ♦

Pr. 13 Starting frequency ☞ *Refer to page 113*
Pr. 71 Applied motor ☞ *Refer to page 122*
Pr. 178 to Pr. 189 (Input terminal function selection) ☞ *Refer to page 133*
IPM motor control ☞ *Refer to page 77*

4.10.3 Selection of a regenerative brake and DC feeding (Pr. 30, Pr. 70)

- When making frequent starts/stops, use the optional brake unit (FR-BU2, BU, FR-BU, MT-BU5) to increase the regenerative brake duty.
- Use a power regeneration common converter (FR-CV) or power regeneration converter (MT-RC) for continuous operation in regenerative status.
  Use a high power factor converter (FR-HC, MT-HC) to reduce harmonics, improve the power factor, or continuously use the regenerative mode.
- You can select DC feeding mode 1, which operates with DC power supply (terminal P/+, N/-), or DC feeding mode 2, which normally operates with AC power supply (terminal R/L1, S/L2, T/L3) and with DC power supply such as battery at power failure occurrence.

Parameter Number	Name	Initial Value	Setting Range	Description	
				Regeneration unit	Terminal for power supply to the inverter
30	Regenerative function selection	0	0	Inverter without regenerative function, brake unit (FR-BU2 *2, FR-BU, BU type)	R/L1, S/L2, T/L3
			10		P/+, N/- (DC feeding mode 1)
			20		R/L1, S/L2, T/L3 - P/+, N/- (DC feeding mode 2)
			1 *1	Brake unit (FR-BU2 *3, MT-BU5), power regeneration converter (MT-RC)	R/L1, S/L2, T/L3
			11 *1		P/+, N/- (DC feeding mode 1)
			21 *1		R/L1, S/L2, T/L3 - P/+, N/- (DC feeding mode 2)
			2	High power factor converter (FR-HC, MT-HC), power regeneration common converter (FR-CV)	P/+, N/-
70	Special regenerative brake duty	0%	0 to 10%	Set the %ED of the brake transistor operation when using a brake unit (MT-BU5). (Setting is available only for the 75K or higher)	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

*1 *Pr.30* can be set to "1, 11, or 21" for 75K or higher.
*2 Used in combination with GZG, GRZG, or FR-BR.
*3 Used in combination with MT-BR5.

<55K or lower>

Regeneration Unit	Power Supply to the Inverter	*Pr. 30* Setting
Inverter without regenerative function, brake unit (FR-BU2 *1, FR-BU, BU)	R/L1, S/L2, T/L3	0 (initial value)
	P/+, N/-	10
	R/L1, S/L2, T/L3 - P/+, N/-	20
High power factor converter (FR-HC), power regeneration common converter (FR-CV)	P/+, N/-	2

<75K or higher>

Regeneration Unit	Power Supply to the Inverter	*Pr. 30* Setting	*Pr. 70* Setting
Inverter without regenerative function	R/L1, S/L2, T/L3	0 (initial value)	—
	P/+, N/-	10	
	R/L1, S/L2, T/L3 - P/+, N/-	20	
Brake unit (FR-BU2 *2)	R, S, T	1	0% (initial value)
	P, N	11	
	R, S, T/P, N	21	
Power regeneration converter (MT-RC)	R/L1, S/L2, T/L3	1	0% (initial value)
Brake unit (MT-BU5)	R/L1, S/L2, T/L3	1	10%
	P/+, N/-	11	
	R/L1, S/L2, T/L3 - P/+, N/-	21	
High power factor converter (MT-HC)	P/+, N/-	2	—

*1 Used in combination with GZG, GRZG, or FR-BR.
*2 Used in combination with MT-BR5.

(1) When the brake unit (FR-BU2, BU, FR-BU) is used (55K or lower)

· Set *Pr. 30* = "0 (initial setting), 10, or 20" for the FR-BU2 operation with GZG/GRZG/FR-BR, or the BU/FR-BU operation. The *Pr. 70* setting is invalid.

CAUTION

· Do not operate the MT-BU5 type brake unit and FR-BU2 in parallel. Doing so could cause an alarm or brake unit failure. Use the FR-BU2 only when performing parallel operation.

(2) When the FR-BU2 brake unit is used (in combination with MT-BR5) (75K or higher)

Set the following parameters to use FR-BU2 with MT-BR5.

· Set "1, 11, or 21" in *Pr. 30*.
· Set "0% (initial setting)" in *Pr. 70*.
· Set "2" in *Pr. 0 Brake mode selection*, a FR-BU2 brake unit parameter.

REMARKS

· Stall prevention (overvoltage), oL, is disabled when *Pr. 30* = "1, 11, or 21."

(3) When using a brake unit (MT-BU5) and power regeneration converter (MT-RC) (75K or higher)

· Set "1, 11 or 21" in *Pr. 30*.
· Set "10%" In *Pr. 70* when using a brake unit (MT-BU5).
· Set "0%" in *Pr. 70* when using a power regeneration converter (MT-RC).

(4) When using the high power factor converter (FR-HC, MT-HC) or power regeneration common converter (FR-CV)

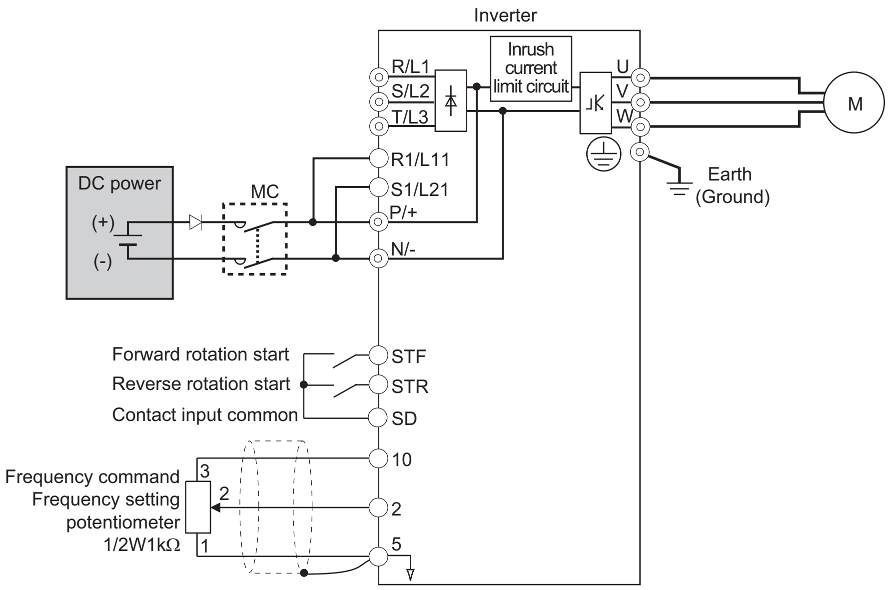
· Set "2" in *Pr. 30*. The *Pr. 70* setting becomes invalid.
· Use any of *Pr. 178 to Pr. 189 (Input terminal function assignment)* to assign the following signals to the contact input terminals.
  (a) X10 signal: FR-HC, MT-HC connection, FR-CV connection (inverter operation enable signal)
  To make protective coordination with the FR-HC, MT-HC or FR-CV, use the inverter operation enable signal to shut off the inverter output. Input the RDY signal of the FR-HC, MT-HC (RDYB signal of the FR-CV).
  (b) X11 signal: FR-HC, MT-HC connection (instantaneous power failure detection signal)
  When the setting has been made to hold the mode at occurrence of an instantaneous power failure for RS-485 communication operation, use this signal to hold the mode. Input the Y1 or Y2 signal (instantaneous power failure detection signal) of the FR-HC, MT-HC.
· For the terminal used for X10 or X11 signal input, assign its function by setting "10" (X10) or "11" (X11) in any of *Pr. 178 to Pr. 189*.

REMARKS

· The MRS signal can also be used instead of the X10 signal. *(Refer to page 135.)*
· When *Pr. 30* = "2", "Err" is displayed on the operation panel as the inverter is reset by the setting.

(5) DC feeding mode 1 (*Pr. 30* = "10, 11")

· Setting "10, 11" in *Pr. 30* enables DC power supply operation.
· Leave the AC power supply connection terminal R/L1, S/L2, and T/L3 open and connect the DC power supply to terminal P/+ and N/-. Also, remove jumpers across terminal R/L1 and R1/L11 as well as S/L2 and S1/L21, and connect terminals R1/L11 and S1/L21 to terminal P/+ and N/-.
· The diagram below is a connection example.

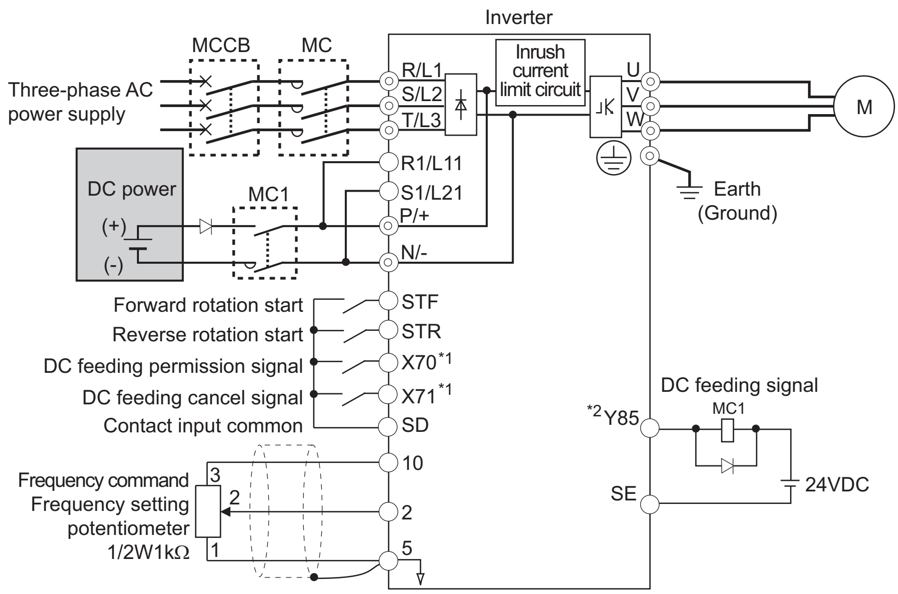


(6) DC feeding mode 2 (*Pr. 30* = "20, 21")

· When "20 or 21" is set in *Pr. 30*, operation is performed with AC power supply normally and with DC power supply such as battery at power failure.
· Connect the AC power supply to terminal R/L1, S/L2, and T/L3 and connect the DC power supply to terminal P/+ and N/-. Also, remove jumpers across terminal R/L1 and R1/L11 as well as S/L2 and S1/L21, and connect terminals R1/L11 and S1/L21 to terminal P/+ and N/-.
· Turning ON the DC feeding operation permission signal (X70) enables DC power supply operation. Refer to the table below for I/O signals.

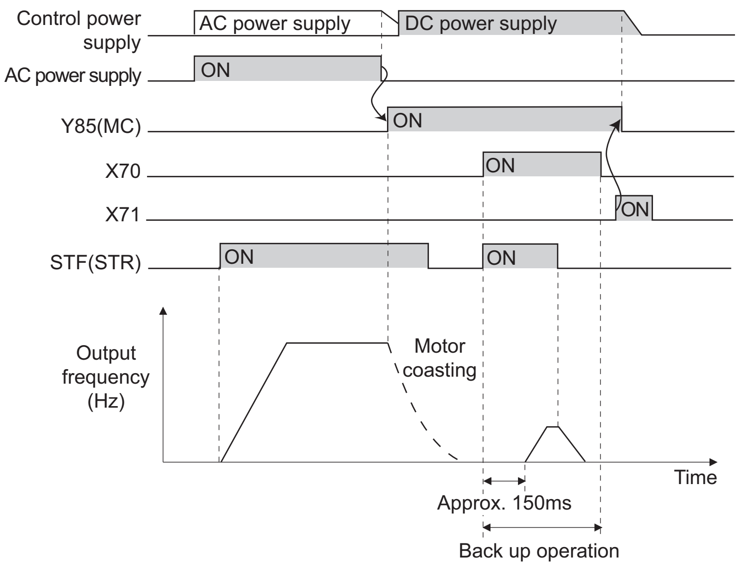
Signal		Name	Description	Parameter Setting
Input	X70	DC feeding operation permission signal	When performing operation with DC feeding, turn ON the X70 signal. When the inverter output is shut off because of power failure, the inverter can be started in about 150ms after switching OFF the X70 signal then ON again. (When automatic restart operation is valid, the inverter starts after additional *Pr. 57* set time has elapsed.) When the X70 signal turns OFF during inverter operation, output is shutoff (*Pr .261* = 0) or the inverter is decelerated to a stop (*Pr. 261* ≠ 0).	Set 70 in any of *Pr. 178* to *Pr. 189*.
	X71	DC feeding cancel signal	Turn this signal ON to stop DC feeding. When the X71 signal is turned ON during inverter operation with turning ON the X70 signal, output is shutoff (*Pr. 261* = 0) or the inverter is decelerated to a stop (*Pr. 261* ≠ 0), then the X85 signal turns OFF after the inverter stop. After turning ON the X71 signal, operation cannot be performed even if the X70 signal is turned ON.	Set 71 in any of *Pr. 178* to *Pr. 189*.
Output	Y85	DC feeding signal	This signal turns ON during power failure or under voltage of AC power. The signal turns OFF when the X71 signal turns ON or power is restored. The Y85 signal does not turn OFF during inverter operation even if the power is restored and turns OFF after an inverter stop. When the Y85 signal turns ON because of undervoltage, the Y85 signal does not turn OFF even if undervoltage is eliminated. ON/OFF status is retained at an inverter reset.	Set "85 (positive logic) or 185 (negative logic)" in any of *Pr. 190* to *Pr. 196*

· The following shows the connection diagram when switching to DC power supply using inverter power failure detection.

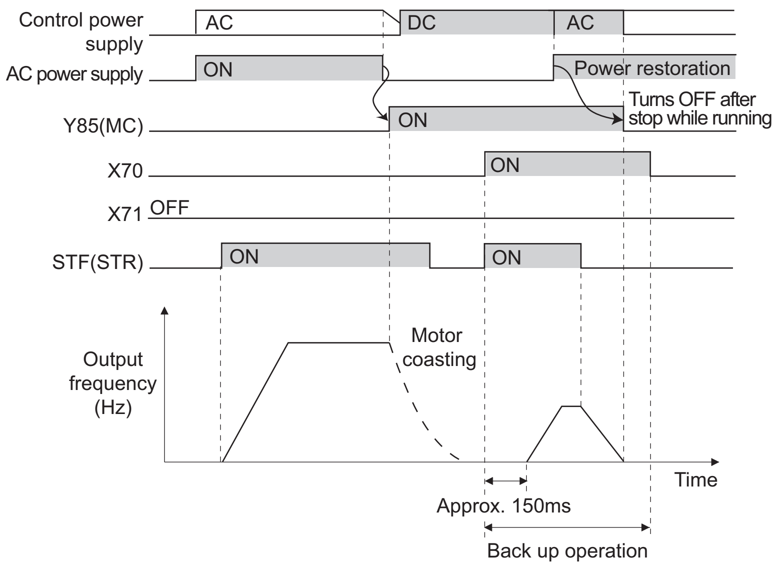


* Assign the function using *Pr. 178 to Pr. 189 (input terminal function selection).*
* Assign the function using *Pr. 190 to Pr. 196 (output terminal function selection).*

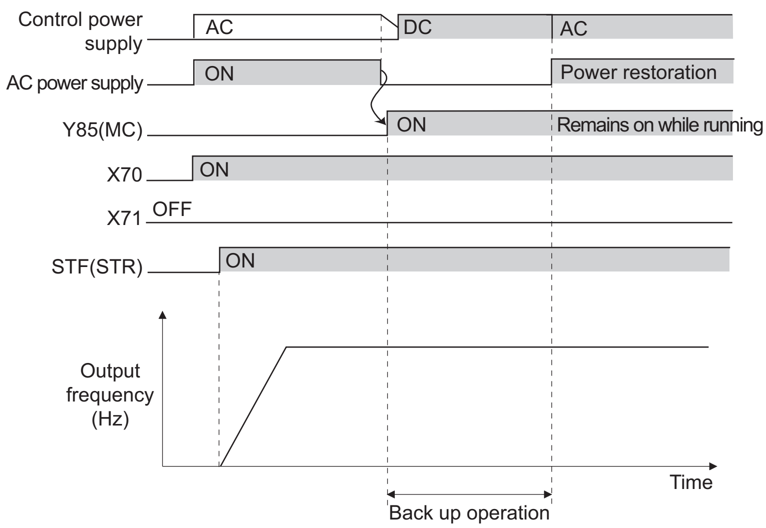
· Operation example 1 at power failure



· Operation example 2 at power failure (when DC power is restored)



· Operation example 3 at power failure (when continuous operation is performed)



(7) Power supply specification at DC feeding

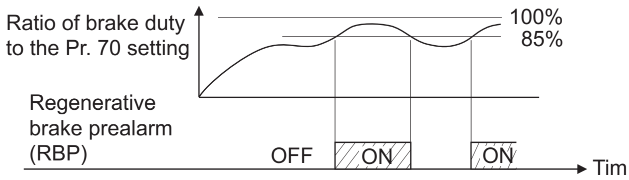
200V class	Rated input DC voltage	283VDC to 339VDC
	Permissible fluctuation	240VDC to 373VDC
400V class	Rated input DC voltage	537VDC to 679VDC
	Permissible fluctuation	457VDC to 740VDC

CAUTION

- As voltage between P/+ and N/- becomes 415VDC (830VDC) or more temporarily at regeneration, make selection of DC power supply carefully.

(8) Regenerative brake duty alarm output and alarm signal (RBP signal) (75K or higher)

100%: regenerative overvoltage protection operation value



- [RB] appears on the operation panel and an alarm signal (RBP) is output when 85% of the regenerative brake duty set in *Pr. 70* is reached. If the regenerative brake duty reaches 100% of the *Pr. 70* setting, a regenerative overvoltage (E.OV1 to E.OV3) occurs.
- The inverter does not shut off the output when the alarm signal is output.
- For the terminal used for the RBP signal output, assign the function by setting "7" (positive logic) or "107" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

REMARKS

- Refer to *pages 34 to 42* for connection of the brake unit, high power factor converter (FR-HC, MT-HC) and power regeneration common converter (FR-CV).
- When AC power is connected to terminal R/L1, S/L2, T/L3 during DC feeding with "2, 10 or 11" (DC feeding) set in *Pr. 30*, an option alarm (E.OPT) occurs.
- When DC feeding operation is performed with "2, 10, 11, 20, or 21" (DC feeding) set in *Pr. 30*, undervoltage protection (E.UVT) and instantaneous power failure (E.IPF) are not detected.

CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

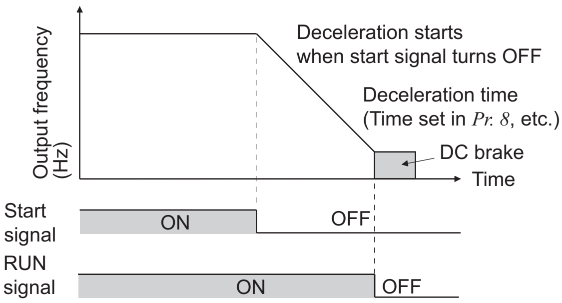
Pr. 57 Restart coasting time ☞ *Refer to page 162*
Pr. 178 to Pr.189 (input terminal function selection) ☞ *Refer to page 133*
Pr. 190 to Pr.196 (output terminal function selection) ☞ *Refer to page 140*
Pr. 261 Power failure stop selection ☞ *Refer to page 169*

4.10.4 Stop selection (Pr. 250)

Used to select the stopping method (deceleration to a stop or coasting) when the start signal turns OFF. Used to stop the motor with a mechanical brake, etc. together with switching OFF of the start signal.
You can also select the operations of the start signals (STF/STR). (Refer to *page 138* for start signal selection)

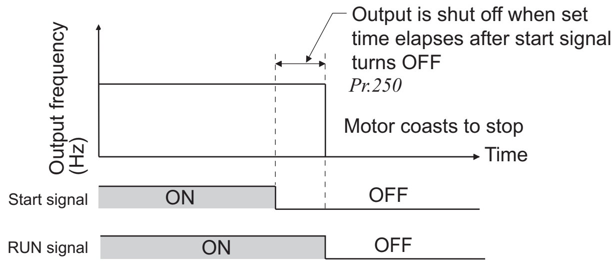
Parameter Number	Name	Initial Value	Setting Range	Description	
				Start Signal (STF/STR) *(Refer to page 138)*	Stop Operation
250	Stop selection	9999	0 to 100s	STF signal: Forward rotation start STR signal: Reverse rotation start	The motor is coasted to a stop when the preset time elapses after the start signal is turned OFF.The motor is coasted to a stop (*Pr. 250* - 1000)s after the start signal is turned OFF.
			1000s to 1100s	STF signal: Start signal STR signal: Forward/reverse signal	
			9999	STF signal: Forward rotation start STR signal: Reverse rotation start	When the start signal is turned OFF, the motor decelerates to stop.
			8888	STF signal: Start signal STR signal: Forward/reverse signal	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*



(1) Decelerate the motor to a stop

- Set *Pr. 250* to "9999" (initial value) or "8888".
- The motor decelerates to a stop when the start signal (STF/STR) turns OFF.



(2) Coast the motor to a stop

- Use *Pr. 250* to set the time from when the start signal turns OFF until the output is shut off. When any of "1000" to "1100" is set, the output is shut off after (*Pr. 250* – 1000)s.
- The output is shut off when the time set in *Pr. 250* has elapsed after the start signal had turned OFF. The motor coasts to a stop.
- The RUN signal turns OFF when the output stops.

REMARKS

Stop selection is invalid when the following functions are activated.
- Power failure stop function *(Pr. 261)*
- PU stop *(Pr. 75)*
- Deceleration stop because of communication error *(Pr. 502)*
- Emergency stop by LonWorks communication

When setting of *Pr. 250* is not 9999 nor 8888, acceleration/deceleration is performed according to the frequency command, until start signal is OFF and output is shutoff.

CAUTION

- When the start signal is turned ON again during motor coasting, the motor starts at *Pr. 13 Starting frequency*.

⚠CAUTION

⚠ An IPM motor is a motor with interior permanent magnets. High voltage is generated at motor terminals while the motor is running. Do not touch motor terminals and other parts until the motor stops to prevent an electric shock.

♦ Parameters referred to ♦

Pr. 7 Acceleration time , Pr. 8 Deceleration time ☞ *Refer to page 109*
Pr. 13 Starting frequency ☞ *Refer to page 113*

4.10.5 Output stop function (Pr.522)

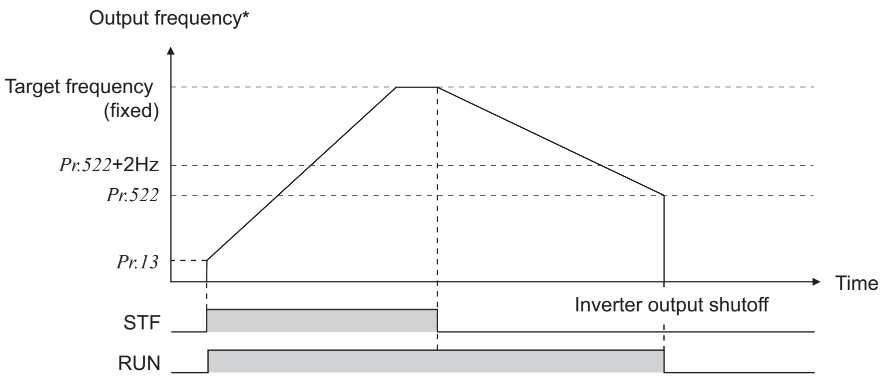
The motor coasts to a stop (inverter output shutoff) when inverter output frequency falls to *Pr. 522* setting or lower.

Parameter Number	Name	Initial Value	Setting Range	Description
522	**Output stop frequency**	9999	0 to 400Hz	Set the frequency to start coasting to a stop (output shutoff).
			9999	No function

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

- When both of the frequency setting signal and output frequency falls to the frequency set in *Pr. 522* or lower, the inverter stops the output and the motor coasts to a stop.
- At a stop condition, the motor starts running when the frequency setting signal exceeds *Pr.522* +2Hz. The motor is accelerated at the *Pr.13 Starting frequency* (0.01Hz under IPM motor control) at the start.

Example of when target frequency>*Pr.522*+2Hz, and start signal is ON/OFF

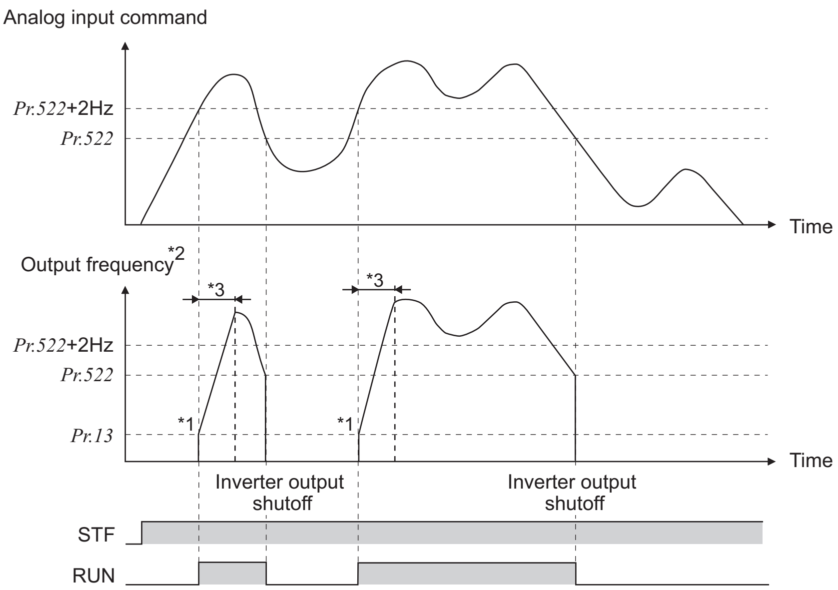


* The output frequency before the slip compensation is compared with the *Pr.522* setting.

REMARKS

When the output stop function is valid (*Pr.522* ≠ "9999"), the DC injunction brake becomes invalid and the motor coasts to stop when the output frequency drops to the *Pr.522* setting or lower.

Example of: target frequency = analog input command, start signal always ON



*1 At a stop condition, the motor is accelerated at the *Pr.13 Starting frequency* (0.01Hz under IPM motor control).
*2 The output frequency before the slip compensation is compared with the *Pr.522* setting.
*3 Steepness of the slope depends on the acceleration/deceleration time settings such as *Pr.7*.

REMARKS

- Motor coasts when the command value drops to *Pr.522* or lower while the start signal is ON. If the command value exceeds *Pr.522*+2Hz again while coasting, the motor starts running at *Pr.13 Starting frequency* (0.01Hz under IPM motor control). When the motor re-accelerates after coasting, the inverter may trip in some parameter settings. (Activation of the restart function is recommended especially for an IPM motor.)
- Output stop function is disabled during PID control, JOG operation, and power failure stop.
- Output stop function does not operate during reverse rotation deceleration. However, when the frequency setting signal and output frequency falls to *Pr.522* or lower, the inverter coasts to a stop.
- During the output stop due to the output stop function (when forward/reverse command is given, but frequency command is not given), FWD/REV LED indication on the operation panel flickers fast.

⚠CAUTION

⚠ An IPM motor is a motor with interior permanent magnets. High voltage is generated at motor terminals while the motor is running. Do not touch motor terminals and other parts until the motor stops to prevent an electric shock.

♦ Parameters referred to ♦

Pr. 10 DC injection brake operation frequency , Pr. 11 DC injection brake operation time , Pr. 12 DC injection brake operation voltage ☞ *Refer to page 123*
Pr. 13 Starting frequency ☞ *Refer to page 113*

4.11 Function assignment of external terminal and control

Purpose	Parameter That Must be Set		Refer to Page
Assign function to input terminal	Input terminal function selection	Pr. 178 to Pr. 189	133
Set MRS signal (output shutoff) to NC contact specification	MRS input selection	Pr. 17	136
Make the second function valid only during constant speed operation.	RT signal function validity condition selection	Pr. 155	137
Assign start signal and forward/ reverse command to other signals	Start signal (STF/STR) operation selection	Pr. 250	138
Assign function to output terminal	Output terminal function assignment	Pr. 190 to Pr. 196	140
Detect output frequency.	Up-to-frequency sensitivity Output frequency detection Speed detection hysteresis	Pr. 41 to Pr. 43, Pr. 50, Pr. 870	144
Detect output current.	Output current detection Zero current detection	Pr. 150 to Pr. 153, Pr. 166, Pr. 167	146
Remote output function	Remote output	Pr. 495 to Pr. 497	148
Detect specified output power	Pulse train output of output power	Pr. 799	149

4.11.1 Input terminal function selection (Pr. 178 to Pr. 189)

Use these parameters to select/change the input terminal functions.

Parameter Number	Name	Initial Value	Initial Signal	Setting Range
178	**STF terminal function selection**	60	STF (forward rotation command)	0 to 8, 10 to 12, 14, 16, 24, 25, 60, 62, 64 to 67, 70 to 72, 9999
179	**STR terminal function selection**	61	STR (reverse rotation command)	0 to 8, 10 to 12, 14, 16, 24, 25, 61, 62, 64 to 67, 70 to 72, 9999
180	**RL terminal function selection**	0	RL (low-speed operation command)	0 to 8, 10 to 12, 14, 16, 24, 25, 62, 64 to 67, 70 to 72, 9999
181	**RM terminal function selection**	1	RM (middle-speed operation command)	
182	**RH terminal function selection**	2	RH (high speed operation command)	
183	**RT terminal function selection**	3	RT (second function selection)	
184	**AU terminal function selection**	4	AU (terminal 4 input selection)	0 to 8, 10 to 12, 14, 16, 24, 25, 62 to 67, 70 to 72, 9999
185	**JOG terminal function selection**	5	JOG (Jog operation selection)	0 to 8, 10 to 12, 14, 16, 24, 25, 62, 64 to 67, 70 to 72, 9999
186	**CS terminal function selection**	6	CS (selection of automatic restart after instantaneous power failure)	
187	**MRS terminal function selection**	24	MRS (output stop)	
188	**STOP terminal function selection**	25	STOP (start self-holding selection)	
189	**RES terminal function selection**	62	RES (inverter reset)	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Input terminal function assignment

- Use *Pr. 178 to Pr. 189* to set the functions of the input terminals.
- Refer to the following table and set the parameters:

Setting	Signal Name	Function		Related Parameters	Refer to Page
0	RL	*Pr. 59* = 0 (initial value)	Low-speed operation command	Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239	102
		Pr. 59 ≠ 0 *1	Remote setting (setting clear)	Pr. 59	106
1	RM	*Pr. 59* = 0 (initial value)	Middle-speed operation command	Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239	102
		Pr. 59 ≠ 0 *1	Remote setting (deceleration)	Pr. 59	106

Setting	Signal Name	Function		Related Parameters	Refer to Page
2	RH	*Pr. 59* = 0 (initial value)	High-speed operation command	Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239	102
		Pr. 59 ≠ 0 *1	Remote setting (acceleration)	Pr. 59	106
3	RT	Second function selection		Pr. 44 to Pr. 51	137
4	AU	Terminal 4 input selection		Pr. 267	185
5	JOG	Jog operation selection		Pr. 15, Pr. 16	104
6	CS	Selection of automatic restart after instantaneous power failure, flying start		Pr. 57, Pr. 58, Pr.162 to Pr.165, Pr. 299, Pr. 611	162
		Electronic bypass function *3		Pr. 57, Pr. 58 Pr. 135 to Pr. 139, Pr. 159	274
7	OH	External thermal relay input *2		Pr. 9	117
8	REX	15-speed selection (combination with three speeds RL, RM, RH, REX)		Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr.232 to Pr.239	102
10	X10	Inverter run enable signal (FR-HC, MT-HC, FR-CV connection)		Pr. 30	125
11	X11	FR-HC, MT-HC connection, instantaneous power failure detection		Pr. 30	125
12	X12	PU operation external interlock		Pr. 79	206
14	X14	PID control valid terminal		Pr. 127 to Pr. 134, Pr. 575 to Pr. 577	261
16	X16	PU/External operation switchover (turning ON X16 selects External operation)		Pr. 79, Pr. 340	212
24	MRS	Output stop		Pr. 17	136
		Electronic bypass function *3		Pr. 57, Pr. 58, Pr. 135 to Pr. 139, Pr. 159	274
25	STOP	Start self-holding selection		—	138
60	STF	Forward rotation command (assigned to STF terminal *(Pr. 178)* only)		—	138
61	STR	Reverse rotation command (assigned to STR terminal *(Pr. 179)* only)		—	138
62	RES	Inverter reset		—	—
63	PTC	PTC thermistor input (assigned to AU terminal *(Pr. 184)* only)		Pr. 9	117
64	X64	PID forward/reverse action switchover		Pr. 127 to Pr. 134	261
65	X65	PU/NET operation switchover (PU operation when X65 turns ON)		Pr. 79, Pr. 340	218
66	X66	External/NET operation switchover (NET operation when X66 turns ON)		Pr. 79, Pr. 340	218
67	X67	Command source switchover (*Pr.338* and *Pr.339* commands are valid when X67 turns ON)		Pr. 338, Pr. 339	219
70	X70	DC feeding operation permission		Pr. 30, Pr. 70	125
71	X71	DC feeding cancel		Pr. 30, Pr. 70	125
72	X72	PID integral value reset		Pr. 127 to Pr. 134, Pr. 241, Pr. 553, Pr. 554, Pr. 575 to Pr. 577, C42 to C45	261
9999	—	No function		—	—

*1 When *Pr. 59 Remote function selection* ≠ "0", the functions of the RL, RM and RH signals change as listed above.
*2 The OH signal turns ON when the relay contact "opens".
*3 These signals are available under V/F control and Simple magnetic flux vector control.

REMARKS

- Same function can be assigned to two or more terminals. In this case, the logic of terminal input is OR.
- The priorities of the speed commands are in order of jog > multi-speed setting (RH, RM, RL, REX) > PID (X14).
- When the X10 signal (FR-HC, MT-HC, FR-CV connection - inverter operation enable signal) is not set or when the PU operation external interlock (X12) signal is not assigned at the *Pr. 79 Operation mode selection* setting of "7", the MRS signal shares this function.
- Same signal is used to assign multi-speeds (7 speeds) and remote setting. They cannot be set individually.
  (Same signal is used since multi-speed (7 speeds) setting and remote setting are not used to set speed at the same time .)

CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Also check that wiring is correct, since the terminal name and the signal function became different. Set parameters after confirming the function of each terminal.

(2) Response time of each signal

· The response time of the X10 signal is within 2ms. However, when the X10 signal is not assigned at the *Pr. 30 Regenerative function selection* setting of "2" (FR-HC/MT-HC/FR-CV connection), the response time of the MRS signal is within 2ms.
Pr. 17 MRS input selection is invalid.

Pr. 30 Setting	MRS Assignment	X10 Assignment	Response Time		*Pr. 17*
			MRS	X10	
2	○	×	Within 2ms	—	Invalid
	×	○	—	Within 2ms	—
	○	○	Within 20ms	Within 2ms	Valid
Other than 2	○	×	Within 20ms	—	Valid
	×	○	—	—	—
	○	○	Within 20ms	—	Valid

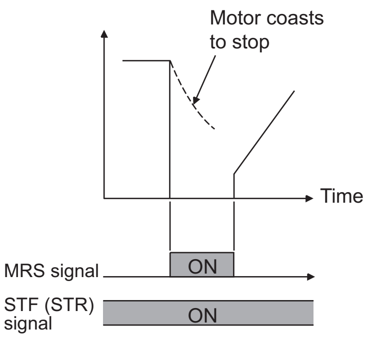
4.11.2 Inverter output shutoff signal (MRS signal, Pr. 17)

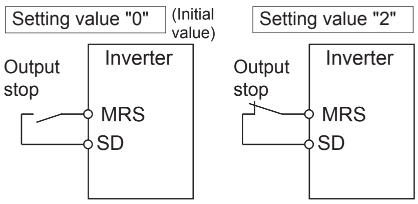
The inverter output can be shut off from the MRS signal. The logic of the MRS signal can also be selected.

Parameter Number	Name	Initial Value	Setting Range	Description
17 Ver.UP	MRS input selection	0	0	Open input always
			2	Close input always (NC contact input specifications)
			4	External terminal: Normally closed input (NC contact input specifications) Communication: Normally open input

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

Ver.UP .... Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.





(1) Output shutoff signal (MRS signal)

· Turning ON the output shutoff signal (MRS) during inverter running shuts off the output immediately.

· Terminal MRS may be used as described below.

(a) When mechanical brake (e.g. electromagnetic brake) is used to stop motor
The inverter output is shut off when the mechanical brake operates.

(b) To provide interlock to disable operation by the inverter
With the MRS signal ON, the inverter cannot be operated if the start signal is entered into the inverter.

(c) Coast the motor to a stop.
When the start signal is turned OFF, the inverter decelerates the motor to a stop in the preset deceleration time, but when the MRS signal is turned ON, the motor coasts to a stop.

(2) MRS signal logic inversion *(Pr. 17)*

· When *Pr. 17* is set to "2", the MRS signal (output stop) can be changed to the normally closed (NC contact) input specification. When the MRS signal turns ON (opens), the inverter shuts off the output.

(3) Assign a different action for each MRS signal input from communication and external terminal (*Pr. 17* = "4")

· When *Pr. 17* is set to "4", the MRS signal from external terminal (output stop) can be changed to the normally closed (NC contact) input, and the MRS signal from communication can be changed to the normally open (NO contact) input. This function is useful to perform operation by communication with MRS signal from external terminal remained ON.

External MRS	Communication MRS	*Pr. 17* Setting		
		0	2	4
OFF	OFF	Operation enabled	Output shutoff	Output shutoff
OFF	ON	Output shutoff	Output shutoff	Output shutoff
ON	OFF	Output shutoff	Output shutoff	Operation enabled
ON	ON	Output shutoff	Operation enabled	Output shutoff

REMARKS

· The MRS signal is assigned to the terminal MRS in the initial setting. By setting "24" in any of *Pr. 178 to Pr. 189 (input terminal function selection)*, the RT signal can be assigned to the other terminal.

· When using an external terminal to input the MRS signal, the MRS signal shuts off the output in any of the operation modes.

CAUTION

· Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

⚠CAUTION

⚠ An IPM motor is a motor with interior permanent magnets. High voltage is generated at motor terminals while the motor is running. Do not touch motor terminals and other parts until the motor stops to prevent an electric shock.

♦ Parameters referred to ♦

Pr. 178 to Pr. 189 (Input terminal function selection) ☞ *Refer to page 133*

4.11.3 Condition selection of function validity by the second function selection signal (RT) (RT signal, Pr. 155)

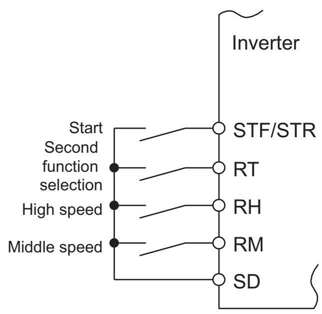
You can select the second function using the external terminal (RT signal).
You can also set the RT signal operation condition (reflection time).

Parameter Number	Name	Initial Value	Setting Range	Description
155	**RT signal function validity condition selection**	0	0	Second function is immediately valid with ON of the RT signal.
			10	Second function is valid only during the RT signal is ON and constant speed operation. (invalid during acceleration/deceleration)

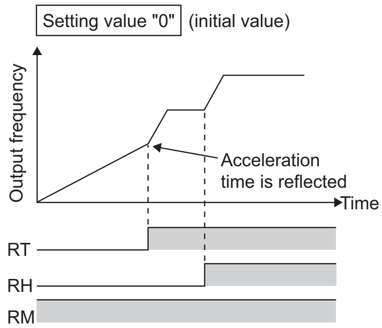
The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

- When the RT signal turns ON, the second function becomes valid.
- The second function has the following applications.
  (a) Switching between normal use and emergency use
  (b) Switching between heavy load and light load
  (c) Changing of acceleration/deceleration time by broken line acceleration/deceleration
  (d) Switching of characteristic between main motor and sub motor

Second function connection diagram



Second acceleration/deceleration time example



When the RT signal is ON, the following functions are selected at the same time.

Function	First Function Parameter Number	Second Function Parameter Number	Applied control mode (○: Valid, —: Invalid)			Refer to Page
			V/F	S MFVC	IPM	
Torque boost	Pr. 0	Pr. 46	○	—	—	87
Base frequency	Pr. 3	Pr. 47	○	○	—	98
Acceleration time	Pr. 7	Pr. 44	○	○	○	109
Deceleration time	Pr. 8	Pr. 44, Pr. 45	○	○	○	109
Electronic thermal relay function	Pr. 9	Pr. 51	○	○	—	117
Stall prevention	Pr. 22	Pr. 48, Pr. 49	○	○	○	91

REMARKS

- The RT signal is assigned to the RT terminal in the initial setting. By setting "3" in any of *Pr. 178 to Pr. 189 (input terminal function selection)*, the RT signal can be assigned to the other terminal.

CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 178 to Pr.189 (input terminal function selection) ☞ *Refer to page 133*

4.11.4 Start signal selection (STF, STR, STOP signal, Pr. 250)

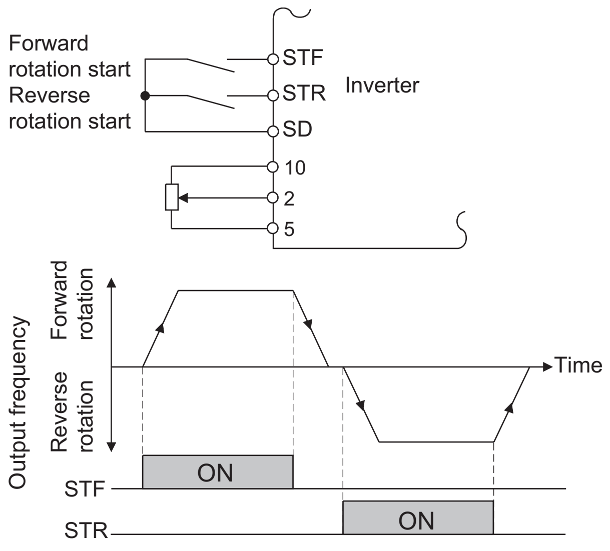
You can select the operation of the start signal (STF/STR).
Used to select the stopping method (deceleration to a stop or coasting) when the start signal turns OFF.
Used to stop the motor with a mechanical brake, etc. together with switching OFF of the start signal.
(Refer to *page 130* for stop selection)

Parameter Number	Name	Initial Value	Setting Range	Description: Start Signal (STF/STR)	Description: Stop Operation *(Refer to page 130)*
250	**Stop selection**	9999	0 to 100s	STF signal: Forward rotation start STR signal: Reverse rotation start	The motor is coasted to a stop when the preset time elapses after the start signal is turned OFF. When the setting is any of 1000s to 1100s, the inverter coasts to a stop in (*Pr. 250* - 1000)s.
			1000s to 1100s	STF signal: Start signal STR signal: Forward/reverse rotation signal	
			9999	STF signal: Forward rotation start STR signal: Reverse rotation start	When the start signal is turned OFF, the motor decelerates to stop.
			8888	STF signal: Start signal STR signal: Forward/reverse rotation signal	

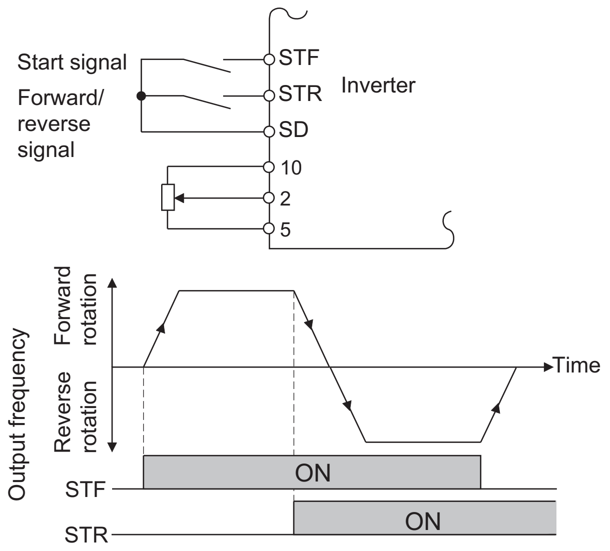
The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) 2-wire type (STF, STR signal)

- A two-wire type connection is shown below.
- In the initial setting, the forward/reverse rotation signals (STF/STR) are used as start and stop signals. Turn ON either of the forward and reverse rotation signals to start the motor in the corresponding direction. If both are turned OFF (or ON) during operation, the motor decelerates to a stop.
- The speed setting signal may either be given by entering 0 to 10VDC across the speed setting input terminal 2 and 5, by setting the required values in *Pr. 4 to Pr. 6 Multi-speed setting (high, middle, low speeds)*, etc. (For multi-speed operation, *refer to page 102*)
- When *Pr. 250* is set in any of "1000 to 1100, 8888", the STF signal becomes a start command and the STR signal a forward/reverse command.



2-wire connection example (*Pr. 250* = "9999")



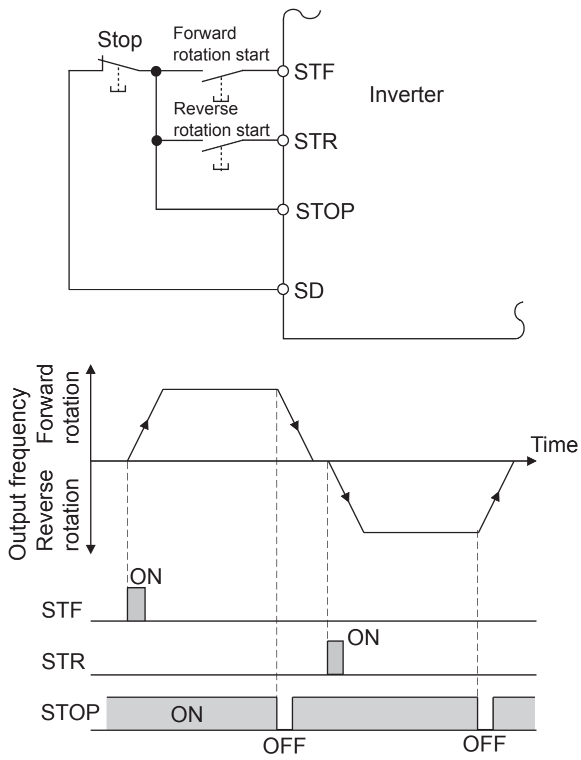
2-wire connection example (*Pr. 250* = "8888")

REMARKS

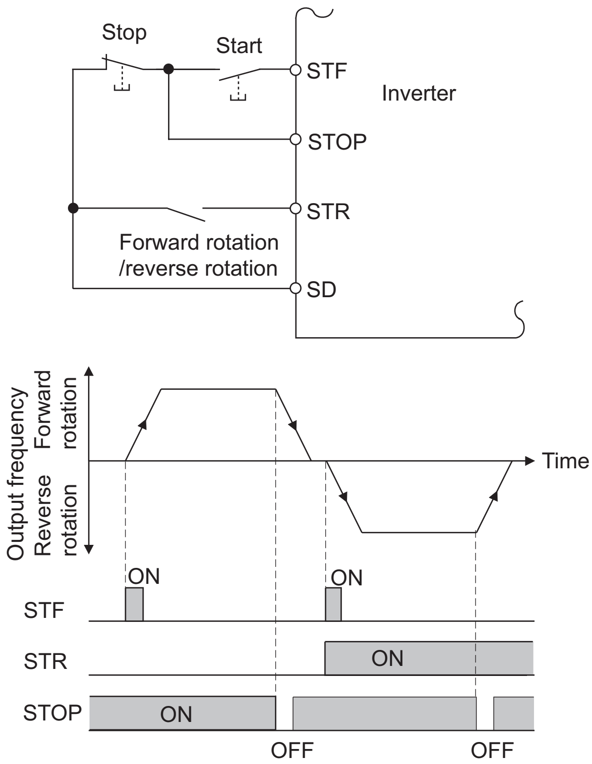
- When *Pr. 250* is set in any of "0 to 100, 1000 to 1100", the motor coasts to a stop if the start command is turned OFF. *(Refer to page 130)*
- The STF and STR signals are assigned to the STF and STR terminals in the initial setting. The STF signal can be assigned to *Pr. 178 STF terminal function selection* and the STR signal to *Pr. 179 STR terminal function selection* only.

(2) 3-wire type (STF, STR, STOP signal)

- A 3-wire type connection is shown below.
- The start self-holding selection becomes valid when the STOP signal is turned ON. In this case, the forward/ reverse rotation signal functions only as a start signal.
- If the start signal (STF or STR) is turned ON and then OFF, the start signal is held and makes a start. When changing the direction of rotation, turn STR (STF) ON once and then OFF.
- To stop the inverter, turning OFF the STOP signal once decelerates it to a stop.



3-Wire Type Connection Example (*Pr. 250* ="9999")



3-Wire Type Connection Example (*Pr. 250* ="8888")

REMARKS

- The STOP signal is assigned to the terminal STOP in the initial setting. By setting "25" in *Pr. 178 to Pr. 189*, the STOP signal can also be assigned to the other terminal.
- When the JOG signal is turned ON to enable jog operation, the STOP signal becomes invalid.
- If the MRS signal is turned ON to stop the output, the self-holding function is not canceled.

(3) Start signal selection

STF	STR	*Pr. 250* Setting Inverter Status	
		0 to 100s, 9999	1000s to 1100s, 8888
OFF	OFF	Stop	Stop
OFF	ON	Reverse rotation	
ON	OFF	Forward rotation	Forward rotation
ON	ON	Stop	Reverse rotation

♦ Parameters referred to ♦

Pr. 4 to Pr. 6 (Multi-speed setting) ☞ *Refer to page 102*
Pr. 178 to Pr. 189 (Input terminal function selection) ☞ *Refer to page 133*

4.11.5 Output terminal function selection (Pr. 190 to Pr. 196)

You can change the functions of the open collector output terminal and relay output terminal.

Parameter Number	Name		Initial Value	Initial Signal	Setting Range
190	**RUN terminal function selection**	**Open collector output terminal**	0	RUN (inverter running)	0 to 5, 7, 8, 10 to 19, 25, 26, 45 to 48, 57, 64, 67, 70, 79, 85, 90 to 96, 98, 99, 100 to 105, 107, 108, 110 to 116, 125, 126, 145 to 148, 157, 164, 167, 170, 179, 185, 190 to 196, 198, 199, 9999
191	**SU terminal function selection**		1	SU (up to frequency)	
192	**IPF terminal function selection**		2	IPF (instantaneous power failure, undervoltage)	
193	**OL terminal function selection**		3	OL (overload alarm)	
194	**FU terminal function selection**		4	FU (output frequency detection)	
195	**ABC1 terminal function selection**	**Relay output terminal**	99	ALM (fault output)	0 to 5, 7, 8, 10 to 19, 25, 26, 45 to 48, 57, 64, 67, 70, 79, 85, 90, 91, 94 to 96, 98, 99, 100 to 105, 107, 108, 110 to 116, 125, 126, 145 to 148, 157, 164, 167, 170, 179, 185, 190, 191, 194 to 196, 198, 199, 9999
196	**ABC2 terminal function selection**		9999	No function	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Output signal list

· You can set the functions of the output terminals.
· Refer to the following table and set the parameters: (0 to 99: Positive logic, 100 to 199: Negative logic)

Setting		Signal Name	Function	Operation	Related Parameters	Refer to Page
Positive Logic	Negative Logic					
0	100	RUN	Inverter running	Output during operation when the inverter output frequency rises to or above *Pr. 13 Starting frequency* (0.01Hz under IPM motor control).	—	142
1	101	SU	Up to frequency *1	Output when the output frequency is reached to the set frequency.	Pr. 41	144
2	102	IPF	Instantaneous power failure/undervoltage	Output at occurrence of an instantaneous power failure or when undervoltage protection is activated.	Pr. 57	162
3	103	OL	Overload warning	Output while stall prevention function is activated.	Pr. 22, Pr. 23, Pr. 66, Pr. 148, Pr. 149, Pr. 154	91
4	104	FU	Output frequency detection	Output when the output frequency reaches the frequency setting in *Pr. 42* (*Pr. 43* for reverse rotation).	Pr. 42, Pr. 43	144
5	105	FU2	Second output frequency detection	Output when the output frequency reaches the frequency setting in *Pr. 50*.	Pr. 50	144
7	107	RBP	Regenerative brake pre-alarm	Output when 85% of the regenerative brake duty set in *Pr. 70* is reached. Setting can be made for the 75K or higher.	Pr. 70	125
8	108	THP	Electronic thermal relay function prealarm	Output when the electronic thermal value reaches 85% of the trip level. (Electronic thermal relay function protection (E.THT/E.THM) activates, when the value reached 100%.)	Pr. 9	120
10	110	PU	PU operation mode	Output when the PU operation mode is selected.	Pr. 79	206
11	111	RY	Inverter operation ready	Output when the reset process is completed (when the inverter can be started by switching the start signal ON or while it is running) after powering ON the inverter.	—	142
12	112	Y12	Output current detection	Output when the output current is higher than the *Pr. 150* setting for longer than the time set in *Pr. 151*.	Pr. 150, Pr. 151	146

Setting		Signal Name	Function	Operation	Related Parameters	Refer to Page
Positive Logic	Negative Logic					
13	113	Y13	Zero current detection	Output when the output power is lower than the *Pr. 152* setting for longer than the time set in *Pr. 153*.	Pr. 152, Pr. 153	146
14	114	FDN	PID lower limit	Output when the feedback value falls below the lower limit of PID control.	Pr. 127 to Pr. 134, Pr. 575 to Pr. 577	261
15	115	FUP	PID upper limit	Output when the feedback value rises above the upper limit of PID control		
16	116	RL	PID forward/reverse rotation output	Output when forward rotation is performed in PID control.		
17	—	MC1	Electronic bypass MC1	Used when the bypass-inverter switchover function is used. These signals are available only under V/F control and Simple magnetic flux vector control.	Pr. 135 to Pr. 139, Pr. 159	274
18	—	MC2	Electronic bypass MC2			
19	—	MC3	Electronic bypass MC3			
25	125	FAN	Fan fault output	Output at the time of a fan alarm.	Pr. 244	281
26	126	FIN	Heatsink overheat pre-alarm	Output when the heatsink temperature reaches about 85% of the heatsink overheat protection operation temperature.	—	316
45	145	RUN3	Inverter running and start command is ON	Output when the inverter is running and start command is ON.	—	142
46	146	Y46	During deceleration at occurrence of power failure (retained until release)	Output when the power failure-time deceleration function is executed. (retained until release)	Pr. 261 to Pr. 266	169
47	147	PID	During PID control activated	Output during PID control.	Pr. 127 to Pr. 134, Pr. 575 to Pr. 577	261
48	148	Y48	PID deviation limit	Output when the absolute value of deviation exceeds the limit value.	Pr. 127 to Pr. 134, Pr. 241, Pr. 553, Pr. 554, Pr. 575 to Pr. 577, C42 to C45	261
57	157	IPM	IPM motor control	Output during IPM motor control.	Pr. 71, Pr. 80, Pr. 998	77
64	164	Y64	During retry	Output during retry processing.	Pr. 65 to Pr. 69	172
67	167	Y67	During power failure	Output during output shutoff due to power failure or under voltage.	Pr. 57	168
70	170	SLEEP	PID output interruption	Output when the PID output interruption function is executed.	Pr. 127 to Pr. 134, Pr. 575 to Pr. 577	261
79	179	Y79	Pulse train output of output power	Output in pulses every time the accumulated output power of the inverter reaches the *Pr.799* setting.	Pr. 799	149
85	185	Y85	DC current feeding	Output during power failure or under voltage of AC power.	Pr. 30, Pr. 70	125
90	190	Y90	Life alarm	Output when any of the control circuit capacitor, main circuit capacitor and inrush current limit circuit or the cooling fan approaches the end of its service life.	Pr. 255 to Pr. 259	282
91	191	Y91	Fault output 3 (power-OFF signal)	Output when a fault occurs due to the internal circuit failure of inverter wiring mistake.	—	143
92	192	Y92	Energy saving average value updated timing	Turned ON and OFF alternately every time the power saving average value is updated when the power saving monitor is used. Cannot be set to *Pr. 195 and Pr. 196* (relay output terminal).	Pr. 52, Pr. 54, Pr. 158, Pr. 891 to Pr. 899	177
93	193	Y93	Current average monitor signal	Average current value and maintenance timer value are output as pulses. Cannot be set to *Pr. 195 and Pr. 196* (relay output terminal).	Pr. 555 to Pr. 557	286
94	194	ALM2	Fault output 2	Output when the fault occurs. Continues outputting the signal during inverter reset and stops outputting after reset is cancelled. *2	—	143
95	195	Y95	Maintenance timer signal	Output when *Pr. 503* rises to or above the *Pr. 504* setting.	Pr. 503, Pr. 504	285

4

PARAMETERS

Setting: Positive Logic	Setting: Negative Logic	Signal Name	Function	Operation	Related Parameters	Refer to Page
96	196	REM	Remote output	Output to the terminal when a value is set to the parameter.	Pr. 495 to Pr. 497	148
98	198	LF	Alarm output	Output when an alarm (fan failure or communication error warning) occurs.	Pr. 121, Pr. 244	229, 281
99	199	ALM	Fault output	Output when the fault occurs. The signal output is stopped when the fault is reset.	—	143
9999		—	No function	—	—	—

*1 Note that when the frequency setting is varied using an analog signal or  of the operation panel (FR-DU07), the output of the SU (up to frequency) signal may alternate ON and OFF depending on that varying speed and the timing of the varying speed due to acceleration/deceleration time setting. (The output will not alternate ON and OFF when the acceleration/deceleration time setting is "0s".)
*2 When a power supply reset is performed, the fault output 2 signal (ALM2) turns OFF as soon as the power supply switches OFF.

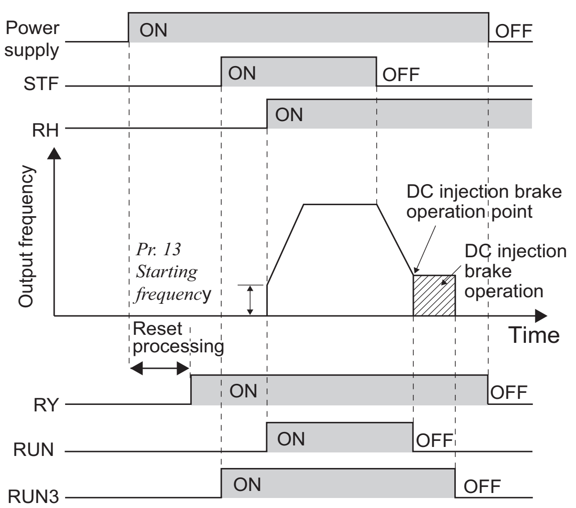
REMARKS

- The same function may be set to more than one terminal.
- When the function is executed, the terminal conducts at the setting of any of "0" to "99", and does not conduct at the setting of any of "100" to "199".
- When *Pr. 76 Fault code output selection* = "1", the output signals of the terminals SU, IPF, OL and FU are switched as set in *Pr. 76*. (When an inverter fault occurs, the signal output is switched to the fault code output.)
- The output assignment of the terminal RUN and fault output relay are as set above regardless of *Pr. 76*.

CAUTION

- Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.
- Do not assign signals which repeat frequent ON/OFF to terminal ABC1, terminal ABC2. Otherwise, the life of the relay contact decreases.

(2) Inverter operation ready signal (RY signal) and inverter running signal (RUN, RUN3 signal)



- When the inverter is ready to operate, the output of the operation ready signal (RY) is ON. It is also on during inverter running.
- When the inverter's output frequency reaches *Pr. 13 Starting frequency* or higher (0.01Hz under IPM motor control), the inverter running signal (RUN) is output. During an inverter stop or DC injection brake operation, the output is OFF.
- The output of the RUN3 signal is ON when the inverter running and start signals are ON.
(For the RUN3 signal, output is ON if the starting command is ON even when a fault occurs or the MRS signal is ON.
- When using the RY, RUN and RUN3 signals, assign functions to *Pr. 190 to Pr. 196 (output terminal selection function)* referring to the table below.

Output Signal	*Pr. 190 to Pr. 196* Setting: Positive logic	*Pr. 190 to Pr. 196* Setting: Negative logic
RY	11	111
RUN	0	100
RUN3	45	145

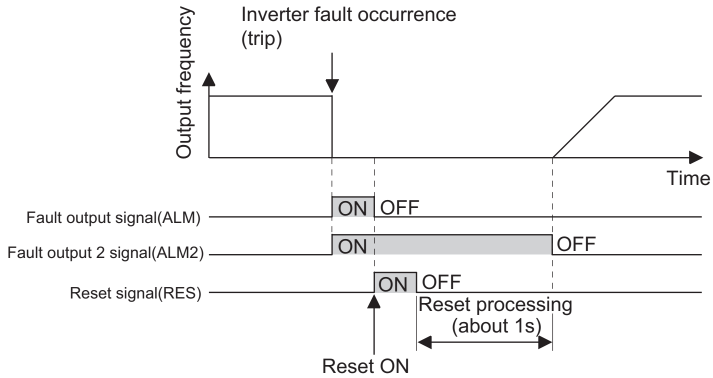
Inverter Status / Output Signal	Start Signal is OFF (during stop)	Start Signal is ON (during stop)	Start Signal is ON (during running)	Under DC Injection Brake	Output Shutoff *2: Start Signal is ON	Output Shutoff *2: Start Signal is OFF	Automatic Restart after Instantaneous Power Failure, Coasting: Start Signal is ON	Automatic Restart after Instantaneous Power Failure, Coasting: Start Signal is OFF	Automatic Restart after Instantaneous Power Failure: Restarting
RY	ON	ON	ON	ON	OFF		ON *1		ON
RUN	OFF	OFF	ON	OFF	OFF		OFF		ON
RUN3	OFF	ON	ON	ON	ON	OFF	ON	OFF	ON

*1 This signal turns OFF during power failure or undervoltage.
*2 Output is shutoff in conditions like a fault and when the MRS signal is ON.

REMARKS

- RUN signal is assigned to the terminal RUN in the initial setting.
- During IPM motor control, the RUN signal is output about 100ms after turning ON the start command (STF, STR). The delay is due to the magnetic pole detection.

(3) Fault output signal (ALM, ALM2 signal)



- If the inverter comes to trip, the ALM and ALM2 signals are output.
- The ALM2 signal remains ON during a reset period after fault occurrence.
- When using the ALM2 signal, set "94 (positive logic)" or "194 (negative logic)" to any of *Pr. 190 to Pr. 196 (output terminal function selection)* to assign the function to the output terminal.
- The ALM signal is assigned to the A1B1C1 contact in the initial setting.

REMARKS

Refer to *page 310* for the inverter fault description.

(4) Input MC shutoff signal (Y91 signal)

- The Y91 signal is output at occurrence of a fault attributable to the failure of the inverter circuit or a fault caused by a wiring mistake.
- When using the Y91 signal, set "91 (positive logic)" or "191 (negative logic)" in any of *Pr. 190 to Pr. 196 (output terminal function selection)* to assign the function to the output terminal.
- The following table indicates the faults that will output the Y91 signal. (Refer to *page 310* for the fault description.)

Fault Definition
Inrush current limit circuit fault (E.IOH)
CPU fault (E.CPU)
CPU fault (E.6)
CPU fault (E.7)
Parameter storage device fault (E.PE)
Parameter storage device fault (E.PE2)
24VDC power output short circuit (E.P24)
Power supply short circuit for operation panel, power supply short circuit for RS-485 (E.CTE)
Output side earth(ground) fault overcurrent (E.GF)
Output phase loss (E.LF)
Brake transistor alarm detection/internal circuit error (E.BE)

♦ Parameters referred to ♦

Pr. 13 Starting frequency ☞ *Refer to page 113*
Pr. 76 Fault code output selection ☞ *Refer to page 174*

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PARAMETERS

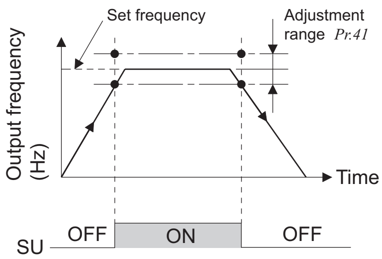
4.11.6 Detection of output frequency (SU, FU, FU2 signal, Pr. 41 to Pr. 43, Pr. 50, Pr. 870)

The inverter output frequency is detected and output to the output signal.

Parameter Number	Name	Initial Value	Setting Range	Description
41	**Up-to-frequency sensitivity**	10%	0 to 100%	Set the level where the SU signal turns ON.
42	**Output frequency detection**	6Hz	0 to 400Hz	Set the frequency where the FU signal turns ON.
43	**Output frequency detection for reverse rotation**	9999	0 to 400Hz	Set the frequency where the FU signal turns ON in reverse rotation.
			9999	Same as *Pr. 42* setting
50	**Second output frequency detection**	30Hz	0 to 400Hz	Set the frequency where the FU2 signal turns ON.
870	**Speed detection hysteresis**	0Hz*	0 to 5Hz	Set the hysteresis width for the detected frequency.

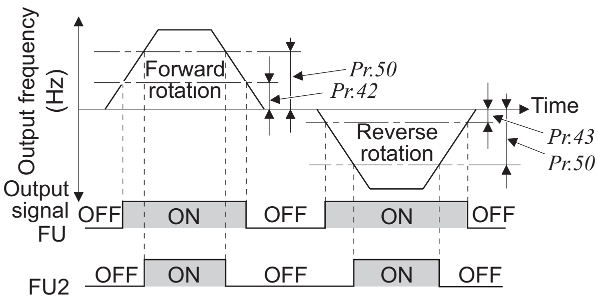
The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

* Performing IPM parameter initialization changes the settings. *(Refer to page 80)*



(1) Up-to-frequency sensitivity (SU signal, *Pr. 41*)

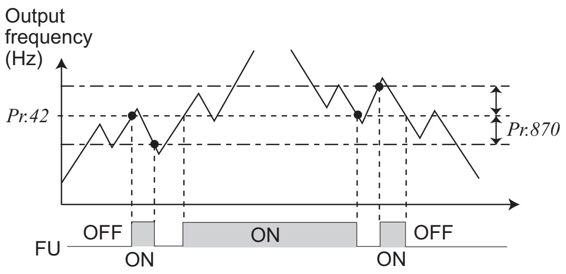
- When the output frequency reaches the set frequency, the up-to-frequency signal (SU) is output.
- The *Pr. 41* value can be adjusted within the range ±1% to ±100% on the assumption that the set frequency is 100%.
- This parameter can be used to ensure that the set frequency has been reached to provide the operation start signal etc. for related equipment.



Parameter Number	Output Signals	*Pr. 190 to Pr. 196* Setting	
		Positive logic	Negative logic
42, 43	FU	4	104
50	FU2	5	105

(2) Output frequency detection (FU signal, FU2 signal, *Pr. 42, Pr. 43, Pr. 50*)

- When the output frequency rises to or above the *Pr. 42* setting, the output frequency detection signal (FU) is output.
- This function can be used for electromagnetic brake operation, open signal, etc.
- Frequency detection that is dedicated to reverse operation can be set by setting detection frequency to *Pr. 43*. This function is effective for switching the timing of electromagnetic brake operation between forward rotation (rise) and reverse rotation (fall) during vertical lift operation, etc.
- When *Pr. 43* ≠ "9999", the *Pr. 42* setting applies to forward rotation and the *Pr. 43* setting applies to reverse rotation.
- When outputting a frequency detection signal besides the FU signal, set the detection frequency in *Pr. 50*. The FU2 signal output when the output frequency reaches or exceeds the *Pr. 50* setting.
- For each signal, assign functions to *Pr. 190 to Pr. 196* (output terminal function selection) referring to the left table.



Example of output frequency detection signal (FU)

(3) Speed detection hysteresis *(Pr.870)*

·This function prevents chattering of the speed detection signals.
When an output frequency fluctuates, the up to frequency signal (SU) and output frequency detection signals (FU and FU2) may repeat ON/OFF (chatters).Setting hysteresis to the detected frequency prevents chattering of these signals.

REMARKS

Setting a higher value to this parameter slows the response of frequency detection signals (SU, FU, and FU2).

REMARKS

The output frequency compared with the set frequency changes depending on the control method.

Control Method	Compared Output Frequency
V/F control	Output frequency
Simple magnetic flux vector control	Output frequency before slip compensation
IPM motor control	Estimated frequency (actual motor rotation per minute)

CAUTION

· Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 190 to Pr. 196 (output terminal function selection) ☞ *Refer to page 140*

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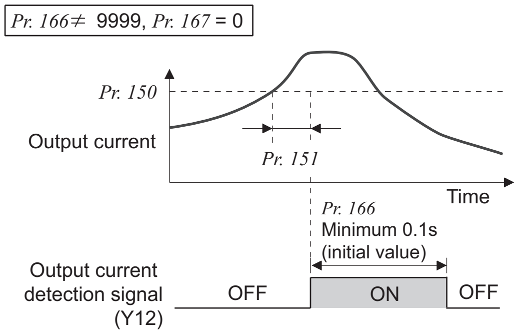
4.11.7 Output current detection function (Y12 signal, Y13 signal, Pr. 150 to Pr. 153, Pr. 166, Pr. 167)

The output current during inverter running can be detected and output to the output terminal.

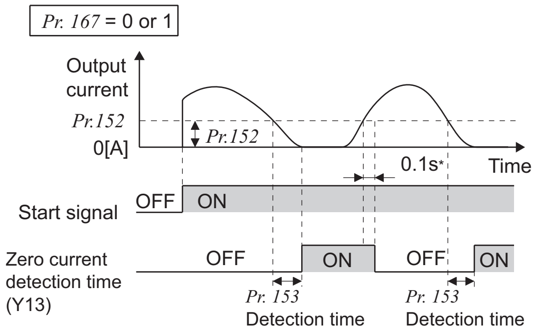
Parameter Number	Name	Initial Value	Setting Range	Description	
150	**Output current detection level**	120%	0 to 150%	Set the output current detection level. 100% is the rated inverter current.	
151	**Output current detection signal delay time**	0s	0 to 10s	Set the output current detection period. Set the time from when the output current has risen above the setting until the output current detection signal (Y12) is output.	
152	**Zero current detection level**	5%	0 to 150%	Set the zero current detection level. The rated inverter current is assumed to be 100%.	
153	**Zero current detection time**	0.5s	0 to 10s	Set the time period from when the output current drops below the *Pr. 152* value until when the zero current detection signal (Y13) is output.	
166	**Output current detection signal retention time**	0.1s	0 to 10s	Set the retention time when the Y12 signal is ON.	
			9999	The Y12 signal ON status is retained. The signal is turned OFF at the next start.	
167	**Output current detection operation selection**	0		**Y12 Signal - ON**	**Y13 Signal - ON**
			0	Operation continued	Operation continued
			1	Fault stop (E.CDO)	Operation continued
			10	Operation continued	Fault stop (E.CDO)
			11	Fault stop (E.CDO)	Fault stop (E.CDO)

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*



(1) Output current detection (Y12 signal, *Pr. 150, Pr. 151, Pr. 166, Pr. 167*)

- The output power detection function can be used for excessive torque detection, etc.
- If the output current remains higher than the *Pr. 150* setting during inverter operation for longer than the time set in *Pr. 151*, the output current detection signal (Y12) is output from the inverter's open collector or relay output terminal.
- When the Y12 signal turns ON, the ON state is held for the time set in *Pr. 166* .
- When *Pr. 166* = "9999", the ON state is held until a next start.
- At the *Pr. 167* setting of "1" or "11", the inverter output is stopped and the output current detection fault (E.CDO) is displayed when the Y12 signal turns ON. When a fault stop occurs, the Y12 signal is ON for the time set in *Pr. 166* at the *Pr. 166* setting of other than "9999", and remains ON until a reset is made at the *Pr. 166* setting of "9999". Setting *Pr. 167* = "1" or "11" at Y12 signal ON does not cause E.CDO. Setting to *Pr. 167* becomes effective after Y12 is turned OFF.
- For the X12 signal, set "12 (positive logic)" or "112 (negative logic)" in any of *Pr. 190 to Pr. 196 (output terminal function selection)* and assign the function to the output terminal.



* Once turned ON, the zero current detection time signal (Y13) is held on for at least 0.1s.

(2) Zero current detection (Y13 signal, *Pr. 152, Pr. 153, Pr. 167*)

- If the output current remains lower than the *Pr. 152* setting during inverter operation for longer than the time set in *Pr. 153*, the zero current detection (Y13) signal is output from the inverter's open collector or relay output terminal.
- When the inverter's output current falls to "0", torque will not be generated. This may cause a drop due to gravity when the inverter is used in vertical lift application. To prevent this, the output current zero signal (Y13) can be output from the inverter to close the mechanical brake when the output current has fallen to "0".
- When *Pr.167* = "10" or "11", turning Y13 signal ON stops the inverter output and causes output current detection fault (E.CDO) to be displayed. ON status of Y13 signal is held for 0.1s at the fault. Setting *Pr. 167* = "10" or "11" while Y13 signal is ON does not cause E.CDO. Setting to *Pr. 167* becomes effective after Y13 is turned OFF.
- For the Y13 signal, set "13 (positive logic)" or "113 (negative logic)" in any of *Pr. 190 to Pr. 196 (output terminal function selection)* to assign the function to the output terminal.

CAUTION

- The response time of Y12 and Y13 signals is approximately 0.1s. Note that the response time changes according to the load condition.
- When *Pr. 152* = "0", detection is disabled.
- Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

⚠ CAUTION

⚠ The zero current detection level setting should not be too low, and the zero current detection time setting not too long. Otherwise, the detection signal may not be output when torque is not generated at a low output current.

⚠ To prevent the machine and equipment from resulting in hazardous conditions by use of the zero current detection signal, install a safety backup such as an emergency brake.

♦ Parameters referred to ♦

Pr. 190 to Pr. 196 (output terminal function selection) ☞ *Refer to page 140*

4.11.8 Remote output function (REM signal, Pr. 495 to Pr. 497)

You can utilize the ON/OFF of the inverter's output signals instead of the remote output terminal of the programmable controller.

Parameter Number	Name	Initial Value	Setting Range	Description	
495	Remote output selection	0	0	Remote output data clear at powering OFF	Remote output data is cleared during an inverter reset
			1	Remote output data retention even at powering OFF	
			10	Remote output data clear at powering OFF	Remote output data is retained during an inverter reset
			11	Remote output data retention even at powering OFF	
496 *	Remote output data 1	0	0 to 4095	Refer to the following diagram.	
497 *	Remote output data 2	0	0 to 4095		

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

* This parameter allows its setting to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.

<Remote output data>

Pr. 496

b11											b0
*1	*1	*1	*1	*1	ABC2	ABC1	FU	OL	IPF	SU	RUN

Pr. 497

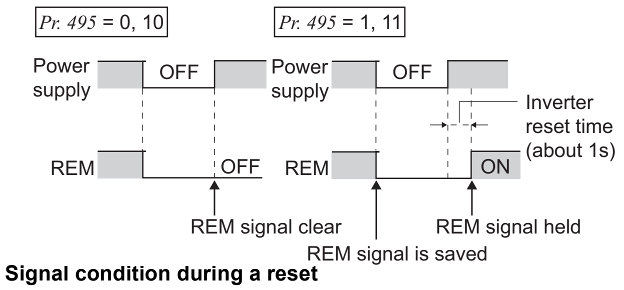
b11											b0
*1	*1	RA3 *3	RA2 *3	RA1 *3	Y6 *2	Y5 *2	Y4 *2	Y3 *2	Y2 *2	Y1 *2	Y0 *2

*1 As desired
*2 Y0 to Y6 are available only when the extension output option (FR-A7AY) is fitted
*3 RA1 to RA3 are available only when the relay output option (FR-A7AR) is fitted

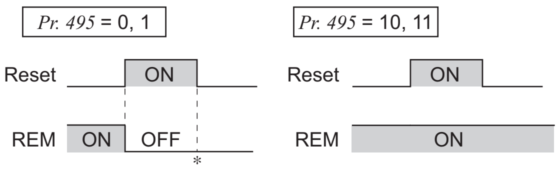
- The output terminal can be turned on/off depending on the *Pr. 496* or *Pr. 497* setting. The remote output selection can be controlled ON/OFF by computer link communication from the PU connector or RS-485 port or by communication from the communication option.
- Set "96" (positive logic) or "196" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*, and assign the remote output (REM) signal to the terminal used for remote output,
- When you refer to the left diagram and set 1 to the terminal bit (terminal where the REM signal has been assigned) of *Pr. 496* or *Pr. 497*, the output terminal turns ON (OFF for negative logic). By setting 0, the output terminal turns OFF (ON for negative logic).

Example)When "96" (positive logic) is set to *Pr. 190 RUN terminal function selection* and "1" (H01) is set to *Pr. 496*, the terminal RUN turns ON.

ON/OFF example for positive logic



Signal condition during a reset



* When *Pr. 495* = "1," the signal condition saved in EEPROM (condition of the last power OFF) is applied.

- When *Pr. 495* = "0 (initial value), 10", performing a power supply reset (including a power failure) clears the REM signal output. (The ON/OFF status of the terminals are as set in *Pr. 190 to Pr. 196*.) The *Pr. 496* and *Pr. 497* settings are also "0".
  When *Pr. 495* = "1, 11", the remote output data before power supply-off is stored into the EEPROM, so the signal output at power recovery is the same as before power supply-off. However, it is not stored when the inverter is reset (terminal reset, reset request through communication).
  (See the chart on the left)
- When *Pr. 495* = "10 or 11," the signal before the reset is held even during an inverter reset.

REMARKS

- The output terminal where the REM signal is not assigned using any of *Pr. 190* to *Pr. 196* does not turn ON/OFF if 0/1 is set to the terminal bit of *Pr. 496* or *Pr. 497*. (It turns ON/OFF with the assigned function.)

CAUTION

- When *Pr. 495*="1, 11"(remote output data retention at power OFF), connect R1/11 with P/+, and S1/L21 with N/- so that the control power is retained. If you do not take such a step, the output signals provided after power-ON are not guaranteed.

♦ Parameters referred to ♦

- *Pr. 190 to Pr. 196 (output terminal function selection)* ☞ *Refer to page 140*

4.11.9 Pulse train output of output power (Y79 signal, Pr. 799)

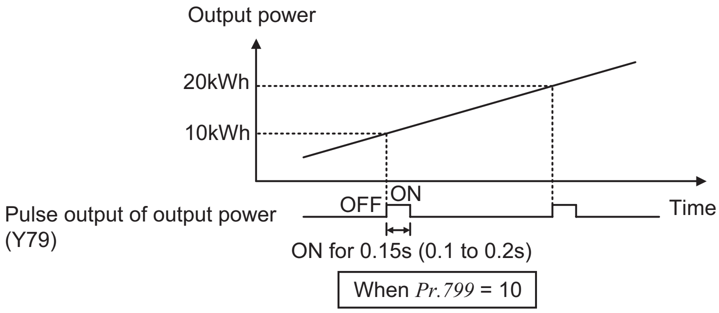
After power ON or inverter reset, output signal (Y79 signal) is output in pulses every time accumulated output power, which is counted after the *Pr.799 Pulse increment setting for output power* is set, reaches the specified value (or its integral multiples).

Parameter Number	Name	Initial Value	Setting Range	Description
799	**Pulse increment setting for output power**	1kWh	0.1kWh, 1kWh, 10kWh, 100kWh, 1000kWh	Pulse train output of output power (Y79) is output in pulses at every output power (kWh) that is specified.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Pulse increment setting for output power (Y79 signal, *Pr.799*)

- After power ON or inverter reset, output signal (Y79 signal) is output in pulses every time accumulated output power of the inverter exceeds *Pr.799 Pulse increment setting for output power*.
- The inverter continues to count the output power at retry function or when automatic restart after instantaneous power failure function works without power OFF of output power (power failure that is too short to cause an inverter reset), and it does not reset the count.
- If power failure occurs, output power is counted from 0kWh again.
- Assign pulse output of output power (Y79: setting value 79 (positive logic), 179 (negative logic)) to any of *Pr.190 to Pr.196 (Output terminal function selection)*.



CAUTION

- Because the accumulated data in the inverter is cleared when control power is lost by power failure or at an inverter reset, the value on the monitor cannot be used to charge electricity bill.
- Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal. *(Refer to page 140)*

REMARKS

- When parameter copy is performed, *Pr.799* = "9999" might be set. However, the inverter operates as *Pr.799* were at "1kWh" (initial value) in such case.

♦ Parameters referred to ♦

- *Pr. 190 to Pr. 196 (output terminal function selection)* ☞ *Refer to page 140*

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PARAMETERS

4.12 Monitor display and monitor output signal

Purpose	Parameter that must be set		Refer to Page
Display motor speed **Set speed**	**Speed display and speed setting**	**Pr. 37, Pr. 144, Pr. 505**	150
Change PU monitor display data	**DU/PU main display data selection** **Cumulative monitor clear**	**Pr. 52, Pr. 170, Pr. 171, Pr. 268, Pr. 891**	152
Change of the monitor output from terminal FM and AM	**Terminal FM, AM function selection**	**Pr. 54, Pr. 158**	152
Set the reference of the monitor output from terminal FM and AM	**Setting of reference of terminal FM and AM**	**Pr. 55, Pr. 56, Pr. 867**	157
Adjust terminal FM, AM outputs	**Terminal FM, AM calibration**	**Pr. 900, Pr. 901**	159

4.12.1 Speed display and speed setting (Pr. 37, Pr. 144, Pr. 505)

You can change the PU (FR-DU07/FR-PU04/FR-PU07) monitor display or frequency setting to motor speed or machine speed.

Parameter Number	Name	Initial Value	Setting Range	Description
37	**Speed display**	0 *1	0	Frequency display, setting
			1 to 9998 *3	Set the machine speed at *Pr.505*.
144	**Speed setting switchover**	4 *2	0, 2, 4, 6, 8, 10, 102, 104, 106, 108, 110	Set the number of motor poles when displaying the motor speed.
505	**Speed setting reference**	60Hz *2	1 to 120Hz	Set the reference speed for *Pr. 37*.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

*1 Performing IPM parameter initialization sets back the settings to the initial settings. *(Refer to page 80)*

*2 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*

*3 The maximum value of the setting range differs according to the *Pr.1 Maximum frequency* and it can be calculated from the following formula.

$$Pr.37 \text{ (set maximum value)} < \frac{65535 \times Pr.\ 505 \text{ setting (Hz)}}{Pr.1 \text{(Hz)}}$$

Note that *Pr.37* (set maximum value) is 9998 if the result of the above formula exceeds 9998.

- To display the machine speed, set in *Pr. 37* the machine speed for operation with frequency set in *Pr. 505*. For example, when *Pr. 505* = "60Hz" and *Pr. 37* = "1000", "1000" is displayed on the running speed monitor when the running frequency is 60Hz. When running frequency is 30Hz, "500" is displayed.
- When displaying the motor speed, set the number of motor poles (2, 4, 6, 8, 10) or number of motor poles + 100 (102, 104, 106, 108, 110) to *Pr. 144*.
- When both *Pr. 37* and *Pr. 144* have been set, their priorities are as given below.
  Pr. 144, 102 to 110 > *Pr. 37*, 1 to 9998 > *Pr. 144*, 2 to 10
- A combination of the *Pr. 37* and *Pr. 144* settings determines the setting increment of monitored items as shown in the table below. (The increments within the bold frame are the initial increments.)

Pr. 37 Setting	*Pr. 144* Setting	Output Frequency Monitor	Set Frequency Monitor	Running Speed Monitor	Frequency Setting Parameter Setting
0 (initial value)	0	0.01Hz	0.01Hz	1r/min *1	0.01Hz
	2 to 10	0.01Hz	0.01Hz	1r/min *1	0.01Hz
	102 to 110	1r/min *1	1r/min *1	1r/min *1	1r/min *1
1 to 9998	0	0.01Hz	0.01Hz	1 (Machine speed *1)	0.01Hz
	2 to 10	1 (Machine speed *1)	1 (Machine speed *1)	1 (Machine speed *1)	1 (Machine speed *1)
	102 to 110	0.01Hz	0.01Hz	1r/min *1	0.01Hz

*1 Motor speed r/min conversion formula............ frequency × 120/number of motor poles (*Pr. 144*)
Machine speed conversion formula.................. *Pr. 37* × frequency/*Pr. 505* setting (Hz)
For *Pr. 144* in the above formula, the value is "*Pr. 144*-100" when "102 to 110" is set in *Pr. 144* and the value is "4" when *Pr. 37* = 0 and *Pr. 144* = 0.
Pr. 505 is always set as frequency (Hz).

CAUTION

- Under V/F control, the output frequency of the inverter is displayed in terms of synchronous speed, and therefore, displayed value = actual speed + motor slip.
- When the running speed display is selected at the setting of *Pr. 37* "0" and *Pr. 144* "0", the monitor display is provided on the assumption that the number of motor poles is 4. (1800r/min is displayed at *Pr. 505* setting (Hz))
- Refer to *Pr. 52* when you want to change the PU main monitor (PU main display).
- Since the panel display of the operation panel (FR-DU07) is 4 digits in length, the monitor value of more than "9999" is displayed "----".
- When an optional FR-A7ND or FR-A7NL card is mounted, frequency is displayed regardless of *Pr. 37* and *Pr. 144* setting.

⚠ CAUTION

⚠ Make sure that the settings of the running speed and number of motor poles are correct. Otherwise, the motor might run at extremely high speed, damaging the machine.

♦ Parameters referred to ♦

Pr. 1 Maximum frequency ☞ Refer to page 96
Pr. 52 DU/PU main display data selection ☞ Refer to page 152

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PARAMETERS

4.12.2 DU/PU monitor display selection (Pr. 52, Pr. 54, Pr. 158, Pr. 170, Pr. 171, Pr. 268, Pr. 563, Pr. 564, Pr. 891)

The monitor to be displayed on the main screen of the operation panel (FR-DU07)/parameter unit (FR-PU04/FR-PU07) can be selected.
In addition, signals to be output from the terminal FM (pulse train output) and AM (analog voltage output) can be selected.

Parameter Number	Name	Initial Value	Setting Range	Description
52*	**DU/PU main display data selection**	0 (output frequency)	0, 5, 6, 8 to 14, 17, 20, 23 to 25, 50 to 57, 100	Select the monitor to be displayed on the operation panel and parameter unit. Refer to the following table for monitor description.
54*	**FM terminal function selection**	1 (output frequency)	1 to 3, 5, 6, 8 to 14, 17, 21, 24, 50, 52, 53	Select the monitor output to terminal FM.
158*	**AM terminal function selection**			Select the monitor output to terminal AM.
170	**Watt-hour meter clear**	9999	0	Set "0" to clear the watt-hour meter monitor.
			10	Sets the maximum value for the monitoring from communication to 9999kWh.
			9999	Sets the maximum value for the monitoring from communication to 65535kWh.
171	**Operation hour meter clear**	9999	0, 9999	Set "0" to clear the operation time monitor. Setting "9999" has no effect.
268 *	**Monitor decimal digits selection**	9999	0	Displayed as integral value.
			1	Displayed in 0.1 increments.
			9999	No function
563	**Energization time carrying-over times**	0	0 to 65535 (reading only)	Displays the numbers of cumulative energization time monitor exceeded 65535h. Reading only
564	**Operating time carrying-over times**	0	0 to 65535 (reading only)	Displays the numbers of operation time monitor exceeded 65535h. Reading only
891*	**Cumulative power monitor digit shifted times**	9999	0 to 4	Set the number of times to shift the cumulative power monitor digit. Clamps the monitor value at maximum.
			9999	No shift Clears the monitor value when it exceeds the maximum value.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
* This parameter allows its setting to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.

(1) Monitor description list *(Pr. 52)*

- Set the monitor to be displayed on the operation panel (FR-DU07) and parameter unit (FR-PU04/FR-PU07) in *Pr. 52 DU/PU main display data selection*.
- Set the monitor to be output to the terminal FM(pulse train output) in *Pr. 54 FM terminal function selection*.
- Set the monitor to be output to the terminal AM (analog output (0 to 10VDC voltage output)) in *Pr. 158 AM terminal function selection*.
- Refer to the following table and set the monitor to be displayed. (The signals marked × cannot be selected for monitoring)

Types of Monitor	Increments	*Pr. 52* Parameter Setting Value		*Pr. 54* (FM) *Pr. 158* (AM) Parameter Setting Value	Full-scale value of the terminal FM and AM	Description
		DU LED	PU main monitor			
Output frequency	0.01Hz	0/100		1	*Pr. 55*	Displays the inverter output frequency
Output current*7	0.01A/0.1A *5	0/100		2	*Pr. 56*	Displays the inverter output current effective value
Output voltage	0.1V	0/100		3	200V class: 400V 400V class: 800V	Displays the inverter output voltage
Fault display	—	0/100		×	—	Displays 8 past faults individually
Frequency setting value	0.01Hz	5	*1	5	*Pr. 55*	Displays the set frequency

Types of Monitor	Increments	*Pr. 52* Parameter Setting Value: DU LED	*Pr. 52* Parameter Setting Value: PU main monitor	*Pr. 54* (FM) *Pr. 158* (AM) Parameter Setting Value	Full-scale value of the terminal FM and AM	Description
Running speed	1(r/min)	6	*1	6	The value converted with the *Pr. 37* value from *Pr. 55*	Displays the motor speed (The display differs depending on the *Pr. 37* and *Pr. 144* settings.) *(For details, refer to page 150 .)*
Converter output voltage	0.1V	8	*1	8	200V class: 400V 400V class: 800V	Displays the DC bus voltage value
Regenerative brake duty	0.1%	9	*1	9	*Pr. 70*	Brake duty set in *Pr. 30* and *Pr. 70* (Setting is available for the 75K or higher)
Electronic thermal relay function load factor	0.1%	10	*1	10	100%	Displays the motor thermal cumulative value on the assumption that the thermal operation level is 100%.
Output current peak value	0.01A/0.1A *5	11	*1	11	*Pr. 56*	Retains the peak value of the output current monitor and displays (clears at every start)
Converter output voltage peak value	0.1V	12	*1	12	200V class: 400V 400V class: 800V	Retains the peak value of the DC bus voltage value and displays (clears at every start)
Input power	0.01kW/ 0.1kW *5	13	*1	13	Rated inverter power × 2	Displays power of the inverter input side
Output power	0.01kW/ 0.1kW *5	14	*1	14	Rated inverter power × 2	Displays power of the inverter output side
Load meter	0.1%	17		17	100%	Displays the torque current in % on the assumption that the *Pr. 56* setting is 100%
Cumulative energization time *2	1h	20		×	—	Displays the cumulative energization time since the inverter shipment You can check the numbers of the monitor value exceeded 65535h with *Pr. 563*.
Reference voltage output	—	—		21	—	Terminal FM:1440 pulse/s is output Terminal AM: 10V is output
Actual operation time *2*3	1h	23		×	—	Displays the cumulative inverter running time. You can check the numbers of the monitor value exceeded 65535h with *Pr. 564*. Use *Pr. 171* to clear the value. *(Refer to page 156 .)*
Motor load factor	0.1%	24		24	200%	Displays the output current value in % on the assumption that the rated inverter current value is 100%. Monitor value = output current monitor value/rated inverter current × 100 [%]
Cumulative power *6	0.01kWh/ 0.1kWh *4, *5	25		×	—	Displays the cumulative power amount according to the output power monitor Use *Pr. 170* to clear the value. *(Refer to page 156.)*
Power saving effect	Variable according to parameters	50		50	Inverter capacity	Displays energy saving effect monitor You can change the monitor to power saving, power saving average value, charge display and % display using parameters. *(For details, refer to page 178.)*
Cumulative saving power *6		51		×	—	
PID set point	0.1%	52		52	100%/ *C42 or C44*	Displays the set point, measured value and deviation during PID control *(For details, refer to page 268.)*
PID measured value	0.1%	53		53	100%/ *C42 or C44*	
PID deviation	0.1%	54		×	—	
Input terminal status	—	55	*1	×	—	Displays ON/OFF status of the input terminal on the PU *(Refer to page 155 for DU display)*
Output terminal status	—		*1	×	—	Displays ON/OFF status of the output terminal on the PU *(Refer to page 155 for DU display)*

Types of Monitor	Increments	*Pr. 52* Parameter Setting Value		*Pr. 54* (FM) *Pr. 158* (AM) Parameter Setting Value	Full-scale value of the terminal FM and AM	Description
		DU LED	PU main monitor			
Option input terminal status	—	56	×	×	—	Displays ON/OFF status of the input terminal of the digital input option (FR-A7AX) on the DU *(refer to page 155 for details)*
Option output terminal status	—	57	×	×	—	Displays ON/OFF status of the output terminal of the digital output option (FR-A7AY) and relay output option (FR-A7AR) on the DU *(refer to page 155 for details)*

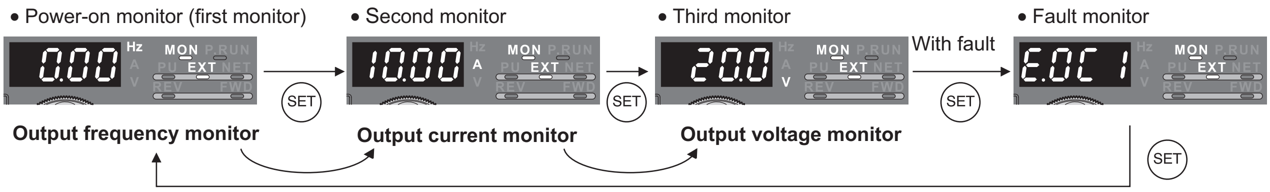
*1 Frequency setting to output terminal status on the PU main monitor are selected by "other monitor selection" of the parameter unit (FR-PU04, FR-PU07).
*2 The cumulative energization time and actual operation time are accumulated from 0 to 65535 hours, then cleared, and accumulated again from 0. When the operation panel (FR-DU07) is used, the time is displayed up to 65.53 (65530h) in the indication of 1h = 0.001, and thereafter, it is added up from 0.
*3 The actual operation time is not added up if the cumulative operation time before power supply-OFF is less than 1h.
*4 When using the parameter unit (FR-PU04/FR-PU07), "kW" is displayed.
*5 The setting depends on capacities. (55K or lower/75K or higher)
*6 Since the panel display of the operation panel is 4 digits in length, the monitor value of more than "9999" is displayed as "----".
*7 When the output current is less than the specified current level (5% of the rated inverter current), the output current is monitored as 0A. Therefore, the monitored value of an output current and output power may be displayed as "0" when using a much smaller-capacity motor compared to the inverter or in other instances that cause the output current to fall below the specified value.

REMARKS

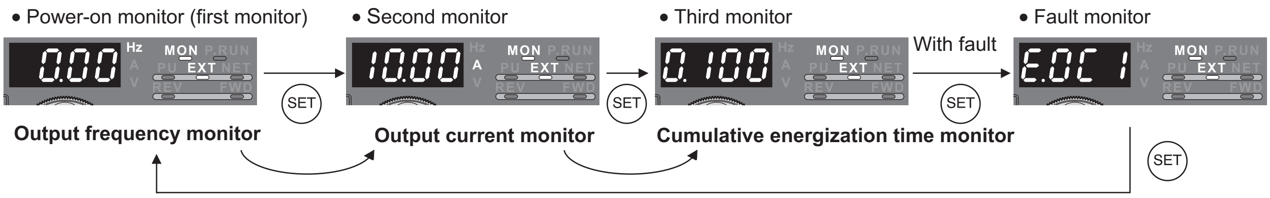
- By setting "0" in *Pr. 52*, the monitoring of output speed to fault display can be selected in sequence by SET.
- When the operation panel (FR-DU07) is used, the displayed units are Hz, V and A only and the others are not displayed.
- The monitor set in *Pr. 52* is displayed in the third monitor position. (The output voltage monitor is changed.) Note that load meter and motor load factor are displayed in the second monitor (output current).

Initial value

* The monitor displayed at powering ON is the first monitor. Display the monitor you want to display on the first monitor and hold down SET for 1s. (To return to the output frequency monitor, hold down SET for 1s after displaying the output frequency monitor.)



Example)When *Pr. 52* is set to "20" (cumulative energization time), the monitor is displayed on the operation panel as described below.



(2) Display set frequency during stop (*Pr. 52*)

- When *Pr. 52* is set to "100", the set frequency monitor is displayed during a stop and the output frequency monitor is displayed during operation. (LED of Hz flickers during stop and is lit during running.)
- When *Pr.52* = "100", the set frequency displayed at a stop indicates frequency to be output when the start command is ON. Different from the frequency setting based on displayed when *Pr.52* = "5", the value maximum/minimum frequency and frequency jump is displayed.

	Pr. 52		
	0	100	
	During running/stop	During stop	During running
Output frequency	Output frequency	Set frequency	Output frequency
Output current	Output current		
Output voltage	Output voltage		
Fault display	Fault display		

REMARKS

- During an error, the output frequency at error occurrence appears.
- During MRS, the values displayed are the same as during a stop.

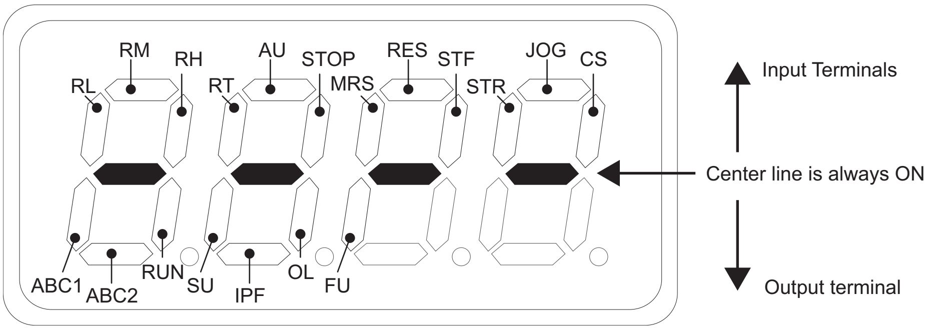
(3) Operation panel (FR-DU07) I/O terminal monitor (*Pr. 52*)

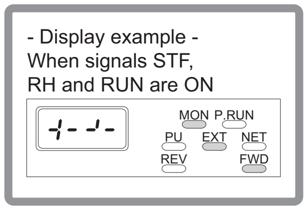
- When *Pr. 52* is set to any of "55 to 57", the I/O terminal states can be monitored on the operation panel (FR-DU07).
- The I/O terminal monitor is displayed on the third monitor.
- The LED is ON when the terminal is ON, and the LED is OFF when the terminal is OFF. The center line of LED is always ON.

Pr. 52 Setting	Monitor Description
55	Displays the I/O and output terminal ON/OFF states of the inverter unit.
56 *	Displays the input terminal ON/OFF states of the digital input option (FR-A7AX).
57 *	Displays the output terminal ON/OFF states of the digital output option (FR-A7AY) or relay output option (FR-A7AR).

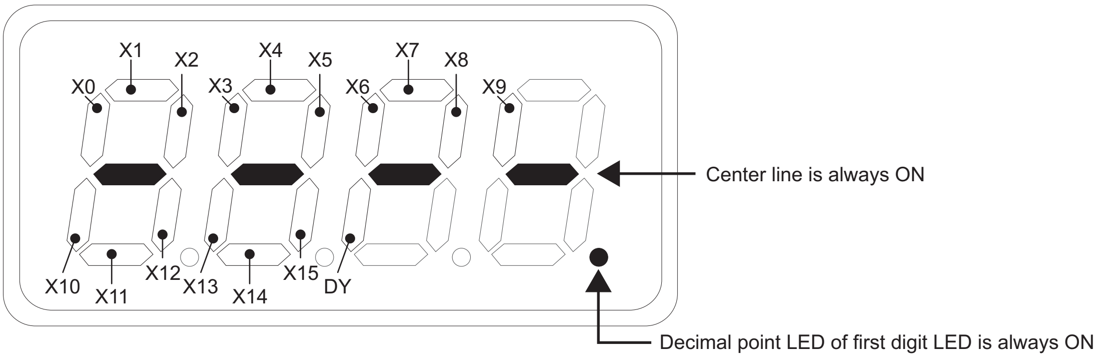
* You can set "56" or "57" even if the option is not fitted. When the option is not fitted, the monitor displays are all OFF.

- On the unit I/O terminal monitor (*Pr. 52* = "55"), the upper LEDs denote the input terminal states and the lower the output terminal states.

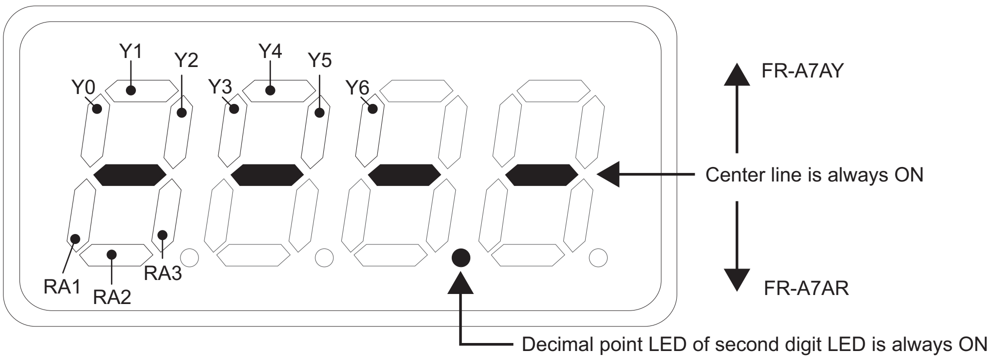




- On the input option terminal monitor (*Pr. 52*= "56"), the decimal point LED of the first digit LED is ON.



- On the output option terminal monitor (*Pr. 52*= "57"), the decimal point LED of the second digit LED is ON.



(4) Cumulative power monitor and clear *(Pr. 170, Pr. 891)*

· On the cumulative power monitor (*Pr. 52* = "25"), the output power monitor value is added up and is updated in 1h increments.
· The operation panel (FR-DU07), parameter unit (FR-PU04/FR-PU07) and communication (RS-485 communication, communication option) display units and display ranges are as indicated below.

Operation Panel *1		Parameter Unit *2		Communication		
Range	Unit	Range	Unit	Range		Unit
				Pr. 170 = 10	*Pr. 170* = 9999	
0 to 99.99kWh	0.01kWh	0 to 999.99kWh	0.01kWh	0 to 9999kWh	0 to 65535kWh (initial value)	1kWh
100.0 to 999.9kWh	0.1kWh	1000.0 to 9999.9kWh	0.1kWh			
1000 to 9999kWh	1kWh	10000 to 99999kWh	1kWh			

*1 Power is measured in the range 0 to 9999.99kWh, and displayed in 4 digits.
When the monitor value exceeds "99.99", a carry occurs, e.g. "100.0", so the value is displayed in 0.1kWh increments.
*2 Power is measured in the range 0 to 99999.99.99kWh, and displayed in 5 digits.
When the monitor value exceeds "999.99", a carry occurs, e.g. "1000.0", so the value is displayed in 0.1kWh increments.

· The monitor data digit can be shifted to the right by the number of *Pr. 891* settings.
For example, if the cumulative power value is 1278.56kWh when *Pr. 891* = "2", the PU/DU display is 12.78 (display in 100kWh increments) and the communication data is 12.
· If the maximum value exceeded at *Pr. 891* = "0 to 4", the power is clamped at the maximum value, indicating that a digit shift is necessary. If the maximum value exceeded at *Pr. 891* = "9999", the power returns to 0 and is recounted. If the maximum value is exceeded at *Pr. 891* = "9999", the power returns to 0 and is recounted.
· Writing "0" in *Pr. 170* clears the cumulative power monitor.

REMARKS
· If "0" is written in *Pr. 170* and *Pr. 170* is read again, "9999" or "10" is displayed.

(5) Cumulative energization time and actual operation time monitor *(Pr. 171, Pr. 563, Pr. 564)*

· On the cumulative energization time monitor (*Pr. 52* = "20"), the inverter running time is added up every hour.
· On the actual operation time monitor (*Pr. 52* = "23"), the inverter running time is added up every hour. (Time is not added up during a stop.)
· If the numbers of monitor value exceeds 65535, it is added up from 0. You can check the numbers of cumulative energization time monitor exceeded 65535h with *Pr. 563* and the numbers of actual operation time monitor exceeded 65535h with *Pr. 564*.
· Writing "0" in *Pr. 171* clears the actual operation time monitor. (Energization time monitor cannot be cleared.)

REMARKS
· The cumulative energization time does not increase if the power is ON for less than an hour.
· The actual operation time does not increase if the cumulative running time during power-ON status is less than an hour.
· If "0" is written in *Pr. 171* and *Pr. 171* is read again, "9999" is always displayed. Setting "9999" does not clear the actual operation time meter.

(6) You can select the decimal digits of the monitor *(Pr. 268)*

· As the operation panel (FR-DU07) display is 4 digits long, the decimal places may vary at analog input, etc. The decimal places can be hidden by selecting the decimal digits.
In such a case, the decimal digits can be selected by *Pr. 268*.

Pr. 268 Setting	Description
9999 (initial value)	No function
0	When 1 or 2 decimal places (0.1 increments or 0.01 increments) are monitored, the decimal places are dropped and the monitor displays an integer value (1 increments). The monitor value of 0.99 or less is displayed as 0.
1	When 2 decimal places (0.01 increments) are monitored, the 0.01 decimal place is dropped and the monitor displays the first decimal place (0.1 increments). When the monitor display digit is originally in 1 increments, it is displayed unchanged in 1 increments.

REMARKS
· The number of display digits on the cumulative energization time (*Pr. 52* = "20"), actual operation time (*Pr. 52* = "23"), cumulative power (*Pr. 52* = "25") or cumulative saving power monitor (*Pr. 52* = "51") does not change.

♦ Parameters referred to ♦

Pr. 30 Regenerative function selection, Pr. 70 Special regenerative brake duty ☞ *Refer to page 125*
Pr. 37 Speed display, Pr. 144 Speed setting switchover ☞ *Refer to page 150*
Pr. 55 Frequency monitoring reference, Pr. 56 Current monitoring reference ☞ *Refer to page 157*

4.12.3 FM, AM terminal function selection (Pr.55, Pr.56, Pr.867)

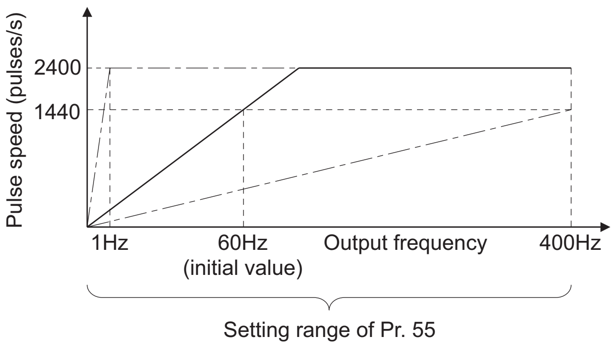
For signal output, two different output terminals are available: pulse train output terminal FM and analog output terminal AM.
You can select the signals output to the terminals FM, AM.

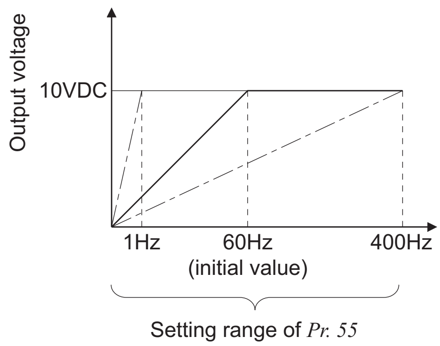
Parameter Number	Name	Initial Value	Setting Range		Description
55 *1	**Frequency monitoring reference**	60Hz *2	0 to 400Hz		Full-scale value when frequency monitor value is output to terminal FM and AM.
56 *1	**Current monitoring reference**	Rated inverter current *2	55K or lower	0 to 500A	Full-scale value when current monitor value is output to terminal FM and AM.
			75K or more	0 to 3600A	
867	**AM output filter**	0.01s	0 to 5s		Set the output filter of terminal AM.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
*1 This parameter allows its setting to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.
*2 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*

(1) Frequency monitoring reference *(Pr.55)*

- Set the full scale value when outputting the frequency monitor from terminal FM or AM.
- For the calibration of terminal FM, set the full-scale value of the connected meter when the pulse speed of terminal FM is 1440 pulse/s.
  Set the frequency to be indicated as the full scale value on the frequency meter (1mA analog meter) connected between terminal FM and SD. (For example, 60Hz or 120Hz.)
  Pulse speed is proportional to the output frequency of the inverter. (Maximum pulse train output is 2400 pulse/s.
- For the calibration of terminal AM, set the full-scale value of the connected meter when output voltage of terminal AM is 10VDC.
  Set the frequency to be indicated as the full scale value on the meter (10VDC voltmeter) connected between terminal AM and 5. (For example, 60Hz or 120Hz)
  Output voltage is proportional to the frequency. (Maximum output voltage is 10VDC.)



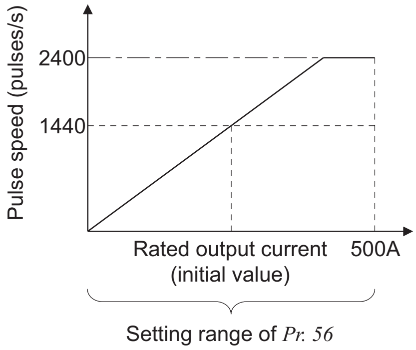


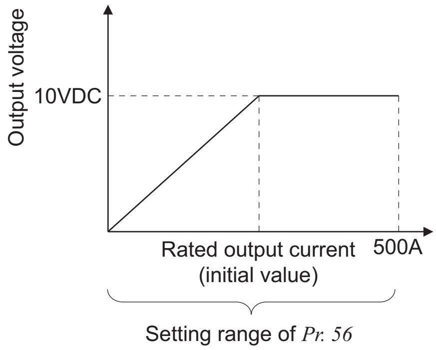
4

PARAMETERS

(2) Current monitoring reference *(Pr.56)*

- Set the full scale value when outputting the current monitor from terminal FM or AM.
- For calibration of terminal FM, set the full-scale value of the connected current meter when the pulse speed of terminal FM is 1440 pulse/s.
  Set the current to be indicated as the full scale value on the meter (1mA analog meter) connected between terminal FM and SD.
  Pulse speed is proportional to the monitored value of output current. (Maximum pulse train output is 2400 pulse/s.)
- For the calibration of terminal AM, set the full-scale value of the connected current meter when the output voltage of terminal AM is 10VDC.
  Set the current to be indicated as the full scale value on the meter (10VDC voltmeter) connected between terminal AM and 5.
  Output voltage is proportional to the monitored value of output current. (Maximum output voltage is 10VDC.)





(3) Terminal AM response adjustment *(Pr.867)*

- Using *Pr. 867*, the output voltage response of the terminal AM can be adjusted within the range 0 to 5s.
- Increasing the setting stabilizes the terminal AM output more but reduces the response level. (Setting "0" sets the response level to 7ms)

4.12.4 Terminal FM, AM calibration (Calibration parameter C0 (Pr. 900), C1 (Pr. 901))

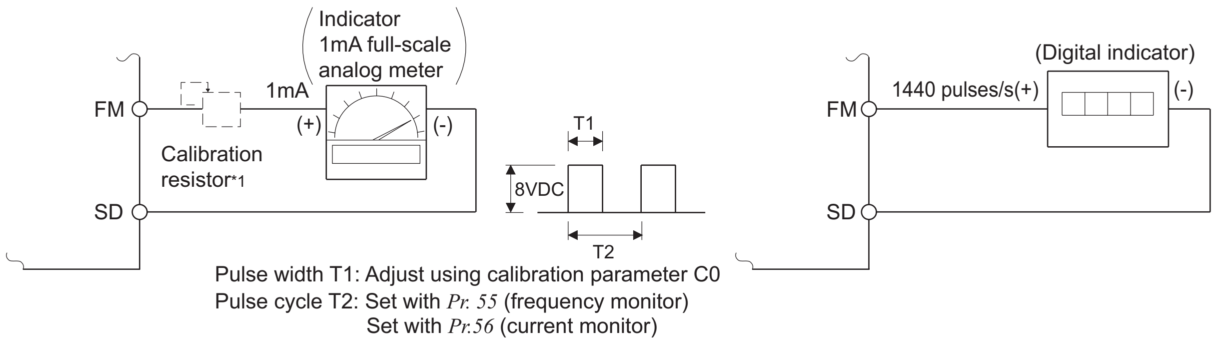
By using the operation panel or parameter unit, you can calibrate terminal FM and terminal AM to full scale deflection.

Parameter Number	Name	Initial Value	Setting Range	Description
C0(900) *1*2*3	FM terminal calibration	—	—	Calibrates the scale of the meter connected to terminal FM.
C1(901) *1*2*3	AM terminal calibration	—	—	Calibrates the scale of the analog meter connected to terminal AM.

*1 This parameter can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*
*2 This parameter number in parentheses is the one for use with the parameter unit (FR-PU04/FR-PU07).
*3 This parameter allows its setting to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.

(1) FM terminal calibration *(C0(Pr.900))*

- The terminal FM is preset to output pulses. By setting the *Calibration parameter C0 (Pr. 900)*, the meter connected to the inverter can be calibrated by parameter setting without use of a calibration resistor.
- Using the pulse train output of the terminal FM, a digital display can be provided by a digital counter. The monitor value is 1440 pulses/s output at the full-scale value of the table on the previous page *(Pr. 54 FM terminal function selection)*.



*1 Not needed when the operation panel (FR-DU07) or parameter unit (FR-PU04/FR-PU07) is used for calibration. Use a calibration resistor when the indicator (frequency meter) needs to be calibrated by a neighboring device because the indicator is located far from the inverter. However, the frequency meter needle may not deflect to full-scale if the calibration resistor is connected. In this case, perform calibration using the operation panel or parameter unit.

- Calibrate the terminal FM in the following procedure.
  1) Connect an indicator (frequency meter) across the terminals FM and SD of the inverter. (Note the polarity. The terminal FM is positive.)
  2) When a calibration resistor has already been connected, adjust the resistance to "0" or remove the resistor.
  3) Refer to the monitor description list *(page 152)* and set *Pr. 54*. When you selected the running frequency or inverter output current as the monitor, preset the running frequency or current value, at which the output signal will be 1440 pulses/s, to *Pr. 55 Frequency monitoring reference* or *Pr. 56 Current monitoring reference*. At 1440 pulses/s, the meter generally deflects to full-scale.

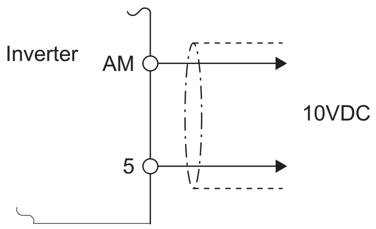
REMARKS

- When calibrating a monitor output signal, which cannot be adjusted to 100% value without an actual load and a measurement equipment, set *Pr. 54* to "21" (reference voltage output). 1440 pulses/s are output from the terminal FM. 1440 pulses/s are output from the terminal FM.
- The wiring length of the terminal FM should be 200m maximum.

CAUTION

- The initial value of the calibration parameter *C0 (Pr.900)* is set to 1mA full scale and 1440 pulse/s FM output frequency when the inverter output frequency is 60Hz. The maximum pulse train output of terminal FM is 2400 pulses/s.
- When a frequency meter is connected to across terminals FM-SD to monitor the running frequency, the FM terminal output is filled to capacity at the initial setting if the maximum output frequency reaches or exceeds 100Hz. In this case, the *Pr. 55* setting must be changed to the maximum frequency.

(2) AM terminal calibration *(C1(Pr.901))*



· Terminal AM is factory-set to provide a 10VDC output in the full-scale status of the corresponding monitor item. Calibration parameter *C1 (Pr. 901)* allows the output voltage ratios (gains) to be adjusted according to the meter scale. Note that the maximum output voltage is 10VDC.

· Calibrate the AM terminal in the following procedure.
1) Connect a 0-10VDC meter (frequency meter) to across inverter terminals AM and 5. (Note the polarity. The terminal AM is positive.)
2) Refer to the monitor description list *(page 152)* and set *Pr. 158*.
When you selected the running frequency or inverter output current as the monitor, preset the running frequency or current value, at which the output signal will be 10V, to *Pr. 55* or *Pr. 56*.
3) When outputting the item that cannot achieve a 100% value easily by operation, e.g. output current, set "21" (reference voltage output) in *Pr. 158* and perform the following operation. After that, set "2" (output current, for example) in *Pr. 158*.

REMARKS

· When calibrating a monitor output signal, which cannot be adjusted to 100% value without an actual load and a measurement equipment, set *Pr. 158* to "21" (reference voltage output).10VDC is output from the terminal AM.

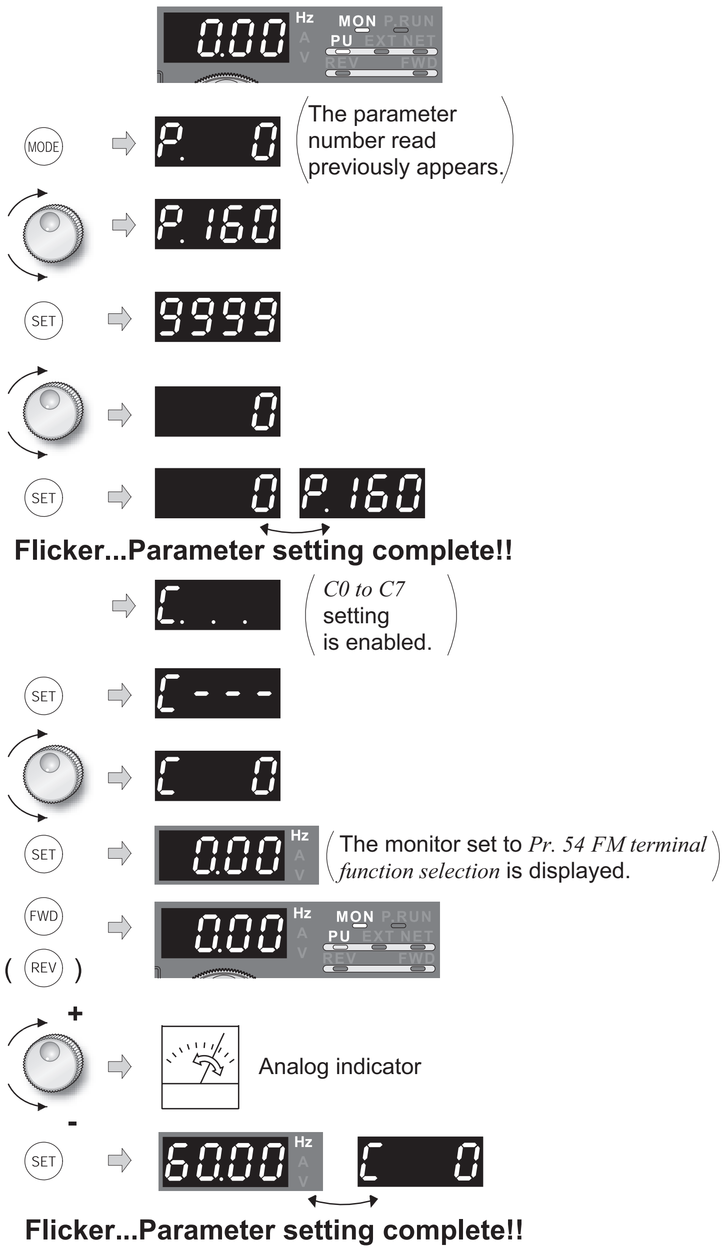
♦Parameters Referred to♦

Pr. 54 FM terminal function selection ☞ *Refer to page 152*
Pr. 55 Frequency monitoring reference ☞ *Refer to page 157*
Pr. 56 Current monitoring reference ☞ *Refer to page 157*
Pr. 158 AM terminal function selection ☞ *Refer to page 152*

4.12.5 How to calibrate the terminal FM when using the operation panel (FR-DU07)

Perform the following procedure to calibrate terminal FM using the operation panel FR-DU07. *Refer to page 159* for the details of parameters.

Operation / **Display** (When *Pr. 54*=1)



1. Confirmation of the RUN indicator and operation mode indicator
2. Press (MODE) to choose the parameter setting mode.
3. Turn the setting dial until P.160 appears.
4. Press (SET) to read the present set value. "9999" (initial value) appears.
5. Turn the setting dial to change it to the setting value of "0".
6. Press (SET) to set.
7. Turn the setting dial until C. . . appears.
8. Press (SET) to display C---.
9. Turn the setting dial until C 0 appears. Set to *C0 FM terminal calibration*.
10. Press (SET) to enable setting.
11. If the inverter is at a stop, (press (FWD) or (REV)) to start the inverter. (Motor needs not be connected.)
12. Turn the setting dial to adjust the indicator needle to the desired position.
13. Press (SET). Setting is complete.

- By turning the setting dial, you can read another parameter.
- Press (SET) to return to the C--- indication (step 8).
- Press (SET) twice to show the next parameter (Pr.CL).

REMARKS

- Calibration can also be made for external operation. Set the frequency in External operation mode, and make calibration in the above procedure.
- Calibration is available even during operation.
- For the operating procedure using the parameter unit (FR-PU04/FR-PU07), refer to the parameter unit instruction manual.

♦ Parameters referred to ♦

C0(Pr.900) FM terminal calibration ☞ *Refer to page 159*
C1(Pr.901) AM terminal calibration ☞ *Refer to page 159*

4.13 Operation selection at power failure and instantaneous power failure

Purpose	Parameter that must be Set		Refer to Page
At instantaneous power failure occurrence, restart inverter without stopping motor (general-purpose motor control)	**Automatic restart operation after instantaneous power failure / flying start**	**Pr. 57, Pr. 58, Pr. 162 to Pr. 165, Pr. 299, Pr. 611**	162
At instantaneous power failure occurrence, restart inverter without stopping motor (IPM motor control)	**Automatic restart operation after instantaneous power failure / flying start**	**Pr. 57, Pr. 162, Pr. 611**	166
When undervoltage or a power failure occurs, the inverter can be decelerated to a stop.	**Power failure-time deceleration-to-stop function**	**Pr. 261 to Pr. 266**	169

4.13.1 Automatic restart after instantaneous power failure/flying start under general-purpose motor control (Pr. 57, Pr. 58, Pr. 162 to Pr. 165, Pr. 299, Pr. 611)

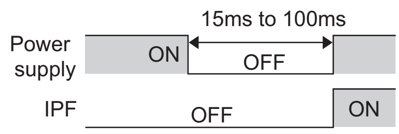
V/F S MFVC

You can restart the inverter without stopping the motor in the following cases.
- when bypass operation is switched to inverter operation
- when power comes back ON after an instantaneous power failure
- when motor is coasting at start

Parameter Number	Name	Initial Value	Setting Range		Description
57	**Restart coasting time**	9999	0		1.5K or lower .... 0.5s 2.2K to 7.5K .... 1s 11K to 55K .... 3.0s 75K or higher .... 5.0s The above times are coasting time.
			55K or lower	0.1 to 5s	Set the waiting time for inverter-triggered restart after an instantaneous power failure.
			75K or higher	0.1 to 30s	
			9999		No restart
58	**Restart cushion time**	1s	0 to 60s		Set a voltage starting time at restart.
162	**Automatic restart after instantaneous power failure selection**	0	0		With frequency search
			1		Without frequency search (Reduced voltage system)
			10		Frequency search at every start
			11		Reduced voltage system at every start
163	**First cushion time for restart**	0s	0 to 20s		Set a voltage starting time at restart. Consider using these parameters according to the load (moment of inertia, torque) magnitude.
164	**First cushion voltage for restart**	0%	0 to 100%		
165	**Stall prevention operation level for restart**	120%	0 to 150%		Considers the rated inverter current as 100% and set the stall prevention operation level during restart operation.
299	**Rotation direction detection selection at restarting**	9999	0		Without rotation direction detection
			1		With rotation direction detection
			9999		When *Pr. 78* = "0", the rotation direction is detected. When *Pr. 78* = "1","2", the rotation direction is not detected.
611	**Acceleration time at a restart**	55K or lower: 5s 75K or higher: 15s	0 to 3600s, 9999		Set the acceleration time to reach *Pr. 20 Acceleration/deceleration reference frequency* at a restart. Acceleration time for restart is the normal acceleration time (e.g. *Pr. 7*) when "9999" is set.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Automatic restart after instantaneous power failure operation

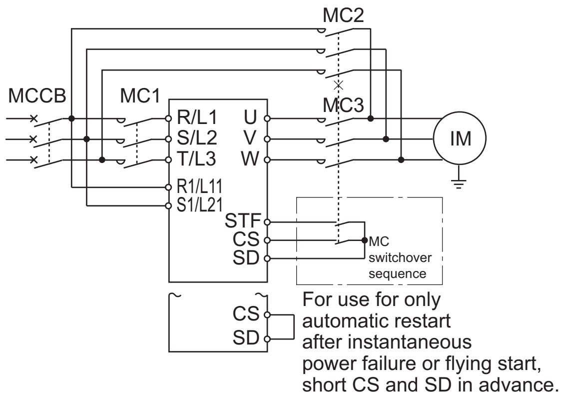


·When Instantaneous power failure protection (E.IPF) and undervoltage protection (E.UVT) are activated, the inverter output is shut off. (Refer to *page 316* for E.IPF and E.UVT.)
When automatic restart after instantaneous power failure operation is set, the motor can be restarted if power is restored after an instantaneous power failure and under voltage. (E.IPF and E.UVT are not activated.)

·When E.IPF and E.UVT are activated, instantaneous power failure/under voltage signal (IPF) is output.

·The IPF signal is assigned to the terminal IPF in the initial setting. The IPF signal can also be assigned to the other terminal by setting "2 (positive logic) or 102 (negative logic)" in any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

(2) Connection (CS signal)



·When the automatic restart after instantaneous power failure selection signal (CS) is turned ON, automatic restart operation is enabled.

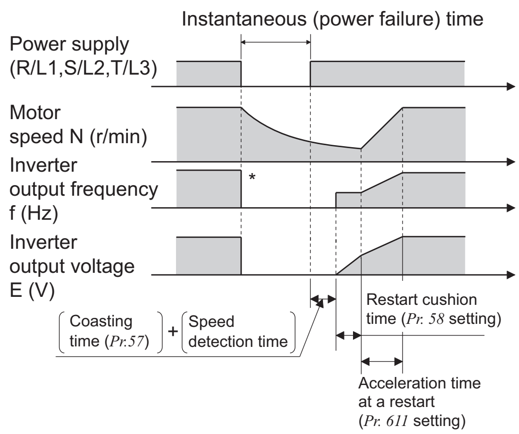
·When *Pr. 57* is set to other than "9999" (automatic restart operation enabled), the inverter will not operate if used with the CS signal remained OFF.

REMARKS

· The CS signal is assigned to the terminal CS in the initial setting. By setting "6" in any of *Pr. 178 to Pr. 189 (input terminal function selection),* you can assign the CS signal to the other terminal.

(3) Automatic restart operation selection *(Pr. 162, Pr. 299)*

When *Pr. 162* = 0, 10 (with frequency search)



* The output shut off timing differs according to the load condition.

●With frequency search

When "0 (initial value), 10" is set in *Pr. 162*, the inverter smoothly starts after detecting the motor speed upon power restoration.

·During reverse rotation, the inverter can be restarted smoothly as the direction of rotation is detected.

·You can select whether to make rotation direction detection or not with *Pr. 299 "Rotation direction detection selection at restarting"*. When capacities of the motor and inverter differ, set "0" (without rotation direction detection) in *Pr. 299*.

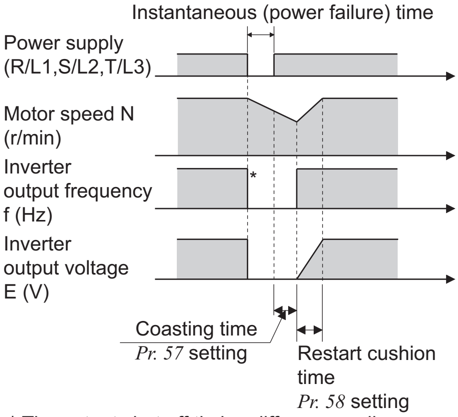
Pr.299 Setting	*Pr.78* Setting		
	0	1	2
9999 (initial value)	○	×	×
0	×	×	×
1	○	○	○

○: with rotation direction detection
×: with rotation direction detection

REMARKS

· Speed detection time (frequency search) changes according to the motor speed. (maximum 500ms)
· When the inverter capacity is two rank or more larger than the motor capacity, the inverter may not start due to overcurrent trip (E.OC□).
· If two or more motors are connected to one inverter, the inverter functions abnormally. (The inverter does not start properly.)
· Since the DC injection brake is operated instantaneously when the speed is detected at a restart, the speed may reduce if the moment of inertia of the load is small.
· When reverse rotation is detected when *Pr. 78*="1" (reverse rotation disabled), the rotation direction is changed to forward rotation after decelerates in reverse rotation when the start command is forward rotation. The inverter will not start when the start command is reverse rotation.

When *Pr. 162* = 1, 11 (without frequency search)



* The output shut off timing differs according to the load condition.

●Without frequency search

When *Pr. 162* = "1, 11", automatic restart operation is performed in a reduced voltage system, where the voltage is gradually risen with the output frequency unchanged from prior to an instantaneous power failure independently of the coasting speed of the motor.

REMARKS

· This system stores the output frequency prior to an instantaneous power failure and increases the voltage. Therefore, if the instantaneous power failure time exceeds 0.2s, the inverter starts at *Pr. 13 Starting frequency* (initial value = 0.5Hz) since the stored output frequency cannot be retained.

●Restart operation at every start

When *Pr. 162* = "10" or "11", automatic restart operation is also performed every start, in addition to the automatic restart after instantaneous power failure. When *Pr. 162* = "0", automatic restart operation is performed at the first start after power supply-ON, but not performed at the second time or later.

(4) Restart coasting time *(Pr. 57)*

·Coasting time is the time from when the motor speed is detected until automatic restart control is started.

·Set *Pr. 57* to "0" to perform automatic restart operation. The coasting time is automatically set to the value below. Generally this setting will pose no problems.

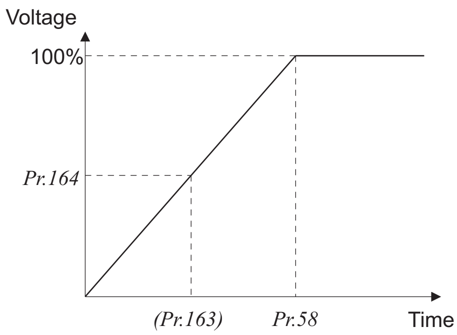
1.5K or lower...... 0.5s, 2.2K to 7.5K...... 1s, 11K to 55K...... 3.0s, 75K or higher...... 5.0s

·Operation may not be performed well depending on the magnitude of the moment of inertia(J) of the load or operation frequency. Adjust the coasting time between 0.1s and 5s according to the load specifications.

(5) Restart cushion time *(Pr. 58)*

·Cushion time is the length of time taken to raise the voltage appropriate to the detected motor speed (output frequency prior to instantaneous power failure when *Pr. 162* = "1" or "11").

·Normally the initial value need not be changed for operation, but adjust it according to the magnitude of the moment of inertia(J) of the load or torque magnitude.



(6) Automatic restart operation adjustment *(Pr. 163 to Pr. 165, Pr. 611)*

·Using *Pr. 163* and *Pr. 164*, you can adjust the voltage rise time at a restart as shown on the left.

·Using *Pr. 165*, you can set the stall prevention operation level at a restart.

·Using *Pr. 611*, you can set the acceleration time until *Pr. 20 Acceleration/deceleration reference frequency* is reached after automatic restart operation is performed besides the normal acceleration time.

REMARKS

· Even if the *Pr. 21 Acceleration/deceleration time increments* setting is changed, the setting increments of *Pr. 611* remain unchanged.

CAUTION

· Changing the terminal assignment using *Pr. 178 to Pr. 196 (I/O terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.
· When automatic restart operation is selected, undervoltage protection (E.UVT) and instantaneous power failure protection (E.IPF) among the fault output signals will not be provided at occurrence of an instantaneous power failure.
· The SU and FU signals are not output during a restart. They are output after the restart cushion time has elapsed.
· Automatic restart operation will also be performed after a reset when a retry is made by the retry function.

⚠ CAUTION

⚠ Provide mechanical interlocks for MC1 and MC2. (Under V/F control or Simple magnetic flux vector control) The inverter will be damaged if the power supply is input to the inverter output section.

⚠ When automatic restart after instantaneous power failure has been selected, the motor and machine will start suddenly (after the reset time has elapsed) after occurrence of an instantaneous power failure. Stay away from the motor and machine. When you have selected automatic restart after instantaneous power failure function, apply in easily visible places the CAUTION stickers supplied to the Instruction Manual (Basic).

♦ Parameters referred to ♦

Pr. 7 Acceleration time, Pr. 21 Acceleration/deceleration time increments ☞ *Refer to page 109*
Pr. 13 Starting frequency ☞ *Refer to page 113*
Pr. 65, Pr. 67 to Pr. 69 Retry function ☞ *Refer to page 172*
Pr. 78 Reverse rotation prevention selection ☞ *Refer to page 201*
Pr. 178 to Pr. 189 (input terminal function selection) ☞ *Refer to page 133*

4.13.2 Automatic restart after instantaneous power failure/flying start under IPM motor control (Pr. 57, Pr. 162, Pr. 611) IPM

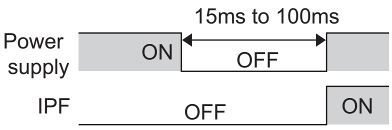
You can restart the inverter without stopping the motor in the following cases:

- When power comes back ON after an instantaneous power failure
- When motor is coasting at start

Parameter Number	Name	Initial Value	Setting Range	Description
57	Restart coasting time	9999	0	No waiting time
			55K or lower: 0.1 to 5s	Set the waiting time for inverter-triggered restart after an instantaneous power failure.
			75K or higher: 0.1 to 30s	
			9999	No restart
162	Automatic restart after instantaneous power failure selection	0	0, 1	Frequency search at an initial start
			10, 11	Frequency search at every start
611	Acceleration time at a restart	55K or lower: 5s	0 to 3600s, 9999	Set the acceleration time that takes to reach *Pr.20 Acceleration/deceleration reference frequency* setting at a restart. When "9999" is set, standard acceleration time (like *Pr.7*) is applied at restart.
		75K or higher: 15s		

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Automatic restart after instantaneous power failure operation



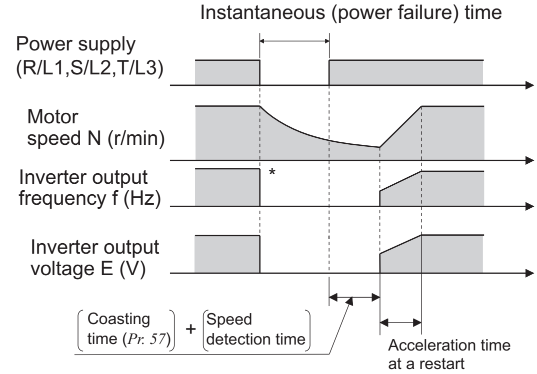
- When instantaneous power failure protection (E.IPF) is activated, the inverter output is shut off. (*Refer to page 316* for E.IPF)
  When automatic restart after instantaneous power failure operation is set, the motor can be restarted if power is restored after an instantaneous power failure. (E.IPF is not activated.)
- When E.IPF is activated, instantaneous power failure signal (IPF) is output.
- The IPF signal is assigned to the terminal IPF in the initial setting. The IPF signal can also be assigned to the other terminal by setting "2 (positive logic) or 102 (negative logic)" to any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

(2) Connection (CS signal)

- When the automatic restart after instantaneous power failure selection signal (CS) is turned on, automatic restart operation is enabled.
- When *Pr. 57* is set to other than "9999" (automatic restart operation enabled), the inverter will not operate if used with the CS signal off.

CAUTION

- The CS signal can be assigned to the input terminal using any of *Pr. 178 to Pr. 189 (Input terminal function selection)*. Changing the terminal assignment may affect the other functions. Set parameters after confirming the function of each terminal.
- When automatic restart operation is selected, instantaneous power failure occurrence (E.IPF) among the alarm output signals will not be provided at occurrence of an instantaneous power failure.
- The SU and FU signals are not output during a restart. They are output after the restart cushion time has elapsed.
- Automatic restart operation will also be performed after a reset or when a retry is made by the retry function.



* The output shut off timing differs according to the load condition.

(3) Automatic restart operation selection *(Pr. 162)*

·The inverter smoothly starts after detecting the motor speed (frequency search) upon power restoration.
·During reverse rotation, the inverter can be restarted smoothly as the direction of rotation is detected.

REMARKS

· Since the DC injection brake is operated instantaneously when the speed is detected at a restart, the speed may reduce if the moment of inertia (J) of the load is small.

· Restart operation at every start

When *Pr. 162* = "10 , (11)", automatic restart operation is also performed every start, in addition to the automatic restart after instantaneous power failure. When *Pr. 162* = "0, (1)" automatic restart operation is performed at the first start after power supply-on, but starts at starting frequency at the second time or later.

REMARKS

· Automatic restart operation with reduced voltage is not available under IPM motor control. While *Pr. 162* = "1 or 11," automatic restart operation is performed with a frequency search (setting "0 or 10").

(4) Restart coasting time *(Pr. 57)*

·Coasting time is the time from when the motor speed is detected until automatic restart control is started.
·Set *Pr. 57* to "0" (without coasting time) to perform automatic restart operation.
Generally this setting will pose no problems.
·Operation may not be performed well depending on the magnitude of the moment of inertia (J) of the load or running frequency. Adjust the coasting time between 0.1s and 5s according to the load specifications.

(5) Automatic restart operation adjustment *(Pr. 611)*

·Using *Pr.611*, the acceleration time to reach *Pr.20 Acceleration/deceleration reference frequency* can be set. This can be set separately from the normal acceleration time.

REMARKS

· Even if the *Pr.21 Acceleration/deceleration time increments* setting is changed, the setting increments of *Pr. 611* remain unchanged.

CAUTION

An IPM motor is a motor with interior permanent magnets. Regression voltage is generated when the motor coasts at an instantaneous power failure or makes a flying start. The inverter's DC bus voltage increases if the motor coasts fast or makes a flying start in this condition.
When using the automatic restart after instantaneous power failure function (*Pr. 57 Restart coasting time* ≠ "9999"), it is recommended to use the regenerative avoidance operation (*Pr. 882 Regeneration avoidance operation selection* = "1") in combination for more a stable start. If the overvoltage protective function (E.OV□) activates at restart even with the regeneration avoidance function, additionally use the retry function (*Pr. 67*).

⚠CAUTION

⚠ An IPM motor is a motor with interior permanent magnets. High voltage is generated at motor terminals while the motor is running. Do not touch motor terminals and other parts until the motor stops to prevent an electric shock.

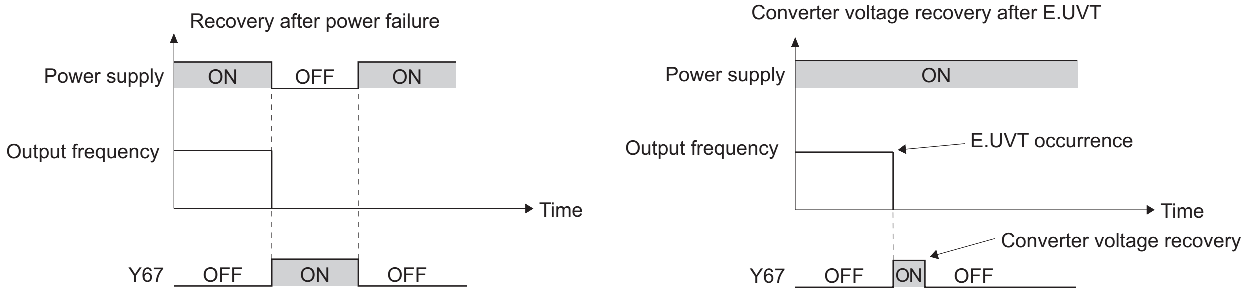
⚠ When automatic restart after instantaneous power failure has been selected, the motor and machine will start suddenly (after the reset time has elapsed) after occurrence of an instantaneous power failure.
Stay away from the motor and machine.
When you have selected the automatic restart after instantaneous power failure function, apply in easily visible places the CAUTION stickers supplied.

♦Parameters Referred to♦

Pr. 13 Starting frequency ☞ *Refer to page 113*
Pr. 65, Pr. 67 to Pr. 69 Retry function ☞ *Refer to page 172*
Pr. 78 Reverse rotation prevention selection ☞ *Refer to page 201*
Pr. 178 to Pr. 189 (input terminal function selection) ☞ *Refer to page 133*
Pr. 882 Regeneration avoidance operation selection ☞ *Refer to page 279*

4.13.3 Power failure signal (Y67 signal)

When output is shutoff due to a power failure or undervoltage, the Y67 signal turns ON regardless of the automatic restart after instantaneous power failure function setting.
Y67 signal turns OFF at power failure recovery or undervoltage recovery.
To use Y67 signal, set "67 (positive logic) or 167 (negative logic)" in any of *Pr. 190* to *Pr. 192* (Output terminal function selection) to assign the function.



CAUTION

· Changing the terminal assignment using *Pr.190* to *Pr.196* (Output terminal function selection) may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 190 to Pr. 196 (output terminal function selection) ☞ Refer to page 140

4.13.4 Power failure-time deceleration-to-stop function (Pr. 261 to Pr. 266)

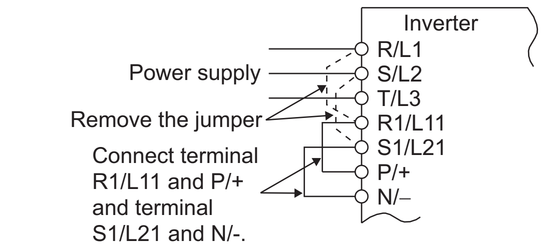
When a power failure or undervoltage occurs, the inverter can be decelerated to a stop or can be decelerated and re-accelerated to the set frequency.

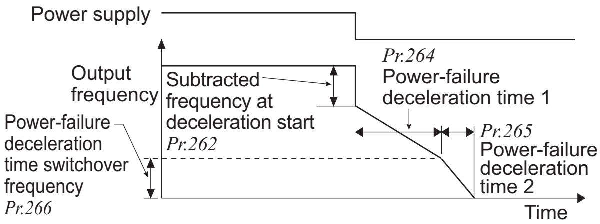
Parameter Number	Name	Initial Value	Setting Range	Description		
				Operation at undervoltage or power failure	**At power restoration during power failure deceleration**	**Deceleration time to a stop**
261	**Power failure stop selection**	0	0	Coasts to a stop	Coasts to a stop	—
			1	Decelerates to a stop	Decelerates to a stop	Depends on *Pr. 262* to *Pr. 266* settings
			2	Decelerates to a stop	Accelerates again	Depends on *Pr. 262* to *Pr. 266* settings
			21	Decelerates to a stop	Decelerates to a stop	Automatically adjusts the deceleration time
			22	Decelerates to a stop	Accelerates again	Automatically adjusts the deceleration time
262	**Subtracted frequency at deceleration start**	3Hz	0 to 20Hz	Normally operation can be performed with the initial value unchanged. But adjust the frequency according to the magnitude of the load specifications (moment of inertia, torque).		
263	**Subtraction starting frequency**	60Hz *2	0 to 120Hz	When output frequency ≥ *Pr. 263* Decelerate from the speed obtained from output frequency minus *Pr. 262*. When output frequency < *Pr. 263* Decelerate from output frequency		
			9999	Decelerate from the speed obtained from output frequency minus *Pr. 262*.		
264	**Power-failure deceleration time 1**	5s	0 to 3600/ 360s *1	Set a deceleration slope down to the frequency set in *Pr. 266*.		
265	**Power-failure deceleration time 2**	9999	0 to 3600/ 360s *1	Set a deceleration slope below the frequency set in *Pr. 266*.		
			9999	Same slope as in *Pr. 264*		
266	**Power failure deceleration time switchover frequency**	60Hz *2	0 to 400Hz	Set the frequency at which the deceleration slope is switched from the *Pr. 264* setting to the *Pr. 265* setting.		

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

*1 When the setting of *Pr. 21 Acceleration/deceleration time increments* is "0" (initial value), the setting range is "0 to 3600s" and the setting increments are "0.1s", and when the setting is "1", the setting range is "0 to 360s" and the setting increments are "0.01s"

*2 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*





(1) Connection and parameter setting

- Remove the jumpers across terminals R/L1 and R1/L11 and across terminals S/L2 and S1/L21, and connect terminals R1/L11 and P/+ and terminals S1/L21 and N/-.
- When setting of *Pr. 261* is not "0", the motor decelerates to a stop if an undervoltage, power failure or input phase loss (when *Pr. 872* ="1"(input phase loss enabled)) occurs.

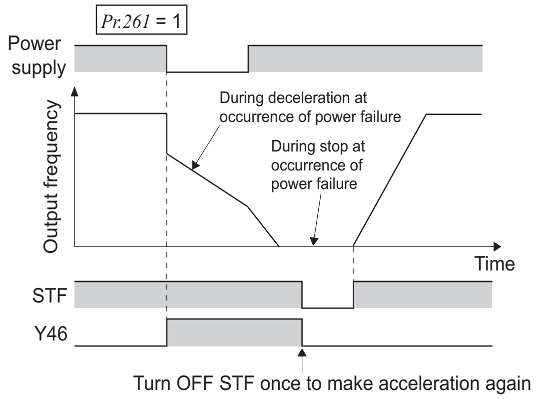
(2) Operation outline of deceleration to stop at power failure

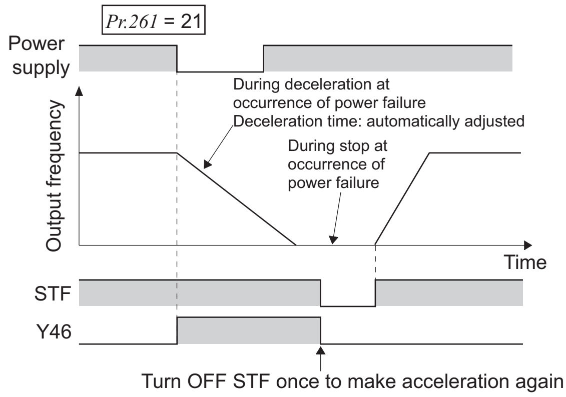
- If an undervoltage or power failure occurs, the output frequency is dropped by the frequency set in *Pr. 262* .
- Deceleration is made in the deceleration time set in *Pr. 264*. (The deceleration time setting is the time required from *Pr. 20 Acceleration/deceleration reference frequency* to a stop.)
- Change the deceleration time (slope) to a stop using *Pr.265* when the frequency is too low to obtain the regenerative energy, or in other instances.
- With the *Pr.261* = "21 or 22" setting, the deceleration time is automatically adjusted to keep (DC bus) voltage constant in the converter when the motor decelerates to a stop.
  (The *Pr.262 to Pr.266* settings become invalid.)

(3) Power failure stop function (*Pr. 261* = "1, 21")

· If power is restored during power failure deceleration, deceleration to a stop is continued and the inverter remains stopped. To restart, turn OFF the start signal once, then turn it ON again.

· With the *Pr.261* = "21" setting, the deceleration time is automatically adjusted to keep (DC bus) voltage constant in the converter when the motor decelerates to a stop at a power failure. (The *Pr.262 to Pr.266* settings become invalid.)

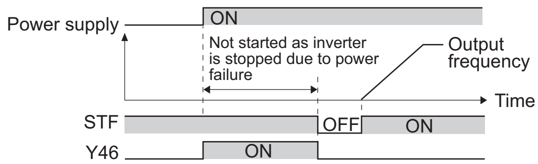




REMARKS

· When automatic restart after instantaneous power failure is selected (*Pr. 57* ≠ "9999"), deceleration to stop function is invalid and the restart after instantaneous power failure operation is performed.

· When the power failure deceleration stop function is active (*Pr.261* ≠ "1, 21"), the inverter will not start even if the power is turned ON with the start signal (STF/STR) ON. After switching ON the power supply, turn OFF the start signal once and then ON again to make a start.



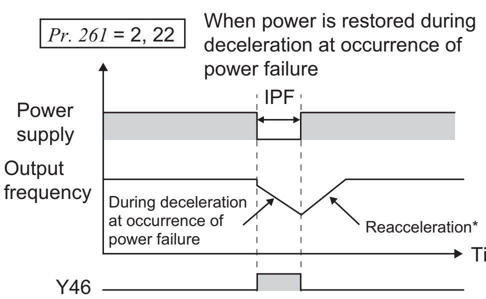
(4) Operation continuation at instantaneous power failure function (*Pr. 261* = "2, 22")

· When power is restored during deceleration after an instantaneous power failure, acceleration is made again up to the set frequency.

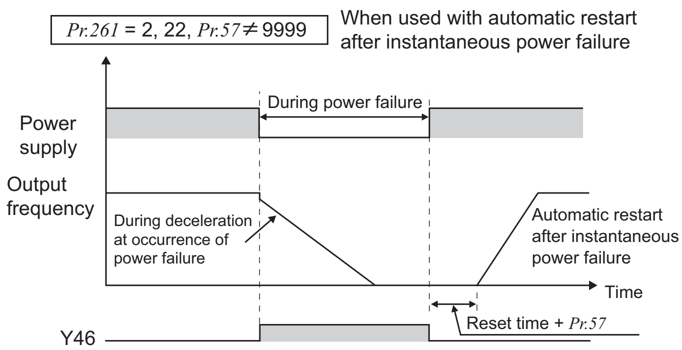
· When this function is used in combination with the automatic restart after instantaneous power failure operation, deceleration is available at a power failure and acceleration is available again after power restoration. When power is restored after a stop by deceleration at an instantaneous power failure, automatic restart operation is performed if automatic restart after instantaneous power failure has been selected (*Pr. 57* ≠ "9999")

· With the *Pr.261*="22" setting, the deceleration time is automatically adjusted to keep (DC bus) voltage constant in the converter when the motor decelerates to a stop at a power failure. The motor re-accelerates to the set frequency if the power is restored during the deceleration to stop.

· Setting *Pr. 261* = "22" disables the settings of *Pr. 262* to *Pr. 266*.



* Acceleration time depends on *Pr. 7* (*Pr. 44*).



(5) Power failure deceleration signal (Y46 signal)

- After a power failure stop, inverter cannot start even if power is restored and the start command is given. In this case, check the power failure deceleration signal (Y46 signal). (at occurrence of input phase loss protection (E.ILF), etc.)
- The Y46 signal is on during deceleration at an instantaneous power failure or during a stop after deceleration at an instantaneous power failure.
- For the Y46 signal, set "46 (forward action)" or "146 (reverse action)" in any of *Pr. 190 to Pr. 196 (output terminal function selection)* to assign the function.

REMARKS

· Stop selection function is disabled while inverter decelerates due to a power failure, even though stop selection *(Pr.250)* is set.

CAUTION

- When *Pr. 30 Regenerative function selection* = "2" (FR-HC, MT-HC, FR-CV is used), the power failure deceleration function is invalid.
- When the (output frequency - *Pr. 262*) at undervoltage or power failure occurrence is negative, the calculation result is regarded as 0Hz. (DC injection brake operation is performed without deceleration).
- During a stop or trip, the power failure stop selection is not performed.
- Y46 signal turns on when undervoltage occurs even when the motor is not decelerating at an instantaneous power failure. For this reason, Y46 signal outputs instantly at powering OFF, which is not a fault.
- When power failure deceleration stop function is selected, undervoltage protection (E.UVT), instantaneous power failure protection (E.IPF), and input phase loss protection (E.ILF) do not function.
- Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other terminals. Set parameters after confirming the function of each terminal.

⚠ CAUTION

⚠ Even if the power failure stop function is valid, some loads may cause the inverter to trip and the motor to coast. The motor will coast if enough regenerative energy is given from the motor.

♦ Parameters referred to ♦

Pr. 12 DC injection brake operation voltage ☞ *Refer to page 123*
Pr. 20 Acceleration/deceleration reference frequency, Pr. 21 Acceleration/deceleration time increments ☞ *Refer to page 109*
Pr. 30 Regenerative function selection ☞ *Refer to page 125*
Pr. 57 Restart coasting time ☞ *Refer to page 162*
Pr. 190 to Pr. 196 (output terminal function selection) ☞ *Refer to page 140*
Pr. 872 Input phase loss protection selection ☞ *Refer to page 175*

4.14 Operation setting at fault occurrence

Purpose	Parameter that must be Set		Refer to Page
Recover by retry operation at fault occurrence	**Retry operation**	**Pr. 65, Pr. 67 to Pr. 69**	172
Output fault code from terminal	**Fault code output function**	**Pr. 76**	174
Do not input/output phase loss alarm	**Input/output phase loss protection selection**	**Pr. 251, Pr. 872**	175

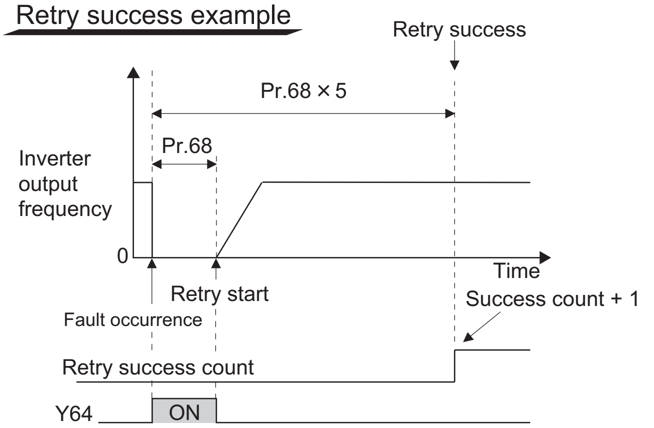
4.14.1 Retry function (Pr. 65, Pr. 67 to Pr. 69)

If a fault occurs, the inverter resets itself automatically to restart. You can also select the fault for a retry.
When automatic restart after instantaneous power failure is selected (*Pr. 57 Restart coasting time* ≠ "9999"), restart operation is performed at retry operation as at an instantaneous power failure. (Refer to *page 162* for the restart function.)

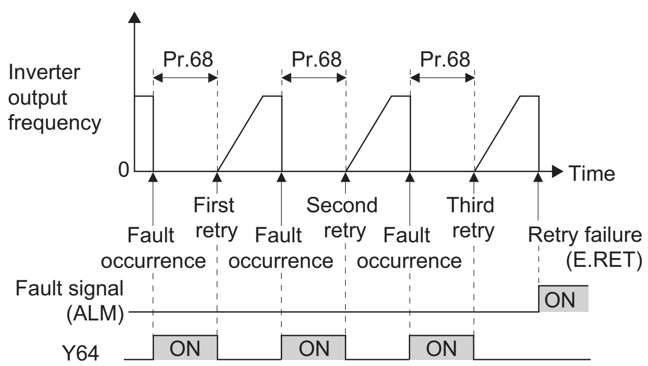
Parameter Number	Name	Initial Value	Setting Range	Description
65	**Retry selection**	0	0 to 5	A fault for retry can be selected. *(Refer to the next page)*
67	**Number of retries at fault occurrence**	0	0	No retry function
			1 to 10	Set the number of retries at fault occurrence. A fault output is not provided during retry operation.
			101 to 110	Set the number of retries at fault occurrence. (The setting value of minus 100 is the number of retries.) A fault output is provided during retry operation.
68	**Retry waiting time**	1s	0 to 10s	Set the waiting time from when an inverter fault occurs until a retry is made.
69	**Retry count display erase**	0	0	Clear the number of restarts succeeded by retry.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

Retry success example



Retry failure example



- Retry operation automatically resets a fault and restarts the inverter at the starting frequency when the time set in *Pr. 68* elapses after the inverter is tripped.
- Retry operation is performed by setting *Pr. 67* to any value other than "0". Set the number of retries at fault occurrence in *Pr. 67*.
- When retries fail consecutively more than the number of times set in *Pr. 67*, a retry count excess fault (E.RET) occurs, resulting in inverter trip.
  (Refer to retry failure example)
- Use *Pr. 68* to set the waiting time from when the inverter trips until a retry is made in the range 0 to 10s.
- Reading the *Pr. 69* value provides the cumulative number of successful restart times made by retry. The cumulative count in *Pr. 69* is increased by 1 when a retry is regarded as successful after normal operation continues without faults occurring for more than four times longer than the time set in *Pr. 68* after a retry start.
  (When retry is successful, cumulative number of retry failure is cleared.)
- Writing "0" in *Pr. 69* clears the cumulative count.
- During a retry, the Y64 signal is ON. For the Y64 signal, assign the function by setting "64 (positive operation)" or "164 (negative operation)" in any of *Pr. 190 to Pr. 196 (output terminal function selection)* .

CAUTION

Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

· Use *Pr. 65* to select the fault to be activated for retries. No retry will be made for the fault not indicated. (Refer to *page 310* for the fault description.)
● indicates the errors selected for retry.

Fault for Retry	Pr. 65 Setting					
	0	1	2	3	4	5
E.OC1	●	●		●	●	●
E.OC2	●	●		●	●	
E.OC3	●	●		●	●	●
E.OV1	●		●	●	●	
E.OV2	●		●	●	●	
E.OV3	●		●	●	●	
E.THM	●					
E.THT	●					
E.IPF	●				●	
E.UVT	●				●	
E.BE	●				●	
E. GF	●				●	

Fault for Retry	Pr. 65 Setting					
	0	1	2	3	4	5
E.OHT	●					
E.OLT	●				●	
E.OPT	●				●	
E.OP1	●				●	
E. PE	●				●	
E.PTC	●					
E.CDO	●				●	
E.SER	●				●	
E.ILF	●				●	
E.SOT	●	●		●	●	●
E.PID	●				●	

CAUTION

· For a retry error, only the description of the first fault is stored.
· When an inverter fault is reset by the retry function at the retry time, the accumulated data of the electronic thermal relay function, regenerative brake duty etc. are not cleared. (Different from the power-ON reset.)
· Retry is not performed if E.PE (Parameter storage device fault) occurred at power ON.
· If a fault that is not selected for a retry occurs during retry operation (retry waiting time), the retry operation stops while the fault indication is still displayed.
· The retry function is invalid for the fault initiated by the fault initiation function.

⚠ CAUTION

⚠ When you have selected the retry function, stay away from the motor and machine in the case of the inverter is tripped. The motor and machine will start suddenly (after the reset time has elapsed) after the inverter trip.
When you have selected the retry function, apply in easily visible places the CAUTION stickers supplied.

♦ Parameters referred to ♦

Pr. 57 Restart coasting time ☞ *Refer to page 162*

4
PARAMETERS

4.14.2 Fault code output selection (Pr.76)

At fault occurrence, its description can be output as a 4-bit digital signal from the open collector output terminals. The fault code can be read by a programmable controller, etc., and its corrective action can be shown on a display, etc.

Parameter Number	Name	Initial Value	Setting Range	Description
76	Fault code output selection	0	0	Without fault code output
			1	With fault code output *(Refer to the following table)*
			2	Fault code output at fault occurrence only *(Refer to the following table)*

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

- By setting *Pr. 76* to "1" or "2", the fault code can be output to the output terminals.
- When the setting is "2", a fault code is output at only fault occurrence, and during normal operation, the terminals output the signals assigned to *Pr. 191 to Pr. 194 (output terminal function selection)*.
- The following table indicates fault codes to be output. (0: output transistor OFF, 1: output transistor ON)

Operation Panel Indication (FR-DU07)	Output of Output Terminals				Fault Code
	SU	IPF	OL	FU	
Normal *	0	0	0	0	0
E.OC1	0	0	0	1	1
E.OC2	0	0	1	0	2
E.OC3	0	0	1	1	3
E.OV1 to E.OV3	0	1	0	0	4
E.THM	0	1	0	1	5
E.THT	0	1	1	0	6
E.IPF	0	1	1	1	7
E.UVT	1	0	0	0	8
E.FIN	1	0	0	1	9
E. BE	1	0	1	0	A
E. GF	1	0	1	1	B
E.OHT	1	1	0	0	C
E.OLT	1	1	0	1	D
E.OPT	1	1	1	0	E
E.OP1	1	1	1	0	E
Other than the above	1	1	1	1	F

* When *Pr. 76* = "2", the output terminals output the signals assigned to *Pr. 191 to Pr. 194*.

CAUTION

- When a value other than "0" is set in *Pr.76*
  When a fault occurs, the output terminals SU, IPF, OL, FU output the signal in the above table, independently of the *Pr. 191 to Pr. 194 (output terminal function selection)* settings. Please be careful when inverter control setting has been made with the output signals of *Pr. 191 to Pr. 194.*

♦ Parameters referred to ♦

Pr. 191 to Pr. 194 (output terminal function selection) ☞ *Refer to page 140*

4.14.3 Input/output phase loss protection selection (Pr. 251, Pr. 872)

You can disable the output phase loss protection function that stops the inverter output if one phase of the inverter output side (load side) three phases (U, V, W) is lost.
The input phase loss protection selection of the inverter input side (R/L1, S/L2, T/L3) can be valid.

Parameter Number	Name	Initial Value	Setting Range	Description
251	**Output phase loss protection selection**	1	0	Without output phase loss protection
			1	With output phase loss protection
872	**Input phase loss protection selection**	0	0	Without input phase loss protection
			1	With input phase loss protection

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Output phase loss protection selection *(Pr. 251)*

- When *Pr. 251* is set to "0", output phase loss protection (E.LF) becomes invalid.

(2) Input phase loss protection selection *(Pr. 872)*

- When *Pr. 872* is set to "1", input phase loss protection (E.ILF) is provided if a phase loss of one phase among the three phases is detected for 1s continuously.

REMARKS

If input phase is lost when *Pr. 872* = "1" (with input phase loss protection) and *Pr. 261* ≠ "0" (power failure stop function valid), input phase loss protection (E.ILF) is not provided but power-failure deceleration is made.

CAUTION

- When an input phase loss occurs in the R/L1 and S/L2 phases, input phase loss protection is not provided but the inverter output is shut off.
- If an input phase loss continues for a long time, the converter section and capacitor lives of the inverter will be shorter.

♦ Parameters referred to ♦

Pr. 261 Power failure stop selection ☞ *Refer to page 169*

4.15 Energy saving operation and energy saving monitor

Purpose	Parameter that must be Set		Refer to Page
Energy saving operation	**Energy saving operation and Optimum excitation control**	**Pr. 60**	176
How much energy can be saved	**Energy saving monitor**	**Pr. 52, Pr. 54, Pr. 158, Pr. 891 to Pr. 899**	177

4.15.1 Energy saving control and Optimum excitation control (Pr. 60) V/F

Without a fine parameter setting, the inverter automatically performs energy saving control.
This inverter is optimum for fan and pump applications.

Parameter Number	Name	Initial Value	Setting Range	Description
60	**Energy saving control selection ***	0	0	Normal operation mode
			4	Energy saving operation mode
			9	Optimum excitation control mode

* When parameter is read using the FR-PU04, a parameter name different from an actual parameter is displayed.

(1) Energy saving operation mode (Setting "4")

· When "4" is set in *Pr. 60*, the inverter operates in the energy saving operation mode.
· In the energy saving operation mode, the inverter automatically controls the output voltage to minimize the inverter output voltage during a constant operation.

REMARKS

· For applications a large load torque is applied to or machines repeat frequent acceleration/deceleration, an energy saving effect is not expected.

(2) Optimum excitation control mode (Setting "9")

· When "9" is set in *Pr. 60*, the inverter operates in the Optimum excitation control mode.
· The Optimum excitation control mode is a control method which controls excitation current to improve the motor efficiency to maximum and determines output voltage as an energy saving method.

REMARKS

· When the motor capacity is too small as compared to the inverter capacity or two or more motors are connected to the inverter, the energy saving effect is not expected.

CAUTION

· When the energy saving mode and Optimum excitation control mode are selected, deceleration time may be longer than the setting value. Since overvoltage fault tends to occur as compared to the constant-torque load characteristics, set a longer deceleration time.
· Since output voltage is controlled in energy saving operation mode and by Optimum excitation control, output current may slightly increase.

♦ Parameters referred to

Pr. 80 Motor capacity ☞ *Refer to page 89*

4.15.2 Energy saving monitor (Pr. 891 to Pr. 899)

From the power consumption estimated value during commercial power supply operation, the energy saving effect by use of the inverter can be monitored/output.

Parameter Number	Name	Initial Value	Setting Range		Description
52	**DU/PU main display data selection**	0 (output frequency)	0, 5, 6, 8 to 14, 17, 20, 23 to 25, 50 to 57, 100		50: Power saving monitor 51: Cumulative saving power monitor
54	**FM terminal function selection**	1 (output frequency)	1 to 3, 5, 6, 8 to 14, 17, 21, 24, 50, 52, 53		50:Power saving monitor
158	**AM terminal function selection**				
891	**Cumulative power monitor digit shifted times**	9999	0 to 4		Set the number of times to shift the cumulative power monitor digit Clamps the monitor value at maximum.
			9999		No shift Clears the monitor value when it exceeds the maximum value.
892	**Load factor**	100%	30 to 150%		Set the load factor for commercial power-supply operation. Multiplied by the power consumption rate *(page 180)* during commercial power supply operation.
893	**Energy saving monitor reference (motor capacity)**	Rated inverter capacity	55K or lower	0.1 to 55kW	Set the motor capacity (pump capacity). Set when calculating power saving rate, power saving rate average value, commercial operation power.
			75K or higher	0 to 3600kW	
894	**Control selection during commercial power-supply operation**	0	0		Discharge damper control (fan)
			1		Inlet damper control (fan)
			2		Valve control (pump)
			3		Commercial power-supply drive (fixed value)
895	**Power saving rate reference value**	9999	0		Consider the value during commercial power-supply operation as 100%
			1		Consider the *Pr. 893* setting as 100%.
			9999		No function
896	**Power unit cost**	9999	0 to 500		Set the power unit cost. Displays the power saving amount charge on the energy saving monitor.
			9999		No function
897	**Power saving monitor average time**	9999	0		Average for 30 minutes
			1 to 1000h		Average for the set time
			9999		No function
898	**Power saving cumulative monitor clear**	9999	0		Cumulative monitor value clear
			1		Cumulative monitor value hold
			10		Accumulation continued (communication data upper limit 9999)
			9999		Accumulation continued (communication data upper limit 65535)
899	**Operation time rate (estimated value)**	9999	0 to 100%		Use for calculation of annual power saving amount. Set the annual operation ratio (consider 365 days × 24h as 100%).
			9999		No function

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
The above parameters allow their settings to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.

(1) Energy saving monitor list

· The following items are monitored by the power saving monitor (*Pr. 52, Pr. 54, Pr. 158* = "50").
(Only 1) Power saving and 3) Power saving average value can be output to *Pr. 54* (terminal FM) and *Pr. 158* (terminal AM))

<table>
<tr><th rowspan="2"></th><th rowspan="2">Energy Saving Monitor Item</th><th rowspan="2">Description and Formula</th><th rowspan="2">Unit</th><th colspan="4">Parameter Setting</th></tr>
<tr><th>Pr. 895</th><th>Pr. 896</th><th>Pr. 897</th><th>Pr. 899</th></tr>
<tr><td>1)</td><td>Power saving</td><td>Difference between the estimated value of power necessary for commercial power supply operation and the input power calculated by the inverter
Power during commercial power supply operation − input power monitor</td><td>0.01kW/
0.1kW *3</td><td>9999</td><td rowspan="3">—</td><td rowspan="3">9999</td><td rowspan="6">—</td></tr>
<tr><td rowspan="2">2)</td><td rowspan="2">Power saving rate</td><td>Ratio of power saving on the assumption that power during commercial power supply operation is 100%
$\frac{\textbf{1) Power saving}}{\textbf{Power during commercial power supply operation}} \times \textbf{100}$</td><td rowspan="2">0.1%</td><td>0</td></tr>
<tr><td>Ratio of power saving on the assumption that Pr. 893 is 100%
$\frac{\textbf{1) Power saving}}{\textit{Pr. 893}} \times \textbf{100}$</td><td>1</td></tr>
<tr><td>3)</td><td>Power saving average value</td><td>Average value of power saving amount per hour during predetermined time (Pr. 897)
$\frac{\Sigma\,(\textbf{1) Power saving} \times \Delta t)}{\textit{Pr. 897}}$</td><td>0.01kWh
/0.1kWh
*3</td><td>9999</td><td rowspan="3">9999</td><td rowspan="4">0 to
1000h</td></tr>
<tr><td rowspan="2">4)</td><td rowspan="2">Power saving rate average value</td><td>Ratio of power saving average value on the assumption that the value during commercial power supply operation is 100%
$\frac{\Sigma\,(\textbf{2) Power saving rate} \times \Delta t)}{\textit{Pr. 897}} \times \textbf{100}$</td><td rowspan="2">0.1%</td><td>0</td></tr>
<tr><td>Ratio of power saving average value on the assumption that Pr. 893 is 100%
$\frac{\textbf{3) Power saving average value}}{\textit{Pr. 893}} \times \textbf{100}$</td><td>1</td></tr>
<tr><td>5)</td><td>Average power cost savings</td><td>Power saving average value represented in terms of cost
3) Power saving average value × Pr. 896</td><td>0.01/0.1
*3</td><td>—</td><td>0 to
500</td></tr>
</table>

· The following shows the items which can be monitored by the cumulative saving power monitor (*Pr. 52* = "51").
(The monitor value of the cumulative monitor can be shifted to the right with *Pr. 891 Cumulative power monitor digit shifted times*.)

<table>
<tr><th rowspan="2"></th><th rowspan="2">Energy Saving Monitor Item</th><th rowspan="2">Description and Formula</th><th rowspan="2">Unit</th><th colspan="4">Parameter Setting</th></tr>
<tr><th>Pr. 895</th><th>Pr. 896</th><th>Pr. 897</th><th>Pr. 899</th></tr>
<tr><td>6)</td><td>Power saving amount</td><td>Power saving is added up per hour.
$\Sigma\,(\textbf{1) Power saving} \times \Delta t)$</td><td>0.01kWh
/0.1kWh
*1*2*3</td><td>—</td><td>9999</td><td rowspan="4">—</td><td rowspan="2">9999</td></tr>
<tr><td>7)</td><td>Power cost savings</td><td>Power saving amount represented in terms of cost
6) Power saving amount × Pr. 896</td><td>0.01/0.1
*1*3</td><td>—</td><td>0 to
500</td></tr>
<tr><td>8)</td><td>Annual power saving amount</td><td>Estimated value of annual power saving amount
$\frac{\textbf{6) Power saving amount}}{\textbf{Operation time during accumulation of power saving amount}} \times \textbf{24} \times \textbf{365} \times \frac{\textit{Pr. 899}}{\textbf{100}}$</td><td>0.01kWh
/0.1kWh
*1*2*3</td><td>—</td><td>9999</td><td rowspan="2">0 to
100%</td></tr>
<tr><td>9)</td><td>Annual power cost savings</td><td>Annual power saving amount represented in terms of cost
8) Annual power saving amount × Pr. 896</td><td>0.01/0.1
*1*3</td><td>—</td><td>0 to
500</td></tr>
</table>

*1 For communication (RS-485 communication, communication option), the display increments are 1. For example, 10.00kWh indicates that communication data is 10.
*2 When using the parameter unit (FR-PU04/FR-PU07), "kW" is displayed.
*3 The setting depends on capacities. (55K or lower/75K or higher)

REMARKS

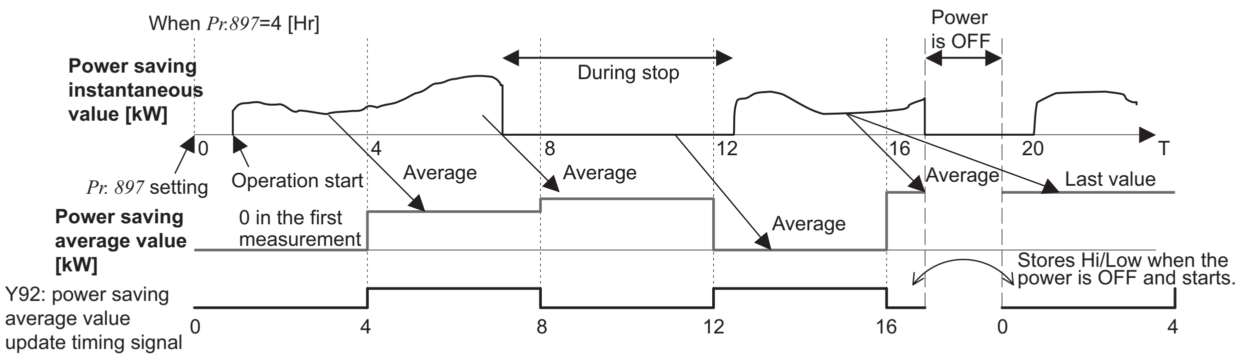
- Since four digits are displayed on the operation panel (FR-DU07), the value is displayed in 0.1 increments when a monitor value in 0.01 increments exceeds 99.99, then rounded up to 100.0. The maximum display is "9999".
- As the operation panel (FR-PU04/FR-PU07) is 5-digit display, it displays in 0.1 increments since a carry occurs, e.g. "1000.0", when a monitor value in 0.01 increments exceeds "999.99". The maximum display is "99999".
- The upper limit of communication (RS-485 communication, communication option) is "65535" when *Pr. 898* Power saving cumulative monitor clear = "9999". The upper limit of 0.01 increments monitor is "655.35" and that of 0.1 increments monitor is "6553.5".

(2) Power saving instantaneous monitor (1) power savings, 2) power saving rate)

- On the power saving monitor (1)), an energy saving effect as compared to the power consumption during commercial power supply operation (estimated value) is calculated and displays on the main monitor.
- In the following case, the power saving monitor (1)) is "0".
  (a)Calculated values of the power saving monitor are negative values.
  (b)During the DC injection brake operation
  (c)Motor is not connected (output current monitor is 0A)
- On the power saving rate monitor (2)), setting "0" in *Pr. 895 Power saving rate reference value* displays the power saving rate on the assumption that power (estimated value) during commercial power supply operation is 100%. When *Pr. 895* = "1", the power saving rate on the assumption that the *Pr. 893 Energy saving monitor reference (motor capacity)* value is 100% is displayed.

(3) Power saving average value monitor (3) power saving average value, 4) average power saving rate average value, 5) average power cost savings)

- Power saving average value monitor is displayed by setting a value other than "9999" in *Pr. 897 Power saving monitor average time*.
- The power saving average value monitor (3)) displays the unit time average value of the power saving amount at averaging.
- The average value is updated every time an average time has elapsed after the *Pr. 897* setting is changed, power is turned ON or the inverter is reset, assuming as a starting point. The power savings average value update timing signal (Y92) is inverted every time the average value is updated.



- The power saving average value monitor (4)) displays the average value per unit time of power saving rate (2)) at every average time by setting "0" or "1" in *Pr. 895 Power saving rate reference value*.
- By setting the charge (power unit) per 1kWh of power amount in *Pr. 896 Power unit cost*, the power saving amount average value monitor (5)) displays the charge relative to the power saving average value (power saving average value (3)) × *Pr. 896*).

(4) Cumulative saving power monitor (6) power saving amount, 7) power cost savings, 8) annual power saving amount, 9) annual power cost savings)

- On the cumulative saving power monitor, the monitor data digit can be shifted to the right by the number of *Pr. 891 Cumulative power monitor digit shifted times* settings. For example, if the cumulative power value is 1278.56kWh when *Pr. 891* = "2", the PU/DU display is 12.78 (display in 100kWh increments) and the communication data is 12. If the maximum value is exceeded at *Pr. 891* = "0 to 4", the power is clamped at the maximum value, indicating that a digit shift is necessary. If the maximum value exceeded at *Pr. 891* = "9999", the power returns to 0 and is recounted. The other monitors are clamped at the display maximum value.
- The cumulative saving power monitor (6)) can measure the power amount during a predetermined period. Measure according to the following steps
  1) Write "9999" or "10" in *Pr. 898 Power saving cumulative monitor clear*.
  2) Write "0" in *Pr. 898* at measurement start timing to clear the cumulative saving power monitor value and start accumulation of power saving.
  3) Write "1" in *Pr. 898* at measurement end timing to hold the cumulative saving power monitor value.

REMARKS

- The cumulative saving power monitor value is stored every hour. Hence, when the power supply is switched OFF within one hour, and switched ON again, the previously stored monitor value is displayed and accumulation starts. (The cumulative monitor value may decrease)

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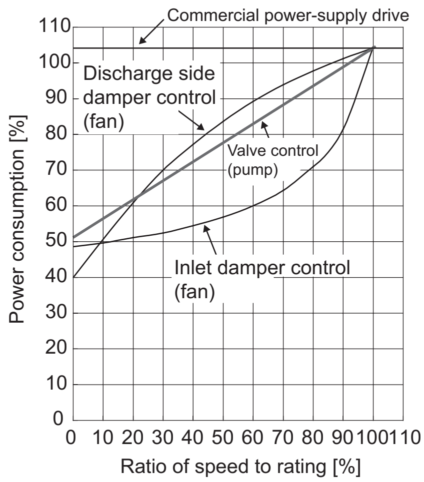
PARAMETERS

(5) Power estimated value of commercial power supply operation *(Pr. 892, Pr. 893, Pr. 894)*

- Select the commercial power supply operation pattern from among the four patterns of discharge damper control (fan), inlet damper control (fan), valve control (pump) and commercial power supply drive, and set it to *Pr. 894 Control selection during commercial power-supply operation*.
- Set the motor capacity (pump capacity) in *Pr. 893 Energy saving monitor reference (motor capacity)*.
- The power consumption rate (%) during commercial power supply operation is estimated from the operation pattern and the ratio of speed to rating (current output frequency / *Pr. 3 Base frequency* (rated frequency under the IPM motor control *(refer to page 81)*) in the following chart.



- From the motor capacity set in *Pr. 893* and *Pr. 892 Load factor*, the power estimated value (kW) during commercial power supply operation is found by the following formula.

Power estimated value (kW) during commercial power supply operation

$$= \textit{Pr. 893}\ \textbf{(kW)} \times \frac{\textbf{Power consumption (\%)}}{\textbf{100}} \times \frac{\textit{Pr. 892}\ \textbf{(\%)}}{\textbf{100}}$$

REMARKS

- Since the speed does not increase above the power supply frequency in commercial power supply operation, it becomes constant when the output frequency rises to or above *Pr. 3 Base frequency* (60Hz under IPM motor control).

(6) Annual power saving amount, power cost *(Pr. 899)*

- By setting the operation time rate [%] (ratio of time when the motor is actually driven by the inverter during a year) in *Pr. 899*, the annual energy saving effect can be predicted.
- When the operation pattern is predetermined to some degree, the estimated value of the annual power saving amount can be found by measurement of the power saving amount during a given measurement period.
- Refer to the following and set the operation time rate.
  1) Predict the average time [h/day] of operation in a day.
  2) Find the annual operation days [days/year]. (Monthly average operation days × 12 months)
  3) Calculate the annual operation time [h/year] from 1) and 2).

Annual operation time (h/year) = Average time (h/day) × Operation days (days/year)

  4) Calculate the operation time rate and set it to *Pr. 899*.

$$\textbf{Operation time rate (\%)} = \frac{\textbf{Annual operation time (h/year)}}{\textbf{24 (h/day) x 365 (days/year)}} \times \textbf{100(\%)}$$

REMARKS

- Operation time rate setting example: When operation is performed for about 21 hours per day and the monthly average operation days are 16 days
  Annual operation time = 21 (h/day) × 16 (days/month) × 12 months = 4032 (h/year)

$$\text{Operation time rate (\%)} = \frac{\text{4032 (h/year)}}{\text{24 (h/day)} \times \text{365 (days/year)}} \times \text{100(\%)} = \underline{\text{46.03\%}}$$

  Set 46.03% to *Pr. 899*.

- Calculate the annual power saving amount from *Pr. 899 Operation time rate (estimated value)* and power saving average value monitor

$$\textbf{Annual power saving amount (kWh/year)} = \begin{array}{c}\textbf{Power saving average value}\\ \textbf{(kW) during accumulation}\\ \textbf{when } \textit{Pr. 898} \textbf{ = 10 or 9999}\end{array} \times \textbf{24h} \times \textbf{365 days} \times \frac{\textit{Pr. 899}}{\textbf{100}}$$

- The annual power saving amount charge can be monitored by setting the power charge per hour in *Pr. 896 Power unit cost*.
  Calculate the annual power saving amount charge in the following method.

Annual power saving amount charge = Annual power saving amount (kWh/year) × *Pr. 896*

REMARKS

In the regeneration mode, make calculation on the assumption that "power saving = power during commercial power supply operation (input power = 0)".

♦ Parameters referred to ♦

Pr. 3 Base frequency ☞ *Refer to page 98*
Pr. 52 DU/PU main display data selection ☞ *Refer to page 152*
Pr. 54 FM terminal function selection ☞ *Refer to page 157*
Pr. 158 AM terminal function selection ☞ *Refer to page 157*

4.16 Motor noise, EMI measures, mechanical resonance

Purpose	Parameter that must be Set		Refer to Page
Reduction of the motor noise **Measures against EMI and leakage currents**	**Carrier frequency and Soft-PWM selection under general-purpose motor control**	**Pr. 72, Pr. 240, Pr. 260**	182
Reduction of the motor noise **Measures against EMI and leakage currents**	**Carrier frequency and Soft-PWM selection under IPM motor control**	**Pr. 72, Pr. 240, Pr. 260**	183
Reduce mechanical resonance	**Speed smoothing control**	**Pr. 653, Pr. 654**	184

4.16.1 Carrier frequency and Soft-PWM selection under general-purpose motor control (Pr. 72, Pr. 240, Pr. 260) V/F S MFVC

You can change the motor sound.

Parameter Number	Name	Initial Value	Setting Range		Description
72 *	**PWM frequency selection**	2	55K or lower	0 to 15	PWM carrier frequency can be changed. The setting displayed is in [kHz]. Note that 0 indicates 0.7kHz, 15 indicates 14.5kHz and 25 indicates 2.5kHz. (25 is exclusively for a sine wave filter.)
			75K or higher	0 to 6, 25	
240 *	**Soft-PWM operation selection**	1	0		Soft-PWM is invalid
			1		When *Pr. 72* = "0 to 5" ("0 to 4" for 75K or higher), soft-PWM is valid.
260	**PWM frequency automatic switchover**	1	0		PWM carrier frequency is constant independently of load. When the carrier frequency is set to 3kHz or more (*Pr. 72* ≥ "3"), perform continuous operation at less than 85% of the rated inverter current.
			1		Decreases PWM carrier frequency automatically when load increases.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*
* This parameter allows its setting to be changed during operation even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.

(1) PWM carrier frequency changing *(Pr. 72)*

- You can change the PWM carrier frequency of the inverter.
- Changing the PWM carrier frequency produces an effect on avoiding the resonance frequency of a mechanical system or motor or on EMI measures or on leakage current reduction caused by the PWM switching.
- When using an option sine wave filter (MT-BSL/BSC) for the 75K or higher, set "25"(2.5kHz) in *Pr. 72*.

(2) Soft-PWM control *(Pr. 240)*

- Soft-PWM control is a control method that changes the motor noise from a metallic tone into an unoffending complex tone.

(3) PWM carrier frequency automatic reduction function *(Pr. 260)*

- If continuous operation is performed at 85% or higher of the rated inverter current (the value in the parenthesis on *page 346*) with *Pr.260* = "1 (initial setting)" and *Pr.72* ≥ "3 (inverter carrier frequency is set to 3kHz is higher)," E.THT (Inverter overload trip) is likely to occur. To avoid that, the carrier frequency is automatically lowered to as low as 2kHz. (Motor noise increases, but not to the point of failure.)
- When *Pr. 260* is set to"0", the carrier frequency becomes constant (*Pr. 72* setting) independently of the load, making the motor sound uniform.
  Note that continuous operation should be performed at less than 85% of the inverter rating.

CAUTION

- Decreasing the PWM carrier frequency is effective on EMI measures and on leakage current reduction, but increases motor noise.
- When PWM carrier frequency is set to 1kHz or less (*Pr.72*≤1), fast-response current limit may function prior to stall prevention operation due to increase in ripple currents, resulting in insufficient torque. In such case, set fast-response current limit operation invalid using *Pr.156 Stall prevention operation selection*.

♦ Parameters referred to ♦

Pr.156 Stall prevention operation selection ☞ *Refer to page 91*

4.16.2 Carrier frequency and Soft-PWM selection under IPM motor control (Pr.72, Pr.240, Pr.260) IPM

You can change the motor sound.

Parameter Number	Name	Initial value	Setting range		Description
72 *1	PWM frequency selection	2	55K or lower	0 to 15	You can change the PWM carrier frequency of the inverter. 0 to 5 : 2kHz 6 to 9 : 6kHz 10 to 13 : 10kHz 14, 15 : 14kHz *Pr.72* cannot be set to "25" during IPM motor control.
			75K or higher	0 to 6, 25	
240 *1	Soft-PWM operation selection	1 *2	0		Soft-PWM is invalid
			1		When *Pr.72* ="0 to 5", soft-PWM is valid.
260	PWM frequency automatic switchover	1 *3	0		PWM carrier frequency is constant regardless of the load. Perform continuous operation at less than 85% of the rated inverter current when the carrier frequency setting is 6kHz or higher (*Pr.72* ≥ 6).
			1		PWM carrier frequency is automatically decreased when the load increases.

The above parameters can be set when *Pr.160 User group read selection* ="0." *(Refer to page 201)*

*1 The above parameters allow their settings to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr.77 Parameter write selection.*

*2 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*

*3 Performing IPM parameter initialization sets back the settings to the initial settings. *(Refer to page 80)*

(1) PWM carrier frequency changing *(Pr.72)*

· You can change the PWM carrier frequency of the inverter.

· Changing the PWM carrier frequency produces an effect on avoiding the resonance frequency of a mechanical system or motor or on EMI measures or on leakage current reduction caused by the PWM switching.

REMARKS

Pr.72 cannot be set to "25" during IPM motor control.

(2) Soft-PWM control *(Pr.240)*

· Soft-PWM control is a control method that changes the motor noise from a metallic tone into unoffending complex tone.

(3) PWM carrier frequency automatic reduction function *(Pr.260)*

· If continuous operation is performed at 85% of the rated inverter current (the value in the parenthesis on *page 346*) while *Pr.260* ="1 (initial setting)" and *Pr.72* ≥ "6 (inverter carrier frequency is set to 6kHz or higher)," E.THT (Inverter overload trip) is likely to occur. To avoid that, the carrier frequency is automatically lowered as low as 2kHz.
(The motor noise increases, but not to the point of failure.)

· When *Pr.260* is set to "0," the carrier frequency becomes constant (*Pr.72* setting) independently of the load, making the motor sound uniform.
Note that continuous operation should be performed at less than 85% of the inverter rating.

CAUTION

· Decreasing the PWM carrier frequency is effective on EMI measures and on leakage current reduction, but increases motor noise.

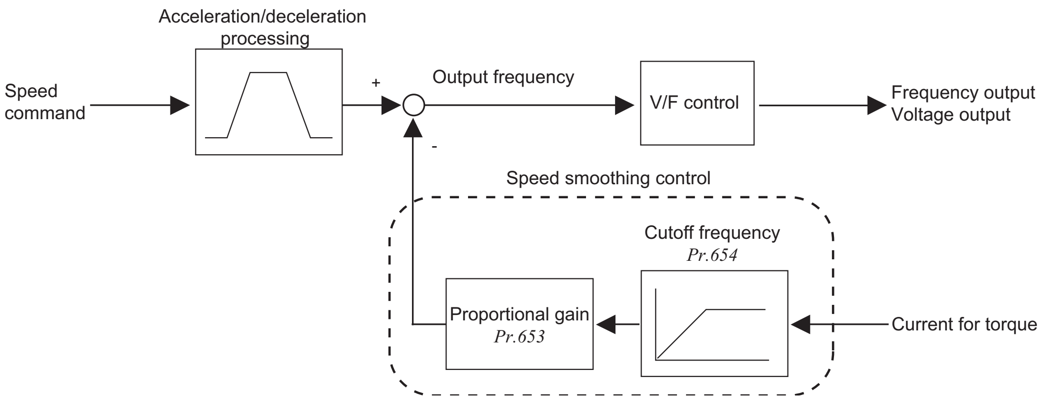
4.16.3 Speed smoothing control (Pr. 653, Pr. 654) V/F S MFVC

Vibration due to mechanical resonance influences the inverter control, causing the output current (torque) to be unstable. In this case, the output current (torque) fluctuation can be reduced to ease vibration by changing the output frequency.

Parameter Number	Name	Initial Value	Setting Range	Description
653	**Speed smoothing control**	0	0 to 200%	The torque fluctuation is reduced to reduce vibration due to mechanical resonance.
654	**Speed smoothing cutoff frequency**	20Hz	0 to 120Hz	Set the minimum value for the torque variation cycle (frequency).

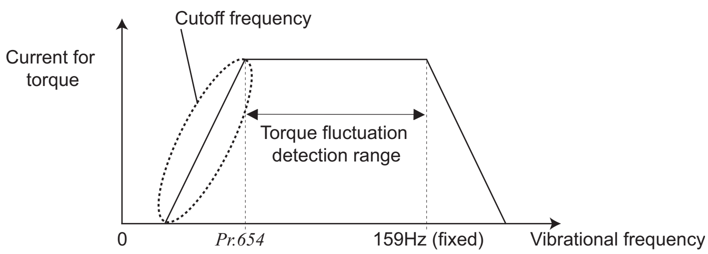
The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Control block diagram



(2) Setting method

If vibration due to mechanical resonance occurs, set 100% in *Pr. 653*, run the inverter at the frequency which generates maximum vibration and check if the vibration will be reduced or not after several seconds.
If effect is not produced, gradually increase the *Pr. 653* setting and check the effect repeatedly until the most effective value is set in *Pr. 653*.
If vibration becomes large by increasing the *Pr. 653* setting, gradually decrease the *Pr. 653* setting from 100% to check the effect in a similar manner.
When the vibrational frequency due to the mechanical resonance (fluctuation of torque, speed, and converter output voltage) is known using a tester and such, set 1/2 to 1 time of the vibrational frequency to *Pr.654*. (Setting vibrational frequency range can suppress the vibration better.)



CAUTION

· Depending on the machine, vibration may not be reduced enough or an effect may not be produced.

4.17 Frequency setting by analog input (terminal 1, 2, 4)

Purpose	Parameter that must be Set		Refer to Page
Selection of voltage/current input (terminal 1, 2, 4) Perform forward/ reverse rotation by analog input.	**Analog input selection**	**Pr. 73, Pr. 267**	185
Adjust the main speed by analog auxiliary input.	**Analog auxiliary input and compensation (added compensation and override function)**	**Pr. 73, Pr. 242, Pr. 243, Pr. 252, Pr. 253**	191
Noise elimination at the analog input	**Input filter**	**Pr. 74**	192
Adjustment (calibration) of analog input frequency and voltage (current)	**Bias and gain of frequency setting voltage (current)**	**Pr. 125, Pr. 126, Pr. 241, C2 to C7 (Pr. 902 to Pr. 905)**	193

4.17.1 Analog input selection (Pr. 73, Pr. 267)

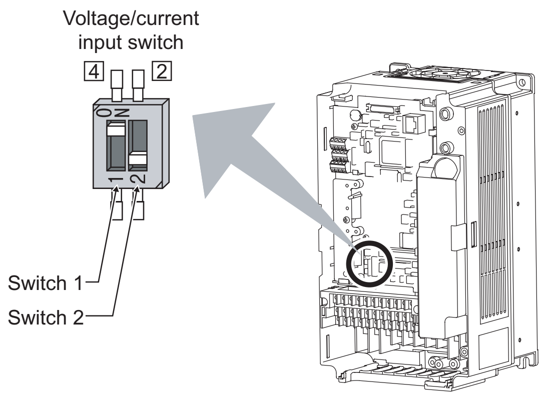
You can select the function that switches between forward rotation and reverse rotation according to the analog input terminal selection specifications, the override function and the input signal polarity.

Parameter Number	Name	Initial Value	Setting Range	Description	
				Voltage/current input switch	
73	**Analog input selection**	1	0 to 5, 10 to 15	Switch 2 - OFF (initial status)	You can select the input specifications of terminal 2 (0 to 5V, 0 to 10V, 0 to 20mA) and input specifications of terminal 1 (0 to ±5V, 0 to ±10V). Override and reversible operation can be selected.
			6, 7, 16, 17	Switch 2 - ON	
267	**Terminal 4 input selection**	0	0	Switch 1 - ON (initial status)	Terminal 4 input 4 to 20mA
			1	Switch 1 - OFF	Terminal 4 input 1 to 5V
			2		Terminal 4 input 2 to 10V

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Selection of analog input selection

· For the terminals 2, 4 used for analog input, voltage input (0 to 5V, 0 to 10V) or current input (4 to 20mA) can be selected. Change parameters (*Pr.73, Pr.267*) and a voltage/current input switch (switch 1, 2) to change input specifications.



Switch 1:Terminal 4 input
ON: Current input (initial status)
OFF: Voltage input

Switch 2: Terminal 2 input
ON: Current input
OFF: Voltage input (initial status)

· Rated specifications of terminal 2 and 4 change according to the voltage/current input switch setting.
Voltage input: Input resistance 10kΩ ± 1kΩ, Maximum permissible voltage 20VDC
Current input: Input resistance 245Ω ± 5Ω, Maximum permissible current 30mA

CAUTION

· Set *Pr.73, Pr.267*, and a voltage/current input switch correctly, then input an analog signal in accordance with the setting. Incorrect setting as in the table below could cause component damage. Incorrect settings other than below can cause abnormal operation.

Setting Causing Component Damage		Operation
Switch setting	Terminal input	
ON (Current input)	Voltage input	This could cause component damage to the analog signal output circuit of signal output devices. (electrical load in the analog signal output circuit of signal output devices increases)
OFF (Voltage input)	Current input	This could cause component damage of the inverter signal input circuit. (output power in the analog signal output circuit of signal output devices increases)

4

PARAMETERS

· Refer to the following table and set *Pr. 73* and *Pr. 267*. (indicates the main speed setting)

AU signal	Terminal 4 Input	*Pr. 73* Setting	Terminal 2 Input	Terminal 1 Input	Compensation Input Terminal and Compensation Method	Polarity Reversible
OFF	—	0	0 to 10V	0 to ±10V	Terminal 1 Added compensation	No (Indicates that a frequency command signal of negative polarity is not accepted.)
		1 (initial value)	0 to to 5V	0 to ±10V		
		2	0 to 10V	0 to ±5V		
		3	0 to 5V	0 to ±5V		
		4	0 to 10V	0 to ±10V	Terminal 2 Override	
		5	0 to 5V	0 to ±5V		
		6	0 to 20mA	0 to ±10V	Terminal 1 Added compensation	
		7	0 to 20mA	0 to ±5V		
		10	0 to 10V	0 to ±10V		Yes
		11	0 to 5V	0 to ±10V		
		12	0 to 10V	0 to ±5V		
		13	0 to 5V	0 to ±5V		
		14	0 to 10V	0 to ±10V	Terminal 2 Override	
		15	0 to 5V	0 to ±5V		
		16	0 to 20mA	0 to ±10V	Terminal 1 Added compensation	
		17	0 to 20mA	0 to ±5V		
ON	*Pr. 267* setting	0	—	0 to ±10V	Terminal 1 Added compensation	No (Indicates that a frequency command signal of negative polarity is not accepted.)
	0 (initial value) — 4 to 20mA	1 (initial value)		0 to ±10V		
		2		0 to ±5V		
		3		0 to ±5V		
		4	0 to 10V	—	Terminal 2 Override	
	1 — 1 to 5V *	5	0 to 5V			
		6	—	0 to ±10V	Terminal 1 Added compensation	
		7		0 to ±5V		
		10		0 to ±10V		Yes
		11		0 to ±10V		
	2 — 2 to 10V *	12		0 to ±5V		
		13		0 to ±5V		
		14	0 to 10V	—	Terminal 2 Override	
		15	0 to 5V			
		16	—	0 to ±10V	Terminal 1 Added compensation	
		17		0 to ±5V		

— : Invalid

* If the input specification to terminal 4 is changed from the current input (*Pr. 267* = "0") to the 0 to 5V or 0 to 10V voltage input (*Pr. 267* ="1 or 2"), calibrate the input with C6. *(Refer to page 193)*

· Set the voltage/current input switch referring to the table below.

Terminal 2 Input Specifications	*Pr. 73* Setting	Switch 2
Voltage input (0 to 10V)	0, 2, 4, 10, 12, 14	OFF
Voltage input (0 to 5V)	1 (initial value), 3, 5, 11, 13, 15	OFF
Current input (0 to 20mA)	6, 7, 16, 17	ON

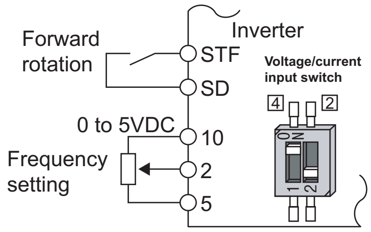
Terminal 4 Input Specifications	*Pr. 267* Setting	Switch 1
Voltage input (2 to 10V)	2	OFF
Voltage input (1 to 5V)	1	OFF
Current input (4 to 20mA)	0 (initial value)	ON

indicates an initial value.

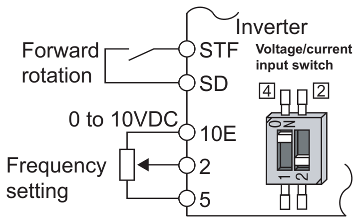
CAUTION

· Turn the AU signal ON to make terminal 4 valid.
· Match the setting of parameter and switch. A different setting may cause a fault, failure or malfunction.
· The terminal 1 (frequency setting auxiliary input) signal is added to the main speed setting signal of the terminal 2 or 4.
· When an override is selected, the terminal 1 or 4 is used for the main speed setting and the terminal 2 for the override signal (50% to 150% at 0 to 5V or 0 to 10V). (When the main speed of the terminal 1 or terminal 4 is not input, compensation by the terminal 2 is invalid.))
· Use *Pr. 125 (Pr. 126) (frequency setting gain)* to change the maximum output frequency at input of the maximum output frequency command voltage (current). At this time, the command voltage (current) need not be input.
Also, the acceleration/deceleration time, which is a slope up/down to the acceleration/deceleration reference frequency, is not affected by the change in *Pr. 73* setting.
· When *Pr. 22 Stall prevention operation level* = "9999", the value of the terminal 1 is as set to the stall prevention operation level.
· When the voltage/current input specifications were changed using *Pr. 73* and *Pr. 267*, be sure to make calibration.

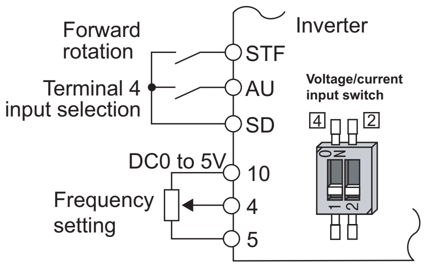
(2) Perform operation by analog input voltage



Connection diagram using terminal 2 (0 to 5VDC)



Connection diagram using terminal 2 (0 to 10VDC)



Connection diagram using terminal 4 (0 to 5VDC)

- The frequency setting signal inputs 0 to 5VDC (or 0 to 10VDC) to across the terminals 2 and 5. The 5V (10V) input is the maximum output frequency. The maximum output frequency is reached when 5V (10V) is input.
- The power supply 5V (10V) can be input by either using the internal power supply or preparing an external power supply. The internal power supply outputs 5VDC across terminals 10 and 5, or 10V across terminals 10E and 5.

Terminal	Inverter Built-in Power Supply Voltage	Frequency Setting Resolution	*Pr. 73* (terminal 2 input voltage)
10	5VDC	0.030Hz/60Hz	0 to 5VDC input
10E	10VDC	0.015Hz/60Hz	0 to 10VDC input

- When inputting 10VDC to the terminal 2, set any of "0, 2, 4, 10, 12, 14" in *Pr. 73*. (The initial value is 0 to 5V)

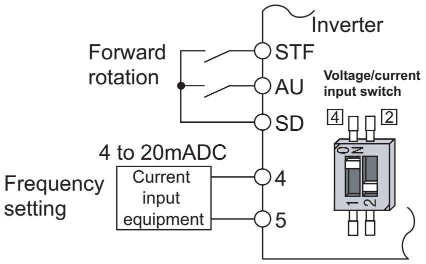
- Setting "1 (0 to 5VDC)" or "2 (0 to 10VDC)" in *Pr. 267* and a voltage/current input switch in the OFF position changes the terminal 4 to the voltage input specification. When the AU signal turns ON, the terminal 4 input becomes valid.

REMARKS

The wiring length of the terminal 10, 2, 5 should be 30m maximum.

4

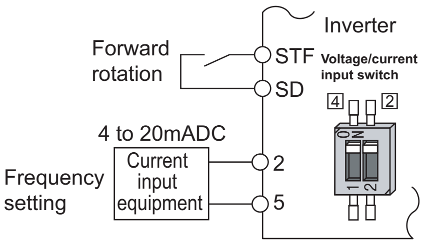
PARAMETERS



Connection diagram using terminal 4 (4 to 20mADC)

(3) Perform operation by analog input current

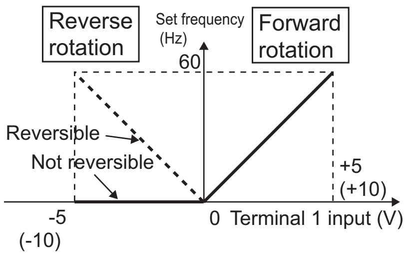
· When the pressure or temperature is controlled constant by a fan, pump, etc., automatic operation can be performed by inputting the output signal 4 to 20mADC of the adjuster to across the terminals 4 and 5.
· The AU signal must be turned ON to use the terminal 4.



Connection diagram using terminal 2 (4 to 20mADC)

· Setting any of "6, 7, 16, 17" in *Pr. 73* and a voltage/current input switch in the ON position changes the terminal 2 to the current input specification. At this time, the AU signal need not be turned ON.

(4) Perform forward/reverse rotation by analog input (polarity reversible operation)



Compensation input characteristic when STF is ON

· Setting any of "10 to 17" in *Pr. 73* enables polarity reversible operation.
· Providing ± input (0 to ±5V or 0 to ±10V) to the terminal 1 enables forward/reverse rotation operation according to the polarity.

♦ Parameters referred to ♦

Pr. 22 Stall prevention operation level ☞ *Refer to page 91*
Pr. 125 Terminal 2 frequency setting gain frequency, Pr. 126 Terminal 4 frequency setting gain frequency ☞ *Refer to page 193*
Pr. 252, Pr. 253 Override bias/gain ☞ *Refer to page 191*
C2(902) Terminal 2 frequency setting bias frequency ☞ *Refer to page 193*
C3(902) Terminal 2 frequency setting bias ☞ *Refer to page 193*
C4(903) Terminal 2 frequency setting gain ☞ *Refer to page 193*
C5(904) Terminal 4 frequency setting bias frequency ☞ *Refer to page 193*
C6(904) Terminal 4 frequency setting bias ☞ *Refer to page 193*
C7(905) Terminal 4 frequency setting gain ☞ *Refer to page 193*

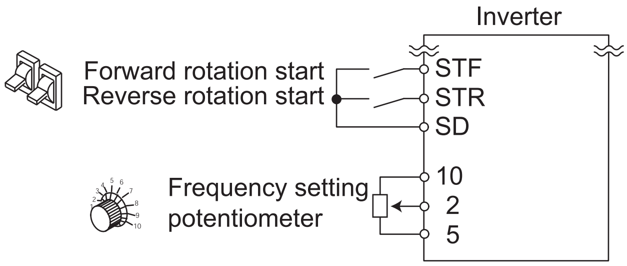
4.17.2 Setting the frequency by analog input (voltage input)

POINT

- Switch ON the STF (STR) signal to give a start command.
- Use the potentiometer (by connecting terminal 2 and 5) to give a frequency command.

[Connection diagram]

(The inverter supplies 5V of power to frequency setting potentiometer. (Terminal 10))

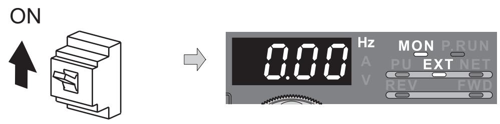


Operation example | Performing operation at 60Hz.

Operation | **Display**

1. Screen at power-ON

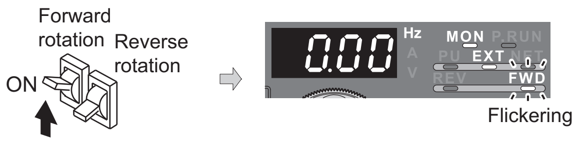
The monitor display appears.



2. Start

Turn the start switch (STF or STR) ON.

[FWD] or [REV] is flickering as no frequency command is given.



CAUTION

When both of STF and STR signals are turned ON, the motor cannot start.
If both are turned ON while the motor is running, the motor decelerates to a stop.

3. Acceleration → constant speed

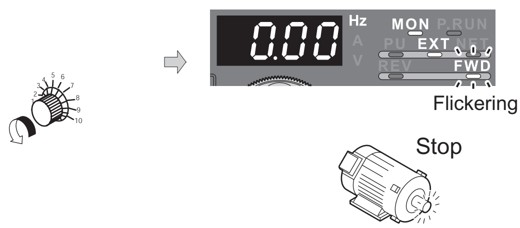
Turn the potentiometer (frequency setting potentiometer) clockwise slowly to full.

The frequency on the display increases in the *Pr.7 Acceleration time*, and "60.00" (60.00Hz) appears. [FWD] indicator is lit during forward rotation, and [REV] indicator is lit during reverse rotation.

4. Deceleration

Turn the potentiometer (frequency setting potentiometer) counterclockwise slowly to full.

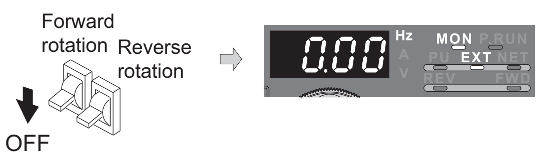
The frequency on the display decreases in the *Pr. 8 Deceleration time*, and the motor stops rotating with "0.00" (0.00Hz) displayed. [FWD] indicator or [EXT] indicator flickers.



5. Stop

Turn the start switch (STF or STR) OFF.

[FWD] indicator or [REV] indicator turns OFF.



REMARKS

Pr. 178 STF terminal function selection must be set to "60" (or *Pr. 179 STR terminal function selection* must be set to "61").
(all are initial values)

? The motor will not rotate ... Why?

☞ Check that [EXT] is lit.
[EXT] is valid when *Pr. 79* = "0" (initial value).
Use PU/EXT to lit [EXT].

☞ Check that wiring is correct. Check once again.

? Change the frequency (0Hz) of the minimum value of potentiometer (at 0V)

☞Adjust the frequency in *calibration parameter C2 Terminal 2 frequency setting bias frequency*. *(Refer to page 193.)*

When you want to compensate frequency setting, use terminal 1.
For details, refer to *page 191.*

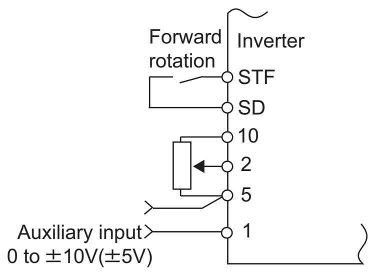
4.17.3 Analog input compensation (Pr. 73, Pr. 242, Pr. 243, Pr. 252, Pr. 253)

A fixed ratio of analog compensation (override) can be made by the added compensation or terminal 2 as an auxiliary input for multi-speed operation or the speed setting signal (main speed) of the terminal 2 or terminal 4.

Parameter Number	Name	Initial Value	Setting Range	Description
73	**Analog input selection**	1	0 to 3, 6, 7, 10 to 13, 16, 17	Added compensation
			4, 5, 14, 15	Override compensation
242	**Terminal 1 added compensation amount (terminal 2)**	100%	0 to 100%	Set the ratio of added compensation amount when terminal 2 is the main speed.
243	**Terminal 1 added compensation amount (terminal 4)**	75%	0 to 100%	Set the ratio of added compensation amount when terminal 4 is the main speed.
252	**Override bias**	50%	0 to 200%	Set the bias side compensation value of override function.
253	**Override gain**	150%	0 to 200%	Set the gain side compensation value of override function.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

(1) Added compensation *(Pr. 242, Pr. 243)*



Added compensation connection example

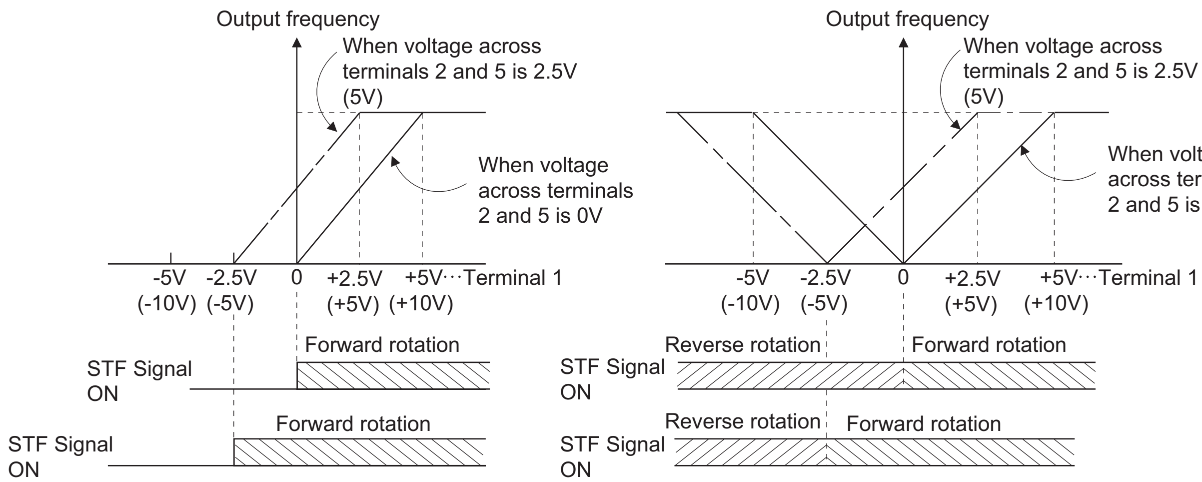
- The compensation signal can be input for the main speed setting for synchronous/continuous speed control operation, etc.
- Setting any of "0 to 3, 6, 7, 10 to 13, 16, 17" in *Pr. 73* adds the voltage across terminals 1 and 5 to the voltage signal across terminals 2-5.
- If the result of addition is negative, it is regarded as 0 at the *Pr. 73* setting of any of "0 to 3, 6, 7", or reverse rotation operation (polarity reversible operation) is performed when the STF signal turns ON at the *Pr. 73* setting of any of "10 to 13, 16, 17".
- The compensation input of the terminal 1 can also be added to the multi-speed setting or terminal 4 (initial value 4 to 20mA).
- The added compensation for terminal 2 can be adjusted by *Pr. 242*, and the compensation for terminal 4 by *Pr. 243*.

Analog command value using terminal 2

$$= \text{Terminal 2 input} + \text{Terminal 1 input} \times \frac{Pr.\ 242}{100(\%)}$$

Analog command value using terminal 4

$$= \text{Terminal 4 input} + \text{Terminal 1 input} \times \frac{Pr.\ 243}{100(\%)}$$



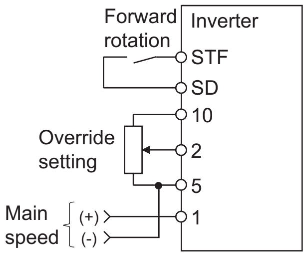
(a) When *Pr. 73* setting is 0 to 5 (b) When *Pr. 73* setting is 10 to 15

Auxiliary input characteristics

CAUTION

- When the *Pr. 73* setting was changed, check the voltage/current input switch setting. Different setting may cause a fault, failure or malfunction. (*Refer to page 185* for setting.)

(2) Override function *(Pr. 252, Pr. 253)*

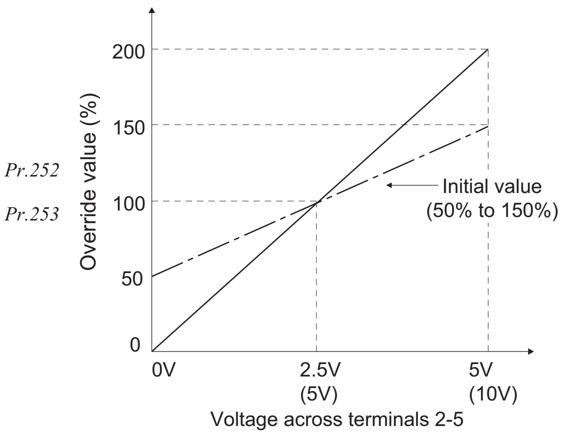


Override connection diagram

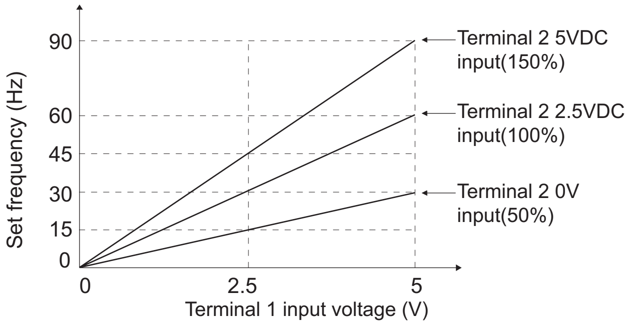
- Use the override function to change the main speed at a fixed ratio.
- Set any of "4, 5, 14, 15" in *Pr. 73* to select an override.
- When an override is selected, the terminal 1 or terminal 4 is used for the main speed setting and the terminal 2 for the override signal. (When the main speed of the terminal 1 or terminal 4 is not input, compensation made by the terminal 2 becomes invalid.)
- Using *Pr. 252* and *Pr. 253*, set the override range.
- How to find the set frequency for override

$$\text{Set frequency (Hz)} = \text{Main speed set frequency (Hz)} \times \frac{\text{Compensation amount (\%)}}{100(\%)}$$

Main speed set frequency (Hz): Terminal 1, 4 input, multi-speed setting
Compensation amount (%): Terminal 2 input



Example)When *Pr. 73* = "5"
The set frequency changes as shown below according to the terminal 1 (main speed) and terminal 2 (auxiliary) inputs.



CAUTION

- When the *Pr. 73* setting was changed, check the voltage/current input switch setting. Different setting may cause a fault, failure or malfunction. (*Refer to page 185* for setting.)

REMARKS

- The AU signal must be turned ON to use the terminal 4.
- When inputting compensation to multi-speed operation or remote setting, set "1" (compensation made) to *Pr. 28 Multi-speed input compensation selection*. (Initial value is "0")

♦ Parameters referred to ♦

Pr. 28 Multi-speed input compensation selection ☞ *Refer to page 106*
Pr. 73 Analog input selection ☞ *Refer to page 185*

4.17.4 Response level of analog input and noise elimination (Pr. 74)

The time constant of the primary delay filter relative to external frequency command (analog input (terminal 1, 2, 4) signal) can be set.

Parameter Number	Name	Initial Value	Setting Range	Description
74	**Input filter time constant**	1	0 to 8	Set the primary delay filter time constant for the analog input. A larger setting results in slower response.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

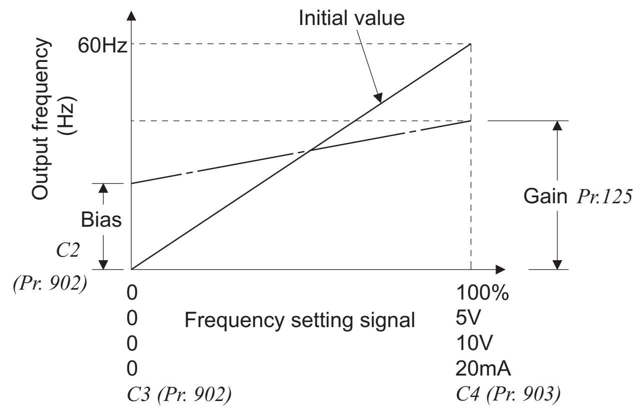
- Effective for eliminating noise in the frequency setting circuit.
- Increase the filter time constant if steady operation cannot be performed due to noise. A larger setting results in slower response. (The time constant can be set between approximately 5ms to 1s with the setting of 0 to 8.)

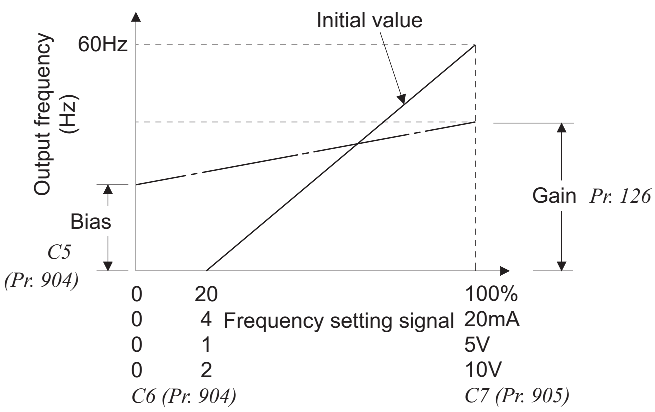
4.17.5 Bias and gain of frequency setting voltage (current) (Pr. 125, Pr. 126, Pr. 241, C2(Pr. 902) to C7(Pr. 905))

You can set the magnitude (slope) of the output frequency as desired in relation to the frequency setting signal (0 to 5V, 0 to 10V or 4 to 20mADC).
Set *Pr. 73* and *Pr. 267* to switch between 0 to 5VDC, 0 to 10VDC and 4 to 20mADC. *(Refer to page 185)*

Parameter Number	Name	Initial Value	Setting Range	Description	
125	**Terminal 2 frequency setting gain frequency**	60Hz *4	0 to 400Hz	Set the frequency of terminal 2 input gain (maximum).	
126	**Terminal 4 frequency setting gain frequency**	60Hz *4	0 to 400Hz	Set the frequency of terminal 4 input gain (maximum).	
241 *1, *3	**Analog input display unit switchover**	0	0	Displayed in %	Select the unit of analog input display.
			1	Displayed in V/mA	
C2(902) *1, *2	**Terminal 2 frequency setting bias frequency**	0Hz	0 to 400Hz	Set the frequency on the bias side of terminal 2 input.	
C3(902) *1, *2	**Terminal 2 frequency setting bias**	0%	0 to 300%	Set the converted % of the bias side voltage (current) of terminal 2 input.	
C4(903) *1, *2	**Terminal 2 frequency setting gain**	100%	0 to 300%	Set the converted % of the gain side voltage (current) of terminal 2 input.	
C5(904) *1, *2	**Terminal 4 frequency setting bias frequency**	0Hz	0 to 400Hz	Set the frequency on the bias side of terminal 4 input.	
C6(904) *1, *2	**Terminal 4 frequency setting bias**	20%	0 to 300%	Set the converted % of the bias side current (voltage) of terminal 4 input.	
C7(905) *1, *2	**Terminal 4 frequency setting gain**	100%	0 to 300%	Set the converted % of the gain side current (voltage) of terminal 4 input.	

*1 This parameter can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*
*2 The parameter number in parentheses is the one for use with the parameter unit (FR-PU04/FR-PU07).
*3 This parameter allows its setting to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.
*4 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*





(1) Change the frequency at maximum analog input *(Pr. 125, Pr. 126)*

- Set a value in *Pr. 125 (Pr. 126)* when changing only the frequency setting (gain) of the maximum analog input power (current). (*C2 (Pr. 902) to C7 (Pr. 905)* setting need not be changed)

(2) Analog input bias/gain calibration (*C2(Pr. 902) to C7(Pr. 905)*)

- The "bias" and "gain" functions are used to adjust the relationship between the input signal entered from outside the inverter to set the output frequency, e.g. 0 to 5V, 0 to 10V or 0 to 20mADC, and the output frequency.
- Set the bias frequency of the terminal 2 input using *C2 (Pr. 902)*. (initial set to the frequency at 0V)
- Using *Pr. 125*, set the output frequency relative to the frequency command voltage (current) set in *Pr. 73 Analog input selection*.
- Set the bias frequency of the terminal 4 input using *C5 (Pr. 904)*. (initial set to the frequency at 4mA)
- Using *Pr. 126*, set the output frequency relative to 20mA of the frequency command current (0 to 20mA).

- There are three methods to adjust the frequency setting voltage (current) bias/gain.
  (a) Method to adjust any point by application of voltage (current) to across the terminals 2 and 5 (4 and 5).
  ☞ *page 195*
  (b) Method to adjust any point without application of a voltage (current) to across terminals 2 and 5 (4 and 5).
  ☞ *page 196*
  (c) Adjusting only the frequency without adjusting the voltage (current).
  ☞ *page 197*

CAUTION

- When the terminal 2 is calibrated to change the inclination of the set frequency, the setting of the terminal 1 is also changed.
- When a voltage is input to the terminal 1 to make calibration, (terminal 2 (4) analog value + terminal 1 analog value) is the analog calibration value.
- When the voltage/current input specifications were changed using *Pr. 73* and *Pr. 267*, be sure to make calibration.

(3) Analog input display unit changing *(Pr. 241)*

- You can change the analog input display unit (%/V/mA) for analog input bias/gain calibration.
- Depending on the terminal input specification set to *Pr. 73* and *Pr. 267*, the display units of *C3 (Pr. 902), C4 (Pr. 903), C6 (Pr. 904) C7 (Pr. 905)* change as shown below.

Analog Command (terminal 2, 4) (according to *Pr. 73, Pr. 267*)	*Pr. 241* = 0 (initial value)	*Pr. 241* = 1
0 to 5V input	0 to 5V → displayed in 0 to 100%(0.1%).	0 to 100% → displayed in 0 to 5V(0.01V).
0 to 10V input	0 to 10V → displayed in 0 to 100%(0.1%).	0 to 100% → displayed in 0 to 10V(0.01V).
4 to 20mA input	0 to 20mA → displayed in 0 to 100%(0.1%).	0 to 100% → displayed in 0 to 20mA(0.01mA).

REMARKS

- Analog input display is not displayed correctly if voltage is applied to terminal 1 when terminal 1 input specifications (0 to ±5V, 0 to ±10V) and main speed (terminal 2, terminal 4 input) specifications (0 to 5V, 0 to 10V, 0 to 20mA) differ. (For example, 5V (100%) is analog displayed when 0V and 10V are applied to terminal 2 and terminal 1 respectively in the initial status.
- Set "0" (initial value is 0% display) in *Pr. 241* to use.

♦ Parameters referred to ♦

Pr. 20 Acceleration/deceleration reference frequency ☞ *Refer to page 109*
Pr. 73 Analog input selection, Pr. 267 Terminal 4 input selection ☞ *Refer to page 185*
Pr. 79 Operation mode selection ☞ *Refer to page 206*

4.17.6 Frequency setting signal (current) bias/gain adjustment method

Perform the following procedure to adjust the bias and gain of the frequency setting voltage (current) using the operation panel FR-DU07.
Refer to page 193 for the details of parameters.

(a)Method to adjust any point by application of voltage (current) across the terminals 2 and 5 (4 and 5).

Operation	Display
1. Confirm the RUN indicator and operation mode indicator ● The inverter must be at a stop. ● The inverter must be in the PU operation mode. (Using PU/EXT)	0.00 Hz MON P.RUN PU EXT NET REV FWD
2. Press MODE to choose the parameter setting mode.	MODE ⇨ P. 0 (The parameter number read previously appears.)
3. Turn ◯ until P.160 appears.	⇨ P.160
4. Press SET to read the present set value. "9999" (initial value) appears.	SET ⇨ 9999
5. Turn ◯ to change it to the setting value of "0".	⇨ 0
6. Press SET to set.	SET ⇨ 0 ⇄ P.160 Flicker...Parameter setting complete!!
7. Turn ◯ until C. . . appears.	⇨ C. . .
8. Press SET to display C - - -.	SET ⇨ C - - - (C0 to C7 setting is enabled.)
9. Turn ◯ until C 4 (C 7) appears. Set to C4 Terminal 2 frequency setting gain.	⇨ C 4 (Terminal 2 input) C 7 (Terminal 4 input)
10. Press SET to display the analog voltage (current) value (%).	SET ⇨ 0.0 (Analog voltage (current) value (%) across terminals 2 and 5 (across terminals 4 and 5))
11. Apply a 5V (20mA) voltage (current). (Turn the external potentiometer connected across terminals 2 and 5 (across terminals 4 and 5) to maximum (any position).)	⇨ 100 * *The value is nearly 100 (%) in the maximum position of the potentiometer.

CAUTION
After performing the operation in step 10, do not touch ◯ until completion of calibration.

Operation	Display
12. Press SET to set.	SET ⇨ 100 * ⇄ C 4 (Terminal 2 input) C 7 (Terminal 4 input) Flicker...Parameter setting complete!! (Adjustment completed) *The value is nearly 100 (%) in the maximum position of the potentiometer.

- By turning ◯, you can read another parameter.
- Press SET to return to the C - - - indication (step 8).
- Press SET twice to show the next parameter (Pr.CL).

REMARKS

- If the frequency meter (indicator) connected to across terminals FM and SD does not indicate exactly 60Hz, set *calibration parameter C0 FM terminal calibration*. *(Refer to page 159)*
- If the gain and bias of frequency setting voltage (current) are too close, an error (Er 3) may be displayed at setting.

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(b) Method to adjust any point without application of a voltage (current) to across terminals 2 and 5 (4 and 5).
(To change from 4V (80%) to 5V (100%))

Operation	Display
1. Confirm the RUN indicator and operation mode indicator ● The inverter must be at a stop. ● The inverter must be in the PU operation mode. (Using PU/EXT)	0.00 Hz MON P.RUN PU EXT NET REV FWD
2. Press MODE to choose the parameter setting mode.	MODE ⇨ P. 0 (The parameter number read previously appears.)
3. Turn the dial until P.160 appears.	⇨ P.160
4. Press SET to read the present set value. "9999" (initial value) appears.	SET ⇨ 9999
5. Turn the dial to change it to the setting value of "0".	⇨ 0
6. Press SET to set.	SET ⇨ 0 ↔ P.160 Flicker...Parameter setting complete!!
7. Turn the dial until C. . . appears.	⇨ C. . .
8. Press SET to display C - - -.	SET ⇨ C - - - (C0 to C7 setting is enabled.)
9. Turn the dial until C 4 (C 7) appears. Set to C4 Terminal 2 frequency setting gain.	⇨ C 4 Terminal 2 input C 7 Terminal 4 input
10. Press SET to display the analog voltage (current) value (%).	SET ⇨ 0.0 Hz A V Analog voltage (current) value (%) across terminals 2 and 5 (across terminals 4 and 5)
11. Turn the dial to set the gain voltage (%). "0V (0mA) equals to 0%, 5V (10V, 20mA) to 100%" REMARKS The current setting at the instant of turning the dial is displayed.	⇨ 100 Hz A V The gain frequency is reached when the analog voltage (current) value across terminals 2 and 5 (across terminals 4 and 5) is 100%. 80 Hz A V
12. Press SET to set.	SET ⇨ 100 Hz A V ↔ C 4 Terminal 2 input / C 7 Terminal 4 input Flicker...Parameter setting complete!! (Adjustment completed)

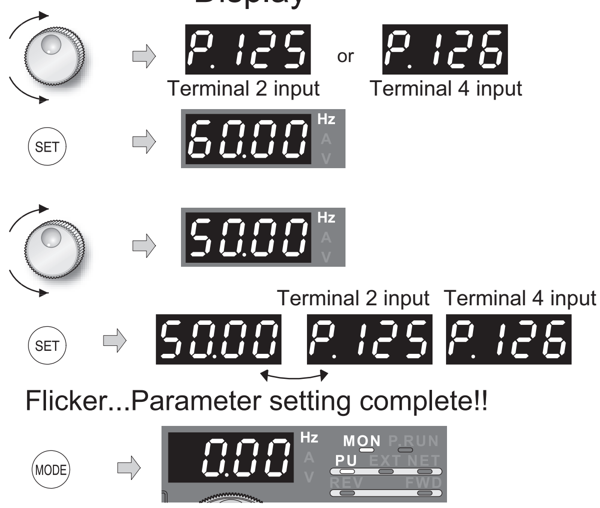
- By turning the dial, you can read another parameter.
- Press SET to return to the C - - - indication (step 8).
- Press SET twice to show the next parameter (Pr.CL).

REMARKS

By pressing the dial after step 10, you can confirm the current frequency setting bias/gain setting.
It cannot be confirmed after execution of step 11.

(c) Method to adjust only the frequency without adjustment of a gain voltage (current).
(When changing the gain frequency from 60Hz to 50Hz)

Operation	Display
1. Turn the setting dial until P.125 (*Pr. 125*) or P.126 (*Pr. 126*) appears.	
2. Press (SET) to show the currently set value. (60.00Hz)	
3. Turn the setting dial to change the set value to "50.00". (50.00Hz)	
4. Press (SET) to set.	
5. Mode/monitor check Press (MODE) twice to choose the monitor/frequency monitor.	
6. Apply a voltage across the inverter terminals 2 and 5 (across 4 and 5) and turn ON the start command (STF, STR). Operation starts at 50Hz.	



REMARKS

- Changing *C4 (Pr. 903)* or *C7 (Pr. 905)* (gain adjustment) value will not change the *Pr. 20* value. The input of terminal 1 (frequency setting auxiliary input) is added to the speed setting signal.
- For the operating procedure using the parameter unit (FR-PU04/FR-PU07), refer to the FR-PU04/FR-PU07 instruction manual.
- When setting the value to 120Hz or more, it is necessary to set *Pr. 18 High speed maximum frequency* to 120Hz or more. *(Refer to page 96)*
- Make the bias frequency setting using *calibration parameter C2 (Pr. 902) or C5 (Pr. 904). (Refer to page 194)*

⚠ CAUTION

⚠ Be cautious when setting any value other than "0" as the bias frequency at 0V (0mA). Even if a speed command is not given, simply turning ON the start signal will start the motor at the preset frequency.

♦ Parameters referred to ♦

Pr. 125 Terminal 2 frequency setting gain frequency ☞ *Refer to page 193*
Pr. 126 Terminal 4 frequency setting gain frequency ☞ *Refer to page 193*
Pr. 241 Analog input display unit switchover ☞ *Refer to page 193*
C2(Pr. 902) Terminal 2 frequency setting bias frequency ☞ *Refer to page 193*
C3(Pr. 902) Terminal 2 frequency setting bias ☞ *Refer to page 193*
C4(Pr. 903) Terminal 2 frequency setting gain ☞ *Refer to page 193*
C5(Pr. 904) Terminal 4 frequency setting bias frequency ☞ *Refer to page 193*
C6(Pr. 904) Terminal 4 frequency setting bias ☞ *Refer to page 193*
C7(Pr. 905) Terminal 4 frequency setting gain ☞ *Refer to page 193*

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4.18 Misoperation prevention and parameter setting restriction

Purpose	Parameter that must be Set		Refer to Page
Limit reset function **Trips stop when PU is disconnected** **Stop from PU**	**Reset selection/disconnected PU detection/PU stop selection**	**Pr. 75**	198
Prevention of parameter rewrite	**Parameter write selection**	**Pr. 77**	200
Prevention of reverse rotation of the motor	**Reverse rotation prevention selection**	**Pr. 78**	201
Display necessary parameters	**Display of applied parameters and user group function**	**Pr. 160, Pr. 172 to Pr. 174**	201
Parameter restriction using password	**Password function**	**Pr. 296, Pr. 297**	203
Control of parameter write by communication	**EEPROM write selection**	**Pr. 342**	230

4.18.1 Reset selection/disconnected PU detection/PU stop selection (Pr. 75)

You can select the reset input acceptance, disconnected PU (FR-DU07/FR-PU04/FR-PU07) connector detection function and PU stop function.

Parameter Number	Name	Initial Value	Setting Range	Description
75*	**Reset selection/disconnected PU detection/PU stop selection**	14	0 to 3, 14 to 17	For the initial value, reset always enabled, without disconnected PU detection, and with PU stop function are set.

·The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
·The *Pr. 75* value can be set any time. Also, if parameter (all) clear is executed, this setting will not return to the initial value.
* This parameter allows its setting to be changed during operation in any operation mode even if "0 (initial value) or 1" is set in *Pr. 77 Parameter write selection*.

Pr. 75 Setting	Reset Selection	Disconnected PU Detection	PU Stop Selection
0	Reset input normally enabled.	If the PU is disconnected, operation will be continued.	Pressing STOP RESET decelerates the motor to a stop only in the PU operation mode.
1	Reset input enabled only when the protective function is activated		
2	Reset input normally enabled.	When the PU is disconnected, the inverter output is shut off.	
3	Reset input enabled only when the protective function is activated		
14 (initial value)	Reset input normally enabled.	If the PU is disconnected, operation will be continued.	Pressing STOP RESET decelerates the motor to a stop in any of the PU, External and Network operation modes.
15	Reset input enabled only when the protective function is activated		
16	Reset input normally enabled.	When the PU is disconnected, the inverter output is shut off.	
17	Reset input enabled only when the protective function is activated		

(1) Reset selection

- You can select the enable condition of reset function (RES signal, reset command through communication) input.
- When *Pr. 75* is set to any of "1, 3, 15, 17", a reset can be input only when a fault occurs.

CAUTION

· When the reset signal (RES) is input during operation, the motor coasts since the inverter being reset shuts off the output. Also, the cumulative value of the electronic thermal relay function is cleared.
· The reset key of the PU is valid only when a fault occurs, independently of the *Pr. 75* setting.

(2) Disconnected PU detection

- This function detects that the PU (FR-DU07/FR-PU04/FR-PU07) has been disconnected from the inverter for longer than 1s and causes the inverter to provide a fault output (E.PUE) and come to trip.
- When *Pr. 75* is set to any of "0, 1, 14, 15", operation is continued if the PU is disconnected.

CAUTION

- When the PU has been disconnected since before power-ON, it is not judged as a fault.
- To make a restart, confirm that the PU is connected and then reset the inverter.
- The motor decelerates to a stop when the PU is disconnected during PU jog operation with *Pr. 75* set to any of "0, 1, 14, 15" (which selects operation is continued if the PU is disconnected).
- When RS-485 communication operation is performed through the PU connector, the reset selection/PU stop selection function is valid but the disconnected PU detection function is invalid.

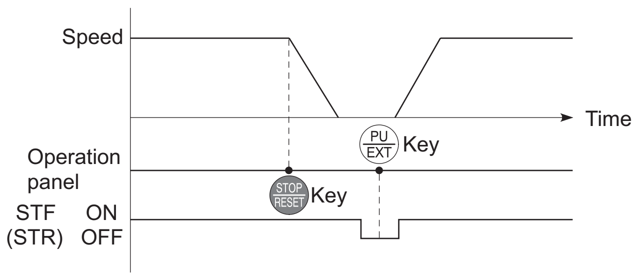
(3) PU stop selection

- In any of the PU operation, External operation and Network operation modes, the motor can be stopped by pressing STOP/RESET of the PU.
- When the inverter is stopped by the PU stop function, "PS" is displayed. A fault signal is not provided.
- When *Pr. 75* is set to any of "0 to 3", deceleration to a stop by STOP/RESET is valid only in the PU operation mode.

REMARKS

The motor will also decelerate to a stop (PU stop) when STOP/RESET is input during operation in the PU mode through RS-485 communication with *Pr. 551 PU mode operation command source selection* set to "1" (PU mode RS-485 terminals).

(4) How to restart the motor stopped by STOP/RESET input from the PU in External operation mode (PU stop (PS) reset method)



Stop/restart example for external operation

(a) When operation panel (FR- DU07) is used

1)After the motor has decelerated to a stop, turn OFF the STF or STR signal.

2)Press PU/EXT three times.

(When *Pr. 79 Operation mode selection* = "0 (initial setting) or 6"••••••(PS cancel)

Pressing it once cancels PS when *Pr. 79 Operation mode selection* = "2, 3, or 7."

3)Turn ON the STF or STR signal.

(b) Connection of the parameter unit (FR-PU04/FR-PU07)

1)After the motor has decelerated to a stop, turn OFF the STF or STR signal.

2)Press EXT.••••••(PS canceled)

3)Turn ON the STF or STR signal.

- The motor can be restarted by making a reset using a power supply reset or RES signal.

CAUTION

- Even if *Pr. 250 Stop selection* is set to other than "9999" to select coasting to a stop, the motor will not coast to a stop but decelerate to a stop by the PU stop function during external operation.

⚠ CAUTION

⚠ Do not reset the inverter with the start signal ON. Doing so will cause the inverter to start immediately after a reset, leading to hazardous conditions.

♦ Parameters referred to ♦

Pr. 250 Stop selection ☞ *Refer to page 130*

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4.18.2 Parameter write selection (Pr. 77)

You can select whether write to various parameters can be performed or not. Use this function to prevent parameter values from being rewritten by misoperation.

Parameter Number	Name	Initial Value	Setting Range	Description
77	**Parameter write selection**	0	0	Write is enabled only during a stop.
			1	Parameter write is not enabled.
			2	Parameter write is enabled in any operation mode regardless of operating status.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*
This parameter allows its setting to be changed during operation in any operation mode even if "0 (initial value) or 1" is set in *Pr. 77 Parameter write selection*.

(1) Write parameters only at a stop (setting "0", initial value)

- Parameters can be written only during a stop in the PU operation mode.
- The parameters marked in the parameter list *(page 64)* ☐ can always be written, regardless of the operation mode and operating status. However, *Pr. 72 PWM frequency selection* and *Pr. 240 Soft-PWM operation selection* can be written during operation in the PU operation mode, but cannot be written in External operation mode.

(2) Disable parameter write (setting "1")

- Parameter write is not enabled. (Reading is enabled.)
- Parameter clear and all parameter clear cannot be performed, either.
- The parameters given on the right can be written if *Pr. 77* = "1".

Parameter Number	Name
22	Stall prevention operation level
75	Reset selection/disconnected PU detection/PU stop selection
77	Parameter write selection
79	Operation mode selection
160	User group read selection
296	Password lock level
297	Password lock/unlock
997	Fault initiation

(3) Write parameters during operation (setting "2")

- Parameters can always be written.
- The parameters given on the right cannot be written during operation if *Pr. 77* = "2". Stop operation when changing their parameter settings.

Parameter Number	Name
23	Stall prevention operation level compensation factor at double speed
48	Second stall prevention operation current
49	Second stall prevention operation frequency
60	Energy saving control selection
66	Stall prevention operation reduction starting frequency
71	Applied motor
79	Operation mode selection
80	Motor capacity
90	Motor constant (R1)
100 to 109	(Adjustable 5 points V/F parameter)
135	Electronic bypass sequence selection
136	MC switchover interlock time
137	Start waiting time
138	Bypass selection at a fault
139	Automatic switchover frequency from inverter to bypass operation
178 to 196	(I/O terminal function selection)
329	Digital input unit selection (Parameter for the plug-in option FR-A7AX)
800	Control method selection
998	IPM parameter initialization
999	Automatic parameter setting

♦ Parameters referred to ♦

Pr. 79 Operation mode selection ☞ *Refer to page 206*

4.18.3 Reverse rotation prevention selection (Pr. 78)

This function can prevent reverse rotation fault resulting from the incorrect input of the start signal.

Parameter Number	Name	Initial Value	Setting Range	Description
78	Reverse rotation prevention selection	0	0	Both forward and reverse rotations allowed
			1	Reverse rotation disabled
			2	Forward rotation disallowed

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*

- Set this parameter when you want to limit the motor rotation to only one direction.
- This parameter is valid for all of the reverse rotation and forward rotation keys of the operation panel (FR-DU07), parameter unit (FR-PU04/FR-PU07), signals (STF, STR signals) via external terminals, and the forward and reverse rotation commands through communication.

4.18.4 Display of applied parameters and user group function (Pr. 160, Pr. 172 to Pr. 174)

Parameter which can be read from the operation panel and parameter unit can be restricted.
In the initial setting, only the simple mode parameters are displayed.

Parameter Number	Name	Initial Value	Setting Range	Description
160 *1	User group read selection	9999	9999	Only the simple mode parameters can be displayed.
			0	The simple mode and extended parameters can be displayed
			1	Only parameters registered in the user group can be displayed.
172 *2	User group registered display/ batch clear	0	(0 to 16)	Displays the number of cases registered as a user group (Read only)
			9999	Batch clear the user group registration
173 *2, *3	User group registration	9999	0 to 999, 9999	Set the parameter numbers to be registered to the user group.
174 *2, *3	User group clear	9999	0 to 999, 9999	Set the parameter numbers to be cleared from the user group.

*1 This parameter allows its setting to be changed during operation in any operation mode even if "0 (initial value) or 1" is set in *Pr. 77 Parameter write selection*.
*2 They can be set when *Pr. 160 User group read selection* = "0".
*3 The values read from *Pr. 173* and *Pr. 174* are always "9999".

(1) Display of simple mode parameters and extended parameters (*Pr. 160*)

- When *Pr. 160* = "9999" (initial value), only the simple mode parameters can be displayed on the operation panel (FR-DU07) and parameter unit (FR-PU04/FR-PU07). (Refer to the parameter list, *pages 64 to 73*, for the simple mode parameters.)
- Set "0" in *Pr. 160* to display of the simple mode parameters and extended parameters.

REMARKS

- When a plug-in option is fitted to the inverter, the option parameters can also be read.
- When reading the parameters using the communication option, all parameters can be read regardless of the *Pr. 160* setting.
- When reading the parameters using the RS-485 terminals, all parameters can be read regardless of the *Pr. 160* setting by setting *Pr.550 NET mode operation command source selection* and *Pr. 551 PU mode operation command source selection*.

Pr.551	Pr.550	Pr.160 Valid/Invalid
1 (RS-485)	—	Valid
2 (PU) (initial value)	0(OP)	Valid
	1(RS-485)	Invalid (all readable)
	9999 (auto-detect) (initial value)	With OP: valid
		Without OP: invalid (all readable)

* OP indicates a communication option

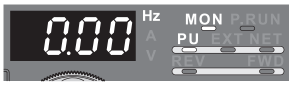
- *Pr. 15 Jog frequency*, *Pr. 16 Jog acceleration/deceleration time*, *Pr. 991 PU contrast adjustment* are displayed as simple mode parameters when the parameter unit (FR-PU04/FR-PU07) is mounted.

(2) User group function (*Pr. 160, Pr. 172 to Pr. 174*)

- The user group function is designed to display only the parameters necessary for setting.
- From among all parameters, a maximum of 16 parameters can be registered to a user group. When *Pr. 160* is set to "1", only the parameters registered to the user group can be accessed. (Reading of parameters other than the user group registration is disabled.)
- To register a parameter to the user group, set its parameter number to *Pr. 173*.
- To delete a parameter from the user group, set its parameter number to *Pr. 174*. To batch-delete the registered parameters, set *Pr. 172* to "9999".

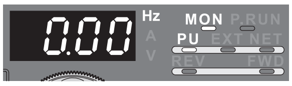
(3) Registration of parameter to user group (*Pr. 173*)

When registering *Pr. 3* to user group

Operation	Indication
1. Confirm the operation display and operation mode display. ● The inverter must be at a stop. ● The inverter must be in the PU operation mode. (Press PU/EXT in the External operation mode.)	
2. Press MODE to choose the parameter setting mode.	MODE ⇨ P. 0 Parameter setting mode
3. Turn the dial until P.173 appears.	⇨ P.173 *Pr. 173* User group registration is displayed.
4. Press SET to display. "9999"	SET ⇨ 9999 When *Pr. 173* is read, "9999" is displayed.
5. Turn the dial until *Pr. 3* appears.	⇨ 3 Select the parameter number to be registered.
6. Press SET to set. "P.173" and "3" are displayed alternately. To continue parameter registration, repeat steps 3 to 6.	SET ⇨ 3 ⟷ P.173 **Flicker ··· Registration of *Pr. 3* to user group completed!!**

(4) Deletion of parameter from user group (*Pr. 174*)

When deleting *Pr. 3* from user group

Operation	Indication
1. Confirm the operation display and operation mode display. ● The inverter must be at a stop. ● The inverter must be in the PU operation mode. (Press PU/EXT in the External operation mode.)	
2. Press MODE to choose the parameter setting mode.	MODE ⇨ P. 0 Parameter setting mode
3. Turn the dial until P.174 appears.	⇨ P.174 *Pr. 174* User group clear is displayed.
4. Press SET to display. "9999"	SET ⇨ 9999 When *Pr. 174* is read, "9999" is displayed.
5. Turn the dial until *Pr. 3* appears.	⇨ 3 Select the parameter number to be deleted.
6. Press SET to clear. "P.174" and "3" are displayed alternately. To continue parameter registration, repeat steps 3 to 6.	SET ⇨ 3 ⟷ P.174 **Flicker ··· Deletion of *Pr. 3* from user group completed!!**

REMARKS

- *Pr. 77, Pr. 160* and *Pr. 991* can always be read, independently of the user group setting.
- *Pr. 77, Pr. 160* and *Pr. 172 to Pr. 174* cannot be registered to the user group.
- When *Pr. 174* is read, "9999" is always displayed. Although "9999" can be written, no function is available.
- When any value other than "9999" is set to *Pr. 172*, no function is available.

♦ Parameters referred to ♦

Pr. 550 NET mode operation command source selection ☞ *Refer to page 219*
Pr. 551 PU mode operation command source selection ☞ *Refer to page 219*

4.18.5 Password function (Pr. 296, Pr. 297)

Registering a 4-digit password can restrict parameter reading/writing.

Parameter Number	Name	Initial Value	Setting Range	Description
296 *1*4	**Password lock level**	9999	0 to 6, 99, 100 to 106, 199	Select restriction level of parameter reading/ writing when a password is registered.
			9999	No password lock
297 *2*4	**Password lock/unlock**	9999	1000 to 9998	Register a 4-digit password
			(0 to 5) *3	Displays password unlock error count. (Reading only) (Valid when *Pr. 296* = "100" to "106")
			9999 *3	Password being unlocked

*1 This parameter can be set when *Pr. 160 User group read selection* = "0".
*2 If *Pr. 296* = "9999" (no password lock), *Pr. 297* can be set while *Pr. 160* = "0." When the password lock is valid, *Pr. 297* can be set regardless of the *Pr. 160* setting.
*3 "0 or 9999" can be set to *Pr.297* at any time although the setting is invalid (the displayed value does not change).
*4 This parameter allows its setting to be changed during operation in any operation mode even if "0 (initial value) or 1" is set in *Pr. 77 Parameter write selection*.

(1) Parameter reading/writing restriction level (*Pr. 296*)

•Level of reading/writing restriction by PU/Network(NET) mode operation command can be selected by *Pr. 296*.

Pr. 296 Setting	PU Mode Operation Command *3		PU Mode Operation Command *4		
	Read *1	Write *2	Read		Write *2
			RS-485 terminal	Communication option	Read
9999	○	○	○		○
0, 100 *6	×	×	×		×
1, 101	○	×	○		×
2, 102	○	×	○		○
3, 103	○	○	○		×
4, 104	×	×	×	○	×
5, 105	×	×	○		○
6, 106	○	○	×	○	×
99, 199	Only the parameters registered in the user group can be read/written. *5 (For the parameters not registered in the user group, same restriction level as "4, 104" applies.)				

○: enabled, ×: restricted

*1 If the parameter reading is restricted by the *Pr. 160* setting, those parameters are unavailable for reading even when "○" is indicated.
*2 If the parameter writing is restricted by the *Pr. 77* setting, those parameters are unavailable for writing even when "○" is indicated.
*3 Parameter access from unit where parameter is written in PU operation mode (initially set to operation panel (FR-DU07), parameter unit) is restricted. (*Refer to page 219* for PU mode operation command source selection)
*4 This restricts parameter access from the command source that can write a parameter under Network operation mode (initially RS-485 terminal or a communication option). (*Refer to page 219* for NET mode command source.)
*5 Read/write is enabled only in the simple mode parameters registered in the user group when *Pr.160 User group read selection* = "9999". *Pr.296* and *Pr.297* are always read/write enabled whether registered to a user group or not.
*6 If a communication option is installed, option fault (E.OPT) occurs, and inverter trips. (*Refer to page 318*.)

(2) Password lock/unlock (*Pr.296, Pr.297*)

<Lock>

1) Set parameter reading/writing restriction level.(*Pr. 296* ≠ 9999)

Pr.296 Setting Value	Restriction of Password Unlock Error	*Pr.297* Display
0 to 6, 99	No restriction	Always 0
100 to 106, 199	Restricted at fifth error	Displays error count (0 to 5)

* During [*Pr. 296* = any of "100 to 106, 199"], if password unlock error has occurred 5 times, correct password will not unlock the restriction. All parameter clear can unlock the restriction.
(In this case, parameter settings are cleared.)

2) Write a four-digit number (1000 to 9998) in *Pr. 297* as a password.
(When *Pr. 296* = "9999", *Pr. 297* cannot be written.)
When password is registered, parameter reading/writing is restricted with the restriction level set in *Pr. 296* until unlocking.

REMARKS

· After registering a password, a read value of *Pr. 297* is always one of "0" to "5".
· When a password restricted parameter is read/written, LOCd is displayed.
· Even if a password is registered, parameters which the inverter itself writes, such as inverter parts life, are overwritten as needed.
· Even if a password is registered, *Pr. 991 PU contrast adjustment* can be read/written when a parameter unit (FR-PU04/FR-PU07) is connected.

<Unlock>

There are two ways of unlocking the password.

- Enter a password in *Pr. 297*.
  Unlocked when a password is correct. If a password is incorrect, an error occurs and not unlocked.
  During [*Pr. 296* = any of "100 to 106, 199"], if password unlock error has occurred 5 times, correct password will not unlock the restriction. (During password lock)
- Perform all parameter clear.

CAUTION

· If the password has been forgotten, perform all parameter clear to unlock the parameter restriction. In that case, other parameters are also cleared.
· Parameter all clear can not be performed during the operation.
· Do not use the FR Configurator when parameter read is restricted (*Pr. 296* = any of "0, 4, 5, 99, 100, 104, 105, 199"). FR Configurator may not function properly.

REMARKS

· The password unlock method is different for operation panel/FR-PU07, RS-485 communication, and communication option.

	Operation panel/ FR-PU07	RS-485 communication	Communication option
All parameter clear (data format H9966, H55AA)	○	○	○
Parameter clear (data format H9696, H5A5A)	×	×	○

○:Password can be unlocked. ×:Password cannot be unlocked.

(3) Parameter operation during password lock/unlock

Parameter operation		Unlocked		Password registered	Locked
		Pr. 296 = 9999 *Pr. 297* = 9999	*Pr. 296* ≠ 9999 *Pr. 297* = 9999	*Pr. 296* ≠ 9999 *Pr. 297* = 0 to 4 (Read value)	*Pr. 296* = 100 to 106, 199 *Pr. 297* = 5 (Read value)
Pr. 296	Read	○ *1	○	○	○
	Write	○ *1	○ *1	×	×
Pr. 297	Read	○ *1	○	○	○
	Write	×	○	○	○ *3
Performing parameter clear		○	○	× *4	× *4
Performing parameter all clear		○	○	○ *2	○ *2
Performing parameter copy		○	○	×	×

○: enabled, ×: restricted

*1 Reading/writing is unavailable when there is restriction to reading by the *Pr. 160* setting. (Reading is available in NET mode regardless of *Pr. 160* setting.)
*2 Unavailable during the operation.
*3 Correct password will not unlock the restriction.
*4 Parameter clear is available only from the communication option.

REMARKS

- When *Pr. 296* = any of "4, 5, 104, 105" (password lock), the setting screen for PU JOG frequency is not displayed in the parameter unit (FR-PU04/FR-PU07).
- During password lock, parameter copy of the operation panel (FR-DU07)/the parameter unit (FR-PU07) cannot be performed.

♦ Parameters referred to ♦

Pr. 77 Parameter write selection ☞ *Refer to page 200*
Pr. 160 Extended function display selection ☞ *Refer to page 201*
Pr. 550 NET mode operation command source selection ☞ *Refer to page 219*
Pr. 551 PU mode operation command source selection ☞ *Refer to page 219*

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PARAMETERS

4.19 Selection of operation mode and operation location

Purpose	Parameter that must be set		Refer to page
Operation mode selection	**Operation mode selection**	**Pr. 79**	206
Started in network operation mode	**Operation mode at power ON**	**Pr. 79, Pr. 340**	218
Selection of operation location	**Selection of start command source, speed command source and operation location during communication operation**	**Pr. 338, Pr. 339, Pr. 550, Pr. 551**	219

4.19.1 Operation mode selection (Pr. 79)

Used to select the operation mode of the inverter.
Mode can be changed as desired between operation using external command signals (external operation), operation from the PU (FR-DU07/FR-PU04/FR-PU07), combined operation of PU operation and external operation (external/PU combined operation, and network operation (when RS-485 terminals or a communication option is used).

Parameter Number	Name	Initial Value	Setting Range
79	Operation mode selection	0	0 to 4, 6, 7

The above parameters can be changed during a stop in any operation mode.

POINT

• Use the easy setting mode to set *Pr. 79* in simple steps. *(Refer to page 62)*

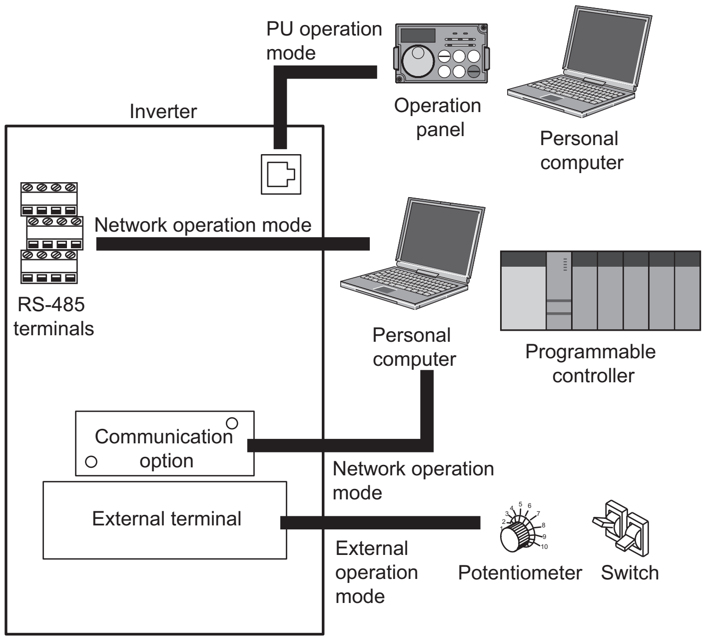
Pr.79 Setting	Description			LED Indication (OFF / ON)	Refer to page
0	Use External/PU switchover mode Press PU/EXT to switch between the PU and External operation mode. At power ON, the inverter is in the External operation mode.			PU operation mode: PU External operation mode: EXT NET operation mode: NET	209
	Operation mode	**Frequency command**	**Start command**		
1	PU operation mode (fixed)	Setting by the operation panel (FR-DU07) and PU (FR-PU04/FR-PU07)	Input by FWD and REV on PU (FR-DU07/FR-PU04/FR-PU07)	PU operation mode: PU	209
2	External operation mode (fixed) The operation can be performed by switching between the External and NET operation modes.	External signal input (from terminal 2, 4, and 1, JOG, multi-speed selection, etc.)	External signal input (from terminal STF and STR)	External operation mode: EXT NET operation mode: NET	209
3	External/PU combined operation mode 1	PU (FR-DU07/FR-PU04/FR-PU07) setting or external signal input (multi-speed setting, across terminals 4 and 5 (valid when AU signal turns ON)). *2	External signal input (from terminal STF and STR)	External/PU combined operation mode: PU EXT	210
4	External/PU combined operation mode 2	External signal input (Terminal 2, 4, 1, JOG, multi-speed selection, etc.)	Input by FWD and REV on PU (FR-DU07/FR-PU04/FR-PU07)		210
6	Switchover mode Switch among PU operation, External operating, and NET operation while keeping the same operating status.			PU operation mode: PU External operation mode: EXT NET operation mode: NET	211
7	External operation mode (PU operation interlock) X12 signal ON: Operation mode can be switched to the PU operation mode. (output stop during External operation) X12 signal OFF: Operation mode cannot be switched to the PU operation mode.				211

*1 This parameter allows its setting to be changed in any operation mode even if "0 (initial value) or 1" is set in *Pr. 77 Parameter write selection*.
*2 The priorities of the frequency commands when *Pr. 79* = "3" are "Multi-speed operation (RL/RM/RH/REX) > PID control (X14) > terminal 4 analog input (AU) > digital input from the operation panel".

REMARKS

If switching of the operation mode is invalid even though *Pr. 79* is set, *refer to 5.5.9 Operation mode is not changed properly (page 327)*.

(1) Operation mode basics

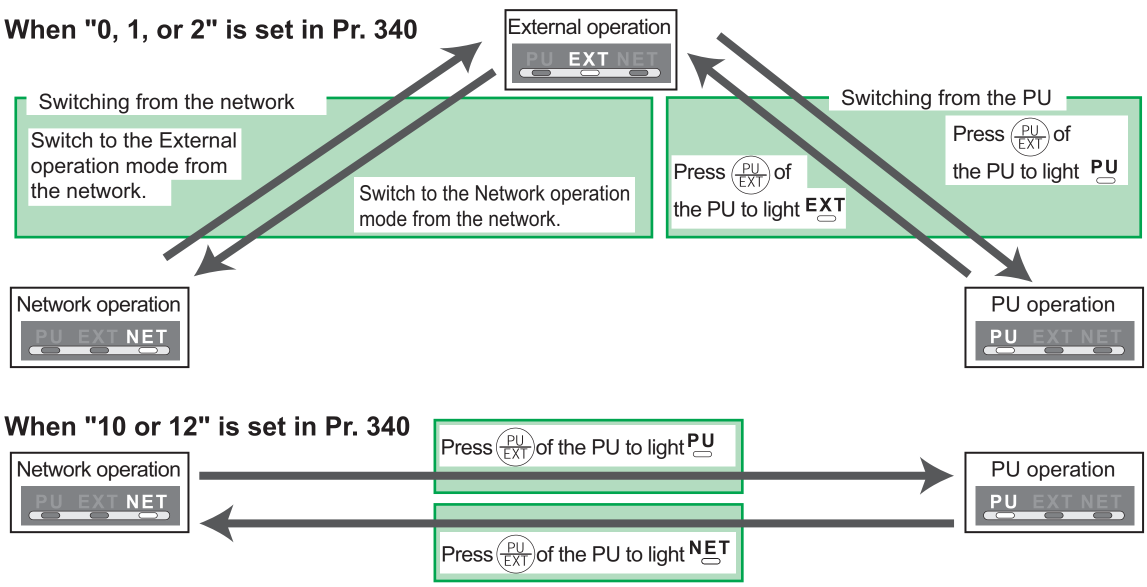


- The operation mode specifies the source of the start command and the frequency command for the inverter.
- Basically, there are following operation modes.
  - **External operation mode:** For inputting start command and frequency command by an external potentiometer and switches which are connected to the control circuit terminal.
  - **PU operation mode:** For inputting start command and frequency command by operation panel (FR-DU07), parameter unit (FR-PU04/FR-PU07) and RS-485 communication with PU connector.
  - **Network operation mode (NET operation mode):** For inputting start command and frequency command by RS-485 terminal and communication options.
- The operation mode can be selected from the operation panel or with the communication instruction code.

REMARKS

- Either "3" or "4" may be set to select the PU/external combined operation, and these settings differ in starting method.
- In the initial setting, the stop function by STOP/RESET of the PU (FR-DU07/FR-PU07) (PU stop selection) is valid also in other than the PU operation mode. *(Pr. 75 Reset selection/disconnected PU detection/PU stop selection. Refer to page 198.)*

(2) Operation mode switching method



REMARKS

- For switching of operation by external terminals, refer to the following:

  PU operation external interlock signal (X12 signal) ☞ *page 211*

  PU-external operation switch-over signal (X16) ☞ *page 212*

  PU-NET operation switchover signal (X65), External-NET operation switchover signal (X66) ☞ *page 213*

  Pr. 340 Communication startup mode selection ☞ *page 218*

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PARAMETERS

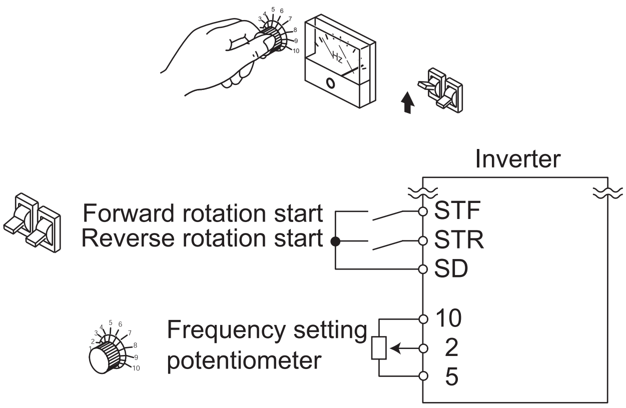
(3) Operation mode selection flow

In the following flowchart, select the basic parameter setting and terminal connection related to the operation mode.

START

Where is the start command source?	Where is the frequency set?	Connection	Parameter setting	Operation
From external (STF/STR terminal)	From external (Terminal 2, 4, JOG, multi-speed, etc.)	STF (forward rotation)/STR (reverse rotation) *(Refer to page 133.)* Terminal 2, 4 (analog), RL, RM, RH, JOG, etc.		Frequency setting terminal ON STF(STR) ON
From external (STF/STR terminal)	From PU (Digital setting)	STF (forward rotation)/STR (reverse rotation) *(Refer to page 133.)*	*Pr. 79* = "3" (External/PU combined operation 1)	DU digital setting STF(STR) ON
From external (STF/STR terminal)	From communication (RS-485 terminals/communication option) — RS-485 terminals or communication option? — RS-485 terminals	STF (forward rotation)/STR (reverse rotation) *(Refer to page 133.)* Connection of RS-485 terminals *(Refer to page 226.)*	*Pr. 338* = "1" *Pr. 340* = "1, 2"	Communication frequency setting command sending STF(STR) ON
From external (STF/STR terminal)	From communication — Communication option	Connection of communication option (Refer to the corresponding communication option instruction manual)	*Pr. 338* = "1" *Pr. 340* = "1"	Communication frequency setting command sending STF(STR) ON
From PU (FWD/REV key)	From external (Terminal 2, 4, JOG, multi-speed, etc.)	Terminal 2, 4 (analog), RL, RM, RH, JOG, etc.	*Pr. 79* = "4" (External/PU combined operation 2)	Frequency setting terminal ON FWD/REV key ON
From PU (FWD/REV key)	From PU (Digital setting)		*Pr. 79* = "1" (Fixed to PU operation)	Digital setting FWD/REV key ON
From PU (FWD/REV key)	From communication (RS-485 terminals/communication option)	Disabled		
From communication (RS-485 terminals/communication option) — RS-485 terminals or communication option? — RS-485 terminals	From external (Terminal 2, 4, JOG, multi-speed, etc.)	Connection of RS-485 terminals *(Refer to page 226.)* Terminal 2, 4 (analog), RL, RM, RH, JOG, etc.	*Pr. 339* = "1" *Pr. 340* = "1, 2"	Frequency setting terminal ON Communication start command sending
From communication — RS-485 terminals	From PU (Digital setting)		Disabled	
From communication — RS-485 terminals	From communication RS-485 terminals	Connection of RS-485 terminals *(Refer to page 226.)*	*Pr. 340* = "1, 2"	Communication frequency setting command sending Communication start command sending
From communication — Communication option	From external (Terminal 2, 4, JOG, multi-speed, etc.)	Connection of communication option (Refer to the corresponding communication option instruction manual) Terminal 2, 4 (analog), RL, RM, RH, JOG, etc.	*Pr. 339* = "1" *Pr. 340* = "1"	Frequency setting terminal ON Communication start command sending
From communication — Communication option	From PU (Digital setting)		Disabled	
From communication — Communication option	From communication (communication option)	Connection of communication option (Refer to the corresponding communication option instruction manual)	*Pr. 340* = "1"	Communication frequency setting command sending Communication start command sending

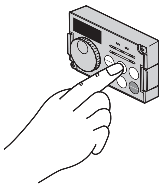
(4) External operation mode (setting "0" (initial value), "2")



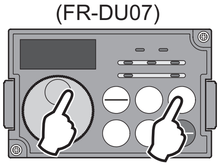
- Select the External operation mode when the start command and the frequency command are applied from a frequency setting potentiometer, start switch, etc. externally and connecting them to the control circuit terminals of the inverter.
- Generally, parameter change cannot be performed with the operation panel in the External operation mode. (Some parameters can be changed. Refer to the detailed description of each parameter.)
- When "0" or "2" is selected for *Pr. 79*, the inverter enters the External operation mode at power ON. (When using the network operation mode, refer to *page 218*.)
- When parameter changing is seldom necessary, setting "2" fixes the operation mode to External operation mode. When frequent parameter changing is necessary, setting "0" (initial value) allows the operation mode to be changed easily to PU operation mode by pressing PU/EXT of the operation panel. When you switched to PU operation mode, always return to External operation mode.
- The STF and STR signal are used as a start command, and the voltage or current signal to terminal 2, 4, multi-speed signal, JOG signal, etc. are used as frequency command.

☞ *Refer to page 191*

(5) PU operation mode (setting "1")



Operation panel
(FR-DU07)



- Select the PU operation mode when applying start and speed command by the key operation of the operation panel (FR-DU07) or parameter unit (FR-PU04/FR-PU07) alone. Also select the PU operation mode when making communication using the PU connector.
- When "1" is selected for *Pr. 79*, the inverter enters the PU operation mode at power ON. You cannot change to the other operation mode.
- The setting dial of the operation panel can be used for setting like a potentiometer. *(Pr. 161 Frequency setting/key lock operation selection, refer to page 295.)*
- When PU operation mode is selected, the PU operation mode signal (PU) can be output.
  For the terminal used for the PU signal output, assign the function by setting "10 (positive logic) or 110 (negative logic)" in any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

☞ *Refer to page 214*

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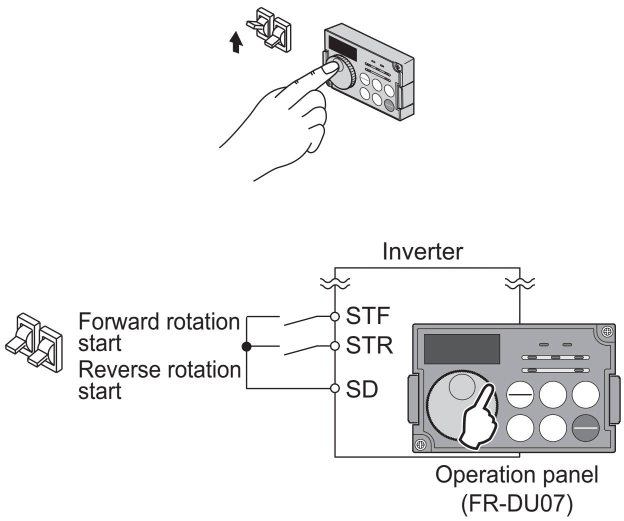
PARAMETERS

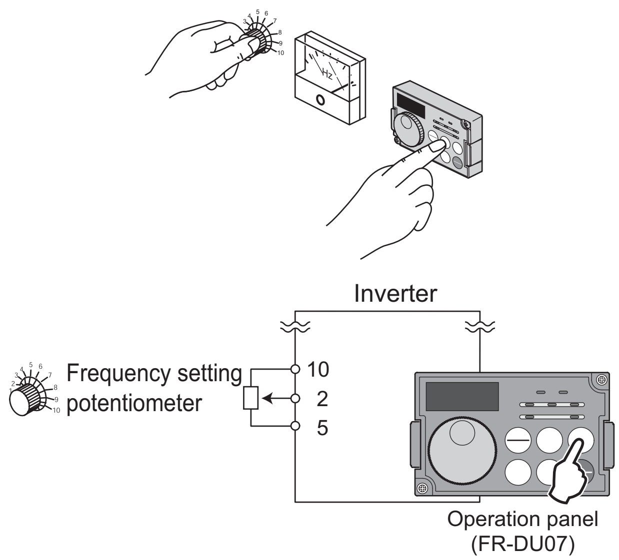
(6) PU/External combined operation mode 1 (setting "3")



- Select the PU/external combined operation mode 1 when applying frequency command from the operation panel (FR-DU07) or parameter unit (FR-PU04/FR-PU07) and inputting the start command with the external start switch.
- Select "3" for *Pr. 79*. You cannot change to the other operation mode.
- When a frequency is input from the external signal by multi-speed setting, it has a higher priority than the frequency setting from the PU. When AU is ON, the command signal to terminal 4 is used.

☞ *Refer to page 191*

(7) PU/External combined operation mode 2 (setting "4")



- Select the PU/External combined operation mode 2 when applying frequency command from the external potentiometer, multi-speed or JOG signal and inputting the start command by key operation of the operation panel (FR-DU07) or parameter unit (FR-PU04/FR-PU07).
- Select "4" for *Pr. 79*. You cannot change to the other operation mode.

☞ *Refer to page 217*

(8) Switch-over mode (Setting "6")

· While continuing operation, you can switch among PU operation, External operation and Network operation (when RS-485 terminals or communication option is used).

Operation Mode Switching	Switching Operation/Operating Status
External operation → PU operation	Select the PU operation mode with the operation panel or parameter unit. · Rotation direction is the same as that of external operation. · The frequency set with the potentiometer (frequency setting command), etc. is used unchanged. (Note that the setting will disappear when power is switched OFF or the inverter is reset.)
External operation → NET operation	Send the mode change command to Network operation mode through communication. · Rotation direction is the same as that of external operation. · The value set with the setting potentiometer (frequency setting command) or like is used unchanged. (Note that the setting will disappear when power is switched OFF or the inverter is reset.)
PU operation → external operation	Press the external operation key of the operation panel, parameter unit. · The rotation direction is determined by the input signal of the external operation. · The set frequency is determined by the external frequency command signal.
PU operation → NET operation	Send the mode change command to Network operation mode through communication. · Rotation direction and set frequency are the same as those of PU operation.
NET operation → external operation	Send the mode change command to External operation mode through communication. · Rotation direction is determined by the external operation input signal. · The set frequency is determined by the external frequency command signal.
NET operation → PU operation	Select the PU operation mode with the operation panel or parameter unit. · The rotation direction and frequency command in Network operation mode are used unchanged.

(9) PU operation interlock (Setting "7")

· The PU operation interlock function is designed to forcibly change the operation mode to External operation mode when the PU operation interlock signal (X12) input turns OFF. This function prevents the inverter from being inoperative by the external command if the mode is accidentally left unswitched from the PU operation mode.
· Set "7" (PU operation interlock) in *Pr. 79*.
· For the terminal used for X12 signal (PU operation interlock signal) input, set "12" in any of *Pr. 178 to Pr. 189 (input terminal function selection)* to assign the function. (Refer to *page 133* for *Pr. 178 to Pr. 189*.)
· When the X 12 signal has not been assigned, the function of the MRS signal switches from MRS (output stop) to the PU operation interlock signal.

X12 (MRS) Signal	Function/Operation	
	Operation mode	Parameter write
ON	Operation mode (external, PU, NET) switching enabled Output stop during external operation	Parameter write enabled (*Pr. 77 Parameter write selection*, depending on the corresponding parameter write condition (Refer to *page 64* for the parameter list))
OFF	Forcibly switched to External operation mode External operation allowed. Switching to PU or NET operation mode disabled	Parameter write disabled with exception of *Pr. 79*

<Function/operation changed by switching ON/OFF the X12 (MRS) signal>

Operating Condition		X12 (MRS) Signal	Operation Mode	Operating Status	Switching to PU, NET Operation Mode
Operation mode	Status				
PU/NET	During stop	ON→OFF *1	External *2	If external operation frequency setting and start signal are entered, operation is performed in that status.	Disallowed
	Running	ON→OFF *1			Disallowed
External	During stop	OFF→ON	External *2	During stop	Enable
		ON→OFF			Disallowed
	Running	OFF→ON		During operation → output stop	Disallowed
		ON→OFF		Output stop → operation	Disallowed

*1 The operation mode switches to External operation mode independently of whether the start signal (STF, STR) is ON or OFF. Therefore, the motor is run in External operation mode when the X12 (MRS) signal is turned OFF with either of STF and STR ON.

*2 At fault occurrence, pressing STOP RESET of the operation panel resets the inverter.

CAUTION

· If the X12 (MRS) signal is ON, the operation mode cannot be switched to PU operation mode when the start signal (STF, STR) is ON.
· When the MRS signal is used as the PU interlock signal, the MRS signal serves as the normal MRS function (output stop) by turning on the MRS signal and then changing the *Pr. 79* value to other than "7" in the PU operation mode. Also as soon as "7" is set in *Pr. 79*, the signal acts as the PU interlock signal.
· When the MRS signal is used as the PU operation interlock signal, the logic of the signal is as set in *Pr. 17*. When *Pr. 17* = "2", read ON as OFF and OFF as ON in the above explanation.
· Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

(10) Switching of operation mode by external signal (X16 signal)

- When external operation and operation from the operation panel are used together, use of the PU-external operation switching signal (X16) allows switching between the PU operation mode and External operation mode during a stop (during a motor stop, start command OFF).
- When *Pr. 79* = any of "0, 6, 7", the operation mode can be switched between the PU operation mode and External operation mode. (*Pr. 79* = "6" At switchover mode, operation mode can be changed during operation)
- For the terminal used for X16 signal input, set "16" in any of *Pr. 178 to Pr. 189 (input terminal function selection)* to assign the function.

<table>
<tr><th colspan="2" rowspan="2">Pr. 79
Setting</th><th colspan="2">X16 Signal State Operation Mode</th><th rowspan="2">Remarks</th></tr>
<tr><th>ON (external)</th><th>OFF (PU)</th></tr>
<tr><td colspan="2">0 (initial value)</td><td>External operation mode</td><td>PU operation mode</td><td>Can be switched to External, PU or NET operation mode</td></tr>
<tr><td colspan="2">1</td><td colspan="2">PU operation mode</td><td>Fixed to PU operation mode</td></tr>
<tr><td colspan="2">2</td><td colspan="2">External operation mode</td><td>Fixed to External operation mode (Can be switched to NET operation mode)</td></tr>
<tr><td colspan="2">3, 4</td><td colspan="2">External/PU combined operation mode</td><td>External/PU combined mode fixed</td></tr>
<tr><td colspan="2">6</td><td>External operation mode</td><td>PU operation mode</td><td>Can be switched to External, PU or NET operation mode with operation continued</td></tr>
<tr><td rowspan="2">7</td><td>X12(MRS) ON</td><td>External operation mode</td><td>PU operation mode</td><td>Can be switched to External, PU or NET operation mode (Output stop in External operation mode)</td></tr>
<tr><td>X12(MRS) OFF</td><td colspan="2">External operation mode</td><td>Fixed to External operation mode (Forcibly switched to External operation mode)</td></tr>
</table>

REMARKS

- The operation mode status changes depending on the setting of *Pr. 340 Communication startup mode selection* and the ON/OFF states of the X65 and X66 signals. (For details, refer to *page 213*.)
- The priorities of *Pr. 79*, *Pr. 340* and signals are *Pr. 79* > X12 > X66 > X65 > X16 > *Pr. 340*.

CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

(11) Switching of operation mode by external signal (X65, X66 signals)

- When *Pr. 79* = any of "0, 2, 6", the operation mode switching signals (X65, X66) can be used to change the PU or External operation mode to Network operation mode during a stop (during a motor stop or start command OFF). (*Pr. 79* = "6" switch-over mode can be changed during operation)
- When switching between the Network operation mode and PU operation mode
  1) Set *Pr. 79* to "0" (initial value) or "6".
  2) Set "10 or 12" in *Pr. 340 Communication startup mode selection*.
  3) Set "65" in any of *Pr. 178 to Pr. 189* to assign the PU-NET operation switchover signal (X65) to the terminal.
  4) The operation mode changes to PU operation mode when the X65 signal turns ON, or to Network operation mode when the X65 signal turns OFF.

Pr. 340 Setting	*Pr. 79* Setting		X65 Signal State		Remarks
			ON (PU)	OFF (NET)	
10, 12	0 (initial value)		PU operation mode *1	NET operation mode *2	—
	1		PU operation mode		Fixed to PU operation mode
	2		NET operation mode		Fixed to NET operation mode
	3, 4		External/PU combined operation mode		External/PU combined mode fixed
	6		PU operation mode *1	NET operation mode *2	Switching operation mode is enabled while running.
	7	X12(MRS)ON	Switching among the external and PU operation mode is enabled *2		Output stop in External operation mode
		X12(MRS)OFF	External operation mode		Forcibly switched to External operation mode

*1 NET operation mode when the X66 signal is ON.
*2 PU operation mode when the X16 signal is OFF. PU operation mode also when *Pr. 550 NET mode operation command source selection* = "0" (communication option command source) and the communication option is not fitted.
External operation mode when the X16 signal is ON.

- When switching between the network operation mode and External operation mode
  1) Set *Pr. 79* to "0" (initial value), "2", "6" or "7". (At the *Pr. 79* setting of "7", the operation mode can be switched when the X12 (MRS) signal turns ON.)
  2) Set "0 (initial value), 1 or 2" in *Pr. 340 Communication startup mode selection*.
  3) Set "66" in any of *Pr. 178 to Pr. 189* to assign the External-NET operation switching signal (X66) to the terminal.
  4) The operation mode changes to network operation mode when the X66 signal turns ON, or to External operation mode when the X66 signal turns OFF.

Pr. 340 Setting	*Pr. 79* Setting		X66 Signal State		Remarks
			ON (NET)	OFF(external)	
0 (initial value), 1, 2	0 (initial value)		NET operation mode *1	External operation mode *2	—
	1		PU operation mode		Fixed to PU operation mode
	2		NET operation mode *1	External operation mode	Switching to PU operation mode is disabled.
	3, 4		External/PU combined operation mode		External/PU combined mode fixed
	6		NET operation mode *1	External operation mode *2	Switching operation mode is enabled while running.
	7	X12(MRS)ON	NET operation mode *1	External operation mode *2	Output stop in External operation mode
		X12(MRS)OFF	External operation mode		Forcibly switched to External operation mode

*1 PU operation mode is selected when *Pr. 550 NET mode operation command source selection* = "0" (communication option command source) and the communication option is not fitted.
*2 PU operation is selected when the X16 signal is OFF. When the X65 signal has been assigned, the operation mode changes with the ON/OFF state of the X65 signal.

REMARKS

- The priorities of *Pr. 79*, *Pr. 340* and signals are *Pr. 79* > X12 > X66 > X65 > X16 > *Pr. 340*.

CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 15 Jog frequency ☞ Refer to page 104.
Pr. 4 to 6, Pr. 24 to 27, Pr. 232 to Pr. 239 Multi-speed operation ☞ Refer to page 102.
Pr. 75 Reset selection/disconnected PU detection/PU stop selection ☞ Refer to page 198.
Pr. 161 Frequency setting/key lock operation selection ☞ Refer to page 295.
Pr. 178 to Pr. 189 (Input terminal function selection) ☞ Refer to page 133.
Pr. 190 to Pr. 196 (Output terminal function selection) ☞ Refer to page 140.
Pr. 340 Communication startup mode selection ☞ Refer to page 218.
Pr. 550 NET mode operation command source selection ☞ Refer to page 219.

4

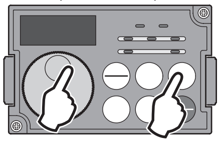
PARAMETERS

4.19.2 Setting the set frequency to operate (example: performing operation at 30Hz)

POINT

Operation panel (FR-DU07) is used to give both of frequency and start commands in PU operation.

Operation panel
(FR-DU07)

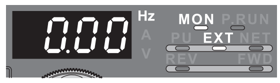


Operation example	Performing operation at 30Hz.

Operation — Display

1. Screen at power-ON

The monitor display appears.



2. Operation mode setting

Press PU/EXT to choose the PU operation mode.

PU indicator is lit.

3. Running frequency setting

Turn (setting dial) to show the frequency " 30.00 " (30.00Hz) you want to set.
The frequency flickers for about 5s.

While the value is flickering, press SET to set the frequency.

(If you do not press SET, the value flickers for about 5s and the display then returns to " 0.00 " (0.00Hz). At this time, return to "Step 3" and set the frequency again. After the value flickered for about 3s, the display returns to " 0.00 " (monitor display).

Flicker ··· Frequency setting complete!!
After 3s, the monitor display appears.

4. Start → acceleration → constant speed

Press FWD or REV to start running.
The frequency on the display increases in the *Pr. 7 Acceleration time*, and " 30.00 " (30.00Hz) appears.

To change the set frequency, perform the operation in above step 3. (Starting from the previously set frequency.)

5. Deceleration → Stop

Press STOP/RESET to stop.
The frequency on the display decreases in the *Pr. 8 Deceleration time*, and the motor stops rotating with " 0.00 " (0.00Hz) displayed.

? Operation cannot be performed at the set frequency ... Why?
- Did you carry out step 4 within 5s after step 3? (Did you press (SET) within 5s after turning ?)

? The frequency does not change by turning ... Why?
- Check to see if the operation mode selected is the External operation mode. (Press (PU/EXT) to change to the PU operation mode.)

? Operation does not change to the PU operation mode ... Why?
- Check that "0" (initial value) is set in *Pr. 79 Operation mode selection*.
- Check that the start command is not on.

? Change acceleration time *Pr. 7 (Refer to page 109)*

? Change deceleration time *Pr. 8 (Refer to page 109)*

? For example, limit the motor speed to 60Hz maximum. Set "60Hz" in *Pr. 1*. *(Refer to page 96)*

REMARKS

· Press to show the set frequency.

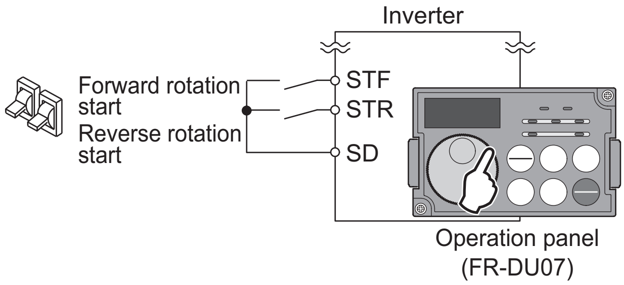
· can also be used like a potentiometer to perform operation. *(Refer to page 297)*

4.19.3 Setting the frequency by the operation panel (Pr. 79 = 3)

POINT

· Switch ON the STF (STR) signal to give a start command.
· Use ( ) on the operation panel (FR-DU07) to give a frequency command.
· Set "3" (External/PU combination operation mode 1) in *Pr. 79 Operation mode selection*.

[Connection diagram]

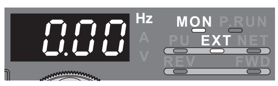


Operation example Performing operation at 30Hz.

Operation — Display

1. Screen at power-ON

The monitor display appears.



2. Operation mode setting

Set "3" in *Pr.79*.
[PU] indicator and [EXT] indicator are lit.
(To change the set value, *refer to page 62*)

4 PARAMETERS

Operation | Display

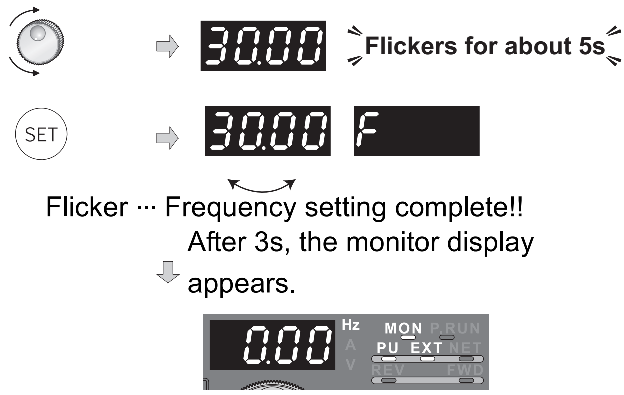
3. Running frequency setting

Turn to show the selected frequency, "30.00" (30.00Hz). The frequency flickers for about 5s.

While the value is flickering, press (SET) to set the frequency.

(If you do not press (SET), the value flickers for about 5s and the display then returns to "0.00" (display) Hz. At this time, return to "Step 8" and set the frequency again.)

After about 3s of flickering of the value, the display goes back to "0.00" (monitor display).

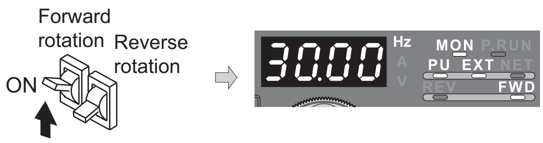


4. Start → acceleration → constant speed

Turn ON the start switch (STF or STR).

The frequency on the display increases in the *Pr.7 Acceleration time* setting, and "30.00" (30.00Hz) appears.

[FWD] indicator is lit during forward rotation, and [REV] indicator is lit during reverse rotation.



CAUTION

When both of STF and STR signals are turned ON, the motor cannot start. If both are turned ON while the motor is running, the motor decelerates to a stop.

To change the set frequency, perform the operation in above steps 9 and 10.
(Starting from the previously set frequency.)

5. Deceleration → Stop

Turn OFF the start switch (STF or STR).

The frequency on the display decreases in the *Pr. 8 Deceleration time*, and the motor stops rotating with "0.00" (0.00Hz) displayed.

REMARKS

- *Pr. 178 STF terminal function selection* must be set to "60" (or *Pr. 179 STR terminal function selection* must be set to "61"). (All are initial values)
- When *Pr. 79 Operation mode selection* is set to "3", multi-speed operation (refer to *page 102*) is also valid.

? When the inverter is stopped by (STOP/RESET) of the operation panel (FR-DU07), PS and 0.00 (Flickering) are displayed alternately.

☞ 1. Turn the start switch (STF or STR) OFF.

2. The display can be reset by (PU/EXT).

? When the setting dial like is used as a potentiometer

☞ 1. Set *Pr.160 User group read selection*="0"(Extended mode parameters valid).

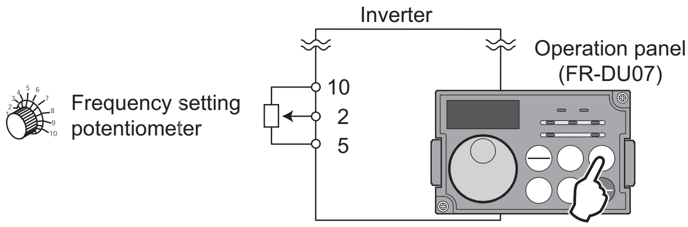
2. Set *Pr.161 Frequency setting/key lock operation selection* = "1" (setting dial potentiometer). (*Refer to page 295.)*

4.19.4 Setting the frequency by analog input (voltage input)

POINT

- Use FWD or REV on the operation panel (FR-DU07) to give a start command.
- Use the potentiometer (by connecting terminal 2 and 5) to give a frequency command.
- Set "4" (External/PU combination operation mode 2) in *Pr. 79 Operation mode selection*.

[Connection diagram]
(The inverter supplies 5V of power to the frequency setting potentiometer.(Terminal 10))

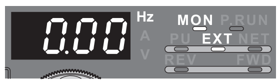


Operation example | Performing operation at 60Hz.

Operation — Display

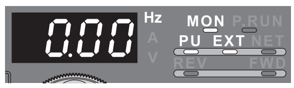
1. Screen at power-ON

The monitor display appears.



2. Operation mode setting

Set "4" in *Pr.79*.
[PU] indicator and [EXT] indicator are lit.
(To change the set value, *refer to page 62*)



3. Start

Press FWD or REV.

[FWD] or [REV] is flickering as no frequency command is given.

4. Acceleration → constant speed

Turn the potentiometer (frequency setting potentiometer) clockwise slowly to full.
The frequency value on the display increases in *Pr. 7 Acceleration time,* and "60.00"(60Hz) appears.

5. Deceleration

Turn the potentiometer (frequency setting potentiometer) counterclockwise slowly to full. The frequency on the display decreases in the *Pr. 8 Deceleration time*, and the motor stops rotating with "0.00" (0.00Hz) displayed.
[FWD] indicator or [REV] indicator flickers.

6. Stop

Press STOP/RESET

[FWD] indicator or [REV] indicator turns OFF.

? Change the frequency (60Hz) of the maximum value of potentiometer (at 5V)
☞ Adjust the frequency in *Pr. 125 Terminal 2 frequency setting gain frequency. (Refer to page 193.)*

? Change the frequency (0Hz) of the minimum value of potentiometer (at 0V)
☞ Adjust the frequency in *calibration parameter C2 Terminal 2 frequency setting bias frequency. (Refer to page 193.)*

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PARAMETERS

4.19.5 Operation mode at power-ON (Pr. 79, Pr. 340)

When power is switched ON or when power comes back on after instantaneous power failure, the inverter can be started up in Network operation mode.
After the inverter has started up in the Network operation mode, parameter write and operation can be performed from a program.
Set this mode for communication operation using the RS-485 terminals or communication option.

Parameter Number	Name	Initial Value	Setting Range	Description
79*1	**Operation mode selection**	0	0 to 4, 6, 7	Select the operation mode. *(Refer to page 208.)*
340 *2*3	**Communication startup mode selection**	0	0	As set in *Pr. 79*.
			1, 2	Started in network operation mode. When the setting is "2", it will resume the pre-instantaneous power failure operation mode after an instantaneous power failure occurs.
			10, 12	Started in network operation mode. Operation mode can be changed between the PU operation mode and Network operation mode from the operation panel. When the setting is "12", it will resume the pre-instantaneous power failure operation mode after an instantaneous power failure occurs.

The above parameters can be changed during a stop in any operation mode.
*1 This parameter allows its setting to be changed in any operation mode even if "0 (initial value) or 1" is set in *Pr. 77 Parameter write selection*.
*2 This parameter allows its setting to be changed in any operation mode even if "0 (initial value)" is set in *Pr. 77 Parameter write selection*.
*3 The parameters can be set when *Pr. 160 User group read selection* = "0". However, the parameters can be set whenever the communication option is connected. *(Refer to page 201.)*.

(1) Specify operation mode at power-ON *(Pr. 340)*

· Depending on the *Pr. 79* and *Pr. 340* settings, the operation mode at power-ON (reset) changes as described below.

Pr. 340 Setting	*Pr. 79* Setting	Operation Mode at Power ON, Power Restoration, Reset	Operation Mode Switching
0 (initial value)	0 (initial value)	External operation mode	Switching among the External, PU, and NET operation mode is enabled *2
	1	PU operation mode	Fixed to PU operation mode
	2	External operation mode	Switching between the External and Net operation mode is enabled Switching to PU operation mode is disabled
	3, 4	External/PU combined operation mode	Operation mode switching is disabled
	6	External operation mode	Switching among the External, PU, and NET operation mode is enabled while running
	7	External operation mode when X12 (MRS) signal ON	Switching among the External, PU, and NET operation mode is enabled *2
		External operation mode when X12 (MRS) signal OFF	Fixed to External operation mode (Forcibly switched to External operation mode.)
1, 2 *1	0	NET operation mode	Same as when *Pr. 340* = "0"
	1	PU operation mode	
	2	NET operation mode	
	3, 4	External/PU combined operation mode	
	6	NET operation mode	
	7	NET operation mode when X12 (MRS) signal ON	
		External operation mode when X12 (MRS) signal OFF	
10, 12 *1	0	NET operation mode	Switching between the PU and NET operation mode is enabled *3
	1	PU operation mode	Same as when *Pr. 340* = "0"
	2	NET operation mode	Fixed to NET operation mode
	3, 4	External/PU combined operation mode	Same as when *Pr. 340* = "0"
	6	NET operation mode	Switching between the PU and NET operation mode is enabled while running *3
	7	External operation mode	Same as when *Pr. 340* = "0"

*1 The *Pr. 340* setting "2" or "12" is mainly used for communication operation using the inverter RS-485 terminals. When a value other than "9999" (selection of automatic restart after instantaneous power failure) is set in *Pr. 57 Restart coasting time*, the inverter will resume the same operation state which was in before after power has been restored from an instantaneous power failure.
When *Pr. 340* = "1, 10", a start command turns OFF if power failure has occurred and then restored during a start command is ON.
*2 The operation mode cannot be switched directly between the PU operation mode and Network operation mode.
*3 Operation mode can be changed between the PU operation mode and Network operation mode with PU/EXT key of the operation panel (FR-DU07) and X65 signal.

♦ Parameters referred to ♦

Pr. 57 Restart coasting time ☞ *Refer to page 162.*
Pr. 79 Operation mode selection ☞ *Refer to page 206.*

4.19.6 Start command source and speed command source during communication operation (Pr. 338, Pr. 339, Pr. 550, Pr. 551)

When the RS-485 terminals or communication option is used, the external start command and frequency command can be valid. Also, the command source in the PU operation mode can be selected.

Parameter Number	Name	Initial Value	Setting Range	Description
338	Communication operation command source	0	0	Start command source communication
			1	Start command source external
339	Communication speed command source	0	0	Frequency command source communication
			1	Frequency command source external
			2	Frequency command source external (Frequency command from communication is valid, frequency command from terminal 2 is invalid)
550 *	NET mode operation command source selection	9999	0	The communication option is the command source when NET operation mode.
			1	RS-485 terminals are the command source when NET operation mode.
			9999	Automatic communication option recognition Normally, RS-485 terminals are the command source. When a communication option is mounted, the communication option is the command source.
551 *	PU mode operation command source selection	2	1	RS-485 terminals are the command source when PU operation mode.
			2	PU connector is the command source when PU operation mode.

The above parameters can be set when *Pr. 160 User group read selection* = "0". However, the parameters can be set whenever the communication option is connected. *(Refer to page 201.)*

* This parameter allows its setting to be changed in any operation mode even if "0 (initial value)" is set in *Pr. 77 Parameter write selection*

(1) Select the command source of the Network operation mode *(Pr. 550)*

· Either the RS-485 terminals or communication option can be specified as the command source in Network operation mode.

· For example, set *Pr. 550* to "1" when executing parameter write, start command or frequency command from the inverter RS-485 terminals in the Network operation mode independently of whether the communication option is connected or not.

CAUTION

· Since *Pr. 550* = "9999" (automatic recognition of the communication option) in the initial setting, parameter write, start command and frequency command cannot be executed by communication using the inverter RS-485 terminals when the communication option is fitted. (Monitor and parameter read can be performed.)

(2) Select the command source of the PU operation mode *(Pr. 551)*

· Either the PU connector or RS-485 terminals can be specified as the source in the PU operation mode.

· When performing parameter write, giving start command and frequency command from communication with the RS-485 terminals in PU operation mode, set "1" in *Pr. 551*.

CAUTION

· The PU operation mode has a higher priority when *Pr. 550* = "1" (NET mode RS-485 terminals) and *Pr. 551* = "1" (PU mode RS-485 terminals). When the communication option is not fitted, therefore, the operation mode cannot be switched to Network operation mode.

· Changed setting value is valid when powering ON or resetting the inverter.

Pr. 550 Setting	*Pr. 551* Setting	Command Source			Remarks
		PU connector	RS-485 terminals	Communication option	
0	1	×	PU operation mode *1	NET operation mode *2	
	2 (initial value)	PU operation mode	×	NET operation mode *2	
1	1	×	PU operation mode *1	×	Switching to NET operation mode disabled
	2 (initial value)	PU operation mode	NET operation mode	×	
9999 (initial value)	1	×	PU operation mode *1	NET operation mode *2	
	2 (initial value)	PU operation mode	×	NET operation mode	Communication option fitted
			NET operation mode	×	Communication option not fitted

*1 The Modbus-RTU protocol cannot be used in the PU operation mode. When using the Modbus-RTU protocol, set *Pr. 551* to "2".
*2 When the communication option is not fitted, the operation mode cannot be switched to Network operation mode.

(3) Controllability through communication

Operation Location	Condition (*Pr. 551* Setting)	Operation Mode / Item	PU Operation	External Operation	External/PU Combined Operation Mode 1 (*Pr. 79* = 3)	External/PU Combined Operation Mode 2 (*Pr. 79* = 4)	NET Operation (when RS-485 terminals are used) *6	NET Operation (when communication option is used) *7
Control by RS-485 communication from PU connector	2 (PU connector)	Run command (start)	○	×	×	○	×	
		Run command (stop)	○	★ *3	★ *3	○	★ *3	
		Running frequency setting	○	×	○	×	×	
		Monitor	○	○	○	○	○	
		Parameter write	○ *4	× *5	○ *4	○ *4	× *5	
		Parameter read	○	○	○	○	○	
		Inverter reset	○	○	○	○	○	
	Except for 2	Run command (start)	×	×	×	×	×	
		Run command (stop)	★ *3	★ *3	★ *3	★ *3	★ *3	
		Running frequency setting	×	×	×	×	×	
		Monitor	○	○	○	○	○	
		Parameter write	× *5	× *5	× *5	× *5	× *5	
		Parameter read	○	○	○	○	○	
		Inverter reset	○	○	○	○	○	
Control by communication from RS-485 terminals	1 (RS-485 terminals)	Run command(start, stop)	○	×	×	○	×	
		Running frequency setting	○	×	○	×	×	
		Monitor	○	○	○	○	○	
		Parameter write	○ *4	× *5	○ *4	○ *4	× *5	
		Parameter read	○	○	○	○	○	
		Inverter reset	○	○	○	○	○	
	Except for 1	Run command (start, stop)	×	×	×	×	○ *1	×
		Running frequency setting	×	×	×	×	○ *1	×
		Monitor	○	○	○	○	○	○
		Parameter write	× *5	× *5	× *5	× *5	○ *4	× *5
		Parameter read	○	○	○	○	○	○
		Inverter reset	×	×	×	×	○ *2	×
Control by communication from communication option	—	Run command (start, stop)	×	×	×	×	×	○ *1
		Running frequency setting	×	×	×	×	×	○ *1
		Monitor	○	○	○	○	○	○
		Parameter write	× *5	× *5	× *5	× *5	× *5	○ *4
		Parameter read	○	○	○	○	○	○
		Inverter reset	×	×	×	×	×	○ *2
Control circuit external terminals	—	Inverter reset	○	○	○	○	○	
		Run command (start, stop)	×	○	○	×	× *1	
		Frequency setting	×	○	×	○	× *1	

○: Enabled, ×: Disabled, ★ : Some are enabled

*1 As set in *Pr. 338 Communication operation command source* and *Pr. 339 Communication speed command source*. *(Refer to page 219)*
*2 At occurrence of RS-485 communication error, the inverter cannot be reset from the computer.
*3 Enabled only when stopped by the PU. At a PU stop, PS is displayed on the operation panel. As set in *Pr. 75 PU stop selection* . *(Refer to page 198)*
*4 Some parameters may be write-disabled according to the *Pr. 77 Parameter write selection* setting and operating status. *(Refer to page 200)*
*5 Some parameters are write-enabled independently of the operation mode and command source presence/absence. When *Pr. 77* = 2, write is enabled. (Refer to *page 64* for the parameter list)Parameter clear is disabled.
*6 When *Pr. 550 NET mode operation command source selection* = 1 (RS-485 terminals valid) or *Pr. 550 NET mode operation command source selection* = 9999 and the communication option is not fitted.
*7 When *Pr. 550 NET mode operation command source selection* = 0 (communication option valid) or *Pr. 550 NET mode operation command source selection* = 9999 and the communication option is fitted.

(4) Operation at error occurrence

<table>
<tr><th>Error Definition</th><th>Operation Mode
Condition
(*Pr. 551* setting)</th><th>PU Operation</th><th>External Operation</th><th>External/PU Combined Operation Mode 1
(*Pr. 79* =3)</th><th>External/PU Combined Operation Mode 2
(*Pr. 79* =4)</th><th>NET Operation (when RS-485 terminals are used) *5</th><th>NET Operation (when communication option is used) *6</th></tr>
<tr><td>Inverter fault</td><td>—</td><td colspan="6">Stop</td></tr>
<tr><td rowspan="2">PU disconnection of the PU connector</td><td>2 (PU connector)</td><td colspan="6">Stop/continued *1, 4</td></tr>
<tr><td>1 (RS-485 terminals)</td><td colspan="6">Stop/continued *1</td></tr>
<tr><td rowspan="2">Communication error of PU connector</td><td>2 (PU connector)</td><td>Stop/continued *2</td><td colspan="2">Continued</td><td>Stop/continued *2</td><td colspan="2">Continued</td></tr>
<tr><td>1 (RS-485 terminals)</td><td colspan="6">Continued</td></tr>
<tr><td rowspan="2">Communication error of RS-485 terminals</td><td>1 (RS-485 terminals)</td><td>Stop/continued *2</td><td colspan="2">Continued</td><td>Stop/continued *2</td><td colspan="2">Continued</td></tr>
<tr><td>2 (PU connector)</td><td colspan="4">Continued</td><td>Stop/continued *2</td><td>Continued</td></tr>
<tr><td>Communication error of communication option</td><td>—</td><td colspan="4">Continued</td><td>Stop/continued *3</td><td>Continued</td></tr>
</table>

*1 Can be selected using *Pr. 75 Reset selection/disconnected PU detection/PU stop selection*
*2 Can be selected using *Pr. 122 PU communication check time interval*, *Pr. 336 RS-485 communication check time interval, Pr. 502 Stop mode selection at communication error* or *Pr. 539 Modbus-RTU communication check time interval.*
*3 As controlled by the communication option.
*4 In the PU jog operation mode, operation is always stopped when the PU is disconnected. Whether fault (E.PUE) occurrence is allowed or not is as set in *Pr. 75 Reset selection/disconnected PU detection/PU stop selection*.
*5 When *Pr. 550 NET mode operation command source selection* = 1 (RS-485 terminals valid) or *Pr. 550 NET mode operation command source selection* = 9999 and the communication option is not fitted
*6 When *Pr. 550 NET mode operation command source selection* = 0 (communication option valid) or *Pr. 550 NET mode operation command source selection* = 9999 and the communication option is fitted

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PARAMETERS

(5) Selection of command source in Network operation mode *(Pr. 338, Pr. 339)*

- There are two control sources: operation command source, which controls the signals related to the inverter start command and function selection, and speed command source, which controls signals related to frequency setting.
- In Network operation mode, the commands from the external terminals and communication (RS-485 terminals or communication option) are as listed below.

Operation Location Selection				*Pr. 338 Communication operation command source*	0: NET			1: External			Remarks
				Pr. 339 Communication speed command source	0: NET	1:External	2:External	0: NET	1:External	2:External	
Fixed function (Terminal-equivalent function)				Running frequency from communication	NET	—	NET	NET	—	NET	
				Terminal 2	—	External	—	—	External	—	
				Terminal 4	—	External		—	External		
				Terminal 1	Compensation						
Selective function	*Pr. 178 to Pr. 189* setting	0	RL	Low-speed operation command/ remote setting clear	NET	External		NET	External		*Pr. 59* = "0" (multi-speeds) *Pr. 59* = "1 , 2" (remote)
		1	RM	Middle-speed operation command/ remote setting deceleration	NET	External		NET	External		
		2	RH	High-speed operation command/ remote setting acceleration	NET	External		NET	External		
		3	RT	Second function selection	NET			External			
		4	AU	Terminal 4 input selection	—	Combined		—	Combined		
		5	JOG	Jog operation selection	—			External			
		6	CS	Selection of automatic restart after instantaneous power failure, flying start	External						
		7	OH	External thermal relay input	External						
		8	REX	15-speed selection	NET	External		NET	External		*Pr. 59* = "0" (multi-speeds)
		10	X10	Inverter run enable signal	External						
		11	X11	FR-HC, MT-HC connection, instantaneous power failure detection	External						
		12	X12	PU operation external interlock	External						
		14	X14	PID control valid terminal	NET	External		NET	External		
		16	X16	PU/External operation switchover	External						
		24	MRS	Output stop	Combined			External			*Pr. 79* ≠ "7"
				PU operation interlock	External						*Pr. 79* = "7" When X12 signal is not assigned
		25	STOP	Start self-holding selection	—			External			
		60	STF	Forward rotation command	NET			External			
		61	STR	Reverse rotation command	NET			External			
		62	RES	Inverter reset	External						
		63	PTC	PTC thermistor input	External						
		64	X64	PID forward/reverse action switchover	NET	External		NET	External		
		65	X65	PU/NET operation switchover	External						
		66	X66	External/NET operation switchover	External						
		67	X67	Command source switchover	External						
		70	X70	DC feeding operation permission	NET			External			
		71	X71	DC feeding cancel	NET			External			
		72	X72	PID integral value reset	NET	External		NET	External		

[Explanation of table]

External : Command only from control terminal signal is valid.
NET : Command only from communication is valid
Combined : Command from either of external terminal and communication is valid.
— : Command from either of external terminal and communication is invalid.
Compensation : Command by signal from external terminal is only valid when *Pr. 28 Multi-speed input compensation selection* = "1"

REMARKS

- The command source of communication is as set in *Pr. 550* and *Pr. 551*.
- The *Pr. 338* and *Pr. 339* settings can be changed while the inverter is running when *Pr. 77* = "2". Note that the setting change is reflected after the inverter has stopped. Until the inverter has stopped, communication operation command source and communication speed command source before the setting change are valid.

(6) Switching of command source by external terminal (X67)

- In Network operation mode, the command source switching signal (X67) can be used to switch the start command source and speed command source. This signal can be utilized to control the signal input from both the control terminal and communication.
- Set "67" in any of *Pr. 178 to Pr. 189* (input terminal function selection) to assign the X67 signal to the control terminal.
- When the X67 signal is OFF, the start command source and speed command source are control terminal.

X67 Signal State	Start Command Source	Speed Command Source
No signal assignment	According to *Pr. 338*	According to *Pr. 339*
ON		
OFF	Command is valid only from control terminal signal.	

REMARKS

- The ON/OFF state of the X67 signal is reflected only during a stop. It is reflected after a stop when the terminal is switched while the inverter is running.
- When the X67 signal is OFF, a reset via communication is disabled.

CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 28 Multi-speed input compensation selection ☞ *Refer to page 106.*
Pr. 59 Remote function selection ☞ *Refer to page 106.*
Pr. 79 Operation mode selection ☞ *Refer to page 206.*

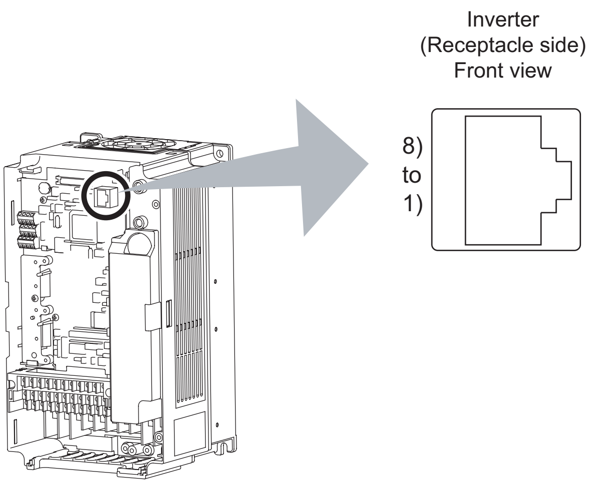
4.20 Communication operation and setting

Purpose	Parameter that must be Set		Refer to Page
Communication operation from PU connector	**Initial setting of computer link communication (PU connector)**	**Pr. 117 to Pr. 124**	229
Communication operation from RS-485 terminals	**Initial setting of computer link communication (RS-485 terminals)**	**Pr. 331 to Pr. 337, Pr. 341, Pr. 502, Pr. 779**	229
	Modbus-RTU communication specifications	**Pr. 331, Pr. 332, Pr. 334, Pr. 343, Pr. 502, Pr. 549, Pr. 779**	247
Restrictions on parameter write through communication	**Communication EEPROM write selection**	**Pr. 342**	230
Operation selection at a communication error	**Stop mode selection at communication error**	**Pr. 502, Pr. 779**	231

4.20.1 Wiring and configuration of PU connector

Using the PU connector, you can perform communication operation from a personal computer etc.
When the PU connector is connected with a personal, FA or other computer by a communication cable, a user program can run and monitor the inverter or read and write to parameters.

(1) PU connector pin-outs



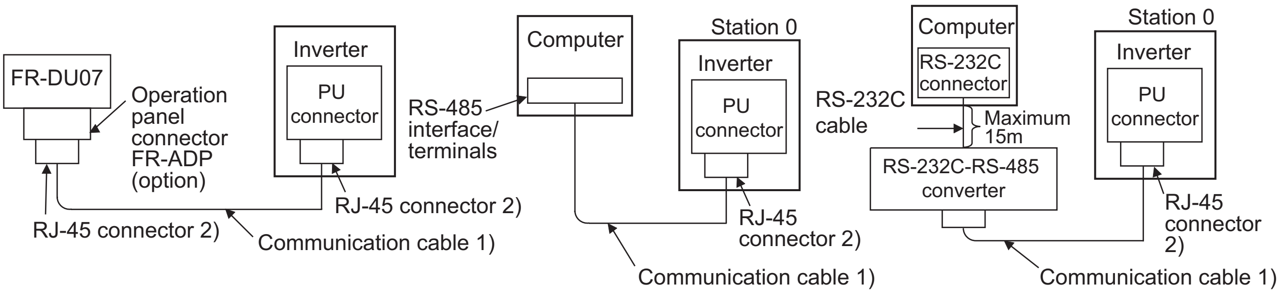
Pin Number	Name	Description
1)	SG	Earth (Ground) (connected to terminal 5)
2)	—	Operation panel power supply
3)	RDA	Inverter receive+
4)	SDB	Inverter send-
5)	SDA	Inverter send+
6)	RDB	Inverter receive-
7)	SG	Earth (Ground) (connected to terminal 5)
8)	—	Operation panel power supply

CAUTION

- Pins No. 2 and 8 provide power to the operation panel or parameter unit. Do not use these pins for RS-485 communication.
- Do not connect the PU connector to the computer's LAN board, FAX modem socket or telephone modular connector. The product could be damaged due to differences in electrical specifications.

(2) PU connector communication system configuration and wiring

● System configuration



● Connection with RS-485 computer

Computer Side Terminals		Cable connection and signal direction	Inverter
Signal name	Description	Communication cable	PU connector RS-485 terminal
RDA	Receive data	←	SDA
RDB	Receive data	←	SDB
SDA	Send data	→	RDA
SDB	Send data	→	RDB
RSA	Request to send	*	
RSB	Request to send	*	
CSA	Clear to send	*	
CSB	Clear to send	*	
SG	Signal ground	← 0.2mm² or more	SG
FG	Frame ground		

* Make connections in accordance with the manual of the computer used. Fully check the terminal numbers of the computer since they change with the model.

REMARKS

· *Refer to page 366* for the commercially available connection cables and connectors when making your own cable on the user side.

CAUTION

When performing RS-485 communication with multiple inverters, use the RS-485 terminals. *(Refer to page 227)*

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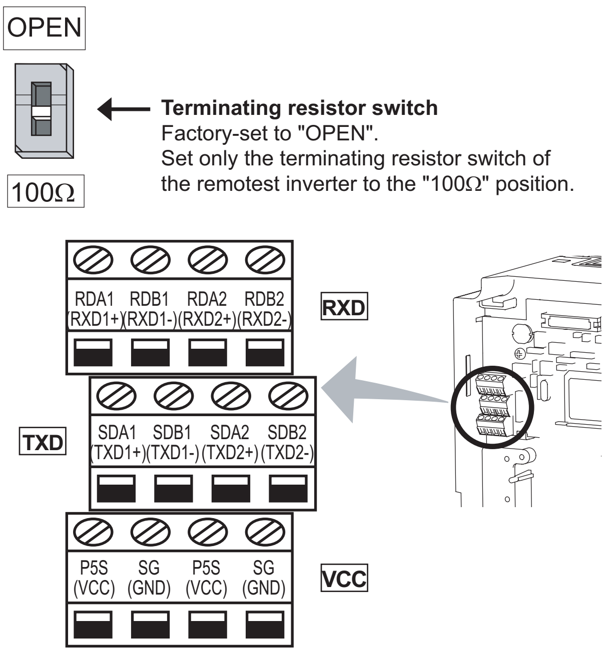
PARAMETERS

4.20.2 Wiring and configuration of RS-485 terminals

(1) RS-485 terminal layout



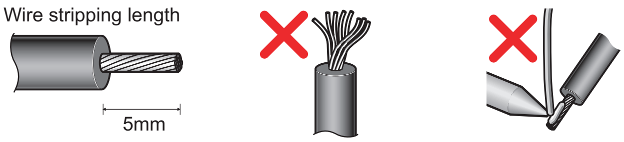
Name	Description
RDA1 (RXD1+)	Inverter receive+
RDB1 (RXD1-)	Inverter receive-
RDA2 (RXD2+)	Inverter receive+ (for branch)
RDB2 (RXD2-)	Inverter receive- (for branch)
SDA1 (TXD1+)	Inverter send+
SDB1 (TXD1-)	Inverter send-
SDA2 (TXD2+)	Inverter send+ (for branch)
SDB2 (TXD2-)	Inverter send- (for branch)
P5S (VCC)	5V Permissible load current 100mA
SG (GND)	Earth (Ground) (connected to terminal SD)

(2) Connection of RS-485 terminals and wires

Loosen the terminal screw and insert the cable into the terminal.

Screw size	M2
Tightening torque	0.22N•m to 0.25N•m
Cable size	0.3mm^2 to 0.75mm^2
Screwdriver	Small ⊖ flathead screwdriver (Tip thickness: 0.4mm /tip width: 2.5mm)

Wire the stripped cable after twisting it to prevent it from becoming loose. In addition, do not solder it.



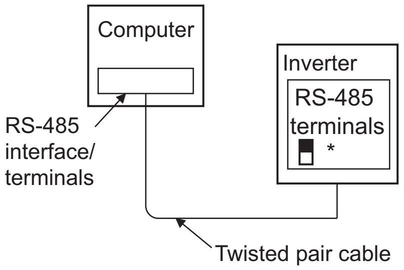
Use a blade terminal as necessary.

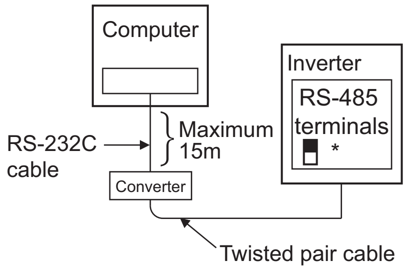
CAUTION

Undertightening can cause signal loss or malfunction. Overtightening can cause a short circuit or malfunction due to damage to the screw or unit.

(3) RS-485 terminal system configuration

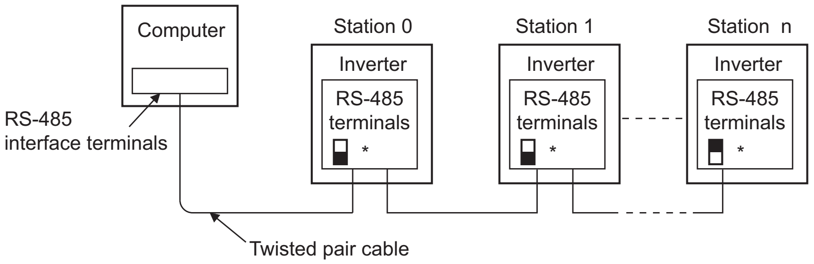
- **Connection of a computer to the inverter (1:1 connection)**



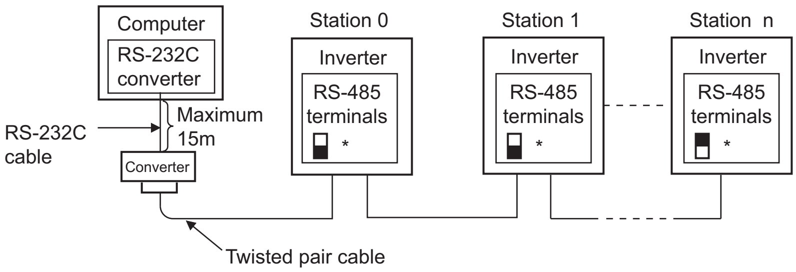


*Set the terminating resistor switch to the "100Ω" position.

- **Combination of computer and multiple inverters (1:n connection)**



*Set only the terminating resistor switch of the remotest inverter to the "100Ω" position.



*Set only the terminating resistor switch of the remotest inverter to the "100Ω" position.

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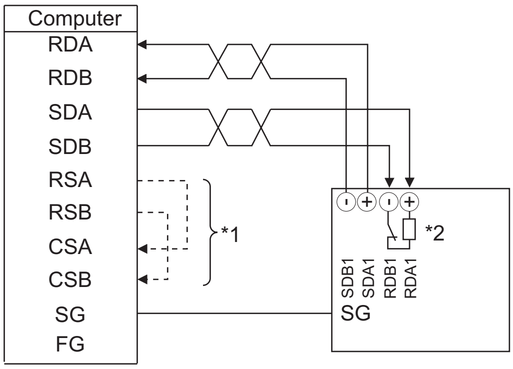
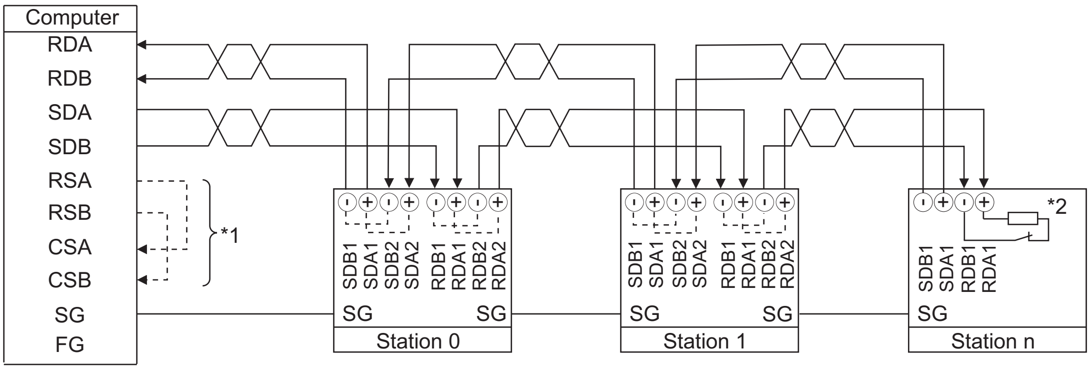
PARAMETERS

(4) RS-485 terminal wiring method

● Wiring of one RS-485 computer and one inverter



● Wiring of one RS-485 computer and "n" inverters (several inverters)

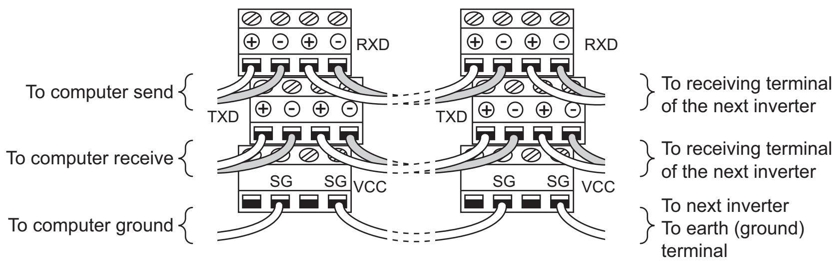


*1 Make connections in accordance with the manual of the computer used.
Fully check the terminal numbers of the computer since they change with the model.

*2 For the inverter farthest from the computer, set the terminating resistor switch to ON (100Ω side).

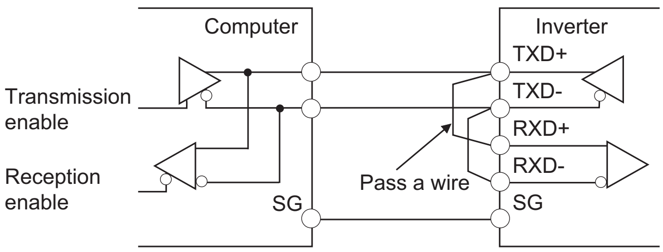
REMARKS

For branching, connect the wires as shown below.



(5) 2-wire type connection

If the computer is 2-wire type, pass wires across receiving terminals and transmission terminals of the RS-485 terminals to enable 2-wire type connection with the inverter.



REMARKS

A program should be created so that transmission is disabled (receiving state) when the computer is not sending and reception is disabled (sending state) during sending to prevent the computer from receiving its own data.

4.20.3 Initial settings and specifications of RS-485 communication (Pr. 117 to Pr. 124, Pr. 331 to Pr. 337, Pr. 341, Pr. 549)

Used to perform required settings for communication between the inverter and personal computer.

- There are two different communications: communication using the PU connector of the inverter and communication using the RS-485 terminals.
- You can perform parameter setting, monitor, etc. from the PU connector or RS-485 terminals of the inverter using the Mitsubishi inverter protocol (computer link communication).
- To make communication between the personal computer and inverter, initialization of the communication specifications must be made to the inverter.
  Data communication cannot be made if the initial settings are not made or there is any setting error.

[PU connector communication related parameter]

<table>
<tr><th>Parameter Number</th><th>Name</th><th>Initial Value</th><th>Setting Range</th><th colspan="2">Description</th></tr>
<tr><td>117</td><td>PU communication station number</td><td>0</td><td>0 to 31</td><td colspan="2">Specifies the inverter station number.
Set the inverter station numbers when two or more inverters are connected to one personal computer.</td></tr>
<tr><td>118</td><td>PU communication speed</td><td>192</td><td>48, 96, 192, 384</td><td colspan="2">Set the communication speed.
The setting value × 100 equals the communication speed.
For example, the communication speed is 19200bps when the setting value is "192".</td></tr>
<tr><td rowspan="5">119</td><td rowspan="5">PU communication stop bit length</td><td rowspan="5">1</td><td></td><td>Stop bit length</td><td>Data length</td></tr>
<tr><td>0</td><td>1 bit</td><td rowspan="2">8 bits</td></tr>
<tr><td>1</td><td>2 bits</td></tr>
<tr><td>10</td><td>1 bit</td><td rowspan="2">7 bits</td></tr>
<tr><td>11</td><td>2 bits</td></tr>
<tr><td rowspan="3">120</td><td rowspan="3">PU communication parity check</td><td rowspan="3">2</td><td>0</td><td colspan="2">Without parity check</td></tr>
<tr><td>1</td><td colspan="2">With odd parity check</td></tr>
<tr><td>2</td><td colspan="2">With even parity check</td></tr>
<tr><td rowspan="2">121</td><td rowspan="2">Number of PU communication retries</td><td rowspan="2">1</td><td>0 to 10</td><td colspan="2">Set the permissible number of retries at occurrence of a data receive error. If the number of consecutive errors exceeds the permissible value, the inverter trips.</td></tr>
<tr><td>9999</td><td colspan="2">If a communication error occurs, the inverter does not trip.</td></tr>
<tr><td rowspan="3">122</td><td rowspan="3">PU communication check time interval</td><td rowspan="3">9999</td><td>0</td><td colspan="2">No PU connector communication</td></tr>
<tr><td>0.1 to 999.8s</td><td colspan="2">Set the interval of communication check time.
If a no-communication state persists for longer than the permissible time, the inverter trips.</td></tr>
<tr><td>9999</td><td colspan="2">No communication check</td></tr>
<tr><td rowspan="2">123</td><td rowspan="2">PU communication waiting time setting</td><td rowspan="2">9999</td><td>0 to 150ms</td><td colspan="2">Set the waiting time between data transmission to the inverter and response.</td></tr>
<tr><td>9999</td><td colspan="2">Set with communication data.</td></tr>
<tr><td rowspan="3">124</td><td rowspan="3">PU communication CR/LF selection</td><td rowspan="3">1</td><td>0</td><td colspan="2">Without CR/LF</td></tr>
<tr><td>1</td><td colspan="2">With CR</td></tr>
<tr><td>2</td><td colspan="2">With CR/LF</td></tr>
</table>

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

[RS-485 terminal communication related parameter]

Parameter Number	Name	Initial Value	Setting Range	Description
331	**RS-485 communication station number**	0	0 to 31 (0 to 247) *1*6	Set the inverter station number. (same specifications as *Pr. 117*)
332	**RS-485 communication speed**	96	3, 6, 12, 24, 48, 96, 192, 384	Used to select the communication speed. (same specifications as *Pr. 118*)
333 *2	**RS-485 communication stop bit length**	1	0, 1, 10, 11	Select stop bit length and data length. (same specifications as *Pr. 119*)
334	**RS-485 communication parity check selection**	2	0, 1, 2	Select the parity check specifications. (same specifications as *Pr. 120*)
335 *3	**RS-485 communication retry count**	1	0 to 10, 9999	Set the permissible number of retries at occurrence of a data receive error. (same specifications as *Pr. 121*)
336 *3	**RS-485 communication check time interval**	0s	0	RS-485 communication is available, but the inverter trips in the NET operation mode.
			0.1 to 999.8s	Set the interval of communication check time. (same specifications as *Pr. 122*)
			9999	No communication check
337 *3	**RS-485 communication waiting time setting**	9999	0 to 150ms, 9999	Set the waiting time between data transmission to the inverter and response. (same specifications as *Pr. 123*)
341 *3	**RS-485 communication CR/LF selection**	1	0, 1, 2	Select presence/absence of CR/LF. (same specifications as *Pr. 124*)
549	**Protocol selection**	0	0	Mitsubishi inverter (computer link) protocol
			1	Modbus-RTU protocol *4

*1 When "1" (Modbus-RTU protocol) is set in *Pr. 549*, the setting range within parenthesis is applied.
*2 For the Modbus-RTU protocol, the data length is always 8 bits and the stop bit depends on the *Pr. 334* setting. *(Refer to page 247)*
*3 Invalid during the Modbus-RTU protocol.
*4 The Modbus-RTU protocol is valid for only communication from the RS-485 terminals.
*5 The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
*6 The inverter works with the initial parameter setting if a value other than the setting range is set.

CAUTION

· If communication is made without *Pr. 336 RS-485 communication check time interval* being changed from "0" (initial value), monitor, parameter read, etc. can be performed, but the inverter results in an alarm as soon as it is switched to the NET operation mode. If the operation mode at power ON is the Network operation mode, a communication fault (E.SER) occurs after first communication.
When performing operation or parameter write through communication, set "9999" or more to *Pr. 336*. (The setting depends on the computer side program.) *(Refer to page 239)*
· Always reset the inverter after making the initial settings of the parameters. After you have changed the communication-related parameters, communication cannot be made until the inverter is reset.

4.20.4 Communication EEPROM write selection (Pr. 342)

When parameter write is performed from PU connector, RS-485 terminal, and communication option connected to the inverter, parameter's storage device can be changed from EEPROM + RAM to only RAM. Set this parameter when frequent parameter changes are required.

Parameter Number	Name	Initial Value	Setting Range	Description
342	**Communication EEPROM write selection**	0	0	Parameter values written by communication are written to the EEPROM and RAM.
			1	Parameter values written by communication are written to the RAM.

The above parameters can be set when *Pr. 160 User group read selection* = "0". However, it can be set any time when the communication option is connected. *(Refer to page 201)*

· When changing the parameter values frequently, set "1" in *Pr. 342* to write them to the RAM. The life of the EEPROM will be shorter if parameter write is performed frequently with the setting unchanged from "0 (initial value)" (EEPROM write).

REMARKS

· When *Pr. 342* is set to "1" (only RAM write), the new values of the parameters will be cleared at power supply-OFF of the inverter. Therefore, the parameter values available when power is switched ON again are the values stored in EEPROM previously.

4.20.5 Operation selection at communication error (Pr.502, Pr.779)

For communication using RS-485 terminals or a communication option, operation at a communication error can be selected. The operation is active under the Network operation mode.

Parameter Number	Name	Initial Value	Setting Range	Description			
				At error occurrence	**Indication**	**Fault output**	**At error removal**
502 Ver.UP	**Stop mode selection at communication error**	0	0	Coasts to stop	E.SER*	Output	Stops (E.SER)*
			1	Decelerates to stop	E.SER after stop*	Output after stop	Stops (E.SER)*
			2	Decelerates to stop	E.SER after stop*	Without output	Restarts
			3	Continues running at *Pr. 779*	—	Without output	Operates normally
779 Ver.UP	**Operation frequency during communication error**	9999	0 to 400Hz	Motor runs at the specified frequency at a communication error.			
			9999	Motor runs at the frequency used before the communication error.			

* E.OP1 appears when using a communication option.

The above parameters can be set when *Pr. 160 User group read selection* = "0." *(Refer to page 201.)*

Ver.UP .... Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

· Select the stop operation at the retry count excess (*Pr. 335*, only with Mitsubishi inverter protocol) or at a signal loss detection (*Pr. 336*, *Pr. 539*).
· Operation at an error

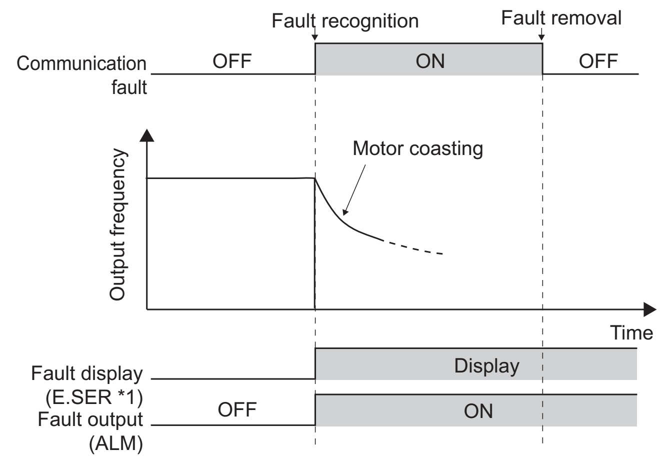
Pr. 502 setting	Operation	Indication	Fault output
0 (Initial setting)	Coasts to stop	E.SER is lit*	Output
1	Decelerates to stop	E.SER is lit after stop*	Output after stop
2			Not output
3	Operates at the frequency set in *Pr.779*.	Normal indication	Not output

· Operation after the error is removed

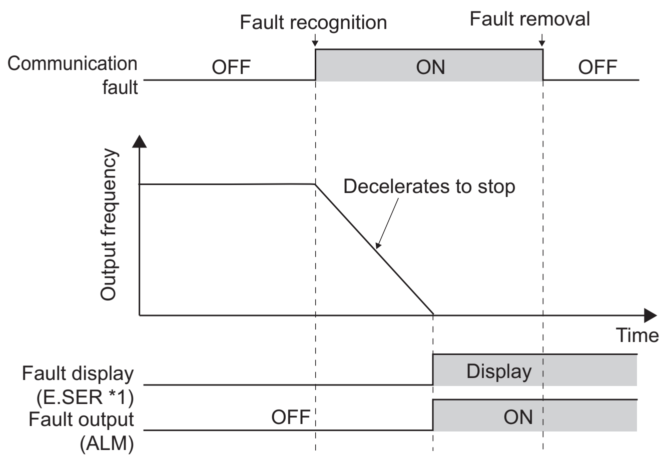
Pr. 502 setting	Operation	Indication	Fault output
0 (Initial setting)	Stop status continues	E.SER continues*	Output continues
1			
2	Restarts	Normal indication	Not output
3	Operates normally	Normal indication	Not output

* E.OP1 appears when using a communication option.

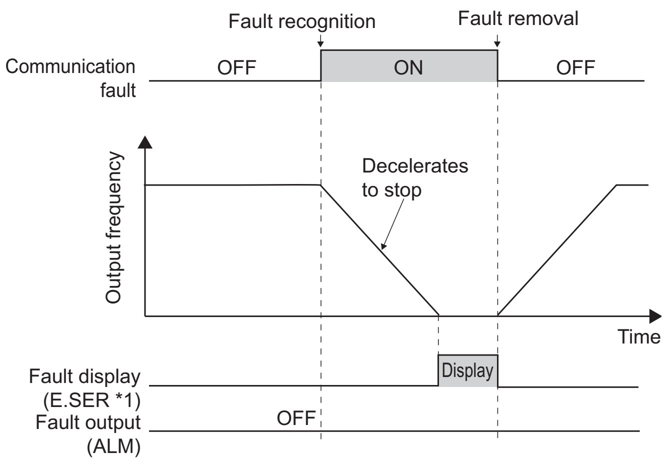
●*Pr. 502* ="0 (initial setting)"



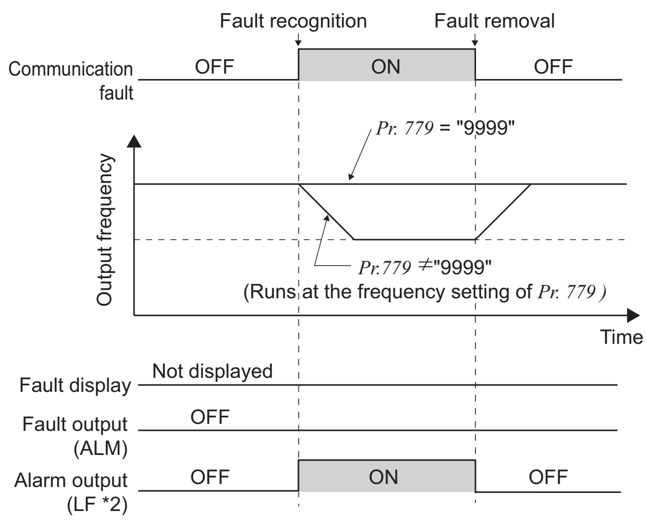
●*Pr. 502* ="1" Ver.UP



●*Pr. 502* ="2"



●*Pr. 502* ="3"



*1 E.OP1 appears when using communication through communication option.
*2 When a communication error is detected while *Pr.502* = "3," the alarm (LF) is output to an output terminal of the inverter. To use the LF signal, assign the function to an output terminal by setting "98 (positive logic) or 198 (negative logic)" in any of *Pr.190 to Pr.196 (Output terminal function selection)*.

Ver.UP ....Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

REMARKS

- Fault output indicates the fault output signal (ALM signal) and an alarm bit output.
- When the fault output setting is active, a fault record is saved in the faults history. (A fault record is written to the faults history at a fault output.)
  When the fault output setting is not active, a fault record is overwritten to the faults history temporarily but not stored.
  After the error is removed, the fault indication goes back to normal indication in the monitor, and the faults history goes back to the previous status.
- If *Pr. 502* is set to "1, 2, or 3," the normal deceleration time setting (settings like *Pr. 8, Pr. 44, and Pr. 45*) is applied as the deceleration time. Normal acceleration time setting (settings like *Pr. 7 and Pr. 44*) is applied as the acceleration time for restart.
- When *Pr.502* = "2 or 3," the inverter operates with the start command and the speed command, which were used before the error.
- If a communication line error occurs, then the error is removed during deceleration while *Pr. 502* = "2," the motor re-accelerates as soon as the error is removed.
- These parameters are valid when communication is performed from the RS-485 terminals or a communication option.
- These parameters are valid under the Network operation mode. When performing communication with RS-485 terminals, set *Pr. 551 PU mode operation command source selection* = "2 (initial setting)."
- *Pr. 502* is valid for the device that has the command source under the Network operation mode. If a communication option is installed while *Pr. 550* = "9999 (initial setting)," a communication error in RS-485 terminals occurs and *Pr. 502* becomes invalid.
- If the communication error setting is disabled with *Pr. 502* = "3," *Pr. 335* = "9999," and *Pr. 539* = "9999," the inverter does not continue its operation with the frequency set by *Pr. 779* at a communication error.
- If a communication error occurs while continuous operation at *Pr. 779* is selected with *Pr. 502* = "3," the inverter operates at the frequency set in *Pr. 779* even though the speed command source is at the external terminals.
  Example) If a communication error occurs while *Pr. 339* = "2" and the external terminal RL is ON, the operation is continued at the frequency set in *Pr. 779*.

♦ Parameters referred to ♦

Pr. 7 Acceleration time Pr. 8 Deceleration time ☞ *Refer to page 109*
Pr. 335 RS-485 communication retry count ☞ *Refer to page 229*
Pr. 336 RS-485 communication check time interval ☞ *Refer to page 229*
Pr. 539 Modbus-RTU communication check time interval ☞ *Refer to page 247*
Pr. 550 NET mode operation command source selection ☞ *Refer to page 219*
Pr. 551 PU mode operation command source selection ☞ *Refer to page 219*

4.20.6 Mitsubishi inverter protocol (computer link communication)

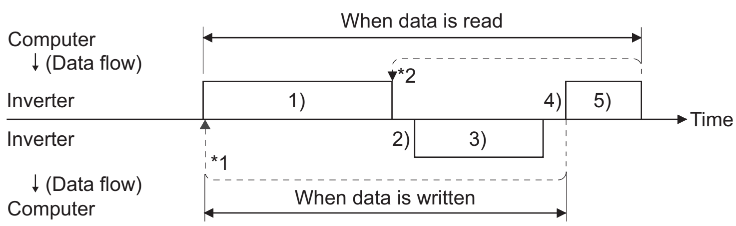
You can perform parameter setting, monitor, etc. from the PU connector or RS-485 terminals of the inverter using the Mitsubishi inverter protocol (computer link communication).

(1) Communication specifications

· The communication specifications are given below.

Item		Description	Related Parameters
Communication protocol		Mitsubishi protocol (computer link)	Pr. 551
Conforming standard		EIA-485 (RS-485)	—
Number of inverters connected		1:N (maximum 32 units), setting is 0 to 31 stations	Pr. 117 Pr. 331
Communication speed	**PU connector**	Selected among 4800/9600/19200/38400bps	Pr. 118
	RS-485 terminal	Selected among 300/600/1200/2400/4800/9600/19200/38400bps	Pr. 332
Control protocol		Asynchronous system	—
Communication method		Half-duplex system	—
Communication specifications	**Character system**	ASCII (7 bits or 8 bits can be selected)	Pr. 119 Pr. 333
	Start bit	1bit	—
	Stop bit length	1 bit or 2 bits can be selected	Pr. 119 Pr. 333
	Parity check	Check (with even or odd parity) or no check can be selected	Pr. 120 Pr. 334
	Error check	Sum code check	—
	Terminator	CR/LF (presence or absence can be selected)	Pr. 124 Pr. 341
Waiting time setting		Selectable between presence and absence	Pr. 123 Pr. 337

(2) Communication procedure



· Data communication between the computer and inverter is made in the following procedure.

1) Request data is sent from the computer to the inverter. (The inverter will not send data unless requested.)
2) After waiting for the waiting time
3) The inverter sends reply data to the computer in response to the computer request.
4) After having waited for the time taken for inverter processing
5) Answer from computer in response to reply data 3) is sent. (Even if 5) is not sent, subsequent communication is made property.)

*1 If a data error is detected and a retry must be made, execute retry operation with the user program. The inverter comes to trip if the number of consecutive retries exceeds the parameter setting.

*2 On receipt of a data error occurrence, the inverter returns "reply data 3)" to the computer again. The inverter comes to trip if the number of consecutive data errors reaches or exceeds the parameter setting.

(3) Communication operation presence/absence and data format types

· Data communication between the computer and inverter is made in ASCII code (hexadecimal code).
· Communication operation presence/absence and data format types are as follows:

Symbol	Operation		Run Command	Running Frequency	Multi command	Parameter Write	Inverter Reset	Monitor	Parameter Read
1)	Communication request is sent to the inverter in accordance with the user program in the computer.		A, A1	A	A2	A	A	B	B
2)	Inverter data processing time		Present	Present	Present	Present	Absent	Present	Present
3)	Reply data from the inverter (Data 1) is checked for error)	No error *1 (Request accepted)	C	C	C1 *3	C	C *2	E, E1, E2, E3	E
		With error. (Request rejected)	D	D	D	D	D *2	D	D
4)	Computer processing delay time		10ms or more						
5)	Answer from computer in response to reply data 3) (Data 3) is checked for error)	No error *1 (No inverter processing)	Absent	Absent	Absent (C)	Absent	Absent	Absent (C)	Absent (C)
		With error (Inverter re-outputs 3))	Absent	Absent	F	Absent	Absent	F	F

*1 In the communication request data from the computer to the inverter, 10ms or more is also required after "no data error (ACK)". *(Refer to page 237)*
*2 The inverter response to the inverter reset request can be selected. *(Refer to page 242)*
*3 At mode error, and data range error, C1 data contains an error code. *(Refer to page 246)* Except for those errors, the error is returned with data format D.

•Data writing format

Communication request data from the computer to the inverter 1)

Format	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
A	ENQ *1	Inverter station number *2		Instruction code		*3	Data				Sum check		*4						
A1	ENQ *1	Inverter station number *2		Instruction code		*3	Data		Sum check		*4								
A2	ENQ *1	Inverter station number *2		Instruction code		*3	Send data type	Receive data type	Data1				Data2				Sum check		*4

Reply data from the inverter to the computer 3) (No data error detected)

Format	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
C	ACK *1	Inverter station number *2		*4															
C1	STX *1	Inverter station number *2		Send data type	Receive data type	Error code 1	Error code 2	Data1				Data2				ETX *1	Sum check		*4

Reply data from the inverter to the computer 3) (With data error)

Format	1	2	3	4	5
D	NAK *1	Inverter station number *2		Error code	*4

*1 Indicate a control code
*2 Specify the inverter station numbers between H00 and H1F (stations 0 to 31) in hexadecimal.
*3 When *Pr.123* and *Pr.337* (Waiting time setting) ≠ 9999, create a communication request data without "waiting time" in the data format. (The number of characters decreases by 1.)
*4 CR, LF code
When data is transmitted from the computer to the inverter, codes CR (carriage return) and LF (line feed) are automatically set at the end of a data group on some computers. In this case, setting must also be made on the inverter according to the computer. Whether the CR and LF codes will be present or absent can be selected using *Pr. 124, Pr. 341* (CR/LF selection).

•Data reading format

Communication request data from the computer to the inverter 1)

Format	Number of Characters								
	1	2	3	4	5	6	7	8	9
B	ENQ *1	Inverter station number *2		Instruction code		*3	Sum check		*4

Reply data from the inverter to the computer 3) (No data error detected)

Format	Number of Characters												
	1	2	3	4	5	6	7	8	9	10	11	12	13
E	STX *1	Inverter station number *2		Read data				ETX *1	Sum check		*4		
E1	STX *1	Inverter station number *2		Read data		ETX *1	Sum check		*4				
E2	STX *1	Inverter station number *2		Read data						ETX *1	Sum check		*4

Format	Number of Characters							
	1	2	3	4 to 23	24	25	26	27
E3	STX *1	Inverter station number *2		Read data (Inverter model information)	ETX *1	Sum check		*4

Reply data from the inverter to the computer 3) (With data error)

Format	Number of Characters				
	1	2	3	4	5
D	NAK *1	Inverter station number *2		Error code	*4

Send data from the computer to the inverter 5)

Format	Number of Characters			
	1	2	3	4
C (Without data error)	ACK *1	Inverter station number *2		*4
F (With data error)	NAK *1	Inverter station number *2		*4

*1 Indicate a control code

*2 Specify the inverter station numbers between H00 and H1F (stations 0 to 31) in hexadecimal.

*3 When *Pr.123* and *Pr.337* (Waiting time setting) ≠ 9999, create a communication request data without "waiting time" in the data format. (The number of characters decreases by 1.)

*4 CR, LF code
When data is transmitted from the computer to the inverter, codes CR (carriage return) and LF (line feed) are automatically set at the end of a data group on some computers. In this case, setting must also be made on the inverter according to the computer. Whether the CR and LF codes will be present or absent can be selected using *Pr. 124, Pr. 341* (CR/LF selection).

(4) Data definitions

1) Control codes

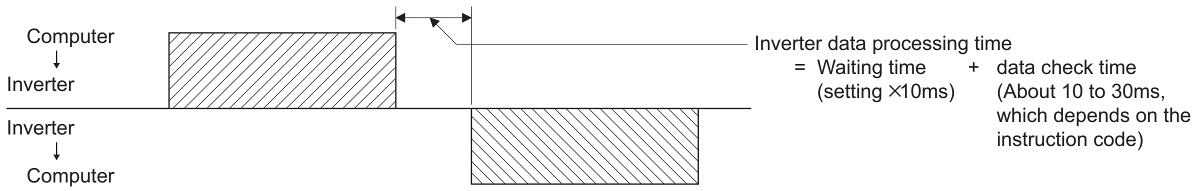
Signal Name	ASCII Code	Description
STX	H02	Start Of Text (start of data)
ETX	H03	End Of Text (end of data)
ENQ	H05	Enquiry (communication request)
ACK	H06	Acknowledge (no data error detected)
LF	H0A	Line Feed
CR	H0D	Carriage Return
NAK	H15	Negative Acknowledge (data error detected)

2) Inverter station number
Specify the station number of the inverter which communicates with the computer.

3) Instruction code
Specify the processing request, e.g. operation or monitoring, given by the computer to the inverter. Hence, the inverter can be run and monitored in various ways by specifying the instruction code as appropriate. *(Refer to page 64)*

4) Data
Indicates the data such as frequency and parameters transferred to and from the inverter. The definitions and ranges of set data are determined in accordance with the instruction codes. *(Refer to page 64)*

5) Waiting time
Specify the waiting time between the receipt of data at the inverter from the computer and the transmission of reply data. Set the waiting time in accordance with the response time of the computer between 0 and 150ms in 10ms increments (e.g. 1 = 10ms, 2 = 20ms).



REMARKS

- When *Pr. 123, Pr. 337 (waiting time setting)* ≠ "9999", create the communication request data without "waiting time" in the data format. (The number of characters decreases by 1.)
- The data check time changes depending on the instruction code. *(Refer to page 238)*

6) Sum check code
The sum check code is 2-digit ASCII (hexadecimal) representing the lower 1 byte (8 bits) of the sum (binary) derived from the checked ASCII data

(Example 1)
Computer→ Inverter

	ENQ	Station number		Instruction code		*Waiting time	Data				Sum check code		
		0	1	E	1	1	0	7	A	D	F	4	←Binary code
ASCII Code →	H05	H30	H31	H45	H31	H31	H30	H37	H41	H44	H46	H34	

H30+H31+H45+H31+H31+H30+H37+H41+H44
=H1F4
Sum

* When the *Pr. 123 (waiting time setting)*≠"9999", create the communication request data without "waiting time" in the data format. (The number of characters decreases by 1.)

(Example 2)
Inverter → Computer

	STX	Station number		Data read				ETX	Sum check code		
		0	1	1	7	7	0		3	0	←Binary code
ASCII Code →	H02	H30	H31	H31	H37	H37	H30	H03	H33	H30	

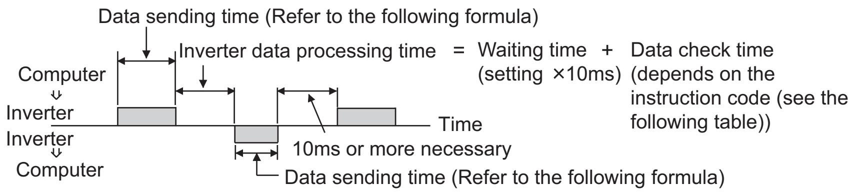
H30+H31+H31+H37+H37+H30
= H130
Sum

7) Error Code

If any error is found in the data received by the inverter, its definition is sent back to the computer.

Error Code	Error Item	Error Definition	Inverter Operation
H0	Computer NAK error	The number of errors consecutively detected in communication request data from the computer is greater than allowed number of retries.	Brought to trip if error occurs continuously more than the allowable number of retries. (E.PUE/E.SER)
H1	Parity error	The parity check result does not match the specified parity.	
H2	Sum check error	The sum check code in the computer does not match that of the data received by the inverter.	
H3	Protocol error	The data received by the inverter has a grammatical mistake. Alternatively, data receive is not completed within the predetermined time. CR or LF is not as set in the parameter.	
H4	Framing error	The stop bit length differs from the initial setting.	
H5	Overrun error	New data has been sent by the computer before the inverter completes receiving the preceding data.	
H6	—	—	—
H7	Character error	The character received is invalid (other than 0 to 9, A to F, control code).	Does not accept received data but is not brought to trip.
H8	—	—	—
H9	—	—	—
HA	Mode error	Parameter write was attempted in other than the computer link operation mode, when operation command source is not selected or during inverter operation.	Does not accept received data but is not brought to trip.
HB	Instruction code error	The specified command does not exist.	
HC	Data range error	Invalid data has been specified for parameter write, frequency setting, etc.	
HD	—	—	—
HE	—	—	—
HF	Normal (no error)	—	—

(5) Response time



[Formula for data sending time]

$$\frac{1}{\text{Communication speed (bps)}} \times \begin{array}{c}\text{Number of data}\\\text{characters}\\\textit{(Refer to page 235)}\end{array} \times \begin{array}{l}\text{Communication specifications}\\\text{(total number of bits)} = \text{Data send time (s)}\\\text{(See below.)}\end{array}$$

●Communication specifications

Name		Number of Bits
Stop bit length		1 bit 2 bits
Data length		7 bits 8 bits
Parity check	Yes	1 bit
	No	0

In addition to the above, 1 start bit is necessary.
Minimum number of total bits....... 9 bits
Maximum number of total bits...... 12 bits

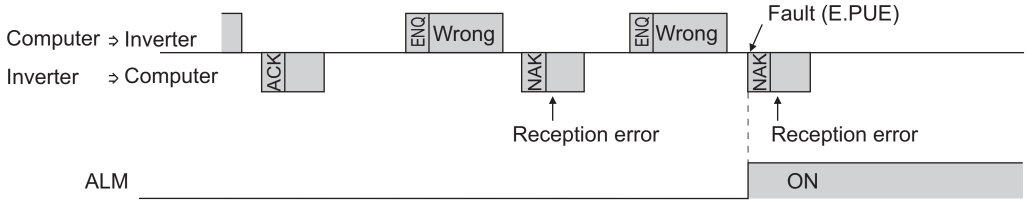
●Data check time

Item	Check Time
Various monitors, run command, frequency setting (RAM)	<12ms
Parameter read/write, frequency setting (EEPROM)	<30ms
Parameter clear/all clear	<5s
Reset command	No answer

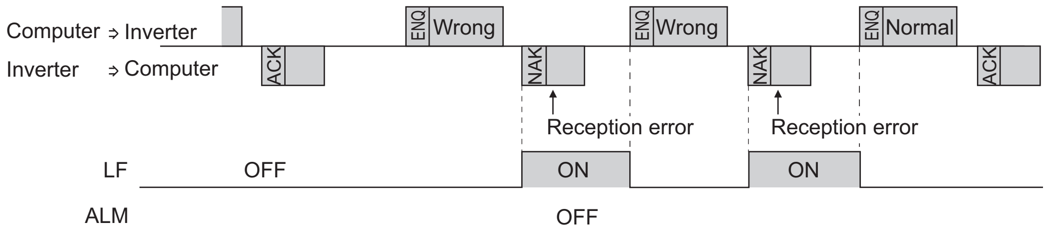
(6) Retry count setting (*Pr. 121, Pr. 335*)

- Set the permissible number of retries at occurrence of a data receive error. (Refer to *page 238* for data receive error for retry)
- When data receive errors occur consecutively and exceed the permissible number of retries set, an inverter trip (E.PUE) may occur and stops the motor.
- When "9999" is set, an inverter will not trip even if data receive error occurs but an alarm output signal (LF) is output. For the terminal used for the LF signal output, assign the function by setting "98 (positive logic) or 198 (negative logic)" in any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

Example: PU connector communication, *Pr. 121* = "1" (initial value)



Example: PU connector communication, *Pr. 121* = "9999"



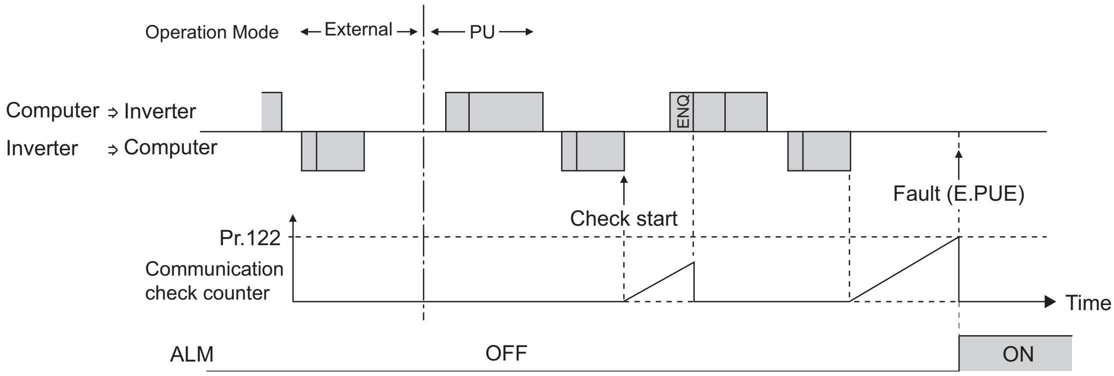
REMARKS

When using RS-485 terminal communication, inverter behavior at fault occurrence varies depending on the *Pr. 502 Stop mode selection at communication error* setting. *(Refer to page 231)*

(7) Signal loss detection *(Pr. 122, Pr. 336 RS-485 communication check time interval)*

- If a signal loss (communication stop) is detected between the inverter and computer as a result of signal loss detection, a communication fault (PU connector communication: E.PUE, RS-485 terminal communication: E.SER) occurs and the inverter trips.
- Signal loss detection is made when the setting is any of "0.1s" to "999.8s". To make a signal loss detection, it is necessary to send data (control code *refer to page 237*) from the computer within the communication check time interval. (The send data has nothing to do with the station number)
- Communication check is started at the first communication in the operation mode having the command source (PU operation mode for PU connector communication in the initial setting or network operation mode for RS-485 terminal communication).
- When the setting is "9999", communication check (a signal loss detection) is not made.
- When the setting is "0", communication from the PU connector cannot be performed. For communication via the RS-485 terminals, monitor, parameter read, etc. can be performed, but a communication error (E.SER) occurs as soon as the inverter is switched to Network operation mode.

Example: PU connector communication, *Pr. 122* = "0.1 to 999.8s"



REMARKS

When using RS-485 terminal communication, inverter behavior at fault occurrence varies depending on the *Pr. 502 Stop mode selection at communication error* setting. *(Refer to page 231)*

(8) Instructions for the program

1) When data from the computer has any error, the inverter does not accept that data. Hence, in the user program, always insert a retry program for data error.
2) All data communication, e.g. run command or monitoring, are started when the computer gives a communication request. The inverter does not return any data without the computer's request. Hence, design the program so that the computer gives a data read request for monitoring, etc. as required.
3) Program example
   To change the operation mode to computer link operation

Programming example of Microsoft® Visual C++® (Ver.6.0)

```
#include <stdio.h>
#include <windows.h>

void main(void){
        HANDLE          hCom;           // Communication handle
        DCB             hDcb;           // Structure for communication setting
        COMMTIMEOUTS            hTim;   // Structure for time out setting

        char            szTx[0x10];             // Send buffer
        char            szRx[0x10];             // Receive buffer
        char            szCommand[0x10];// Command
        int             nTx,nRx;                // For buffer size storing
        int             nSum;                   // For sum code calculation
        BOOL            bRet;
        int             nRet;
        int             i;

        //**** Opens COM1 port****
        hCom = CreateFile ("COM1", (GENERIC_READ | GENERIC_WRITE), 0, NULL, OPEN_EXISTING, FILE_ATTRIBUTE_NORMAL, NULL);
        if (hCom != NULL) {
                //**** Makes a communication setting of COM1 port****
                GetCommState(hCom,&hDcb);                               // Retrieves current communication information
                hDcb.DCBlength = sizeof(DCB);                           // Structure size setting
                hDcb.BaudRate  = 19200;                                 // Communication speed=19200bps
                hDcb.ByteSize  = 8;                                     // Data length=8bit
                hDcb.Parity    = 2;                                     // Even parity
                hDcb.StopBits  = 2;                                     // Stop bit=2bit
                bRet = SetCommState(hCom,&hDcb);                        // Sets the changed communication data
                if (bRet == TRUE) {
                        //**** Makes a time out setting of COM1 port****
                        Get CommTimeouts(hCom,&hTim);                   // Obtains the current time out value
                        hTim.WriteTotalTimeoutConstant = 1000;          // Write time out 1s
                        hTim.ReadTotalTimeoutConstant  = 1000;          // Read time out 1s
                        SetCommTimeouts(hCom,&hTim);                    // Changed time out value setting
                        //**** Sets the command to switch the operation mode of the station 1 inverter to the network operation mode ****
                        sprintf(szCommand,"01FB10000");                 // Send data (NET operation write)
                        nTx = strlen(szCommand);                        //Send data size
                        //**** Generates sum code****
                        nSum = 0;                                       // Initialization of sum data
                        for (i = 0;i < nTx;i++) {
                                nSum += szCommand[i];                   // Calculates sum code
                                nSum &= (0xff);                         // Masks data
                        }

                        //**** Generates send data****
                        memset(szTx,0,sizeof(szTx));                    // Initialization of send buffer
                        memset(szRx,0,sizeof(szRx));                    // Initialization of receive buffer
                        sprintf(szTx,"\5%s%02X",szCommand,nSum);// ENQ code+send data+sum code
                        nTx = 1 + nTx + 2;                              // Number of ENQ code+number of send data+number of sum code

                        nRet = WriteFile(hCom,szTx,nTx,&nTx,NULL);
                        //**** Sending ****
                        if(nRet != 0) {
                                nRet = ReadFile(hCom,szRx,sizeof(szRx),&nRx,NULL);
                        //**** Receiving ****
                                if(nRet != 0) {
                                        //**** Displays the receive data ****
                                        for(i = 0;i < nRx;i++) {
                                                printf("%02X ",(BYTE)szRx[i]);// Consol output of receive data
                                                // Displays ASCII coder in hexadecimal. Displays 30 when "0"
                                        }
                                        printf("\n\r");
                                }
                        }
                }
                CloseHandle(hCom);                                      // Close communication port
        }
}
```

General flowchart

Port open
↓
Communication setting
↓
Time out setting
↓
Send data processing
- ○Data setting
- ○Sum code calculation
- ○Data transmission

↓
Receive data waiting
↓
Receive data processing
- ○Data retrieval
- ○Screen display

⚠ CAUTION

⚠ Always set the communication check time interval before starting operation to prevent hazardous conditions.

⚠ Data communication is not started automatically but is made only once when the computer provides a communication request. If communication is disabled during operation due to signal loss etc., the inverter cannot be stopped. When the communication check time interval has elapsed, the inverter will come to trip (E.PUE, E.SER). The inverter can be coasted to a stop by switching on its RES signal or by switching power OFF.

⚠ If communication is broken due to signal loss, computer fault etc., the inverter does not detect such a fault. This should be fully noted.

(9) Setting items and set data

After completion of parameter setting, set the instruction codes and data then start communication from the computer to allow various types of operation control and monitoring.

<table>
<tr><th>No.</th><th colspan="2">Item</th><th>Read /write</th><th>Instruction Code</th><th>Data Description</th><th>Number of Data Digits (format)</th></tr>
<tr><td rowspan="2">1</td><td colspan="2" rowspan="2">Operation Mode</td><td>Read</td><td>H7B</td><td rowspan="2">H0000: Network operation
H0001: External operation
H0002: PU operation
(RS-485 communication operation via PU connector)</td><td>4 digits (B.E/D)</td></tr>
<tr><td>Write</td><td>HFB</td><td>4 digits (A,C/D)</td></tr>
<tr><td rowspan="8">2</td><td rowspan="8">Monitor</td><td>Output frequency/ speed</td><td>Read</td><td>H6F</td><td>H0000 to HFFFF: Output frequency in 0.01Hz increments
Speed in 1r/min increments (when Pr. 37 = 1 to 9998 or Pr. 144 = 2 to 10, 102 to 110)</td><td>4 digits (B.E/D)</td></tr>
<tr><td>Output current</td><td>Read</td><td>H70</td><td>H0000 to HFFFF: Output current (hexadecimal) in 0.01A increments (55K or lower) / 0.1A increments (75K or higher)</td><td>4 digits (B.E/D)</td></tr>
<tr><td>Output voltage</td><td>Read</td><td>H71</td><td>H0000 to HFFFF: Output voltage (hexadecimal) in 0.1V increments</td><td>4 digits (B.E/D)</td></tr>
<tr><td>Special monitor</td><td>Read</td><td>H72</td><td>H0000 to HFFFF: Monitor data selected in instruction code HF3</td><td>4 digits (B.E/D)</td></tr>
<tr><td rowspan="2">Special monitor selection No.</td><td>Read</td><td>H73</td><td rowspan="2">H01 to H41: Monitor selection data
Refer to the special monitor No. table (page 244)</td><td>2 digits (B.E1/D)</td></tr>
<tr><td>Write</td><td>HF3</td><td>2 digits (A1,C/D)</td></tr>
<tr><td>Fault record</td><td>Read</td><td>H74 to H77</td><td>H0000 to HFFFF: Two most recent fault records

b15 — b8 b7 — b0
H74: Second fault in past | Latest fault
H75: Fourth fault in past | Third fault in past
H76: Sixth fault in past | Fifth fault in past
H77: Eighth fault in past | Seventh fault in past

Refer to the fault data table (page 245)</td><td>4 digits (B.E/D)</td></tr>
<tr><td colspan="3"></td><td colspan="2"></td></tr>
<tr><td rowspan="2">3</td><td colspan="2">Run command (extended)</td><td>Write</td><td>HF9</td><td rowspan="2">You can set the control input commands such as the forward rotation signal (STF) and reverse rotation signal (STR). (Refer to page 245 for details)</td><td>4 digits (A,C/D)</td></tr>
<tr><td colspan="2">Run command</td><td>Write</td><td>HFA</td><td>2 digits (A1,C/D)</td></tr>
<tr><td rowspan="2">4</td><td colspan="2">Inverter status monitor (extended)</td><td>Read</td><td>H79</td><td rowspan="2">You can monitor the states of the output signals such as forward rotation, reverse rotation and inverter running (RUN). (Refer to page 246 for details)</td><td>4 digits (B.E/D)</td></tr>
<tr><td colspan="2">Inverter status monitor</td><td>Read</td><td>H7A</td><td>2 digits (B.E1/D)</td></tr>
<tr><td rowspan="4">5</td><td colspan="2">Set frequency (RAM)</td><td rowspan="2">Read</td><td>H6D</td><td rowspan="2">Read the set frequency/speed from the RAM or EEPROM.
H0000 to HFFFF: Set frequency in 0.01Hz increments
Speed in 1r/min increments (When Pr. 37 = 1 to 9998 or Pr. 144 = 2 to 10, 102 to 110)</td><td rowspan="2">4 digits (B.E/D)</td></tr>
<tr><td colspan="2">Set frequency (EEPROM)</td><td>H6E</td></tr>
<tr><td colspan="2">Set frequency (RAM)</td><td rowspan="2">Write</td><td>HED</td><td rowspan="2">Write the set frequency/speed into the RAM or EEPROM.
H0000 to H9C40 (0 to 400.00Hz) : frequency in 0.01Hz increments
H0000 to H270E (0 to 9998) : speed in r/min increments (when Pr. 37 = 1 to 9998 or Pr. 144 = 2 to 10, 102 to 110)
· To change the running frequency consecutively, write data to the inverter RAM. (Instruction code: HED)</td><td rowspan="2">4 digits (A,C/D)</td></tr>
<tr><td colspan="2">Set frequency (RAM, EEPROM)</td><td>HEE</td></tr>
<tr><td rowspan="2">6</td><td colspan="2" rowspan="2">Inverter reset</td><td rowspan="2">Write</td><td rowspan="2">HFD</td><td>H9696: resets the inverter
· As the inverter is reset at start of communication by the computer, the inverter cannot send reply data back to the computer.</td><td>4 digits (A,C/D)</td></tr>
<tr><td>H9966: resets the inverter
· When data is sent normally, ACK is returned to the computer and then the inverter is reset.</td><td>4 digits (A,D)</td></tr>
</table>

Refer to *page 235* for data formats (A, A1, A2, B, C, C1, D, E, E1, E2, E3, F)

<table>
<tr><th>No.</th><th colspan="2">Item</th><th>Read /write</th><th>Instruction Code</th><th>Data Description</th><th>Number of Data Digits (format)</th></tr>
<tr><td>7</td><td colspan="2">Faults history batch clear</td><td>Write</td><td>HF4</td><td>H9696: clears the faults history as a batch</td><td>4 digits (A,C/D)</td></tr>
<tr><td>8</td><td colspan="2">Parameter clear
All parameter clear</td><td>Write</td><td>HFC</td><td>All parameters return to the initial values.
Whether to clear communication parameters or not can be selected according to data. (○: clear, ×: not clear)
Refer to page 368 for parameter clear, all clear, and communication parameters.
<table><tr><th>Clear type</th><th>Data</th><th>Communication parameters</th></tr><tr><td rowspan="2">Parameter clear</td><td>H9696</td><td>○</td></tr><tr><td>H5A5A</td><td>×</td></tr><tr><td rowspan="2">All parameter clear</td><td>H9966</td><td>○</td></tr><tr><td>H55AA</td><td>×</td></tr></table>When clear is executed for H9696 or H9966, communication-related parameter settings also return to the initial values. When resuming operation, set the parameters again.
Executing clear will clear the instruction code HEC, HF3, and HFF settings.
Only H9966 and H55AA (all parameter clear) are valid during the password lock.</td><td>4 digits (A,C/D)</td></tr>
<tr><td>9</td><td colspan="2" rowspan="2">Parameters</td><td>Read</td><td>H00 to H63</td><td rowspan="2">Refer to the instruction code (page 368) and write and/or read the values as required.
When setting Pr.100 and later, link parameter expansion setting must be set.</td><td>4 digits (B.E/D)</td></tr>
<tr><td>10</td><td>Write</td><td>H80 to HE3</td><td>4 digits (A,C/D)</td></tr>
<tr><td rowspan="2">11</td><td colspan="2" rowspan="2">Link parameter extended setting</td><td>Read</td><td>H7F</td><td rowspan="2">Parameter description is changed according to the H00 to H09 setting.
For details of the setting, refer to the instruction code (page 368).</td><td>2 digits (B.E1/D)</td></tr>
<tr><td>Write</td><td>HFF</td><td>2 digits (A1,C/D)</td></tr>
<tr><td rowspan="2">12</td><td colspan="2" rowspan="2">Second parameter changing (instruction code HFF=1)</td><td>Read</td><td>H6C</td><td rowspan="2">When setting the calibration parameters *1
H00:Frequency *2
H01: Parameter-set analog value
H02: Analog value input from terminal
*1 Refer to the list of calibration parameters on the next page for calibration parameters.
*2 The gain frequency can also be written using Pr. 125 (instruction code H99) or Pr. 126 (instruction code H9A).</td><td>2 digits (B.E1/D)</td></tr>
<tr><td>Write</td><td>HEC</td><td>2 digits (A1,C/D)</td></tr>
<tr><td>13</td><td colspan="2">Multi command</td><td>Write/ Read</td><td>HF0</td><td>Available for writing 2 commands, and monitoring 2 items for reading data (Refer to page 246 for detail)</td><td>10 digits (A2,C1/D)</td></tr>
<tr><td rowspan="2">14</td><td rowspan="2">Inverter model monitor</td><td>Inverter model</td><td>Read</td><td>H7C</td><td>Reading inverter model in ASCII code.
"H20" (blank code) is set for blank area
Example of FR-F720P
H46, H52, H2D, H46, H37, H32, H30, H50, H20 .. H20</td><td>20 digits (B,E3/D)</td></tr>
<tr><td>Capacity</td><td>Read</td><td>H7D</td><td>Reading inverter capacity in ASCII code.
Data is read in increments of 0.1kW, and rounds down to 0.01kW increments
"H20" (blank code) is set for blank area
Example
0.75K................"   7" (H20, H20, H20, H20, H20, H37)</td><td>6 digits (B,E2/D)</td></tr>
</table>

Refer to *page 235* for data formats (A, A1, A2, B, C, C1, D, E, E1, E2, E3, F)

REMARKS

- Set 65520 (HFFF0) as a parameter value "8888" and 65535 (HFFFF) as "9999".
- For the instruction codes HFF, HEC and HF3, their values are held once written but cleared to zero when an invegrter reset or all clear is performed.

Example) When reading the *C3 (Pr. 902) and C6 (Pr. 904)* settings from the inverter of station No. 0

	Computer Send Data	Inverter Send Data	Description
1)	ENQ 00 FF 0 01 82	ACK 00	Set "H01" in the extended link parameter.
2)	ENQ 00 EC 0 01 7E	ACK 00	Set "H01" in second parameter changing.
3)	ENQ 00 5E 0 0F	STX 00 0000 ETX 25	*C3 (Pr. 902)* is read. 0% is read.
4)	ENQ 00 60 0 FB	STX 00 0000 ETX 25	*C6 (Pr. 904)* is read. 0% is read.

To read/write *C3 (Pr. 902)* and *C6 (Pr. 904)* after inverter reset or parameter clear, execute from 1) again.

●List of calibration parameters

Parameter	Name	Instruction code Read	Write	Extended
C2 (902)	Terminal 2 frequency setting bias frequency	5E	DE	1
C3 (902)	Terminal 2 frequency setting bias	5E	DE	1
125 (903)	Terminal 2 frequency setting gain frequency	5F	DF	1
C4 (903)	Terminal 2 frequency setting gain	5F	DF	1
C5 (904)	Terminal 4 frequency setting bias frequency	60	E0	1
C6 (904)	Terminal 4 frequency setting bias	60	E0	1
126 (905)	Terminal 4 frequency setting gain frequency	61	E1	1
C7 (905)	Terminal 4 frequency setting gain	61	E1	1
C42 (934)	PID display bias coefficient	22	A2	9
C43 (934)	PID display bias analog value	22	A2	9
C44 (935)	PID display gain coefficient	23	A3	9
C45 (935)	PID display gain analog value	23	A3	9

[Special monitor selection No.]

Refer to *page 152* for details of the monitor description.

Data	Description	Unit
H01	Output frequency/speed *4	0.01Hz/1
H02	Output current	0.01A/0.1A *3
H03	Output voltage	0.1V
H05	Frequency setting value/speed setting *4	0.01Hz/1
H06	Running speed	1r/min
H08	Converter output voltage	0.1V
H09	Regenerative brake duty	0.1%
H0A	Electronic thermal relay function load factor	0.1%
H0B	Output current peak value	0.01A/0.1A *3
H0C	Converter output voltage peak value	0.1V
H0D	Input power	0.01kW/ 0.1kW *3
H0E	Output power	0.01kW/ 0.1kW *3
H0F	Input terminal status *1	—
H10	Output terminal status *2	—
H11	Load meter	0.1%
H14	Cumulative energization time	1h
H17	Actual operation time	1h
H18	Motor load factor	0.1%
H19	Cumulative power	1kWh
H32	Power saving effect	Variable
H33	Cumulative saving power	Variable
H34	PID set point	0.1%
H35	PID measured value	0.1%
H36	PID deviation	0.1%
H3A	Option input terminal status 1 *5	—
H3B	Option input terminal status 2 *6	—
H3C	Option output terminal status *7	—
H4D	32-bit cumulative power (lower 16-bit) Ver.UP	1kWh
H4E	32-bit cumulative power (upper 16-bit) Ver.UP	1kWh
H4F	32-bit cumulative power (lower 16-bit) Ver.UP	0.01kWh/ 0.1kWh *1
H50	32-bit cumulative power (upper 16-bit) Ver.UP	0.01kWh/ 0.1kWh *1

Ver.UP ....Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

*1 Input terminal monitor details

b15															b0
—	—	—	—	CS	RES	STOP	MRS	JOG	RH	RM	RL	RT	AU	STR	STF

*2 Output terminal monitor details

b15															b0
—	—	—	—	—	—	—	—	—	ABC2	ABC1	FU	OL	IPF	SU	RUN

*3 The setting depends on capacities. (55K or lower/75K or higher)

*4 When *Pr.37* = "1 to 9998" or *Pr. 144* = "2 to 10, 102 to 110," the unit is an integral value (one increment). *(Refer to page 150)*

*5 Option input terminal 1 monitor details (input terminal status of FR-A7AX)-all terminals are OFF when an option is not fitted

b15															b0
X15	X14	X13	X12	X11	X10	X9	X8	X7	X6	X5	X4	X3	X2	X1	X0

*6 Option input terminal 2 monitor details (input terminal status of FR-A7AX)-all terminals are OFF when an option is not fitted

b15															b0
—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	DY

*7 Option output terminal monitor details (output terminal status of FR-A7AY)-all terminals are OFF when an option is not fitted

b15															b0
—	—	—	—	—	—	RA3	RA2	RA1	Y6	Y5	Y4	Y3	Y2	Y1	Y0

[Fault data]

Refer to *page 309* for details of fault description.

Data	Description	Data	Description	Data	Description	Data	Description
H00	No fault	H50	IPF	HA0	OPT	HC5	IOH
H10	OC1	H51	UVT	HA1	OP1	HC6	SER
H11	OC2	H52	ILF	HB0	PE	HC7	AIE
H12	OC3	H60	OLT	HB1	PUE	HE6	PID
H20	OV1	H61	SOT	HB2	RET	HF1	E.1
H21	OV2	H70	BE	HB3	PE2	HF5	E.5
H22	OV3	H80	GF	HC0	CPU	HF6	E.6
H30	THT	H81	LF	HC1	CTE	HF7	E.7
H31	THM	H90	OHT	HC2	P24	HFD	E.13
H40	FIN	H91	PTC	HC4	CDO		

Fault record display example (instruction code H74)

For read data H30A0
(Previous fault ...... THT)
(Latest fault ...... OPT)

b15							b8	b7							b0
0	0	1	1	0	0	0	0	1	0	1	0	0	0	0	0

$\underbrace{\text{b15 – b8}}_{\text{Previous fault (H30)}}$ $\underbrace{\text{b7 – b0}}_{\text{Latest fault (HA0)}}$

[Run command]

Item	Instruction Code	Bit Length	Description	Example
Run command	HFA	8 bits	b0: AU (current input selection) *1 *3 b1: Forward rotation command b2: Reverse rotation command b3: RL (low speed operation command) *1 *3 b4: RM (middle speed operation command) *1 *3 b5: RH (high speed operation command) *1 *3 b6: RT (second function selection) *1 *3 b7: MRS (output stop) *1 *3	[Example 1] H02 Forward rotation b7 … b0 0 0 0 0 0 0 1 0 [Example 2] H00 Stop b7 … b0 0 0 0 0 0 0 0 0
Run command (extended)	HF9	16 bits	b0:AU (current input selection) *1 *3 b1:Forward rotation command b2:Reverse rotation command b3:RL (low speed operation command) *1 *3 b4:RM (middle speed operation command) *1 *3 b5: RH (high speed operation command) *1 *3 b6:RT (second function selection) *1 *3 b7:MRS (output stop) *1 *3 b8:JOG (Jog operation) *2 *3 b9:CS (selection of automatic restart after instantaneous power failure) *2 *3 b10: STOP (start self-holding) *2 *3 b11:RES (reset) *2 *3 b12:— b13:— b14:— b15:—	[Example 1] H0002 Forward rotation b15 … b0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 [Example 2] H0800 low speed operation (When Pr. 189 RES terminal function selection is set to "0") b15 … b0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0

*1 The signal within parentheses is the initial setting. The description changes depending on the setting of *Pr. 180 to Pr. 184, Pr. 187 (input terminal function selection) (page 133)*.

*2 The signal within parentheses is the initial setting. Since jog operation/selection of automatic restart after instantaneous power failure/start self-holding/reset cannot be controlled by the network, bit 8 to bit 11 are invalid in the initial status. When using bit 8 to bit 11, change the signals with *Pr. 185, Pr. 186, Pr. 188, Pr. 189 (input terminal function selection) (page 140)*. (Reset can be executed with the instruction code HFD.)

*3 Only forward rotation command and reverse rotation command are available for RS-485 communication using PU connector.

[Inverter status monitor]

Item	Instruction Code	Bit Length	Description	Example
Inverter status monitor	H7A	8 bits	b0:RUN (inverter running)* b1:Forward rotation b2:Reverse rotation b3:SU (up to frequency) * b4:OL (overload) * b5:IPF (instantaneous power failure) * b6:FU (frequency detection)* b7:ABC1 (fault) *	[Example 1] H02 ··· During forward rotation b7 … b0 0 0 0 0 0 0 1 0 [Example 2] H80 ··· Stop at fault occurrence b7 … b0 1 0 0 0 0 0 0 0
Inverter status monitor (extended)	H79	16 bits	b0:RUN (inverter running) * b1:Forward rotation b2:Reverse rotation b3:SU (up to frequency) * b4:OL (overload) * b5:IPF (instantaneous power failure) * b6:FU (frequency detection) * b7:ABC1 (fault) * b8:ABC2 (—)* b9:— b10:— b11:— b12:— b13:— b14:— b15: Fault occurrence	[Example 1] H0002 ···During forward rotation b15 … b0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 [Example 2] H8080 ···Stop at fault occurrence b15 … b0 1 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0

* The signal within parentheses is the initial setting. The description changes depending on the setting of *Pr. 190 to Pr. 196 (output terminal function selection)*.

[Multi command (HF0)]

Sending data format from computer to inverter

Format	Number of Characters																		
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
A2	ENQ	Inverter station number		Instruction Code (HF0)		Waiting time	Send data type *1	Receive data type *2	Data1 *3				Data2 *3				Sum check		CR/LF

Reply data format from inverter to computer (No data error detected)

Format	Number of Characters																		
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
C1	STX	Inverter station number		Send data type *1	Receive data type *2	Error code 1 *5	Error code 2 *5	Data1 *4				Data2 *4				ETX	Sum check		CR/LF

*1 Specify the data type of sending data (from computer to inverter).
*2 Specify the data type of reply data (from inverter to computer).
*3 Combination of data 1 and data 2 for sending

Data Type	Data 1	Data 2	Remarks
0	Run command (extended)	Set frequency (RAM)	Run command (extended) is same as instruction code HF9 (*Refer to page 245*)
1	Run command (extended)	Set frequency (RAM, EEPROM)	

*4 Combination of data 1 and data 2 for reply

Data Type	Data 1	Data 2	Remarks
0	Inverter status monitor (extended)	Output frequency (speed)	Inverter status monitor (extended) is same as instruction code H79 (*Refer to page 245*)
1	Inverter status monitor (extended)	Special monitor	Replys the monitor item specified in instruction code HF3 for special monitor.(*Refer to page 244*)

*5 Error code for sending data 1 is set in error code 1, and error code for sending data 2 is set in error code 2.
Mode error (HA), instruction code error (HB), data range error (HC) or no error (HF) is replied. (*Refer to page 238* for the details of the error codes.)

4.20.7 Modbus-RTU communication specifications (Pr. 331, Pr. 332, Pr. 334, Pr. 343, Pr. 539, Pr. 549, Pr. 779)

Using the Modbus-RTU communication protocol, communication operation or parameter setting can be performed from the RS-485 terminals of the inverter.

<table>
<tr><th>Parameter Number</th><th>Name</th><th>Initial Value</th><th>Setting Range</th><th colspan="4">Description</th></tr>
<tr><td rowspan="2">331</td><td rowspan="2">RS-485 communication station number</td><td rowspan="2">0</td><td>0</td><td colspan="4">Broadcast communication is selected.</td></tr>
<tr><td>1 to 247 *</td><td colspan="4">Specifies the inverter station number.
Set the inverter station numbers when two or more inverters are connected to one personal computer.</td></tr>
<tr><td>332</td><td>RS-485 communication speed</td><td>96</td><td>3, 6, 12, 24, 48, 96, 192, 384</td><td colspan="4">Set the communication speed.
The setting value × 100 equals the communication speed.
For example, the communication speed is 9600bps when the setting value is "96".</td></tr>
<tr><td rowspan="3">334</td><td rowspan="3">RS-485 communication parity check selection</td><td rowspan="3">2</td><td>0</td><td colspan="4">Without parity check
Stop bit length 2 bits</td></tr>
<tr><td>1</td><td colspan="4">With odd parity check
Stop bit length 1 bit</td></tr>
<tr><td>2</td><td colspan="4">With even parity check
Stop bit length 1 bit</td></tr>
<tr><td>343</td><td>Communication error count</td><td>0</td><td>—</td><td colspan="4">Displays the number of communication errors during Modbus-RTU communication. Reading only</td></tr>
<tr><td rowspan="5">502
Ver.UP</td><td rowspan="5">Stop mode selection at communication error</td><td rowspan="5">0</td><td></td><td>At Fault Occurrence</td><td>Indication</td><td>Fault Output</td><td>At Fault Removal</td></tr>
<tr><td>0</td><td>Coasts to stop.</td><td>E.SER</td><td>Output</td><td>Stop (E.SER)</td></tr>
<tr><td>1</td><td>Decelerates to stop</td><td>After stop E.SER</td><td>Output after stop</td><td>Stop (E.SER)</td></tr>
<tr><td>2</td><td>Decelerates to stop</td><td>After stop E.SER</td><td>Without output</td><td>Automatic restart functions</td></tr>
<tr><td>3</td><td>Continues running at Pr.779</td><td>—</td><td>Without output</td><td>Operates in normal condition</td></tr>
<tr><td rowspan="3">539</td><td rowspan="3">Modbus-RTU communication check time interval</td><td rowspan="3">9999</td><td>0</td><td colspan="4">Modbus-RTU communication is available, but the inverter trips in the NET operation mode.</td></tr>
<tr><td>0.1 to 999.8s</td><td colspan="4">Set the interval of communication check time.
(same specifications as Pr. 122)</td></tr>
<tr><td>9999</td><td colspan="4">No communication check (signal loss detection)</td></tr>
<tr><td rowspan="2">549</td><td rowspan="2">Protocol selection</td><td rowspan="2">0</td><td>0</td><td colspan="4">Mitsubishi inverter (computer link) protocol</td></tr>
<tr><td>1</td><td colspan="4">Modbus-RTU protocol</td></tr>
<tr><td rowspan="2">779
Ver.UP</td><td rowspan="2">Operation frequency during communication error</td><td rowspan="2">9999</td><td>0 to 400Hz</td><td colspan="4">Motor runs at the specified frequency at a communication error.</td></tr>
<tr><td>9999</td><td colspan="4">Motor runs at the frequency used before the communication error.</td></tr>
</table>

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

* The inverter works with the initial parameter setting if a value other than the setting range is set.

Ver.UP ....Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

CAUTION

When Modbus-RTU communication is performed from the master with address 0 (station 0) set, broadcast communication is selected and the inverter does not send a response message to the master.
When response from the inverter is necessary, set a value other than "0" in *Pr. 331*.
Some functions are invalid for broadcast communication. *(Refer to page 250.)*

REMARKS

- When using the Modbus-RTU protocol, set *Pr. 549 Protocol selection* to "1".
- When the communication option is fitted with *Pr. 550 NET mode operation command source selection* set to "9999" (initial value), the command source (e.g. run command) from the RS-485 terminals is invalid. *(Refer to page 219)*

♦ Parameters referred to ♦

Pr. 502 Stop mode selection at communication error ☞ *Refer to page 231.*
Pr. 550 NET mode operation command source selection ☞ *Refer to page 219.*
Pr. 779 Operation frequency during communication error ☞ *Refer to page 231.*

(1) Communication specifications

· The communication specifications are given below.

Item		Description	Related Parameters
Communication protocol		Modbus-RTU protocol	Pr. 549
Conforming standard		EIA-485 (RS-485)	—
Number of inverters connected		1: N (maximum 32 units), setting is 0 to 247 stations	Pr. 331
Communication speed		Selected among 300/600/1200/2400/4800/9600/19200/38400bps	Pr. 332
Control protocol		Asynchronous system	—
Communication method		Half-duplex system	—
Communication specifications	Character system	Binary(fixed to 8 bits)	—
	Start bit	1 bit	—
	Stop bit length	Select from the following three types · No parity, stop bit length 2 bits · Odd parity, stop bit length 1 bit · Even parity, stop bit length 1 bit	Pr. 334
	Parity check		
	Error check	CRC code check	—
	Terminator	Not used	—
Waiting time setting		Not used	—

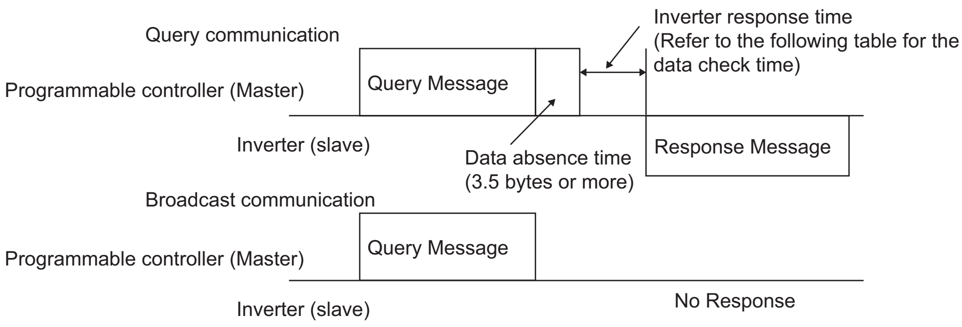
(2) Outline

The Modbus protocol is the communication protocol developed by Modicon for programmable controller.
The Modbus protocol performs serial communication between the master and slave using the dedicated message frame. The dedicated message frame has the functions that can perform data read and write. Using the functions, you can read and write the parameter values from the inverter, write the input command of the inverter, and check the operating status. In this product, the inverter data are classified in the holding register area (register addresses 40001 to 49999). By accessing the assigned holding register address, the master can communicate with the inverter which is a slave.

REMARKS

There are two different serial transmission modes: ASCII (American Standard Code for Information Interchange) mode and RTU (Remote Terminal Unit) mode. This product supports only the RTU mode in which 1-byte (8-bit) data is transmitted as-is.
Only the communication protocol is defined by the Modbus protocol, and the physical layer is not stipulated.

(3) Message format



●Data check time

Item	Check Time
Various monitors, operation command, frequency setting (RAM)	< 12ms
Parameter read/write, frequency setting (EEPROM)	< 30ms
Parameter clear/all clear	< 5s
Reset command	No answer

1) Query
The master sends a message to the slave (= inverter) at the specified address.

2) Normal Response
After receiving the query from the master, the slave executes the requested function and returns the corresponding normal response to the master.

3) Error Response
If an invalid function code, address or data is received, the slave returns it to the master.
When a response description is returned, the error code indicating that the request from the master cannot be executed is added.
No response is returned for the hardware-detected error, frame error and CRC check error.

4) Broadcast
By specifying address 0, the master can send a message to all slaves. All slaves that received the message from the master execute the requested function. In this communication, the slaves do not return a response to the master.

REMARKS
The slave executes the function independently of the inverter station number setting (*Pr. 331*) during broadcast communication.

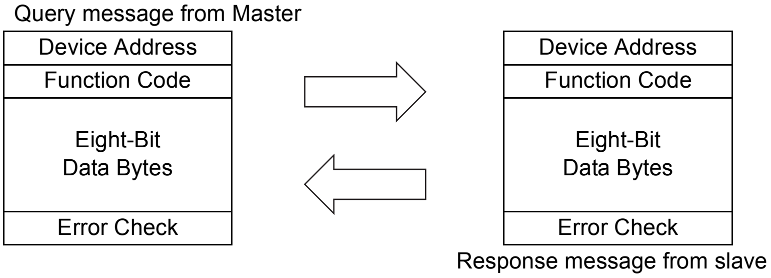
4

PARAMETERS

(4) Message frame (protocol)

- Communication method

Basically, the master sends a query message (question) and the slave returns a response message (response). When communication is normal, Device Address and Function Code are copied as they are, and when communication is abnormal (function code or data code is illegal), bit 7 (= 80h) of Function Code is turned on and the error code is set to Data Bytes.



The message frame consists of the four message fields as shown above.
By adding the no-data time (T1: Start, End) of 3.5 characters to the beginning and end of the message data, the slave recognizes it as one message.

- Protocol details

The four message fields will be explained below.

Start	1) ADDRESS	2) FUNCTION	3) DATA	4) CRC CHECK		End
T1	8 bits	8 bits	n × 8 bits	L 8 bits	H 8 bits	T1

<table>
<tr><th>Message Field</th><th>Description</th></tr>
<tr><td>1) ADDRESS field</td><td>Is 1 byte long (8 bits), and can be set to any of 0 to 247. Set 0 to send a broadcast message (all-address instruction) or any of 1 to 247 to send a message to each slave.
When the slave responds, it returns the address set from the master.
The value set to Pr. 331 RS-485 communication station number is the slave address.</td></tr>
<tr><td>2) FUNCTION field</td><td>The function code is 1 byte long (8 bits) and can be set to any of 1 to 255. The master sets the function that it wants to request from the slave, and the slave performs the requested operation. The following table gives the supported function codes. An error response is returned if the set function code is other than those in the following table.
When the slave returns a normal response, it returns the function code set by the master.
When the slave returns an error response, it returns H80 + function code.
<table>
<tr><th>Code</th><th>Function Name</th><th>Outline</th><th>Broadcast Communication</th></tr>
<tr><td>H03</td><td>Read Holding Register</td><td>Reads the holding register data.</td><td>Disallowed</td></tr>
<tr><td>H06</td><td>Preset Single Register</td><td>Writes data to the holding register.</td><td>Allowed</td></tr>
<tr><td>H08</td><td>Diagnostics</td><td>Makes a function diagnosis.
(communication check only)</td><td>Disallowed</td></tr>
<tr><td>H10</td><td>Preset Multiple Registers</td><td>Writes data to multiple consecutive holding registers.</td><td>Allowed</td></tr>
<tr><td>H46</td><td>Read Holding Register Access Log</td><td>Reads the number of registers that succeeded in communication last time.</td><td>Disallowed</td></tr>
</table>
Table 1: Function code list</td></tr>
<tr><td>3) DATA field</td><td>The format changes depending on the function code (refer to page251). Data includes the byte count, number of bytes, description of access to the holding register, etc.</td></tr>
<tr><td>4) CRC CHECK field</td><td>The received message frame is checked for error. CRC check is performed, and 2 byte long data is added to the end of the message. When CRC is added to the message, the low-order byte is added first and is followed by the high-order byte.
The CRC value is calculated by the sending side that adds CRC to the message. The receiving side recalculates CRC during message receiving, and compares the result of that calculation and the actual value received in the CRC CHECK field. If these two values do not match, the result is defined as error.</td></tr>
</table>

(5) Message format types

The message formats corresponding to the function codes in Table 1 on *page 250* will be explained.

- **Read holding register data (H03 or 03)**
  Can read the description of 1) system environment variables, 2) real-time monitor, 3) faults history, and 4) inverter parameters assigned to the holding register area (refer to the register list *(page 256)*).

Query Message

1) Slave Address	2) Function	3) Starting Address		4) No. of Points		CRC Check	
(8 bits)	H03 (8 bits)	H (8 bits)	L (8 bits)	H (8 bits)	L (8 bits)	L (8 bits)	H (8 bits)

Response message

1) Slave Address	2) Function	5) Byte Count	6) Data			CRC Check	
(8 bits)	H03 (8 bits)	(8 bits)	H (8 bits)	L (8 bits)	... (n × 16 bits)	L (8 bits)	H (8 bits)

· **Query message setting**

Message	Setting Description
1)Slave Address	Set the address to which the message will be sent. Broadcast communication cannot be made (0 is invalid)
2) Function	Set H03.
3)Starting Address	Set the address at which holding register data read will be started. Starting address = starting register address (decimal) − 40001 For example, setting of the starting address 0001 reads the data of the holding register 40002.
4)No. of Points	Set the number of holding registers from which data will be read. The number of registers from which data can be read is a maximum of 125.

· **Description of normal response**

Message	Setting Description
5)Byte Count	The setting range is H02 to HFA (2 to 250). Twice greater than the No. of Points specified at 4) is set.
6)Data	The number of data specified at 4) is set. Data are read in order of Hi byte and Lo byte, and set in order of starting address data, starting address + 1 data, starting address + 2 data, ...

Example) To read the register values of 41004 *(Pr. 4)* to 41006 *(Pr. 6)* from the slave address 17 (H11)

Query message

Slave Address	Function	Starting Address		No. of Points		CRC Check	
H11 (8 bits)	H03 (8 bits)	H03 (8 bits)	HEB (8 bits)	H00 (8 bits)	H03 (8 bits)	H77 (8 bits)	H2B (8 bits)

Normal response (Response message)

Slave Address	Function	Byte Count	Data						CRC Check	
H11 (8 bits)	H03 (8 bits)	H06 (8 bits)	H17 (8 bits)	H70 (8 bits)	H0B (8 bits)	HB8 (8 bits)	H03 (8 bits)	HE8 (8 bits)	H2C (8 bits)	HE6 (8 bits)

Read value
Register 41004 *(Pr. 4)*: H1770 (60.00Hz)
Register 41005 *(Pr. 5)*: H0BB8 (30.00Hz)
Register 41006 *(Pr. 6)*: H03E8 (10.00Hz)

- **Write multiple holding register data (H06 or 06)**
  You can write the description of 1) system environment variables and 4) inverter parameters assigned to the holding register area (refer to the register list *(page 256)*).

Query message

1) Slave Address	2) Function	3) Register Address		4) Preset Data		CRC Check	
(8 bits)	H06 (8 bits)	H (8 bits)	L (8 bits)	H (8 bits)	L (8 bits)	L (8 bits)	H (8 bits)

Normal response (Response message)

1) Slave Address	2) Function	3) Register Address		4) Preset Data		CRC Check	
(8 bits)	H06 (8 bits)	H (8 bits)	L (8 bits)	H (8 bits)	L (8 bits)	L (8 bits)	H (8 bits)

· **Query message setting**

Message	Setting Description
1) Slave Address	Set the address to which the message will be sent. Setting of address 0 enables broadcast communication
2) Function	Set H06.
3) Register Address	Set the address of the holding register to which data will be written. Register address = holding register address (decimal) – 40001 For example, setting of register address 0001 writes data to the holding register address 40002.
4) Preset Data	Set the data that will be written to the holding register. The written data is always 2 bytes.

· **Description of normal response**
1) to 4) (including CRC check) of the normal response are the same as those of the query message.
No response is made for broadcast communication.

Example) To write 60Hz (H1770) to 40014 (running frequency RAM) at slave address 5 (H05).

Query message

Slave Address	Function	Register Address		Preset Data		CRC Check	
H05 (8 bits)	H06 (8 bits)	H00 (8 bits)	H0D (8 bits)	H17 (8 bits)	H70 (8 bits)	H17 (8 bits)	H99 (8 bits)

Normal Response (Response message)
Same data as the query message

CAUTION

For broadcast communication, no response is returned in reply to a query. Therefore, the next query must be made when the inverter processing time has elapsed after the previous query.

- **Function diagnosis (H08 or 08)**

A communication check is available since the query message sent is returned unchanged as a response message (function of subfunction code H00). Subfunction code H00 (Return Query Data)

Query Message

1) Slave Address	2) Function	3) Subfunction		4) Date		CRC Check	
(8 bits)	H08 (8 bits)	H00 (8 bits)	H00 (8 bits)	H (8 bits)	L (8 bits)	L (8 bits)	H (8 bits)

Normal Response (Response message)

1) Slave Address	2) Function	3) Subfunction		4) Date		CRC Check	
(8 bits)	H08 (8 bits)	H00 (8 bits)	H00 (8 bits)	H (8 bits)	L (8 bits)	L (8 bits)	H (8 bits)

· **Query message setting**

Message	Setting Description
1) Slave Address	Set the address to which the message will be sent. Broadcast communication cannot be made (0 is invalid)
2) Function	Set H08.
3) Subfunction	Set H0000.
4) Data	Any data can be set if it is 2 bytes long. The setting range is H0000 to HFFFF.

· **Description of normal response**

1) to 4) (including CRC check) of the normal response are the same as those of the query message.

CAUTION

For broadcast communication, no response is returned in reply to a query. Therefore, the next query must be made when the inverter processing time has elapsed after the previous query.

- **Write multiple holding register data (H10 or 16)**

You can write data to multiple holding registers.

Query message

1) Slave Address	2) Function	3) Starting Address		4) No. of Registers		5) ByteCount	6) Data			CRC Check	
(8 bits)	H10 (8 bits)	H (8 bits)	L (8 bits)	H (8 bits)	L (8 bits)	(8 bits)	H (8 bits)	L (8 bits)	... ($n \times 2 \times 8$ bits)	L (8 bits)	H (8 bits)

Normal Response (Response message)

1) Slave Address	2) Function	3) Starting Address		4) No. of Registers		CRC Check	
(8 bits)	H10 (8 bits)	H (8 bits)	L (8 bits)	H (8 bits)	L (8 bits)	L (8 bits)	H (8 bits)

· **Query message setting**

Message	Setting Description
1) Slave Address	Set the address to which the message will be sent. Setting of address 0 enables broadcast communication
2) Function	Set H10.
3) Starting Address	Set the address where holding register data write will be started. Starting address = starting register address (decimal) − 40001 For example, setting of the starting address 0001 reads the data of the holding register 40002.
4) No. of Points	Set the number of holding registers where data will be written. The number of registers where data can be written is a maximum of 125.
5) Byte Count	The setting range is H02 to HFA (2 to 250). Set twice greater than the value specified at 4).
6) Data	Set the data specified by the number specified at 4). The written data are set in order of Hi byte and Lo byte, and arranged in order of the starting address data, starting address + 1 data, starting address + 2 data ...

· **Description of normal response**

1) to 4) (including CRC check) of the normal response are the same as those of the query message.

Example) To write 0.5s (H05) to 41007 *(Pr. 7)* at the slave address 25 (H19) and 1s (H0A) to 41008 *(Pr. 8)*.

Query Message

Slave Address	Function	Starting Address		No. of Points		Byte Count	Data				CRC Check	
H19 (8 bits)	H10 (8 bits)	H03 (8 bits)	HEE (8 bits)	H00 (8 bits)	H02 (8 bits)	H04 (8 bits)	H00 (8 bits)	H05 (8 bits)	H00 (8 bits)	H0A (8 bits)	H86 (8 bits)	H3D (8 bits)

Response message (Response message)

Slave Address	Function	Starting Address		No. of Points		CRC Check	
H19 (8 bits)	H10 (8 bits)	H03 (8 bits)	HEE (8 bits)	H00 (8 bits)	H02 (8 bits)	H22 (8 bits)	H61 (8 bits)

- **Read holding register access log (H46 or 70)**

A response can be made to a query made by the function code H03 or H10.
The starting address of the holding registers that succeeded in access during previous communication and the number of successful registers are returned.
In response to the query for other than the above function code, 0 is returned for the address and number of registers.

Query Message

1) Slave Address	2) Function	CRC Check	
(8 bits)	H46 (8 bits)	L (8 bits)	H (8 bits)

Normal Response (Response message)

1) Slave Address	2) Function	3) Starting Address		4) No. of Points		CRC Check	
(8 bits)	H46 (8 bits)	H (8 bits)	L (8 bits)	H (8 bits)	L (8 bits)	L (8 bits)	H (8 bits)

· **Query message setting**

Message	Setting Description
1) Slave Address	Set the address to which the message will be sent. Broadcast communication cannot be made (0 is invalid)
2) Function	Set H46.

· **Description of normal response**

Message	Setting Description
3) Starting Address	The starting address of the holding registers that succeeded in access is returned. Starting address = starting register address (decimal) − 40001 For example, when the starting address 0001 is returned, the address of the holding register that succeeded in access is 40002.
4) No. of Points	The number of holding registers that succeeded in access is returned.

Example) To read the successful register starting address and successful count from the slave address 25 (H19).

Query Message

Slave Address	Function	CRC Check	
H19 (8 bits)	H46 (8 bits)	H8B (8 bits)	HD2 (8 bits)

Normal Response (Response message)

Slave Address	Function	Starting Address		No. of Points		CRC Check	
H19 (8 bits)	H10 (8 bits)	H03 (8 bits)	HEE (8 bits)	H00 (8 bits)	H02 (8 bits)	H22 (8 bits)	H61 (8 bits)

Success of two registers at starting address 41007 *(Pr. 7)* is returned.

● Error response

An error response is returned if the query message received from the master has an illegal function, address or data. No response is returned for a parity, CRC, overrun, framing or busy error.

CAUTION

No response message is sent in the case of broadcast communication also.

Error response (Response message)

1) Slave Address	2) Function	3) Exception Code	CRC Check	
(8 bits)	H80 + Function (8 bits)	(8 bits)	L (8 bits)	H (8 bits)

Message	Setting Description
1) Slave address	Set the address received from the master.
2) Function	The master-requested function code + H80 is set.
3) Exception code	The code in the following table is set.

Error code list

Code	Error Item	Error Definition
01	ILLEGAL FUNCTION	The set function code in the query message from the master cannot be handled by the slave.
02	ILLEGAL DATA ADDRESS *1	The set register address in the query message from the master cannot be handled by the inverter. (No parameter, parameter read disabled, parameter write disabled)
03	ILLEGAL DATA VALUE	The set data in the query message from the master cannot be handled by the inverter. (Out of parameter write range, mode specified, other error)

*1 An error will not occur in the following cases.
1) Function code H03 (Read Holding Register Data)
When the No. of Points is 1 or more and there is one or more holding registers from which data can be read
2) Function code H10 (Write Multiple Holding Register Data)
When the No. of Points is 1 or more and there is 1 or more holding registers to which data can be written
Namely, when the function code H03 or H10 is used to access multiple holding registers, an error will not occur if a non-existing holding register or read disabled or write disabled holding register is accessed.

REMARKS

An error will occur if all accessed holding registers do not exist.
Data read from a non-existing holding register is 0, and data written there is invalid.

· **Message data mistake detection**

To detect the mistakes of message data from the master, they are checked for the following errors. If an error is detected, a trip will not occur.

Error check item

Error Item	Error Definition	Inverter Side Operation
Parity error	The data received by the inverter differs from the specified parity (*Pr. 334* setting).	1) *Pr. 343* is increased by 1 at error occurrence. 2) The terminal LF is output at error occurrence.
Framing error	The data received by the inverter differs from the specified stop bit length (*Pr. 334*).	
Overrun error	The following data was sent from the master before the inverter completes data receiving.	
Message frame error	The message frame data length is checked, and the received data length of less than 4 bytes is regarded as an error.	
CRC check error	A mismatch found by CRC check between the message frame data and calculation result is regarded as an error.	

(6) Modbus registers

- System environment variable

Register	Definition	Read/Write	Remarks
40002	Inverter reset	Write	Any value can be written
40003	Parameter clear	Write	Set H965A as a written value.
40004	All parameter clear	Write	Set H99AA as a written value.
40006	Parameter clear *1	Write	Set H5A96 as a written value.
40007	All parameter clear *1	Write	Set HAA99 as a written value.
40009	Inverter status/control input instruction *2	Read/write	See below.
40010	Operation mode/inverter setting *3	Read/write	See below.
40014	Running frequency (RAM value)	Read/write	According to the *Pr. 37* and *Pr. 144* settings, the frequency and selectable speed are in 1r/min increments.
40015	Running frequency (EEPROM value)	Write	

*1 The communication parameter values are not cleared.
*2 For write, set the data as a control input instruction. For read, data is read as an inverter operating status.
*3 For write, set data as the operation mode setting. For read, data is read as the operation mode status.

<Inverter status/control input instruction>

Bit	Definition: Control input instruction	Definition: Inverter status
0	Stop command	RUN (inverter running) *2
1	Forward rotation command	Forward rotation
2	Reverse rotation command	Reverse rotation
3	RH (high speed operation command) *1	SU (up to frequency) *2
4	RM (middle speed operation command) *1	OL (overload) *2
5	RL (low speed operation command) *1	IPF (instantaneous power failure) *2
6	JOG (Jog operation) *1	FU (frequency detection) *2
7	RT (second function selection) *1	ABC1 (fault) *2
8	AU (current input selection) *1	ABC2 (—) *2
9	CS (selection of automatic restart after instantaneous power failure) *1	0
10	MRS (output stop) *1	0
11	STOP (start self-holding) *1	0
12	RES (reset) *1	0
13	0	0
14	0	0
15	0	Fault occurrence

<Operation mode/inverter setting>

Mode	Read Value	Written Value
EXT	H0000	H0010*
PU	H0001	H0011*
EXT JOG	H0002	—
PU JOG	H0003	—
NET	H0004	H0014
PU+ EXT	H0005	—

* Writing is available depending on the *Pr. 79* and *Pr. 340* setting. *Refer to page 218* for details.

The restrictions depending on the operation mode changes according to the computer link specifications.

*1 The signal within parentheses is the initial setting. The description changes depending on the setting of *Pr. 180 to Pr. 189 (input terminal function selection) (page133)*.
Each assigned signal is valid or invalid depending on NET. *(Refer to page 219)*
*2 The signal within parentheses is the initial setting. The description changes depending on the setting of *Pr. 190 to Pr. 196 (output terminal function selection) (page140)*.

- Real-time monitor

Refer to *page 152* for details of the monitor description.

Register	Description	Increments
40201	Output frequency/Speed*4	0.01Hz/1
40202	Output current	0.01A/0.1A*1
40203	Output voltage	0.1V
40205	Frequency setting value/Speed setting*4	0.01Hz/1
40206	Running speed	1r/min
40208	Converter output voltage	0.1V
40209	Regenerative brake duty	0.1%
40210	Electronic thermal relay function load factor	0.1%
40211	Output current peak value	0.01A/0.1A*1
40212	Converter output voltage peak value	0.1V
40213	Input power	0.01kW/ 0.1kW *1
40214	Output power	0.01kW/ 0.1kW *1
40215	Input terminal status *2	—
40216	Output terminal status *3	—
40217	Load meter	0.1%
40220	Cumulative energization time	1h

Register	Description	Increments
40223	Actual operation time	1h
40224	Motor load factor	0.1%
40225	Cumulative power	1kWh
40250	Power saving effect	Variable
40251	Cumulative saving power	Variable
40252	PID set point	0.1%
40253	PID measured value	0.1%
40254	PID deviation	0.1%
40258	Option input terminal status 1 *5	—
40259	Option input terminal status 2 *6	—
40260	Option output terminal status *7	—
40267	PID measured value 2	0.1%
40277	32-bit cumulative power (lower 16 bits) Ver.UP	1kWh
40278	32-bit cumulative power (upper 16 bits) Ver.UP	1kWh
40279	32-bit cumulative power (lower 16 bits) Ver.UP	0.01kWh/ 0.1kWh *1
40280	32-bit cumulative power (upper 16 bits) Ver.UP	0.01kWh/ 0.1kWh *1

Ver.UP .... Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

*1 The setting depends on capacities. (55K or lower/75K or higher)

*2 Input terminal monitor details

b15															b0
—	—	—	—	CS	RES	STOP	MRS	JOG	RH	RM	RL	RT	AU	STR	STF

*3 Output terminal monitor details

b15															b0
—	—	—	—	—	—	—	—	—	ABC2	ABC1	FU	OL	IPF	SU	RUN

*4 When *Pr.37* = "1 to 9998" or *Pr. 144* = "2 to 10, 102 to 110," the unit is an integral value (one increment). (*Refer to page 150*)

*5 Option input terminal 1 monitor details (input terminal status of FR-A7AX) All OFF if option is not installed.

b15															b0
X15	X14	X13	X12	X11	X10	X9	X8	X7	X6	X5	X4	X3	X2	X1	X0

*6 Option input terminal 2 monitor details (input terminal status of FR-A7AX) All OFF if option is not installed.

b15															b0
—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	DY

*7 Option output terminal monitor details (output terminal status of FR-A7AY) All OFF if option is not installed.

b15															b0
—	—	—	—	—	—	RA3	RA2	RA1	Y6	Y5	Y4	Y3	Y2	Y1	Y0

- Parameter

Parameters	Register	Parameter Name	Read/Write	Remarks
0 to 999	**41000 to 41999**	Refer to the parameter list *(page 64)* for the parameter names.	Read/write	The parameter number + 41000 is the register number.
C2(902)	**41902**	Terminal 2 frequency setting bias (frequency)	Read/write	
C3(902)	**42092**	Terminal 2 frequency setting bias (analog value)	Read/write	The analog value (%) set to *C3 (902)* is read.
	43902	Terminal 2 frequency setting bias (terminal analog value)	Read	The analog value (%) of the voltage (current) applied to the terminal 2 is read.
125(903)	**41903**	Terminal 2 frequency setting gain (frequency)	Read/write	
C4(903)	**42093**	Terminal 2 frequency setting gain (analog value)	Read/write	The analog value (%) set to *C4 (903)* is read.
	43903	Terminal 2 frequency setting gain (terminal analog value)	Read	The analog value (%) of the voltage (current) applied to the terminal 2 is read.
C5(904)	**41904**	Terminal 4 frequency setting bias (frequency)	Read/write	
C6(904)	**42094**	Terminal 4 frequency setting bias (analog value)	Read/write	The analog value (%) set to *C6 (904)* is read.
	43904	Terminal 4 frequency setting bias (terminal analog value)	Read	The analog value (%) of the current (voltage) applied to the terminal 4 is read.
126(905)	**41905**	Terminal 4 frequency setting gain (frequency)	Read/write	
C7(905)	**42095**	Terminal 4 frequency setting gain (analog value)	Read/write	The analog value (%) set to *C7 (905)* is read.
	43905	Terminal 4 frequency setting gain (terminal analog value)	Read	The analog value (%) of the current (voltage) applied to the terminal 4 is read.
C42(934)	**41934**	PID display bias coefficient	Read/write	
C43(934)	**42124**	PID display bias analog value	Read/write	The analog value (%) set to *C43 (934)* is read.
	43934	PID display bias analog value (terminal analog value)	Read	The analog value (%) of the current (voltage) applied to the terminal 4 is read.
C44(935)	**41935**	PID display gain coefficient	Read/write	
C45(935)	**42125**	PID display gain analog value	Read/write	The analog value (%) set to *C45 (935)* is read.
	43935	PID display gain analog value (terminal analog value)	Read	The analog value (%) of the current (voltage) applied to the terminal 4 is read.

- Faults history

Register	Definition	Read/Write	Remarks
40501	Fault history 1	Read/write	Being 2 bytes in length, the data is stored as "H00○○". Refer to the lowest 1 byte for the fault code. Performing write using the register 40501 batch-clears the faults history. Set any value as data.
40502	Fault history 2	Read	
40503	Fault history 3	Read	
40504	Fault history 4	Read	
40505	Fault history 5	Read	
40506	Fault history 6	Read	
40507	Fault history 7	Read	
40508	Fault history 8	Read	

Fault code list

Data	Description	Data	Description	Data	Description	Data	Description
H00	No fault	H40	FIN	H91	PTC	HC4	CDO
H10	OC1	H50	IPF	HA0	OPT	HC5	IOH
H11	OC2	H51	UVT	HA1	OP1	HC6	SER
H12	OC3	H52	ILF	HB0	PE	HC7	AIE
H20	OV1	H60	OLT	HB1	PUE	HE6	PID
H21	OV2	H61	SOT	HB2	RET	HF1	E.1
H22	OV3	H70	BE	HB3	PE2	HF5	E.5
H30	THT	H80	GF	HC0	CPU	HF6	E.6
H31	THM	H81	LF	HC1	CTE	HF7	E.7
		H90	OHT	HC2	P24	HFD	E.13

- Model information monitor Ver.UP

Register	Definition	Read/Write	Remarks
44001 to 44010	Inverter type	Read	Reading inverter type in ASCII code. "H20" (blank code) is set for blank area Example of FR-F720P H46, H52, H2D, H46, H37, H32, H30, H50, H20 ....H20
44011 to 44013	Capacity	Read	Reading inverter capacity in ASCII code. Data is read in increments of 0.1kW, and rounds down to 0.01kW increments "H20" (blank code) is set for blank area Example 0.75K............... " 7" (H20, H20, H20, H20, H20, H37)

Ver.UP .... Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

(7) Pr. 343 Communication error count

You can check the cumulative number of communication errors.

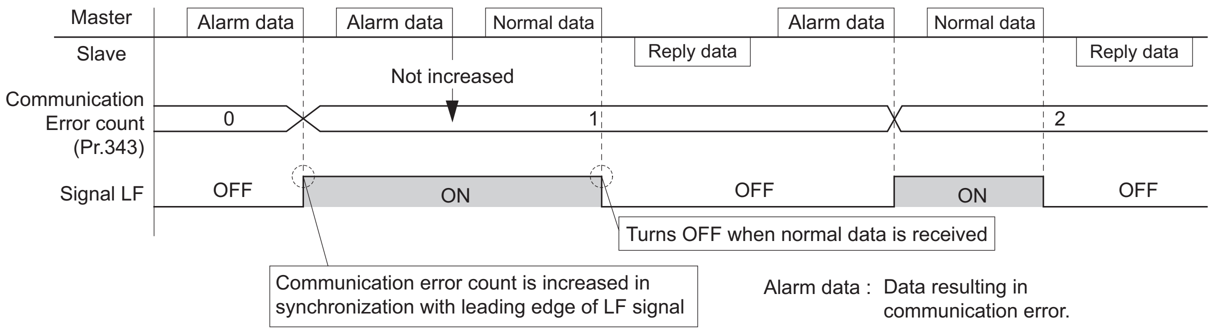
Parameters	Setting Range	Minimum Setting Range	Initial Value
343	(Read only)	1	0

CAUTION

The number of communication errors is temporarily stored into the RAM. As it is not stored into the EEPROM, performing a power supply reset or inverter reset clears the value to 0.

(8) Output signal LF "alarm output (communication error warnings)"

During a communication error, the alarm signal (LF signal) is output by open collector output. The LF signal can be assigned to the output terminal using any of *Pr. 190 to Pr. 196 (output terminal function selection)*.



CAUTION

The LF signal can be assigned to the output terminal using any of *Pr.190 to Pr.196*. Changing the terminal assignment may affect the other functions. Set parameters after confirming the function of each terminal.

4

PARAMETERS

(9) Signal loss detection (*Pr. 539 Modbus-RTU communication check time interval*)

If a signal loss (communication stop) is detected between the inverter and master as a result of a signal loss detection, a communication error (E.SER) occurs and the inverter output is shut off.

· When the setting is "9999", communication check (signal loss detection) is not made.

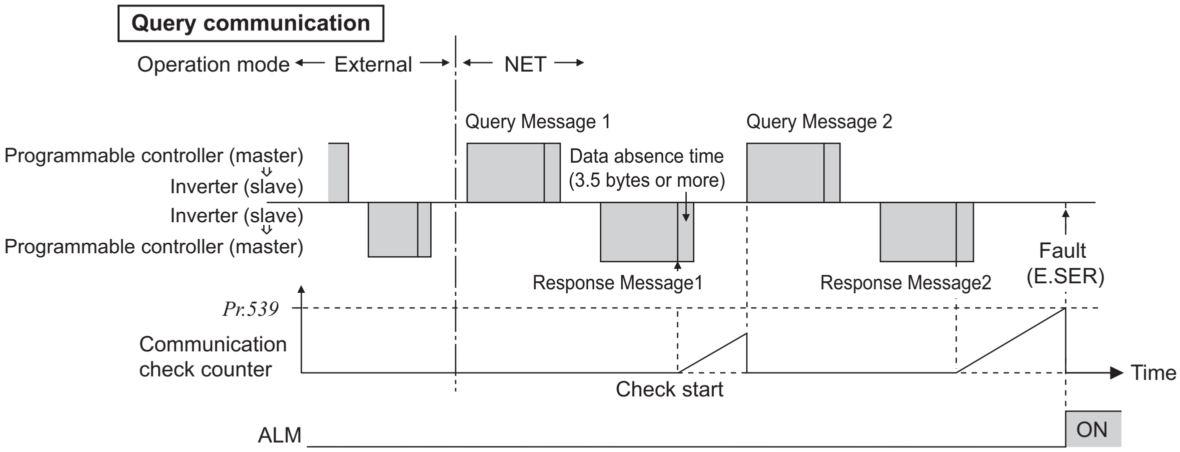
· When the setting value is "0", monitor, parameter read, etc. can be performed. However, a communication error (E.SER) occurs as soon as the inverter is switched to the network operation mode.

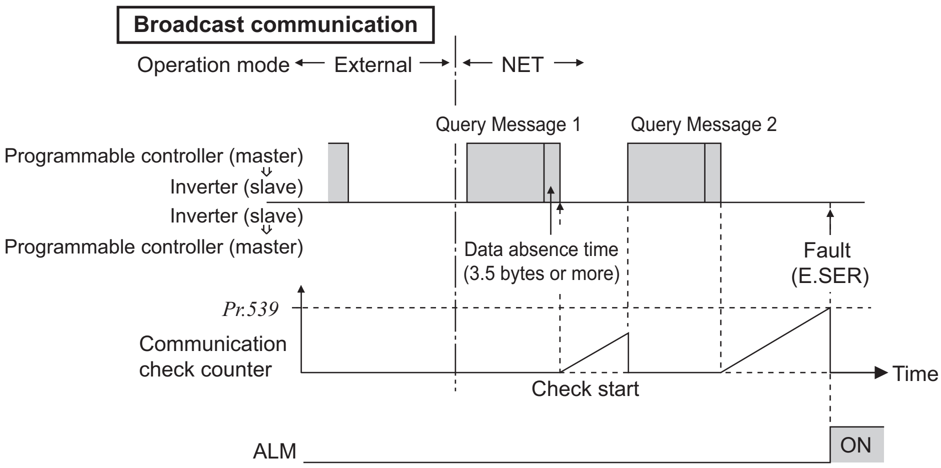
· A signal loss detection is made when the setting is any of "0.1s to 999.8s". To make a signal loss detection, it is necessary to send data from the master within the communication check time interval. (The inverter makes communication check (clearing of communication check counter) regardless of the station number setting of the data sent from the master.)

· Communication check is started from the first communication after switching to the network operation mode (use *Pr. 551 PU mode operation command source selection* to change).

· Communication check time of query communication includes data absence time (3.5 byte).
Since this data absence time differs according to the communication speed, make setting considering this absence time.

Example: RS-485 terminal communication, *Pr. 539* **= "0.1 to 999.8s"**





REMARKS

When using RS-485 terminal communication, inverter behavior at fault occurrence is different depending on the *Pr. 502 Stop mode selection at communication error* setting. *(Refer to page 231)*

4.21 Special operation and frequency control

Purpose	Parameter that must be Set		Refer to Page
Perform process control such as pump and air volume.	**PID control**	**Pr. 127 to Pr. 134, Pr. 241, Pr. 553, Pr. 554, Pr. 575 to Pr. 577, C42 (Pr. 934) to C45 (Pr. 935)**	261
Switch between the inverter operation and bypass operation to operate.	**Bypass-inverter switchover function**	**Pr. 135 to Pr. 139, Pr. 159**	274
Avoid overvoltage alarm due to regeneration by automatic adjustment of output frequency.	**Regeneration avoidance function**	**Pr.665, Pr. 882 to Pr. 886**	279

4.21.1 PID control (Pr. 127 to Pr. 134, Pr. 241, Pr. 553, Pr. 554, Pr. 575 to Pr. 577, C42 (Pr. 934) to C45 (Pr. 935))

The inverter can be used to exercise process control, e.g. flow rate, air volume or pressure.
The terminal 2 input signal or parameter setting is used as a set point and the terminal 4 input signal used as a feedback value to constitute a feedback system for PID control.

Parameter Number	Name	Initial Value	Setting Range	Description	
127	**PID control automatic switchover frequency**	9999	0 to 400Hz	Set the frequency at which the control is automatically changed to PID control.	
			9999	Without PID automatic switchover function	
128	**PID action selection**	10	10, 110 *2	PID reverse action	Deviation value signal input (terminal 1 *4)
			11, 111 *2	PID forward action	
			20, 120 *2	PID reverse action	Measured value (terminal 4 *5) Set point (terminal 2 *4 or *Pr. 133*)
			21, 121 *2	PID forward action	
			50 *2	PID reverse action	Deviation value signal input (LONWORKS , CC-Link communication)
			51 *2	PID forward action	
			60 *2	PID reverse action	Measured value, set point input (LONWORKS , CC-Link communication)
			61 *2	PID forward action	
129 *1	**PID proportional band**	100%	0.1 to 1000%	If the proportional band is narrow (parameter setting is small), the manipulated variable varies greatly with a slight change of the measured value. Hence, as the proportional band narrows, the response sensitivity (gain) improves but the stability deteriorates, e.g. hunting occurs. Gain Kp = 1/proportional band	
			9999	No proportional control	
130 *1	**PID integral time**	1s	0.1 to 3600s	When deviation step is input, time (Ti) is the time required for integral (I) action to provide the same manipulated variable as proportional (P) action. As the integral time decreases, the set point is reached earlier but hunting occurs more easily.	
			9999	No integral control.	
131	**PID upper limit**	9999	0 to 100% *3	Set the upper limit value. If the feedback value exceeds the setting, the FUP signal is output. The maximum input (20mA/5V/10V) of the measured value (terminal 4) is equivalent to 100%.	
			9999	No function	
132	**PID lower limit**	9999	0 to 100% *3	Set the lower limit value. If the measured value falls below the setting range, the FDN signal is output. The maximum input (20mA/5V/10V) of the measured value (terminal 4) is equivalent to 100%.	
			9999	No function	
133 *1	**PID action set point**	9999	0 to 100% *3	Used to set the set point for PID control.	
			9999	Terminal 2 input is the set point.	
134 *1	**PID differential time**	9999	0.01 to 10.00s	When deviation lamp is input, time (Td) is the time required to provide the manipulated variable of only the proportional (P) action. As the differential time increases, greater response is made to a deviation change.	
			9999	No differential control.	

Parameter Number	Name	Initial Value	Setting Range	Description	
241 *1	**Analog input display unit switchover**	0	0	Displayed in %	Select the unit of analog input display.
			1	Displayed in V/mA	
553	**PID deviation limit**	9999	0 to 100.0%*3	Y48 signal is output when the absolute value of deviation amount exceeds the deviation limit value.	
			9999	No function	
554	**PID signal operation selection**	0	0 to 3, 10 to 13	Select the operation to be performed at the detection of upper, lower, and deviation limit for the measured value input. The operation for PID output suspension function can be selected.	
575	**Output interruption detection time**	1s	0 to 3600s	The inverter stops operation if the output frequency after PID operation remains at less than the *Pr. 576* setting for longer than the time set in *Pr. 575*.	
			9999	Without output interruption function	
576	**Output interruption detection level**	0Hz	0 to 400Hz	Set the frequency at which the output interruption processing is performed.	
577	**Output interruption cancel level**	1000% *3	900 to 1100% *3	Set the level (*Pr. 577* minus 1000%) to release the PID output interruption function.	
C42 (934) *6	**PID display bias coefficient**	9999	0 to 500.00	Set the coefficient on bias (minimum) side of terminal 4 input.	
			9999	Displayed in %.	
C43 (934) *6	**PID display bias analog value**	20%	0 to 300.0%	Set the converted % on bias (minimum) side current /voltage of terminal 4 input.	
C44 (935) *6	**PID display gain coefficient**	9999	0 to 500.00	Set the coefficient on gain (maximum) side of the terminal 4 input.	
			9999	Displayed in %.	
C45 (935) *6	**PID display gain analog value**	100%	0 to 300.0%	Set the converted % on gain (maximum) side of current/ voltage of terminal 4 input.	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

*1 This parameter allows its setting to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.

*2 PID control is available without turning X14 signal ON when *Pr.128* = "50, 51, 60, 61, 110, 111, 120, 120".

*3 If *C42(Pr.934)* and *C44(Pr.935)* are both set to values other than "9999," the setting range for *Pr.131* to *Pr.133* and *Pr.553* become only "9999," and % is not displayed in the setting range of *Pr.577*. (Values set in *Pr.553* and *Pr.577* are converted as differentials.)

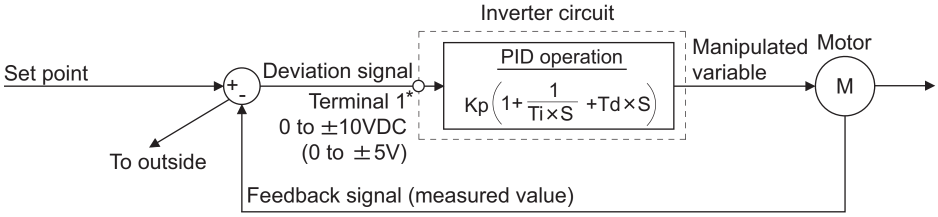
*4 Input specification for the terminals are determined by *Pr.73 Analog input selection*.

*5 Input specification for the terminal is determined by *Pr.267 Terminal 4 input selection*.

*6 The parameter number in parentheses is the one for use with the parameter unit (FR-PU04/FR-PU07).

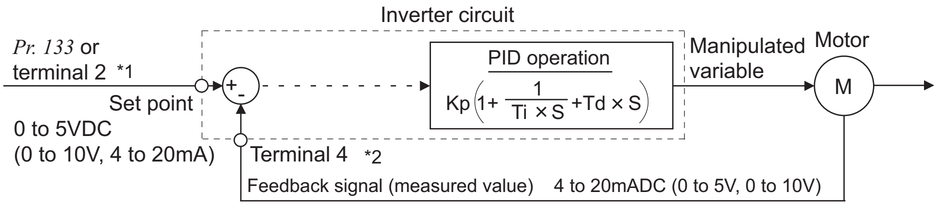
(1) PID control basic configuration

· *Pr. 128* = "10, 11, 110, 111" (Deviation value signal input)



Kp: Proportionality constant Ti: Integral time S: Operator Td: Differential time

· *Pr. 128* = "20, 21, 120, 121" (Measured value input)



Kp: Proportionality constant Ti: Integral time S: Operator Td: Differential time

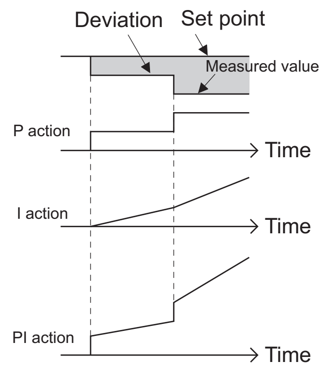
(2) PID action overview

1) PI action

A combination of P action (P) and I action (I) for providing a manipulated variable in response to deviation and changes with time.

[Operation example for stepped changes of measured value]

(Note) PI action is the sum of P and I actions.

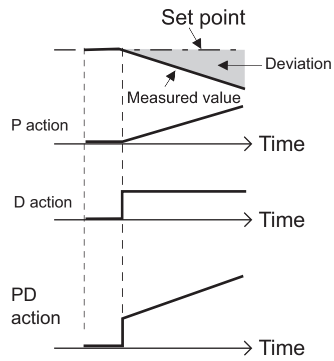


2) PD action

A combination of P action (P) and differential control action (D) for providing a manipulated variable in response to deviation speed to improve the transient characteristic.

[Operation example for proportional changes of measured value]

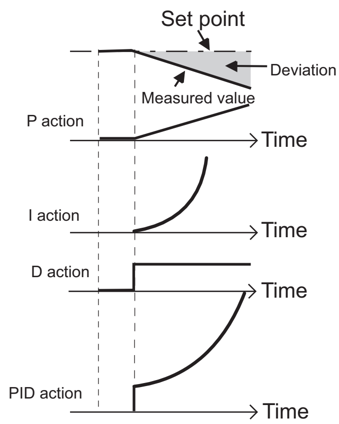
(Note) PD action is the sum of P and D actions.



3) PID action

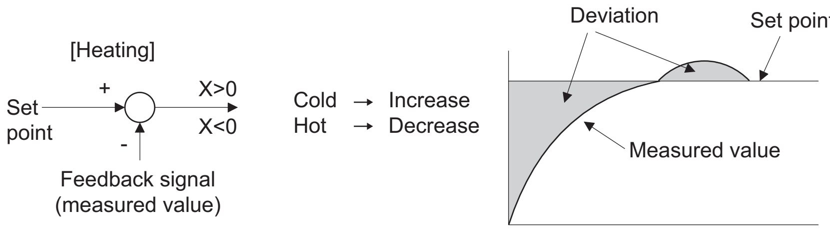
The PI action and PD action are combined to utilize the advantages of both actions for control.

(Note) PID action is the sum of P, I and D actions.



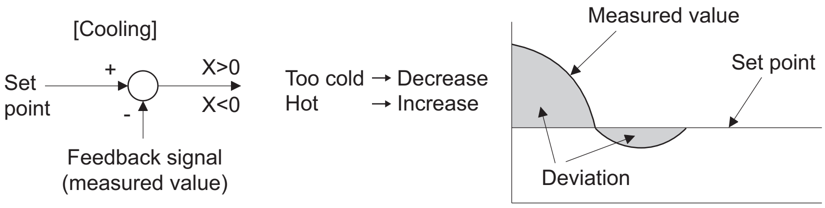
4)Reverse action

Increases the manipulated variable (output frequency) if deviation X = (set point - measured value) is positive, and decreases the manipulated variable if deviation is negative.



5)Forward action

Increases the manipulated variable (output frequency) if deviation X = (set point - measured value) is negative, and decreases the manipulated variable if deviation is positive.

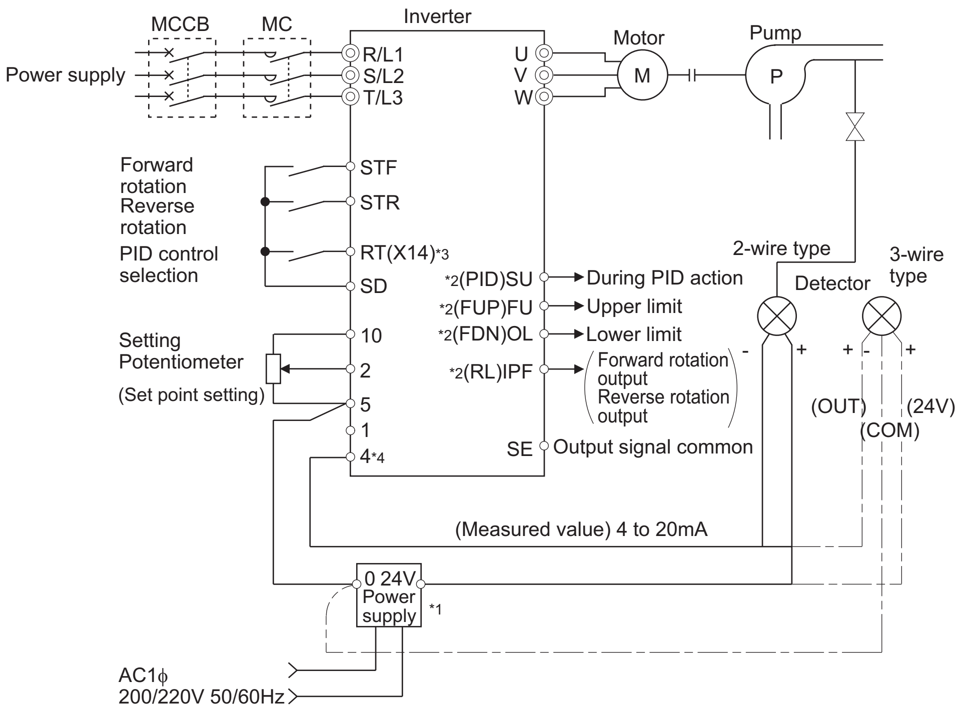


Relationships between deviation and manipulated variable (output frequency)

	Deviation	
	Positive	Negative
Reverse action	↗	↘
Forward action	↘	↗

(3) Connection diagram

- Sink logic
- *Pr. 128* = 20
- *Pr. 183* = 14
- *Pr. 191* = 47
- *Pr. 192* = 16
- *Pr. 193* = 14
- *Pr. 194* = 15



*1 The power supply must be selected in accordance with the power specifications of the detector used.

*2 The used output signal terminal changes depending on the *Pr. 190 to Pr. 196 (output terminal selection)* setting.

*3 The used input signal terminal changes depending on the *Pr. 178 to Pr. 189 (input terminal selection)* setting.

*4 The AU signal need not be input.

(4) I/O signals and parameter setting

- Turn ON the X14 signal to perform PID control. When this signal is OFF, PID action is not performed and normal inverter operation is performed. (However, turning X14 ON is not necessary when *Pr.128* = "50, 51, 60, 61, 110, 111, 120, 121".)
- Enter the set point across inverter terminals 2-5 or into *Pr. 133* and enter the measured value signal across inverter terminals 4 and 5. At this time, set any of "20, 21, 120, 121" in *Pr. 128*.
- When entering the externally calculated deviation signal, enter it across terminals 1 and 5. At this time, set any of "10, 11, 110, 111" in *Pr. 128*.

	Signal	Terminal Used	Function	Description	Parameter Setting
Input	X14	Depending on *Pr. 178 to Pr. 189*	PID control selection	Turn ON X14 to perform PID control.	Set 14 in any of *Pr. 178 to Pr. 189.*
	X64		PID forward/ reverse action switchover	By turning ON X64, forward action can be selected for PID reverse action (*Pr. 128* = 10, 20, 110, 120), and reverse action for forward action (*Pr. 128* = 11, 21, 111, 121).	Set 64 in any of *Pr. 178 to Pr. 189.*
	X72		PID integral value reset	ON: Integral and differential values are reset OFF: Normal processing	Set 72 in any of *Pr. 178 to Pr. 189.*
	2	2 *4	Set point input	Enter the set point for PID control.	*Pr. 128* = 20, 21, 120, 121 *Pr. 133* =9999
				0 to 5V................0 to 100%	*Pr. 73* = 1 *1, 3, 5, 11, 13, 15
				0 to 10V.............0 to 100%	*Pr. 73* = 0, 2, 4, 10, 12, 14
				0 to 20mA...........0 to 100%	*Pr. 73* = 6, 7, 16, 17
	PU	—	Set point input	Set the set value *(Pr. 133)* from the operation panel or parameter unit.	*Pr. 128* = 20, 21, 120, 121 *Pr. 133* = 0 to 100%
	1	1	Deviation signal input	Input the deviation signal calculated externally.	*Pr. 128* = 10 *1, 11, 110, 111
				-5V to +5V ....-100% to +100%	*Pr. 73* = 2, 3, 5, 7, 12, 13, 15, 17
				-10V to +10V ......-100% to +100%	*Pr. 73* = 0, 1 *1, 4, 6, 10, 11, 14, 16
	4	4 *4	Measured value input	Input the signal from the detector (measured value signal).	*Pr. 128* = 20, 21, 120, 121
				4 to 20mA...........0 to 100%	*Pr. 267* = 0 *1
				1 to 5V................0 to 100%	*Pr. 267* = 1
				2 to 10V.............0 to 100%	*Pr. 267* = 2
	Communi-cation *2	—	Deviation value input	Input the deviation value from LONWORKS, CC-Link communication.	*Pr. 128* = 50, 51
			Set value, measured value input	Input the set value and measured value from LONWORKS , CC-Link communication.	*Pr. 128* = 60, 61
Output	FUP	Depending on *Pr. 190 to Pr. 196*	Upper limit output	Output to indicate that the measured value signal exceeded the upper limit value *(Pr. 131)*.	*Pr. 128* =20, 21, 60, 61, 120, 121 *Pr. 131* ≠ 9999 Set 15 or 115 in any of *Pr. 190 to Pr. 196.* *3
	FDN		Lower limit output	Output when the measured value signal falls below the lower limit *(Pr. 132)*.	*Pr. 128* =20, 21, 60, 61, 120, 121 *Pr. 132* ≠ 9999 Set 14 or 114 in any of *Pr. 190 to Pr. 196.* *3
	RL		Forward (reverse) rotation direction output	"Hi" is output to indicate that the output indication of the parameter unit is forward rotation (FWD), and "Low" to indicate that it is reverse rotation (REV) or stop (STOP).	Set 16 or 116 in any of *Pr. 190 to Pr. 196.* *3
	PID		During PID control activated	Turns ON during PID control.	Set 47 or 147 in any of *Pr. 190 to Pr. 196.* *3
	SLEEP		PID output interruption	Turns ON when the PID output interruption function is performed.	*Pr. 575* ≠ 9999 Set 70 or 170 in any of *Pr. 190 to Pr. 196.* *3
	Y48		PID deviation limit	Output when the absolute value of deviation exceeds the limit value.	*Pr. 553* ≠ 9999 Set 48 or 148 in any of *Pr. 190 to Pr. 196.* *3
	SE	SE	Output terminal common	Common terminal for terminals assigned to FUP signal, FDN signal, RL signal, PID signal, SLEEP signal, and Y48 signal	

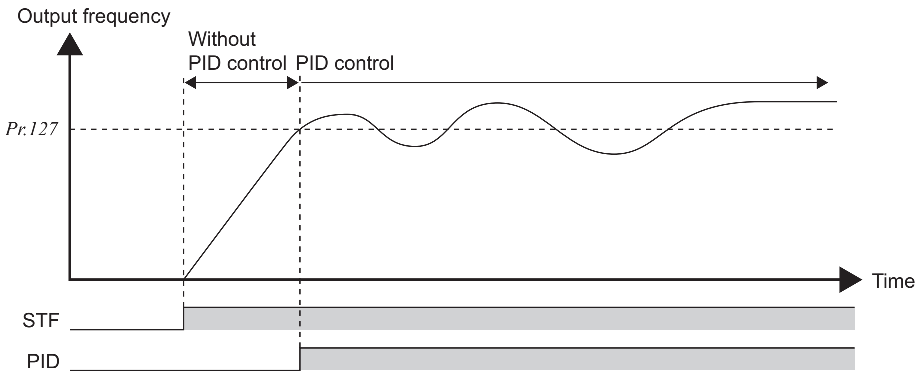
*1 The shaded area indicates the parameter initial value.
*2 For the setting method via LONWORKS communication, refer to the LONWORKS communication option (FR-A7NL) instruction manual.
For the setting method via CC-Link communication, refer to the CC-Link communication option (FR-A7NC) instruction manual.
*3 When 100 or larger value is set to any of *Pr. 190 to Pr. 196 (output terminal function selection)*, the terminal output has negative logic. *(Refer to page 140 for details)*
*4 When the voltage/current input specifications were changed using *Pr. 73* and *Pr. 267*, be sure to make calibration. *(Refer to page 268 for calibration examples for PID control.)*

CAUTION

- Changing the terminal assignment using any of *Pr. 178 to Pr. 189, and 190 to Pr. 196* may affect the other functions. Set parameters after confirming the function of each terminal.
- After changing *Pr.73 or Pr.267*, check the voltage/current input selection switch. Incorrect setting may cause a fault, failure or malfunction. (*Refer to page 185* for setting.)

(5) PID control automatic switchover control *(Pr. 127)*

- The inverter can be started up without PID control mode only at a start.
- When the frequency is set to *Pr. 127 PID control automatic switchover frequency* within the range of 0 to 400Hz, the system starts up without PID operation from a start until output frequency reaches *Pr. 127*, and then it shifts to PID control operation mode. Once the system has entered PID control operation, it continues PID control if the output frequency falls to or below *Pr. 127*.



(6) Selecting operation to be performed at the output of Upper limit signal, Lower limit signal, and PID deviation limit signal (FUP signal, FDN signal, Y48 signal, *Pr.554*)

You can select the operation to be performed at the detection of upper, lower and deviation limit for the measured value input. With *Pr. 554 PID signal operation selection*, signal output or signal output + alarm stop (E.PID) can be selected for each of upper limit output signal (FUP signal), lower limit output signal (FDN signal), and PID deviation limit signal (Y48 signal).

Pr. 554 Setting	FUP Signal, FDN Signal *	Y48 Signal *	SLEEP Function
0 (Initial value)	Only signal output	Only signal output	Motor coasts to a stop at the start of SLEEP operation
1	Signal output + stop by fault (E.PID)		
2	Only signal output	Signal output + stop by fault (E.PID)	
3	Signal output + stop by fault (E.PID)		
10	Only signal output	Only signal output	Motor decelerates to a stop at the start of SLEEP operation
11	Signal output + stop by fault (E.PID)		
12	Only signal output	Signal output + stop by fault (E.PID)	
13	Signal output + stop by fault (E.PID)		

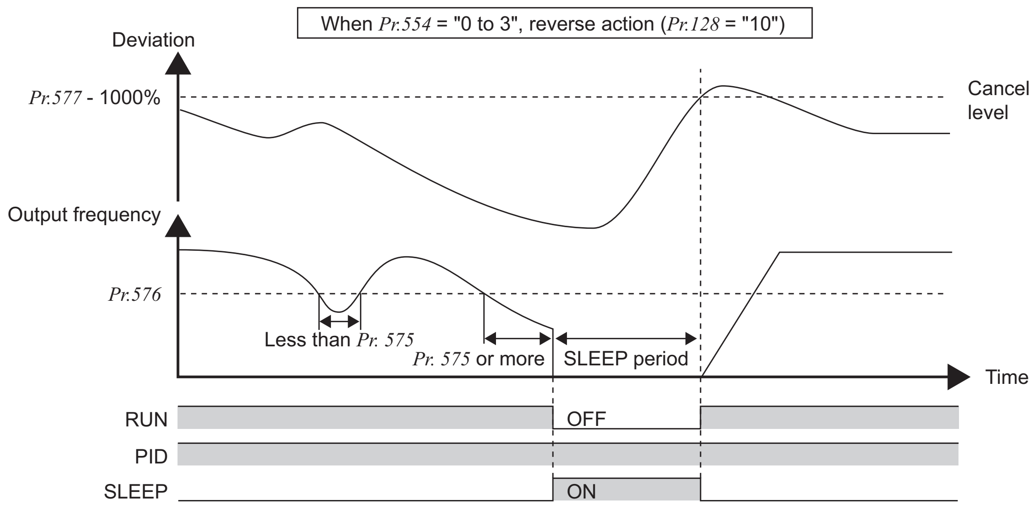
* When the settings for *Pr.131 PID upper limit*, *Pr.132 PID lower limit*, and *Pr.553 PID deviation limit*, which corresponds with FUP, FDN, and Y48 signals, are "9999" (no function), the signal is not output, or the alarm stop is not performed.

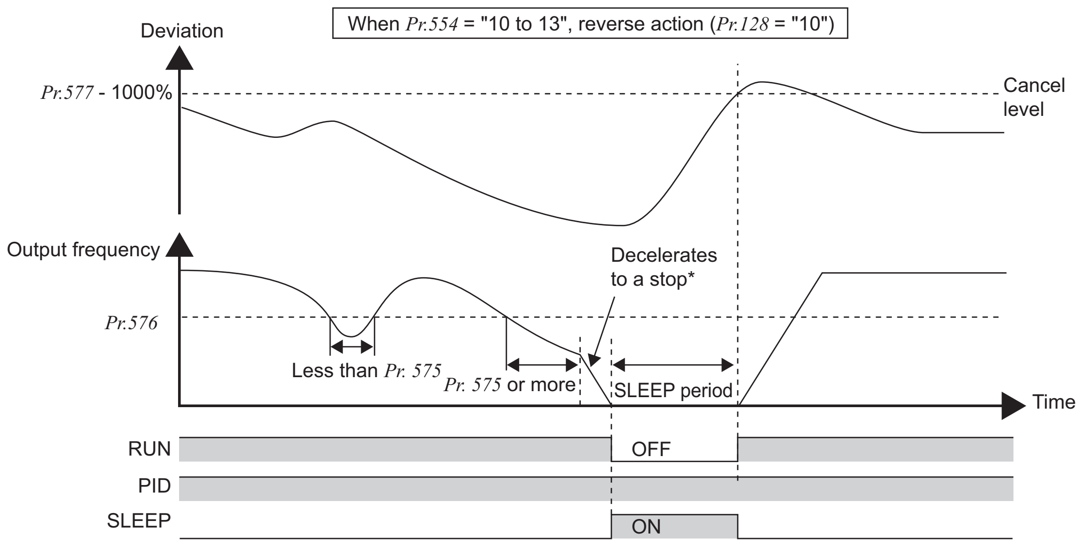
(7) PID output suspension function (SLEEP function) (SLEEP signal, *Pr. 554, Pr. 575 to Pr. 577*)

· The inverter stops operation if the output frequency after PID control remains at less than the *Pr. 576 Output interruption detection level* setting for longer than the time set in *Pr. 575 Output interruption detection time*. (At this time, if "0 to 3" is set to *Pr.554 PID signal operation selection*, output is shut off (the inverter coasts to stop) when SLEEP operation starts. If "10 to 13" is set, the motor decelerates to a stop in the deceleration time set in *Pr.8* when SLEEP operation starts.)
This function can reduce energy consumption in the low-efficiency, low-speed range.

Pr.554 Setting	SLEEP Function	FUP Signal, FDN Signal	Y48 Signal
0 (Initial value)	Motor coasts to a stop at the start of SLEEP operation	Only signal output	Only signal output
1		Signal output + stop by fault (E.PID)	
2		Only signal output	Signal output + stop by fault (E.PID)
3		Signal output + stop by fault (E.PID)	
10	Motor decelerates to a stop at the start of SLEEP operation	Only signal output	Only signal output
11		Signal output + stop by fault (E.PID)	
12		Only signal output	Signal output + stop by fault (E.PID)
13		Signal output + stop by fault (E.PID)	

· When the deviation (= set value - measured value) reaches the PID output shutoff cancel level (*Pr. 577* setting - 1000%) while the PID output interruption function is on, the PID output interruption function is canceled and PID control operation is resumed automatically.
· While the PID output interruption function is ON, the PID output interruption signal (SLEEP) is output. At this time, the inverter running signal (RUN) is OFF and the PID control operating signal (PID) is ON.
· For the terminal used for the SLEEP signal output, assign the function by setting "70" (positive logic) or "170" (negative logic) in *Pr. 190 to Pr. 196 (output terminal function selection)*.





* When the output rises to the output interruption cancel level during deceleration to a stop, output interruption gets cancelled, and the motor accelerates again to continue PID control. *Pr.576 Output interruption detection level* is invalid during deceleration.

(8) PID monitor function

- The PID control set value, measured value and deviation value can be displayed on the operation panel and output from terminal FM, AM.
- Integral value indicating a negative % can be displayed on the deviation monitor. 0% is displayed as 1000. (The deviation monitor cannot be output from the terminal FM, AM.)
- For the monitors, set the following values in *Pr. 52 DU/PU main display data selection*, *Pr. 54 FM terminal function selection*, and *Pr. 158 AM terminal function selection*.

Setting	Monitor Description	Minimum Increments*	Terminal FM, AM Full Scale*	Remarks
52	**PID set point**	0.1	100%/*C42(Pr.934)* or *C44(Pr.935)*	For deviation input (*Pr. 128* = 10, 11, 110, 111), the monitor value is always displayed as 0.
53	**PID measured value**			
54	**PID deviation**	0.1	—	Value cannot be set to *Pr. 54 or Pr. 158*. The PID deviation value of 0% is displayed as 1000.

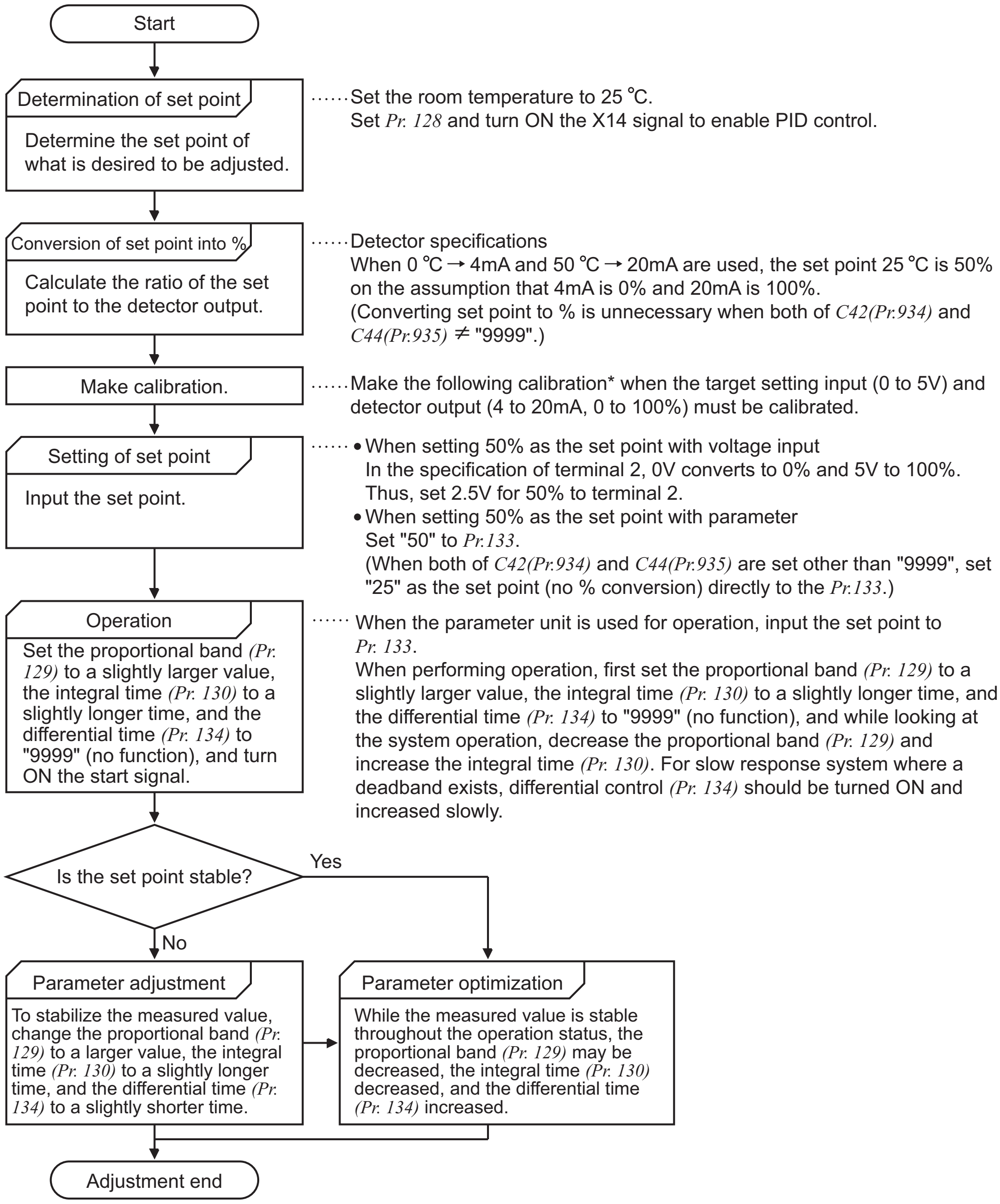
* When neither of *C42(Pr.934)* nor *C44(Pr.935)* setting is "9999", minimum increment changes from % to no unit, and the full scale value for terminal FM/AM changes from 100% to the larger value between *C42(Pr.934) PID display bias coefficient* and *C44(Pr.935) PID display gain coefficient*. (The smaller value between *C42(Pr.934)* and *C44(Pr.935)* becomes the minimum value.)

(9) Adjustment procedure

Parameter setting	Adjust the PID control parameters, *Pr. 127 to Pr. 134, Pr. 553, Pr. 554, and Pr. 575 to Pr. 577*.
Terminal setting	Set the I/O terminals for PID control. *(Pr. 178 to Pr. 189 (Input terminal function selection), Pr. 190 to Pr. 196 (output terminal function selection))*
Turn on the X14 signal.	PID control is available without turning X14 signal ON when *Pr.128* = "50, 51, 60, 61, 110, 111, 120, 121".
Operation	

(10) Calibration example

(A detector of 4mA at 0°C and 20mA at 50°C is used to adjust the room temperature to 25°C under PID control.
The set point is given to across inverter terminals 2 and 5 (0 to 5V).)



* When calibration is required
To perform calibration for detector output and set point input, set calibration parameters *Pr. 902* and *Pr. 903* (terminal 2), or *Pr. 904* and *Pr. 905* (terminal 4). However, use *Pr. 934* and *Pr. 935* instead of *Pr. 904* and *Pr. 905* when both of *C42 (Pr. 934)* and *C44(Pr. 935)* ≠ "9999". Make calibration in the PU mode during an inverter stop.
(For the details of *Pr. 902* to *Pr. 905*, *refer to page 193*. For the details of *Pr. 934* and *Pr. 935*, *refer to page 270*.)

<Set point input calibration>

1) Setting with terminal 2 input

1. Apply the input voltage of 0% set point setting (e.g. 0V) across terminals 2 and 5.
2. Enter in *C2 (Pr. 902)* the frequency which should be output by the inverter at the deviation of 0% (e.g. 0Hz).
3. In *C3 (Pr. 902)*, set the voltage value at 0%.
4. Apply the voltage of 100% set point (e.g. 5V) to across terminals 2 and 5.
5. Enter in *Pr. 125* the frequency which should be output by the inverter at the deviation of 100% (e.g. 60Hz).
6. In *C4 (Pr. 903)*, set the voltage value at 100%.

2) Setting with *Pr. 133*

When both or one of *C42 (Pr.934) and C44 (Pr.935)* is "9999".
For the set point, set a % converted value in the range of 0 to 100%.

When both of *C42 (Pr.934) and C44 (Pr.935)* ≠ "9999".
For the set point, set PID coefficient, which corresponds with 0 to 100%.

<Measured value calibration>

1) When both or one of *C42 (Pr.934)* and *C44 (Pr.935)* is "9999".

1. Apply the input current of 0% measured value (e.g. 4mA) across terminals 4 and 5.
2. Make calibration using *C6 (Pr. 904)*.
3. Apply the input current of 100% measured value (e.g. 20mA) across terminals 4 and 5.
4. Make calibration using *C7 (Pr. 905)*.

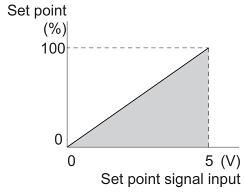
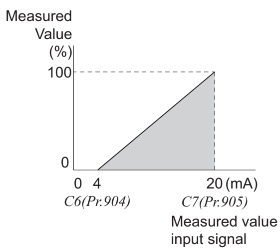
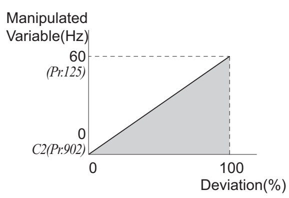
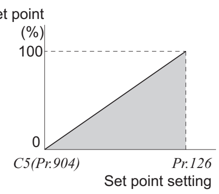
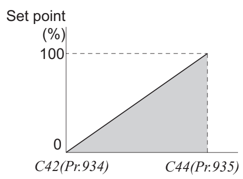
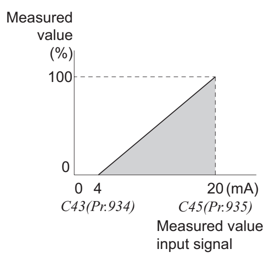
2) When both of *C42 (Pr.934)* and *C44 (Pr.935)* ≠ "9999".

1. Apply the input current of 0% measured value (e.g. 4mA) across terminals 4 and 5.
2. Set PID display value at 0% measured value (example: 15(°C)) to *C42 (Pr.934)* , and calibrate *C43 (Pr.934)*.
3. Apply the input current of 100% measured value (e.g. 20mA) across terminals 4 and 5.
4. Set PID display value at 100% measured value (example: 35(°C)) to *C44 (Pr.935)*, and calibrate *C45 (Pr.935)*.

REMARKS

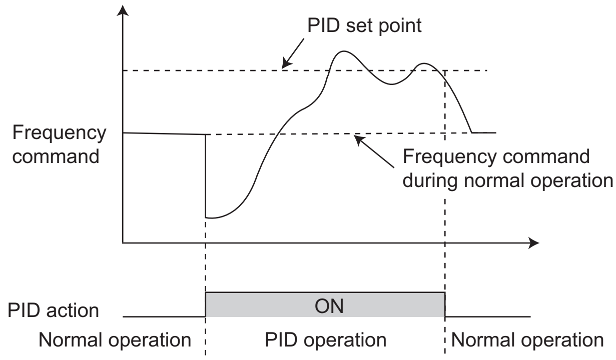
· The frequency set in *C5 (Pr. 904)* and *Pr. 126* should be the same as set in *C2 (Pr. 902)* and *Pr. 125*.

The results of the above calibration are as shown below:

<table>
<tr><th>Pr.133 Setting</th><th>Pr.934, Pr.935 Setting</th><th>Set Point Setting</th><th>Measured Value (Terminal 4)</th><th>Manipulated Variable</th></tr>
<tr><td>9999</td><td>—</td><td>(Terminal 2)
</td><td rowspan="2"></td><td rowspan="3"></td></tr>
<tr><td rowspan="2">Other than 9999</td><td>Both or one is 9999</td><td>(Pr.133)
</td></tr>
<tr><td>Other than 9999</td><td>(Pr.133)

Set PID coefficient corresponding with 0 to 100%.</td><td></td></tr>
</table>

CAUTION

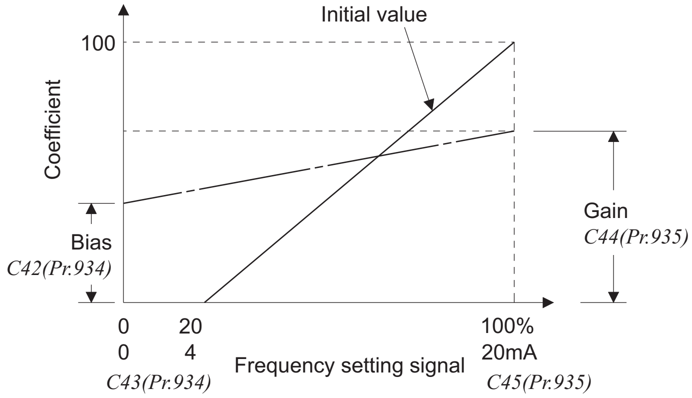
- If the multi-speed (RH, RM, RL signal) or Jog operation (JOG signal) is entered with the X14 signal ON, PID control is stopped and multi-speed or jog operation is started.
- If the setting is as follows, PID control becomes invalid.
  Pr. 22 Stall prevention operation level = "9999" (analog variable)
  Pr. 79 Operation mode selection = "6" (switchover mode))
- When the *Pr. 128* setting is "20, 21, 120, 121", note that the input across inverter terminals 1 and 5 is added to the set value across terminals 2 and 5.
- Changing the terminal function using any of *Pr. 178 to Pr. 189, Pr. 190 to Pr. 196* may affect the other functions. Set parameters after confirming the function of each terminal.
- When PID control is selected, the minimum frequency is the frequency set in *Pr. 902* and the maximum frequency is the frequency set in *Pr. 903*. (*Pr. 1 Maximum frequency* and *Pr. 2 Minimum frequency* settings are also valid.)
- The remote operation function is invalid during PID operation.
- When the control is switched to PID control during normal operation, the frequency command value calculated by PID operation using 0Hz as standard is used without the frequency during the operation.



Operation when control is switched to PID control during normal operation

(11) Bias and gain calibration for PID displayed values (*C42(Pr. 934) to C45(Pr. 935)*)

- When both of *C42(Pr.934)* and *C44(Pr.935)* ≠ "9999", bias/gain calibration is available for analog value of set point, measured value, deviation value to perform PID control.
- "Bias" / "gain" function can adjust the relation between PID displayed coefficient and measured value input signal. Examples of measured value input signals are 0 to 5VDC, 0 to 10VDC, or 4 to 20mADC, and they are externally input.
- Set PID display bias coefficient for terminal 4 input with *C42(Pr.934)*.
  (Initial value is the coefficient for 4mA.)
- Set PID display gain coefficient for 20mA of the frequency command current (4 to 20mA) with *C44(Pr.935)*.
- When both of *C42(Pr.934)* and *C44(Pr.935)* ≠ "9999" and *Pr.133* is set as the set point, the setting of *C42(Pr.934)* is treated as 0%, and *C44(Pr.935)* as 100%.



- Three methods of bias/gain adjustment for PID displayed values are the following.
  (a)Method to adjust any point by application of voltage (current) across the terminals 4 and 5.
  (b)Method to adjust any point without application of voltage (current) across terminals 4 and 5.
  (c)Method to adjust only the frequency without adjusting the voltage (current).
  (For the detail of (a) to (c), *refer to page 193*.
  Make adjustment by assuming *C7 (Pr.905)* as *C45 (Pr.935)*, and *Pr.126* as *C44 (Pr.935)*.)

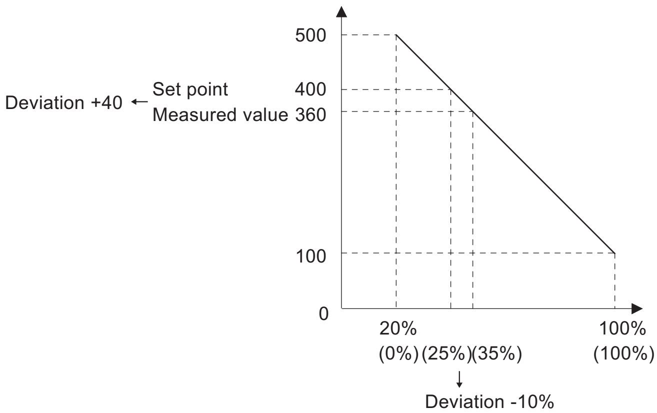
CAUTION

- When the voltage/current input specifications are changed with voltage/current input switch and using *Pr. 73* and *Pr. 267*, be sure to make calibration.

- Take caution when the following condition is satisfied because the inverter recognizes the deviation value as a negative (positive) value even though a positive (negative) deviation is given:
  Pr. 934 PID display bias coefficient > *Pr. 935 PID display gain coefficient*
  To perform a reverse operation, set the forward operation in *Pr. 128 PID action selection*. To perform a forward operation, set the reverse operation in *Pr. 128*. In this case, the PID output shutoff release level is (1000 - *Pr. 577*).

Pr. 934 < *Pr. 935* **(normal setting)**		*Pr. 934* ≥ *Pr. 935*	
Reverse operation	Reverse operation setting to *Pr. 128*	Reverse operation	Forward operation setting to *Pr. 128*
Forward operation	Forward operation setting to *Pr. 128*	Forward operation	Reverse operation setting to *Pr. 128*
PID output shutoff release level	*Pr. 577* - 1000	PID output shutoff release level	1000 - *Pr. 577*

(Example) Set the following: *Pr. 934* = "500" and 20% (4mA is applied), *Pr. 935* = "100" and 100% (20mA is applied).
When the set point=400 and the measured value=360, the deviation is +40 (>0), but the inverter recognizes the deviation with -10% (<0). Because of this, operation amount does not increase in the reverse operation setting.
The operation amount increases when the forward operation is set.
To perform PID output shutoff release at deviation of +40 or higher, set *Pr. 577* = "960."



* ( ) indicates the deviation value which the inverter can recognize

(12) Analog input display unit changing *(Pr. 241)*

- You can change the analog input display unit (%/V, mA) for analog input bias/gain calibration.
- Depending on the terminal input specification set to *Pr. 73*, *Pr. 267*, and voltage/current input switch the display units of *C3(Pr. 902), C4(Pr. 903), C43(Pr. 934), C45(Pr. 935)* change as shown below.

Analog Command (Terminal 4) (according to *Pr. 73*, *Pr. 267*, and Voltage/Current Input Switch)	*Pr. 241* = 0 (Initial Value)	*Pr. 241* = 1
0 to 5V input	0 to 5V → displayed in 0 to 100%(0.1%).	0 to 100% → displayed in 0 to 5V(0.01V).
0 to 10V input	0 to 10V → displayed in 0 to 100%(0.1%).	0 to 100% → displayed in 0 to 10V(0.01V).
4 to 20mA input	0 to 20mA → displayed in 0 to 100%(0.1%).	0 to 100% → displayed in 0 to 20mA(0.01mA).

♦ Parameters referred to ♦

Pr. 59 Remote function selection ☞ *Refer to page 106*
Pr. 73 Analog input selection ☞ *Refer to page 185*
Pr. 79 Operation mode selection ☞ *Refer to page 206*
Pr. 178 to Pr. 189 (input terminal function selection) ☞ *Refer to page 133*
Pr. 190 to Pr. 196 (output terminal function selection) ☞ *Refer to page 140*
C2 (Pr. 902) to C7 (Pr. 905) Frequency setting voltage (current) bias/gain ☞ *Refer to page 193*

4.21.2 Bypass-inverter switchover function (pr. 57, Pr. 58, Pr. 135 to Pr. 139, Pr. 159)

V/F S MFVC

The complicated sequence circuit for bypass operation is built in the inverter. Hence, simply inputting the start, stop or automatic switchover selection signal facilitates the interlock operation of the switchover magnetic contactor.

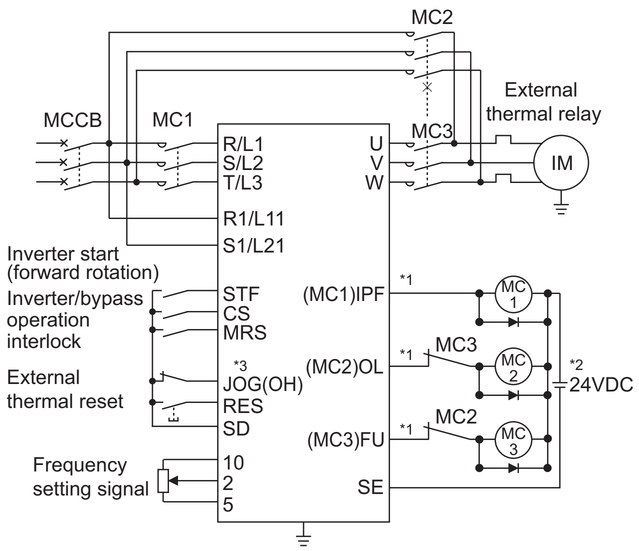
Parameter Number	Name	Initial Value	Setting Range	Description
57	Restart coasting time	9999	0	· 1.5K or lower....................0.5s, · 2.2K to 7.5K....................1s, · 11K to 55K....................3.0s, · 75K or higher ....5.0s, The above times are coasting time.
			55K or lower: 0.1 to 5s 75K or higher: 0.1 to 30s	Set the waiting time for inverter-triggered restart after an instantaneous power failure.
			9999	No restart
58	Restart cushion time	1s	0 to 60s	Set a voltage starting time at restart.
135	Electronic bypass sequence selection	0	0	Without electronic bypass sequence
			1	With electronic bypass sequence
136	MC switchover interlock time	1s	0 to 100s	Set the operation interlock time of MC2 and MC3.
137	Start waiting time	0.5s	0 to 100s	Set the time slightly longer (0.3 to 0.5s or so) than the time from when the ON signal enters MC3 until it actually turns ON.
138	Bypass selection at a fault	0	0	Inverter output is stopped (motor coast) at inverter fault.
			1	Operation is automatically switched to bypass operation at inverter fault (Not switched when an external thermal relay operation (E.OHT) or CPU fault (E.CPU) occurs).
139	Automatic switchover frequency from inverter to bypass operation	9999	0 to 60Hz	Set the frequency to switch inverter operation to bypass operation. Inverter operation is performed from a start until *Pr. 139* is reached, and when the output frequency is at or above *Pr. 139*, inverter operation is automatically switched to bypass operation.
			9999	Without automatic switchover
159	Automatic switchover frequency range from bypass to inverter operation	9999	0 to 10Hz	Valid during automatic switchover operation (*Pr. 139* ≠ 9999) When the frequency command decreases below (*Pr. 139* - *Pr. 159*) after operation is switched from inverter operation to bypass operation, the inverter automatically switches operation to inverter operation and operates at the frequency of frequency command. When the inverter start command (STF/STR) is turned OFF, operation is switched to inverter operation also.
			9999	Valid during automatic switchover operation (*Pr. 139* ≠ 9999) When the inverter start command (STF/STR) is turned OFF after operation is switched from inverter operation to bypass operation, operation is switched to inverter operation and the motor decelerates to stop.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*

- When the motor is operated at 60Hz (or 50Hz), more efficient operation can be performed by the commercial power supply than by the inverter. When the motor cannot be stopped for a long time for the maintenance/inspection of the inverter, it is recommended to provide the commercial power supply circuit.
- To avoid commercial power supply being applied to the inverter output side when switching between inverter operation and commercial power supply operation, provide an interlock which the MC of the commercial power supply side turns ON only when the MC of the inverter output side is OFF. Using the electronic bypass sequence function that outputs the timing signal for operation of the magnetic contactor, a complicated commercial power supply switchover interlock can be provided by the inverter.

(1) Connection diagram

· The following shows the connection diagram of a typical electronic bypass sequence. Sink logic, *Pr. 185* = "7", *Pr. 192* = "17", *Pr. 193* = "18", *Pr. 194* = "19"



Electronic bypass sequence connection diagram

*1 Take caution for the capacity of the sequence output terminal.
The used terminal changes depending on the setting of *Pr. 190 to Pr. 196 (output terminal function selection)*.

Output Terminal Capacity	Output Terminal Permissible Load
Inverter open collector output (RUN, SU, IPF, OL, FU)	24VDC 0.1A
Inverter relay output (A1 and C1, B1 and C1, A2 and B2, B2 and C2) Relay output option (FR-A7AR)	230VAC 0.3A 30VDC 0.3A

*2 When connecting a DC power supply, insert a protective diode. When connecting an AC power supply, connect a relay output option (FR-A7AR) and use a contact output.

*3 The used terminal changes depending on the setting of *Pr. 180 to Pr. 189 (input terminal function selection)*.

CAUTION

- Use the bypass operation function in External operation mode. Be sure to connect the other power supply since the function is not performed normally unless the connection terminals R1/L11, S1/L21 are not connected to the other power supply (power supply that does not pass MC1).
- Be sure to provide mechanical interlocks for MC2 and MC3.
- The bypass operation cannot be performed with an IPM motor. Applying the commercial power supply will burn the IPM motor. Therefore, never connect the commercial power supply.

· Operations of magnetic contactors (MC1, MC2, MC3)

Magnetic Contactor	Installation Place	Operation (○: Shorted, ×: Open)		
		Bypass operation	During inverter operation	At an inverter fault occurrence
MC1	Between power supply and inverter input	○	○	× (Shorted by reset)
MC2	Between power supply and motor	○	×	× (Can be selected using *Pr. 138*, always open when external thermal relay is ON)
MC3	Between inverter output and motor	×	○	×

· The input signals are as indicated below.

Signal	Terminal Used	Function	Operation	MC Operation *6		
				MC1 *5	MC2	MC3
MRS	MRS	Operation enable/disable selection *1	ON ..... Bypass-inverter operation enabled	○	—	—
			OFF ... Bypass-inverter operation disabled	○	×	No change
CS	CS	Inverter/bypass *2	ON...... Inverter operation	○	×	○
			OFF ... Bypass operation	○	○	×
STF (STR)	STF(STR)	Inverter operation command (Invalid for bypass) *3	ON...... Forward rotation (reverse rotation)	○	×	○
			OFF .... Stop	○	×	○
OH	Set "7" in any of *Pr. 180 to Pr. 189*.	External thermal relay input	ON ..... Motor normal	○	—	—
			OFF .... Motor abnormal	×	×	×
RES	RES	Operating status initialization *4	ON...... Initialization	No change	×	No change
			OFF .... Normal operation	○	—	—

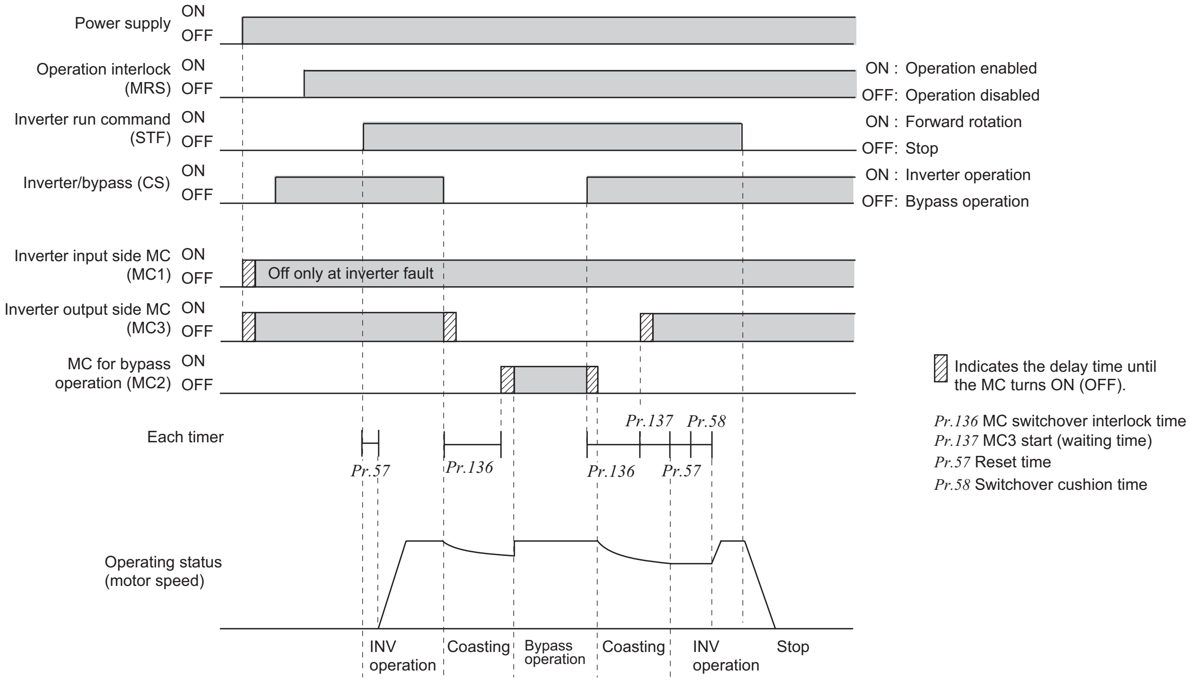
*1 Unless the MRS signal is turned ON, neither bypass operation nor inverter operation can be performed.
*2 The CS signal functions only when the MRS signal is ON.
*3 STF (STR) functions only when both the MRS signal and CS signal are ON.
*4 The RES signal enables reset input acceptance selection using *Pr. 75 Reset selection/disconnected PU detection/PU stop selection*.
*5 MC1 turns OFF when an inverter fault occurs.
*6 MC operation
○ : MC-ON
× : MC-OFF
— : Inverter operation.. MC2 is OFF and MC3 is ON
Bypass operation .... MC2 is ON and MC3 is OFF
No change : The status before the signal turns ON or OFF is held.

· The output signals are as indicated below.

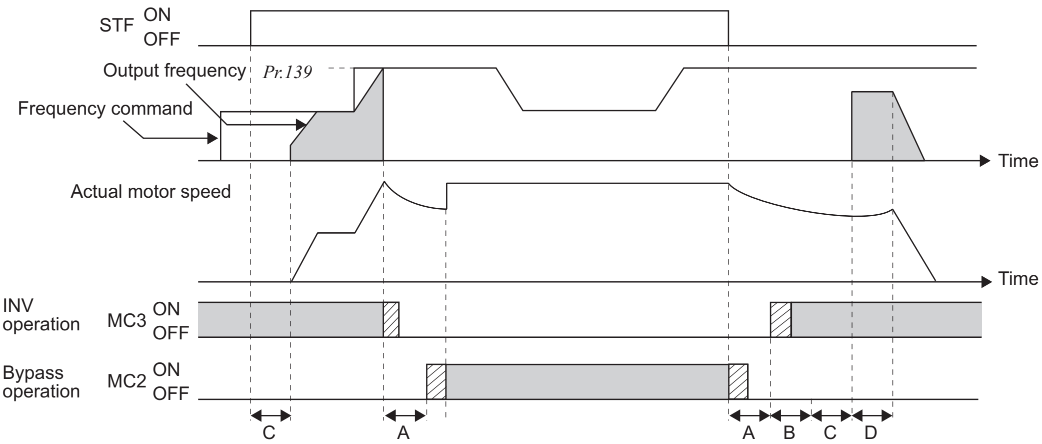
Signal	Terminal Used (*Pr. 190 to Pr. 196* setting)	Description
MC1	17	Control signal output of inverter input side magnetic contactor MC1
MC2	18	Control signal output of bypass operation magnetic contactor MC2
MC3	19	Control signal output of inverter output side magnetic contactor MC3

(2) Electronic bypass operation sequence

· Operation sequence example when there is no automatic switchover sequence (*Pr. 139* = "9999")

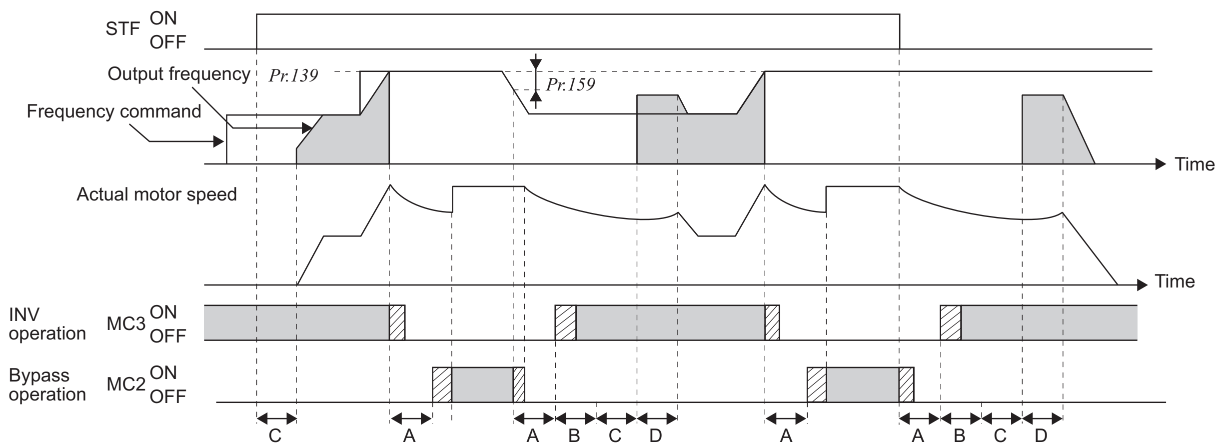


· Operation sequence example when there is automatic switchover sequence (*Pr. 139* ≠ "9999", *Pr. 159* = "9999")



A : *Pr.136* MC switchover interlock time B : *Pr.137* Start waiting time
C : *Pr.57* Restart coasting time D : *Pr.58* Restart cushion time

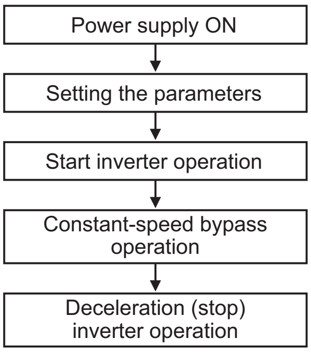
· Operation sequence example when there is automatic switchover sequence (*Pr. 139* ≠ "9999", *Pr. 159* ≠ "9999")



A : *Pr.136* MC switchover interlock time B : *Pr.137* Start waiting time
C : *Pr.57* Restart coasting time D : *Pr.58* Restart cushion time

(3) Operating procedure

· Procedure for operation
  Operation pattern



· *Pr. 135* = "1" (open collector output terminal of inverter)
· *Pr. 136* = "2.0s"
· *Pr. 137* = "1.0s" (Set the time longer than the time from when MC3 actually turns ON until the inverter and motor are connected. If the time is short, a restart may not function properly.)
· *Pr. 57* = "0.5s"
· *Pr. 58* = "0.5s" (Be sure to set this parameter when bypass operation is switched to inverter operation.)

2)Signal ON/OFF after parameter setting

	MRS	**CS**	**STF**	**MC1**	**MC2**	**MC3**	**Remarks**
Power supply ON	OFF (OFF)	OFF (OFF)	OFF (OFF)	OFF → ON (OFF → ON)	OFF (OFF)	OFF → ON (OFF → ON)	External operation mode (PU operation mode)
At start (inverter)	OFF → ON	OFF → ON	OFF → ON	ON	OFF	ON	
At constant speed (commercial power supply)	ON	ON → OFF	ON	ON	OFF → ON	ON → OFF	MC2 turns ON after MC3 turns OFF (coasting status during this period) Waiting time 2s
Switched to inverter for deceleration (inverter)	ON	OFF → ON	ON	ON	ON → OFF	OFF → ON	MC3 turns ON after MC2 turns OFF (coasting status during this period) Waiting time 4s
Stop	ON	ON	ON → OFF	ON	OFF	ON	

CAUTION

· Connect the control power supply (R1/L11, S1/L21) in front of input side MC1. If the control power supply is connected behind input side MC1, the electronic bypass sequence function is not executed.
· The electronic bypass sequence function is valid only when *Pr. 135* = "1" in the external operation or combined operation mode (PU speed command, external operation command *Pr. 79* = "3"). When *Pr. 135* = "1" in the operation mode other than the above, MC1 and MC3 turn ON.
· When the MRS and CS signals are ON and the STF (STR) signal is OFF, MC3 is ON, but when the motor was coasted to a stop from bypass operation last time, a start is made after the time set to *Pr. 137* has elapsed.
· Inverter operation can be performed when the MRS, STF (STR) and CS signals turn ON. In any other case (MRS signal - ON), bypass operation is performed.
· When the CS signal is turned OFF, the motor switches to bypass operation. However, when the STF (STR) signal is turned OFF, the motor is decelerated to a stop in the inverter operation mode.
· When both MC2 and MC3 are OFF and either MC2 or MC3 is then turned ON, there is a waiting time set in *Pr. 136*.
· If electronic bypass sequence is valid (*Pr. 135* = "1"), the *Pr. 136 and Pr. 137* settings are ignored in the PU operation mode. The input terminals (STF, CS, MRS, OH) of the inverter return to their normal functions.
· When the electronic bypass sequence function (*Pr. 135* = "1") and PU operation interlock function (*Pr. 79* = "7") are used simultaneously, the MRS signal is shared by the PU operation external interlock signal unless the X12 signal is assigned. (When the MRS and CS signals turn ON, inverter operation is enabled)
· Set the acceleration time to the level that does not activate the stall prevention operation.
· Changing the terminal function using any of *Pr. 178 to Pr. 189, 190 to Pr. 196* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 11 DC injection brake operation time ☞ *Refer to page 123*
Pr. 57 Restart coasting time ☞ *Refer to page 162*
Pr. 58 Restart cushion time ☞ *Refer to page 162*
Pr. 79 Operation mode selection ☞ *Refer to page 206*
Pr. 178 to Pr. 189 (Input terminal function selection) ☞ *Refer to page 133*
Pr. 190 to Pr. 196 (Output terminal function selection) ☞ *Refer to page 140*

4.21.3 Regeneration avoidance function (Pr. 665, Pr. 882 to Pr. 886)

This function detects a regeneration status and increases the frequency to avoid the regeneration status.

- Possible to avoid regeneration by automatically increasing the frequency and continue operation if the fan happens to rotate faster than the set speed due to the effect of another fan in the same duct.

Parameter Number	Name	Initial Value	Setting Range	Description
882	**Regeneration avoidance operation selection**	0	0	Regeneration avoidance function invalid
			1	Regeneration avoidance function valid
			2	Regeneration avoidance function is valid only during a constant speed operation
883	**Regeneration avoidance operation level**	200V class: 380VDC 400V class: 760VDC	300 to 800V	Set the bus voltage level at which regeneration avoidance operates. When the bus voltage level is set to low, overvoltage error will be less apt to occur. However, the actual deceleration time increases. The set value must be higher than the power supply voltage × $\sqrt{2}$.
884	**Regeneration avoidance at deceleration detection sensitivity**	0	0	Regeneration avoidance by bus voltage change ratio is invalid
			1 to 5	Set sensitivity to detect the bus voltage change ratio Setting 1 ⟶ 5 Detection sensitivity low ⟶ high
885 Ver.UP	**Regeneration avoidance compensation frequency limit value**	6Hz *1	0 to 30Hz	Set the limit value of frequency which rises at activation of regeneration avoidance function.
			9999	Frequency limit invalid
886	**Regeneration avoidance voltage gain**	100%	0 to 200%	Adjust responsiveness at activation of regeneration avoidance. A larger setting will improve responsiveness to the bus voltage change. However, the output frequency could become unstable. When vibration is not suppressed by decreasing the *Pr. 886* setting, set a smaller value in *Pr. 665*.
665	**Regeneration avoidance frequency gain**	100%	0 to 200%	

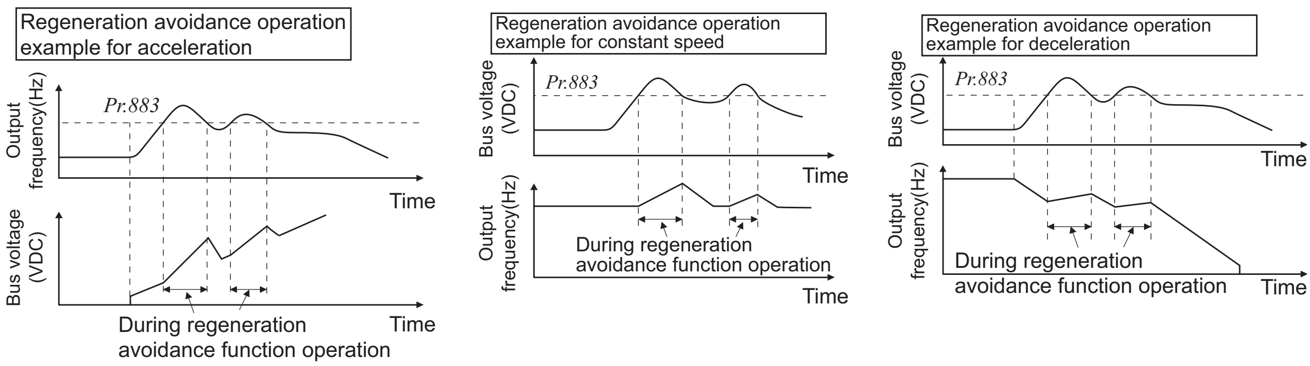
The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

Ver.UP ....Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.

*1 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*

(1) What is regeneration avoidance function? *(Pr. 882, Pr. 883)*

- When the regeneration status is serious, the DC bus voltage rises and an overvoltage fault (E. OV□) may occur. When this bus voltage rise is detected and the bus voltage level reaches or exceeds *Pr. 883*, increasing the frequency avoids the regeneration status.
- The regeneration avoidance operation, you can select whether it is always activated or activated only a constant speed.



- Setting *Pr. 882* to "1, 2" validates the regeneration avoidance function.

REMARKS

- The inclination of the frequency increased or decreased by the regeneration avoidance function changes depending on the regeneration status.
- The DC bus voltage of the inverter is normally about $\sqrt{2}$ times greater than the input voltage.
  When the input voltage is 220VAC, the bus voltage is about 311VDC.
  When the input voltage is 440VAC, the bus voltage is about 622VDC.
  However, it varies with the input power waveform.
- The *Pr. 883* setting should be kept higher than the DC bus voltage level. Otherwise, the regeneration avoidance function is always ON even in the non-regeneration status and the frequency increases.
- While overvoltage stall (oL) is activated only during deceleration and stops the decrease in output frequency, the regeneration avoidance function is always ON (*Pr. 882* = 1) or activated only during a constant speed (*Pr. 882* = 2) and increases the frequency according to the regeneration amount.

4

PARAMETERS

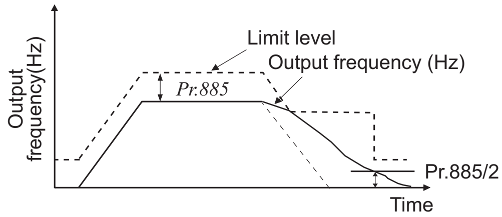
(2) To detect the regeneration status during deceleration faster *(Pr. 884)*

· As the regeneration avoidance function cannot respond to an abrupt voltage change by detection of the bus voltage level, the ratio of bus voltage change is detected to stop deceleration if the bus voltage is less than *Pr. 883 Regeneration avoidance operation level*.
Set that detectable bus voltage change ratio to *Pr. 884* as detection sensitivity.
Increasing the setting raises the detection sensitivity

CAUTION

Too small setting (low detection sensitivity) will disable detection, and too large setting will turn ON the regeneration avoidance function if the bus voltage is varied by an input power change, etc.

(3) Limit regeneration avoidance operation frequency *(Pr. 885)*



You can limit the output frequency compensated for (increased) by the regeneration avoidance function.

· The frequency is limited to the output frequency (frequency prior to regeneration avoidance operation) + *Pr. 885 Regeneration avoidance compensation frequency limit value* during acceleration or constant speed. If the frequency increased by regeneration avoidance function exceeds the limit value during deceleration, the limit value is held until the output frequency falls to 1/2 of *Pr. 885*.
· When the frequency increased by regeneration avoidance function has reached *Pr. 1 Maximum frequency*, it is limited to the maximum frequency.
· *Pr. 885* is set to "9999", regeneration avoidance function operation frequency setting is invalid.

(4) Regeneration avoidance function adjustment *(Pr. 665, Pr. 886)*

· If the frequency becomes unstable during regeneration avoidance operation, decrease the setting of *Pr. 886 Regeneration avoidance voltage gain*. Reversely, if sudden regeneration causes an overvoltage fault, increase the setting.
· When vibration is not suppressed by decreasing the *Pr. 886 Regeneration avoidance voltage gain* setting, set a smaller value in *Pr. 665 Regeneration avoidance frequency gain*.

CAUTION

· When regeneration avoidance operation is performed, oL (overvoltage stall) is displayed and the OL signal is output. Set the operation pattern at an OL signal output using *Pr.156 Stall prevention operation selection*. Set the output timing of the OL signal using *Pr. 157 OL signal output timer*.
· When regeneration avoidance operation is performed, stall prevention is also activated.
· The regeneration avoidance function cannot shorten the actual deceleration time taken to stop the motor. The actual deceleration time depends on the regenerative energy consumption capability. When shortening the deceleration time, consider using the regeneration unit (FR-BU2, BU, FR-BU, MT-BU5, FR-CV, FR-HC, MT-HC) to consume regenerative energy at constant speed.
· When using a regeneration unit (FR-BU2, BU, FR-BU, MT-BU5, FR-CV, FR-HC, MT-HC) to consume regenerative energy at constant speed, set *Pr. 882* = "0 (initial value)" (Regenerative avoidance function invalid). When using the regeneration unit, etc. to consume regenerative energy at deceleration, set *Pr. 882* = "2" (regeneration avoidance function valid only at a constant speed).

♦ Parameters referred to ♦

Pr. 1 Maximum frequency ☞ *Refer to page 96*
Pr. 8 Deceleration time ☞ *Refer to page 109*
Pr. 22 Stall prevention operation level ☞ *Refer to page 91*

4.22 Useful functions

Purpose	Parameter that must be Set		Refer to Page
Increase cooling fan life	**Cooling fan operation selection**	**Pr. 244**	281
To determine the maintenance time of parts.	**Inverter part life display**	**Pr. 255 to Pr. 259**	282
	Maintenance output function	**Pr. 503, Pr. 504**	285
	Current average value monitor signal	**Pr. 555 to Pr. 557**	286
Freely available parameter	**Free parameter**	**Pr. 888, Pr. 889**	288
To initiate a fault alarm	**Fault initiation**	**Pr. 997**	289
To save time for parameter setting	**Automatic parameter setting**	**Pr. 999**	290

4.22.1 Cooling fan operation selection (Pr. 244)

You can control the operation of the cooling fan (FR-F720P-2.2K or higher, FR-F740P-3.7K or higher) built in the inverter.

Parameter Number	Name	Initial Value	Setting Range	Description
244	**Cooling fan operation selection**	1	0	Operates at power ON Cooling fan ON/OFF control invalid (The cooling fan is always ON at power ON)
			1	Cooling fan ON/OFF control valid The fan is always ON while the inverter is running. During a stop, the inverter status is monitored and the fan switches ON-OFF according to the temperature.

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*

- In either of the following cases, fan operation is regarded as faulty, [FN] is shown on the operation panel, and the fan alarm output (FAN) and alarm (LF) signals are output.
  ·*Pr. 244* = "0"
  When the fan comes to a stop with power ON.
  ·*Pr. 244* = "1"
  When the fan stops during the fan ON command while the inverter is running.
- For the terminal used for the FAN signal output, set "25" (positive logic) or "125" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*, and for the LF signal, set "98" (positive logic) or "198" (negative logic).

CAUTION

- Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 190 to Pr. 196 (output terminal function selection) *Refer to page 140*

4

PARAMETERS

4.22.2 Display of the life of the inverter parts (Pr. 255 to Pr .259)

Degrees of deterioration of main circuit capacitor, control circuit capacitor, cooling fan and inrush current limit circuit can be diagnosed by monitor.
When any part has approached the end of its life, an alarm can be output by self diagnosis to prevent a fault.
(Use the life check of this function as a guideline since the life except the main circuit capacitor is calculated theoretically.)
For the life check of the main circuit capacitor, the alarm signal (Y90) will not be output if a measuring method of (4) is not performed.

Parameter Number	Name	Initial Value	Setting Range	Description
255	**Life alarm status display**	0	(0 to 15)	Displays whether the control circuit capacitor, main circuit capacitor, cooling fan, and each parts of the inrush current limit circuit has reached the life alarm output level or not. Reading only
256	**Inrush current limit circuit life display**	100%	(0 to 100%)	Displays the deterioration degree of the inrush current limit circuit. Reading only
257	**Control circuit capacitor life display**	100%	(0 to 100%)	Displays the deterioration degree of the control circuit capacitor. Reading only
258	**Main circuit capacitor life display**	100%	(0 to 100%)	Displays the deterioration degree of the main circuit capacitor. Reading only Displays the value measured by *Pr. 259*.
259	**Main circuit capacitor life measuring**	0	0, 1 (2, 3, 8, 9)	Setting "1" and switching the power supply OFF starts the measurement of the main circuit capacitor life. When the *Pr. 259* value is "3" after powering ON again, the measuring is completed. Reads the deterioration degree in *Pr. 258*.

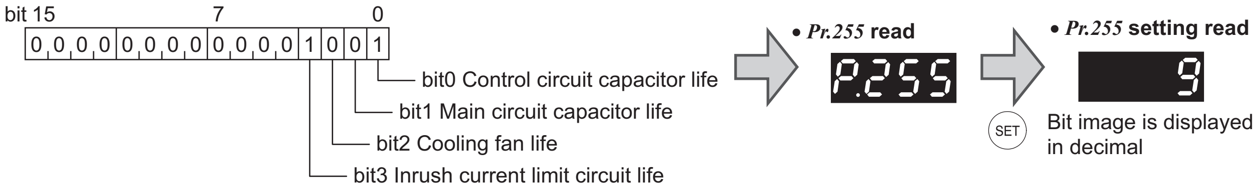
The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*

REMARKS

· Since repeated inrush currents at power ON will shorten the life of the converter circuit, frequent starts and stops of the magnetic contactor must be avoided.

(1) Life alarm display and signal output (Y90 signal, *Pr. 255*)

· Whether any of the control circuit capacitor, main circuit capacitor, cooling fan and inrush current limit circuit has reached the life alarm output level or not can be checked by *Pr. 255 Life alarm status display* and life alarm signal (Y90).



Pr. 255 (decimal)	Bit (binary)	Inrush Current Limit Circuit Life	Cooling Fan Life	Main Circuit Capacitor Life	Control Circuit Capacitor Life
15	1111	○	○	○	○
14	1110	○	○	○	×
13	1101	○	○	×	○
12	1100	○	○	×	×
11	1011	○	×	○	○
10	1010	○	×	○	×
9	1001	○	×	×	○
8	1000	○	×	×	×
7	0111	×	○	○	○
6	0110	×	○	○	×
5	0101	×	○	×	○
4	0100	×	○	×	×
3	0011	×	×	○	○
2	0010	×	×	○	×
1	0001	×	×	×	○
0	0000	×	×	×	×

○: With warnings, ×: Without warnings

· The life alarm signal (Y90) turns ON when any of the control circuit capacitor, main circuit capacitor, cooling fan and inrush current limit circuit reaches the life alarm output level.
· For the terminal used for the Y90 signal, set "90" (positive logic) or "190" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

REMARKS

· The digital output option (FR-A7AY, FR-A7AR, FR-A7NC) allows the control circuit capacitor life signal (Y86), main circuit capacitor life signal (Y87), cooling fan life signal (Y88) and inrush current limit circuit life signal (Y89) to be output individually.

CAUTION

· Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

(2) Life display of the inrush current limit circuit *(Pr. 256)*

· The life of the inrush current limit circuit (relay, contactor and inrush resistor) is displayed in *Pr. 259*.
· The number of contact (relay, contactor, thyristor) ON times is counted, and it is counted down from 100% (0 times) every 1%/10,000 times. As soon as 10% (900,000 times) is reached, *Pr. 255* bit 3 is turned ON and also an alarm is output to the Y90 signal.

(3) Control circuit capacitor life display *(Pr. 257)*

· The deterioration degree of the control circuit capacitor is displayed in *Pr. 257* as a life.
· In the operating status, the control circuit capacitor life is calculated from the energization time and temperature, and is counted down from 100%. As soon as the control circuit capacitor life falls below 10%, *Pr. 255* bit 0 is turned ON and also an alarm is output to the Y90 signal.

(4) Main circuit capacitor life display *(Pr. 258, Pr. 259)*

- The deterioration degree of the main circuit capacitor is displayed in *Pr. 258* as a life.
- On the assumption that the main circuit capacitor capacitance at factory shipment is 100%, the capacitor life is displayed in *Pr. 258* every time measurement is made. When the measured value falls to or below 85%, *Pr. 255* bit 1 is turned ON and also an alarm is output to the Y90 signal.
- Measure the capacitor capacity according to the following procedure and check the deterioration level of the capacitor capacity.
  1) Check that the motor is connected and at a stop.
  2) Set "1" (measuring start) in *Pr. 259*
  3) Switch power OFF. The inverter applies DC voltage to the motor to measure the capacitor capacity while the inverter is OFF.
  4) After making sure that the power lamp is OFF, switch ON the power supply again.
  5) Check that "3" (measuring completion) is set in *Pr. 259*, read *Pr .258*, and check the deterioration degree of the main circuit capacitor.

Pr. 259	Description	Remarks
0	No measurement	Initial value
1	Measurement start	Measurement starts when the power supply is switched OFF.
2	During measurement	Only displayed and cannot be set
3	Measurement complete	
8	Forced end	
9	Measurement error	

REMARKS

- When the main circuit capacitor life is measured under the following conditions, "forced end" (*Pr. 259* = "8") or "measuring error" (*Pr. 259* ="9") occurs or it remains in "measuring start" (*Pr. 259* = "1").
  When measuring, avoid the following conditions beforehand. In addition, even when "measurement completion" (*Pr. 259* = "3") is confirmed under the following conditions, proper measurement cannot be taken.
  (a) The FR-HC, MT-HC, FR-CV, MT-RC or sine wave filter is connected
  (b) Terminals R1/L11, S1/L21 or DC power supply is connected to the terminal P/+ and N/-.
  (c) Switch power ON during measuring.
  (d) The motor is not connected to the inverter.
  (e) The motor is running. (The motor is coasting.)
  (f) The motor capacity is two rank smaller as compared to the inverter capacity.
  (g) The inverter is tripped or a fault occurred while power is OFF.
  (h) The inverter output is shut off with the MRS signal.
  (i) The start command is given while measuring.
- Operating environment: Surrounding air temperature (annual average 40°C (free from corrosive gas, flammable gas, oil mist, dust and dirt))
  Output current (80% of the inverter rated current)

POINT

For the accurate life measuring of the main circuit capacitor, perform after more than 3h passed since the turn OFF of the power as it is affected by the capacitor temperature.

⚠ WARNING

⚠ When measuring the main circuit capacitor capacity (*Pr. 259 Main circuit capacitor life measuring* = "1"), the DC voltage is applied to the motor for 1s at powering OFF. Never touch the motor terminal, etc. right after powering OFF to prevent an electric shock.

(5) Cooling fan life display

- The cooling fan speed of 50% or less is detected and "FN" is displayed on the operation panel (FR-DU07) and parameter unit (FR-PU04/FR-PU07). As an alarm display, *Pr. 255* bit 2 is turned ON and also an alarm is output to the Y90 signal.

REMARKS

- When the inverter is mounted with two or more cooling fans, "FN" is displayed with one or more fans with speed of 50% or less.

CAUTION

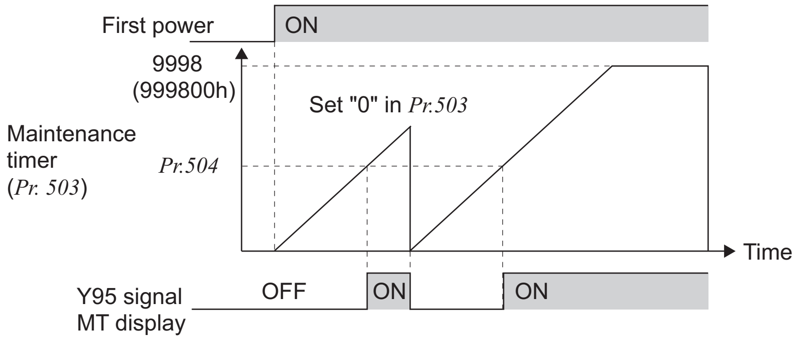
- For replacement of each part, contact the nearest Mitsubishi FA center.

4.22.3 Maintenance timer alarm (Pr. 503, Pr. 504)

When the cumulative energization time of the inverter reaches the parameter set time, the maintenance timer output signal (Y95) is output. MT (MT) is displayed on the operation panel (FR-DU07).
This can be used as a guideline for the maintenance time of peripheral devices.

Parameter Number	Name	Initial Value	Setting Range	Description
503	**Maintenance timer**	0	0 (1 to 9998)	Displays the cumulative energization time of the inverter in 100h increments. Reading only Writing the setting of "0" clears the cumulative energization time.
504	**Maintenance timer alarm output set time**	9999	0 to 9998	Set the time taken until when the maintenance timer alarm output signal (Y95) is output.
			9999	No function

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*



- The cumulative energization time of the inverter is stored into the EEPROM every hour and indicated in *Pr. 503 Maintenance timer* in 100h increments. *Pr. 503* is clamped at 9998 (999800h).
- When the *Pr. 503* value reaches the time set in *Pr. 504 Maintenance timer alarm output set time* (100h increments), the maintenance timer alarm output signal (Y95) is output.
- For the terminal used for the Y95 signal output, assign the function by setting "95" (positive logic) or "195" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

CAUTION

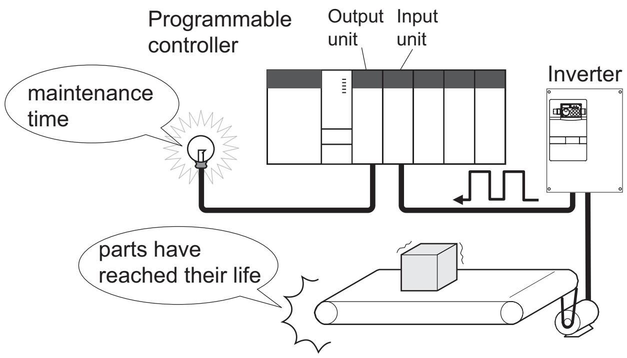
- The cumulative energization time is counted every hour. The energization time of less than 1h is not counted.
- Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 190 to Pr. 196(output terminal function selection) ☞ *Refer to page 140*

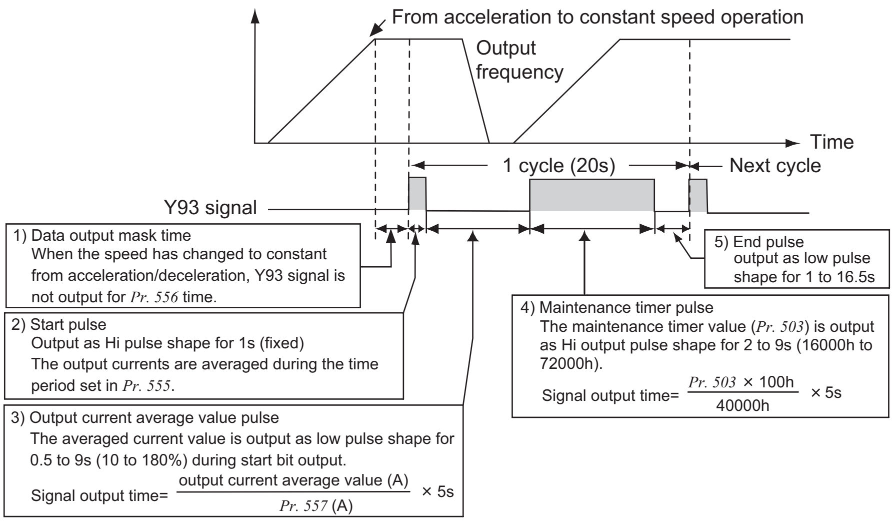
4.22.4 Current average value monitor signal (Pr. 555 to Pr. 557)

The average value of the output current during constant speed operation and the maintenance timer value are output as a pulse to the current average value monitor signal (Y93).
The pulse width output to the I/O module of the programmable controller or the like can be used as a guideline due to abrasion of machines and elongation of belt and for aged deterioration of devices to know the maintenance time.
The current average value monitor signal (Y93) is output as pulse for 20s as 1 cycle and repeatedly output during constant speed operation.



Parameter Number	Name	Initial Value	Setting Range		Description
555	**Current average time**	1s	0.1 to 1.0s		Set the time taken to average the current during start bit output (1s).
556	**Data output mask time**	0s	0.0 to 20.0s		Set the time for not obtaining (mask) transient state data.
557	**Current average value monitor signal output reference current**	Rated inverter current *1	55K or lower	0 to 500A	Set the reference (100%) for outputting the signal of the current average value.
			75K or higher	0 to 3600A	

The above parameters can be set when *Pr. 160 User group read selection*= "0". *(Refer to page 201)*
The above parameters allow their settings to be changed during operation in any operation mode even if "0 (initial value)" is set in *Pr. 77 Parameter write selection*.
*1 Performing IPM parameter initialization changes the settings. *(Refer to page 80)*



· The pulse output of the current average value monitor signal (Y93) is shown above.
· For the terminal used for the Y93 signal output, assign the function by setting "93" (positive logic) or "193" (negative logic) in any of *Pr. 190 to Pr. 194 (output terminal function selection)*. (The function cannot be assigned to *Pr. 195 ABC1 terminal function selection* and *Pr. 196 ABC2 terminal function selection*.)

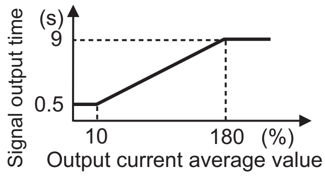
(1) Setting of *Pr. 556 Data output mask time*
The output current is unstable (transient state) right after the operation is changed from the acceleration/deceleration state to the constant speed operation. Set the time for not obtaining (mask) transient state data in *Pr. 556*.

(2) Setting of the *Pr. 555 Current average time*
The average output current is calculated during Hi output of start bit (1s). Set the time taken to average the current during start bit output in *Pr. 555*.

(3) Setting of *Pr. 557 Current average value monitor signal output reference current*
Set the reference (100%) for outputting the signal of the current average value. Obtain the time to output the signal from the following calculation.

$$\frac{\textbf{Output current average value}}{\textit{Pr. 557}\ \textbf{setting}} \times \textbf{5s} \quad \textbf{(output current average value 100\%/5s)}$$

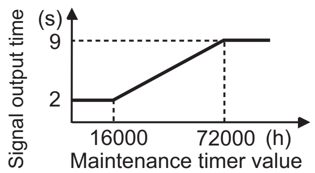
Note that the output time range is 0.5 to 9s, and it is 0.5s when the output current average value is less than 10% of the setting value of *Pr. 557* and 9s when exceeds 180%.
Example)When *Pr. 557* = 10A and the average value of output current is 15A
As 15A/10A × 5s = 7.5, the current average value monitor signal is output as low pulse shape for 7.5s.



(4) Output of *Pr. 503 Maintenance timer*
After the output current average value is output as low pulse shape, the maintenance timer value is output as high pulse shape. The output time of the maintenance timer value is obtained from the following calculation.

$$\frac{\textit{Pr. 503} \times \textbf{100}}{\textbf{40000h}} \times \textbf{5s} \quad \textbf{(maintenance timer value 100\%/5s)}$$

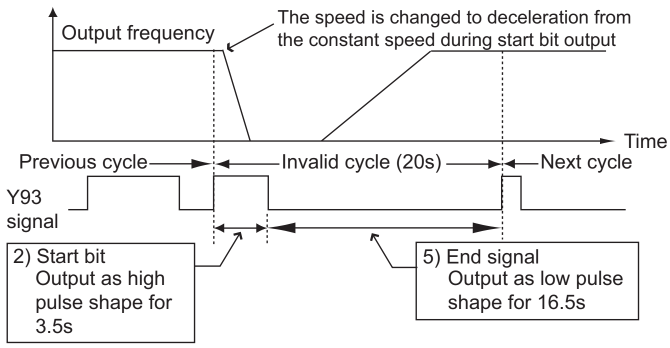
Note that the output time range is 2 to 9s, and it is 2s when *Pr. 503* is less than 16000h and 9s when exceeds 72000h.



REMARKS

· Mask of data output and sampling of output current are not performed during acceleration/deceleration.

· When the speed is changed to acceleration/deceleration from constant speed during start bit output, the data is judged as invalid, the start bit is output as high pulse shape for 3.5s, and the end signal is output as low pulse shape for 16.5s.
The signal is output for at least 1 cycle even when acceleration/deceleration state continues after the start bit output is completed.



· When the output current value (inverter output current monitor) is 0A on completion of the 1 cycle signal output, the signal is not output until the speed becomes constant next time
· The current average value monitor signal (Y93) is output as low pulse shape for 20s (without data output) under the following condition.
(a)When the motor is in the acceleration/deceleration state on completion of the 1 cycle signal output
(b)When 1-cycle signal output was ended during restart operation with the setting of automatic restart after instantaneous power failure (*Pr. 57* ≠ "9999")
(c)When automatic restart operation was being performed with automatic restart after instantaneous power failure selected (*Pr. 57* ≠ "9999") on completion of the data output mask

CAUTION

· Changing the terminal assignment using *Pr. 190 to Pr. 196 (output terminal function selection)* may affect the other functions. Set parameters after confirming the function of each terminal.

♦ Parameters referred to ♦

Pr. 190 to Pr. 196(output terminal function selection) ☞ *Refer to page 140*
Pr. 503 Maintenance timer ☞ *Refer to page 285*
Pr. 57 Restart coasting time ☞ *Refer to page 162*

4.22.5 Free parameter (Pr. 888, Pr. 889)

Parameters you can use for your own purposes.
You can input any number within the setting range 0 to 9999.
For example, the number can be used:
- As a unit number when multiple units are used.
- As a pattern number for each operation application when multiple units are used.
- As the year and month of introduction or inspection.

Parameter Number	Name	Initial Value	Setting Range	Description
888	**Free parameter 1**	9999	0 to 9999	Desired values can be input. Data is held even if the inverter power is turned off.
889	**Free parameter 2**	9999	0 to 9999	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201)*
The above parameters allow their settings to be changed during operation in any operation mode even if "0 (initial value)" is set in *Pr. 77 Parameter write selection*.

REMARKS

Pr. 888 and *Pr. 889* do not influence the inverter operation.

4.22.6 Initiating a fault (Pr.997)

A fault is initiated by setting the parameter.
This function is useful to check how the system operates at a fault.

Parameter number	Name	Initial value	Setting range	Description
997 * Ver.UP	Fault initiation	9999	16 to 18, 32 to 34, 48, 49, 64, 80 to 82, 96, 97, 112, 128, 129, 144, 145, 160, 161, 176 to 179, 192 to 194, 196 to 199, 230, 241, 245 to 247, 253	The setting range is same with the one for fault data codes of the inverter (which can be read through communication). Written data is not stored in EEPROM. When "0" is set, nothing happens.
			9999	The read value is always "9999." This setting does not initiate a fault.

Ver.UP ....Specifications differ according to the date assembled. *Refer to page 378* to check the SERIAL number.
The above parameters can be set when User group read selection="0." *(Refer to page 201)*
* This parameter allows its setting to be changed during operation in any operation mode even if "0 (initial value) or 1" is set in *Pr. 77 Parameter write selection*.

(1) Fault initiation *(Pr. 997)*

- To initiate a fault, set the assigned number of the fault you want to initiate in *Pr. 997 Fault initiation*.
- The value set in *Pr. 997 Fault initiation* is not stored in EEPROM.
- When a fault occurs, the inverter trips, and the fault is displayed and output (ALM, ALM2).
- While the initiated fault is occurring, the fault is displayed as the latest fault in the faults history. After a reset, the faults history goes back to the previous status. (The fault generated by the fault initiation function is not saved in the faults history.)
- Perform inverter reset to cancel the fault.

●Setting for *Pr. 997 Fault initiation* and corresponding faults

Setting (Data code)	Fault
16(H10)	OC1
17(H11)	OC2
18(H12)	OC3
32(H20)	OV1
33(H21)	OV2
34(H22)	OV3
48(H30)	THT
49(H31)	THM
64(H40)	FIN
80(H50)	IPF
81(H51)	UVT
82(H52)	ILF
96(H60)	OLT

Setting (Data code)	Fault
97(H61)	SOT
112(H70)	BE
128(H80)	GF
129(H81)	LF
144(H90)	OHT
145(H91)	PTC
160(HA0)	OPT
161(HA1)	OP1
176(HB0)	PE
177(HB1)	PUE
178(HB2)	RET
179(HB3)	PE2
192(HC0)	CPU

Setting (Data code)	Fault
193(HC1)	CTE
194(HC2)	P24
196(HC4)	CDO
197(HC5)	IOH
198(HC6)	SER
199(HC7)	AIE
230(HE6)	PID
241(HF1)	E.1
245(HF5)	E.5
246(HF6)	E.6
247(HF7)	E.7
253(HFD)	E.13

REMARKS
- If a fault is already occurring in the inverter, a fault cannot be initiated by *Pr. 997*.
- The retry function is invalid for the fault initiated by the fault initiation function.
- If another fault occurs after a fault has been initiated, the fault indication does not change.
  The fault is not saved in the faults history either.

4.22.7 Setting multiple parameters as a batch (Pr.999)

- Parameter settings are changed as a batch. Those include communication parameter settings for the Mitsubishi human machine interface (GOT) connection, rated frequency settings of 50Hz/60Hz, and acceleration/deceleration time increment settings.
- Multiple parameters are changed automatically. Users do not have to consider each parameter number. (Parameter setting mode)

Parameter Number	Name	Initial value	Setting range	Description
999 *	**Automatic parameter setting**	9999	10	GOT initial setting (PU connector)
			11	GOT initial setting (RS485 terminals)
			20	50Hz rated frequency
			21	60Hz rated frequency
			30	Acceleration/deceleration time (0.1s increment)
			31	Acceleration/deceleration time (0.01s increment)
			9999	No action

* This parameter allows its setting to be changed in any operation mode even if "0 (initial value)" is set in *Pr. 77 Parameter write selection*.

(1) Automatic parameter setting *(Pr.999)*

- Select which parameters to be automatically set, and set that to *Pr. 999*. Multiple parameter settings are changed automatically. *Refer to page 293* for the list of parameters that are changed automatically.

Pr.999 setting	Description		Operation in the parameter setting mode
10	Automatically sets the communication parameters for the GOT connection with a PU connector		"AUTO" → "GOT" → Write "1"
11	Automatically sets the communication parameters for the GOT connection with RS-485 terminals		—
20	50Hz rated frequency	Sets the related parameters of the rated frequency according to the power supply frequency	"AUTO" → "F50" → Write "1"
21	60Hz rated frequency		—
30	0.1s increment	Changes the setting increments of acceleration/deceleration time parameters without changing acceleration/deceleration settings	—
31	0.01s increment		"AUTO" → "T0.01" → Write "1"

REMARKS

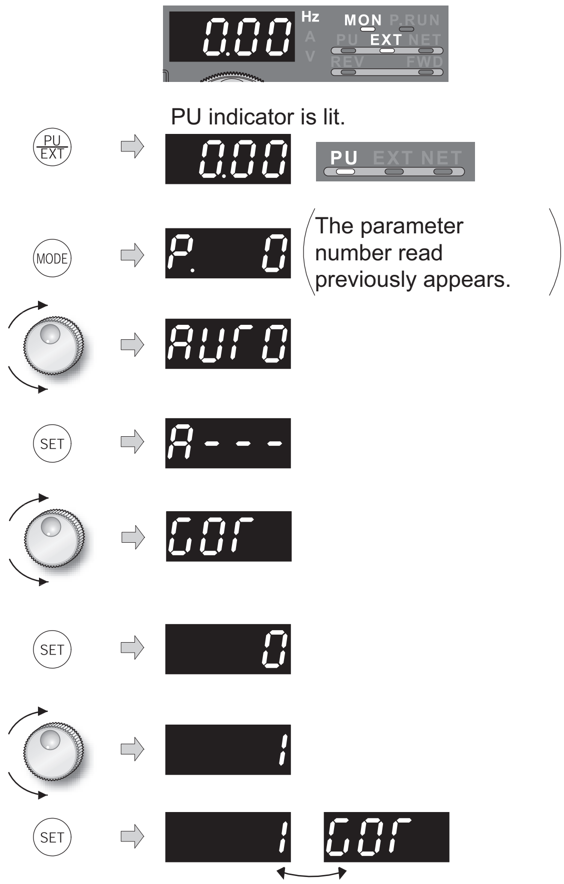
If the automatic setting is performed, the selected settings including the changed parameter settings will be changed.

(2) Automatic parameter setting using the operation panel (parameter setting mode)

Operation example	The communication setting parameters for the GOT connection with a PU connector are automatically set.

Operation — **Display**

1. Screen at power-ON
   The monitor display appears.
2. Press PU/EXT to choose the PU operation mode.
3. Press MODE to choose the parameter setting mode.
4. Turn the dial until AUrO (AUTO) appears.
5. Press SET to enter the automatic parameter setting mode.
6. Turn the dial until GOr (GOT) appears.
7. Press SET to read the present set value.
   "0" appears.
8. Turn the dial to change it to the set value "1".
9. Press SET set.



Flicker··· Parameter setting complete!!

- Turn the dial to read another parameter.
- Press SET to show the setting again.
- Press SET twice to show the next parameter.

Pr.999 setting	Description	Operation in the parameter setting mode
10	GOT initial setting (PU connector)	AUrO (AUTO) → GOr (GOT) → Write "1"
20	50Hz rated frequency	AUrO (AUTO) → F50 (F50) → Write "1"
31	Acceleration/deceleration time (0.01s increment)	AUrO (AUTO) → r0.01 (T0.01) → Write "1"

? 1 ⇄ Er4 are displayed alternately ... Why?

☞ The inverter is not in the PU operation mode.

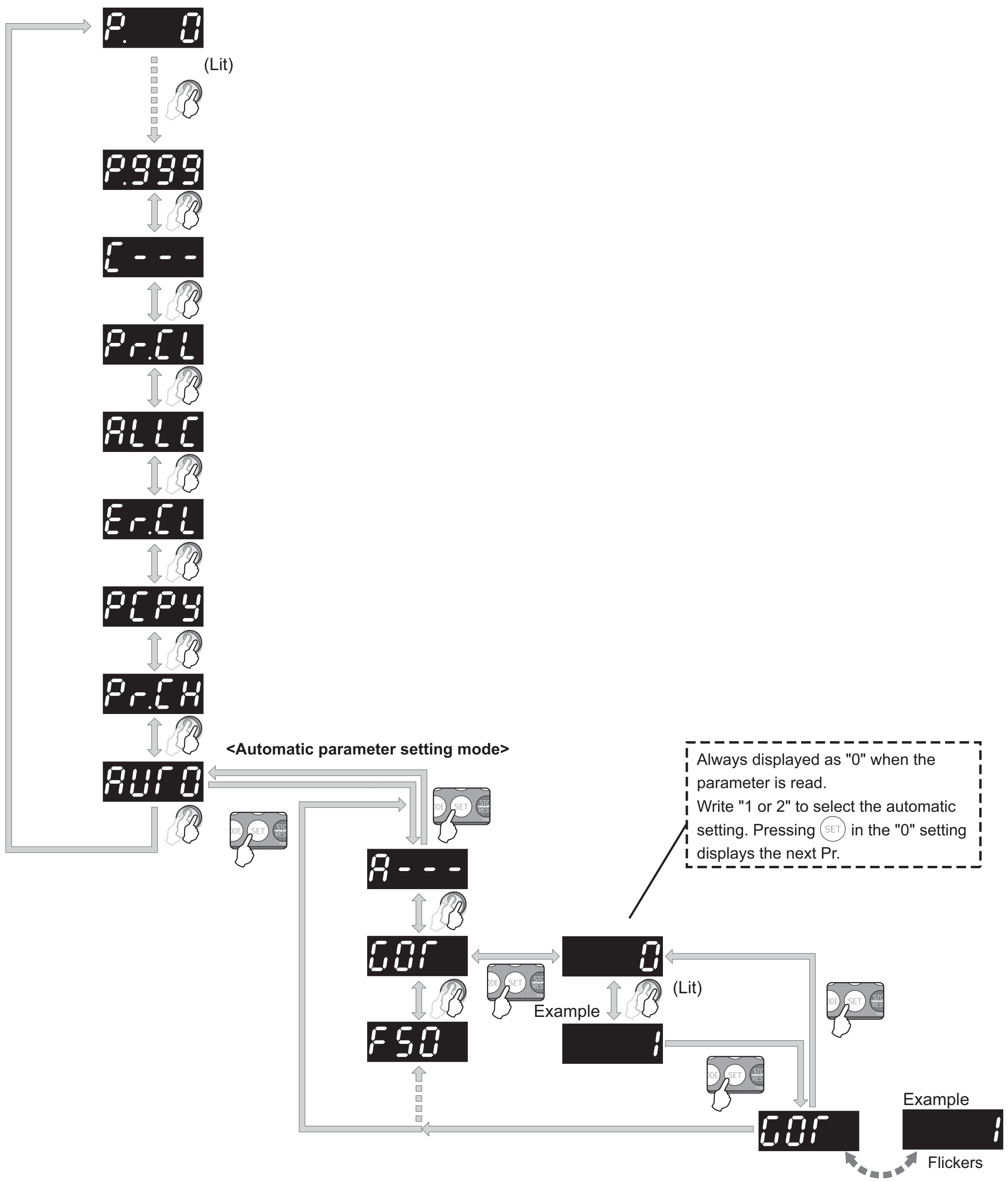
1. Press PU/EXT.

   PU is lit and the monitor (4-digit LED) displays "0." (When *Pr.79*="0 (initial setting)")
2. Carry out operation from step 3 again.

4

PARAMETERS

(3) Parameter setting mode



(4) List of automatically-set parameters

The following tables show which parameters are changed in each of the automatic parameter settings.

CAUTION

- If the automatic setting is performed with *Pr.999* or the parameter setting mode, the listed settings including the changed parameter settings (changed from the initial setting) will be automatically changed. Before performing the automatic setting, confirm that changing the listed parameters will not cause any problem.

- GOT initial setting (PU connector) (*Pr.999* = "10")

Parameter	Name	Initial value	Automatically set to	Refer to page
79	**Operation mode selection**	0	1	*206*
118	**PU communication speed**	192	192	*229*
119	**PU communication stop bit length**	1	10	*229*
120	**PU communication parity check**	2	1	*229*
121	**Number of PU communication retries**	1	9999	*229*
122	**PU communication check time interval**	9999	9999	*229*
123	**PU communication waiting time setting**	9999	0ms	*229*
124	**PU communication CR/LF selection**	1	1	*229*
340	**Communication startup mode selection**	0	0	*218*

REMARKS

Always perform an inverter reset after the initial setting.

- GOT initial setting (RS-485 terminals) (*Pr.999* = "11")

Parameter	Name	Initial value	Automatically set to	Refer to page
79	**Operation mode selection**	0	0	*206*
332	**RS-485 communication speed**	96	192	*229*
333	**RS-485 communication stop bit length**	1	10	*229*
334	**RS-485 communication parity check selection**	2	1	*229*
335	**RS-485 communication retry count**	1	9999	*229*
336	**RS-485 communication check time interval**	0s	9999	*229*
337	**RS-485 communication waiting time setting**	9999	0ms	*229*
340	**Communication startup mode selection**	0	1	*218*
341	**RS-485 communication CR/LF selection**	1	1	*229*
549	**Protocol selection**	0	0	*247*

REMARKS

Always perform an inverter reset after the initial setting.

· Rated frequency (*Pr. 999* = "20(50Hz), 21(60Hz)")

Parameter	Name	Initial value	*Pr.999* = "21"	*Pr.999* = "20" Automatic parameter setting	Refer to page
3	Base frequency	60Hz	60Hz	50Hz	*98*
4	Multi-speed setting (high speed)	60Hz	60Hz	50Hz	*102*
20	Acceleration/deceleration reference frequency	60Hz	60Hz	50Hz	*109*
55	Frequency monitoring reference	60Hz	60Hz	50Hz	*157*
66	Stall prevention operation reduction starting frequency	60Hz	60Hz	50Hz	*91*
125 (903)	Terminal 2 frequency setting gain frequency	60Hz	60Hz	50Hz	*193*
126 (905)	Terminal 4 frequency setting gain frequency	60Hz	60Hz	50Hz	*193*
263	Subtraction starting frequency	60Hz	60Hz	50Hz	*169*
266	Power failure deceleration time switchover frequency	60Hz	60Hz	50Hz	*169*
390*	% setting reference frequency	60Hz	60Hz	50Hz	FR-A7NL manual
505	Speed setting reference	60Hz	60Hz	50Hz	*150*

* This parameter can be set when the option FR-A7NL is mounted.

· Acceleration/deceleration time increment (*Pr.999* ="30(0.1s) or 31(0.01s)")

Parameter	Name	Initial set increment	*Pr.999* = "30"	*Pr.999* = "31" Automatic parameter setting	Refer to page
7	Acceleration time	0.1s	0.1s	0.01s	*109*
8	Deceleration time	0.1s	0.1s	0.01s	*109*
16	Jog acceleration/deceleration time	0.1s	0.1s	0.01s	*104*
21	Acceleration/deceleration time increments	1	0 *	1 *	*109*
44	Second acceleration/ deceleration time	0.1s	0.1s	0.01s	*109*
45	Second deceleration time	0.1s	0.1s	0.01s	*109*
264	Power-failure deceleration time 1	0.1s	0.1s	0.01s	*169*
265	Power-failure deceleration time 2	0.1s	0.1s	0.01s	*169*
791	Acceleration time in low-speed range	0.1s	0.1s	0.01s	*109*
792	Deceleration time in low-speed range	0.1s	0.1s	0.01s	*109*

* The set value is changed for *Pr. 21*.

REMARKS

- When a parameter is set as the acceleration/deceleration time (0.1s), the 0.01s increment is dropped.
- When a parameter is set as the acceleration/deceleration time (0.01s), the parameters are limited at the maximum value of the parameter setting range. For example, *Pr.7* = "361.0s" when 0.1s increment is selected, and *Pr.7* = "360.00s" when 0.01s increment is selected.

4.23 Setting from the parameter unit, operation panel

Purpose	Parameter that must be Set		Refer to Page
Switch the display language of the parameter unit	**PU display language selection**	**Pr. 145**	295
Use the setting dial of the operation panel like a potentiometer for frequency setting. Key lock of operation panel	**Operation panel operation selection**	**Pr. 161**	295
Control of the parameter unit, operation panel buzzer	**PU buzzer control**	**Pr. 990**	298
Adjust the LCD contrast of the parameter unit	**PU contrast adjustment**	**Pr. 991**	298

4.23.1 PU display language selection (Pr. 145)

The display language of the parameter unit (FR-PU04/FR-PU07) can be changed to other languages.

Parameter Number	Name	Initial Value	Setting Range	Definition
145	**PU display language selection**	0	0	Japanese
			1	English
			2	Germany
			3	French
			4	Spanish
			5	Italian
			6	Swedish
			7	Finnish

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*

4.23.2 Setting dial potentiometer mode/key lock selection (Pr. 161)

The setting dial of the operation panel (FR-DU07) can be used like a potentiometer to perform operation.
The key operation of the operation panel can be disabled.

Parameter Number	Name	Initial Value	Setting Range	Description	
161	**Frequency setting/key lock operation selection**	0	0	Setting dial frequency setting mode	Key lock invalid
			1	Setting dial potentiometer mode	
			10	Setting dial frequency setting mode	Key lock valid
			11	Setting dial potentiometer mode	

The above parameters can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*

(1) Setting the frequency with the setting dial

Operation example	Operate at 30Hz.

Operation — Display

1. Screen at power-ON

   The monitor display appears.

2. Operation mode change

   Press (PU/EXT) to choose the PU operation mode.

3. Frequency setting

   Turn the setting dial to show the frequency " 30.00 " (30.00Hz) you want to set. The frequency flickers for about 5s.

4. While the value is flickering, press (SET) to set the frequency.

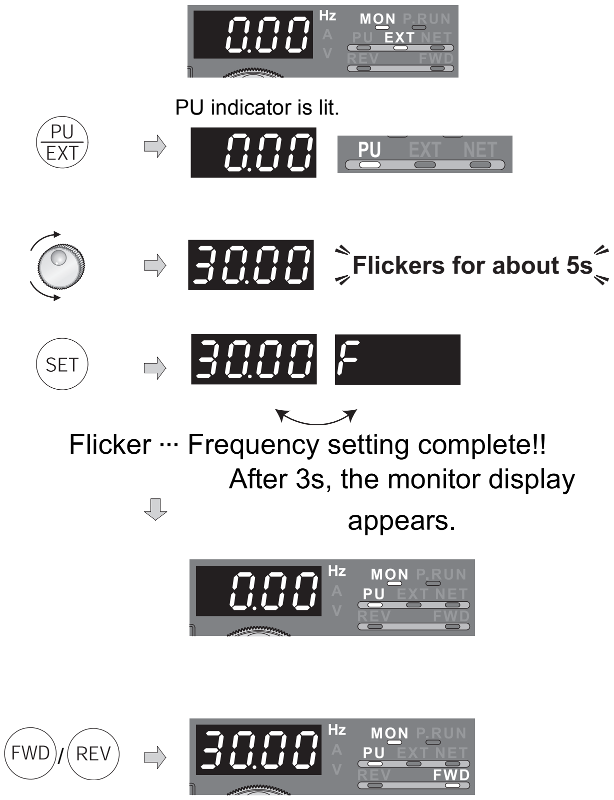
   (If (SET) is not pressed, the indication of the value goes back to " 0.00 " (0.00Hz) after about 5s of flickering. In that case, turn the setting dial again, and set the frequency.)

   After about 3s of flickering, the indication of the value goes back to " 0.00 " (monitor display).

5. Start → acceleration → constant speed

   Press (FWD) or (REV) to start operation.

   The frequency value on the display increases in *Pr. 7 Acceleration time*, and " 30.00 " (30.00Hz) appears.



6. To change the set frequency, perform the operation in above step 3 and 4. (Starting from the previously set frequency.)

7. Deceleration → stop

   Press (STOP/RESET) to stop. The frequency value on the indication decreases in *Pr. 8 Deceleration time*, and the motor stops rotating with " 0.00 "(0.00Hz) displayed.

REMARKS

- If (SET) is not pressed within 5s after the setting dial is turned, the operation may not performed at the set frequency.

(2) Using the setting dial like a potentiometer to set the frequency

Operation example Changing the frequency from 0Hz to 60Hz during operation

Operation	Display
1. Screen at power-ON The monitor display appears.	0.00 Hz MON EXT
2. Operation mode setting Press (PU/EXT) to choose the PU operation mode.	PU indicator is lit. 0.00 PU
3. Press (MODE) to choose the parameter setting mode.	P. 0 The parameter number read previously appears.
4. Turn (dial) until P. 160 (*Pr. 160*) appears.	P. 160
5. Press (SET) to read the present set value. " 9999 " (initial value) appears.	9999
6. Turn (dial) to change it to the setting value of " 0 ".	0
7. Press (SET) to set.	0 ⟷ P. 160 **Flicker ··· Parameter setting complete!!**
8. Change *Pr. 161* to the setting value of " 1 " in the similar manner. (Refer to step 4 to 7.)	1 ⟷ P. 161 **Flicker ··· Parameter setting complete!!**
9. Mode/monitor check Press (MODE) twice to choose monitor/frequency monitor.	0.00 Hz MON PU
10. Start Press (FWD) (or (REV)) to start the inverter.	0.00 Hz MON PU FWD
11. Turn (dial) until "60.00" appears. The flickering frequency is the set frequency. You need not press (SET).	0 → 60.00 The frequency flickers for about 5s.

REMARKS

- If the display changes from flickering "60.00" to "0.00", the setting of *Pr. 161 Frequency setting/key lock operation selection* may not be "1".
- Independently of whether the inverter is running or at a stop, the frequency can be set by simply turning the dial.
- When the frequency is changed, it will be stored in EEPROM as the set frequency after 10s.

CAUTION

- When using the setting dial under general-purpose motor control, the frequency goes up to the set value of *Pr.1 Maximum frequency* (initial value:120Hz (55K or lower)/60Hz (75K or higher). When using the setting dial under IPM motor control, the frequency goes up to the set value of the maximum motor speed (frequency)
  Adjust the setting of *Pr.1 Maximum frequency* according to the application.

(3) Disable the setting dial and key operation of the operation panel (Press [MODE] long (2s))

- Operation using the setting dial and key of the operation panel can be made invalid to prevent parameter change, and unexpected start or frequency setting.
- Set "10 or 11" in *Pr. 161*, then press MODE for 2s to make the setting dial and key operation invalid.
- When the setting dial and key operation are invalid, HOLd appears on the operation panel. If dial or key operation is attempted while dial and key operation are invalid, HOLd appears (When dial or key is not touched for 2s, monitor display appears.)
- To make the setting dial and key operation valid again, press MODE for 2s.

REMARKS

- Even if the setting dial and key operation are disabled, the monitor display STOP/RESET is valid.

4.23.3 Buzzer control (Pr. 990)

You can make the buzzer "beep" when you press key of the operation panel (FR-DU07) and parameter unit (FR-PU04/FR-PU07).

Parameter Number	Name	Initial Value	Setting Range	Description
990	**PU buzzer control**	1	0	Without buzzer
			1	With buzzer

The above parameter can be set when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*
The above parameter allows its setting to be changed during operation in any operation mode even if "0 (initial value)" is set in *Pr. 77 Parameter write selection*.

4.23.4 PU contrast adjustment (Pr. 991)

Contrast adjustment of the LCD of the parameter unit (FR-PU04/FR-PU07) can be performed.
Decreasing the setting value makes contrast light.

Parameter Number	Name	Initial Value	Setting Range	Description
991	**PU contrast adjustment**	58	0 to 63	0 : Light ↓ 63: Dark

The above parameter is displayed as simple mode parameters only when the parameter unit (FR-PU04/FR-PU07) is connected.
The above parameter allows its setting to be changed during operation in any operation mode even if "0 (initial value)" is set in *Pr. 77 Parameter write selection*.
When the operation panel is connected, they can be set only when *Pr. 160 User group read selection* = "0". *(Refer to page 201.)*

4.24 Parameter clear

POINT

· Set "1" in *Pr. CL parameter clear* to initialize parameters. (Parameters are not cleared when "1" is set in *Pr. 77 Parameter write selection*. In addition, calibration parameters are not cleared.)

Operation	Display
1.Screen at power-ON The monitor display appears.	0.00 Hz MON P.RUN PU EXT NET REV FWD
2.Operation mode setting Press (PU/EXT) to choose the PU operation mode.	PU indicator is lit. 0.00 PU EXT NET
3.Press (MODE) to choose the parameter setting mode.	P. 0 The parameter number read previously appears.
4.Turn (dial) until "Pr.CL" (parameter clear) appears.	Pr.CL
5.Press (SET) to read the present set value. "0"(initial value) appears.	0
6.Turn (dial) to change it to the setting value "1".	1
7.Press (SET) to set.	1 ⟷ Pr.CL

Flicker ··· Parameter setting complete!!

· Turn (dial) to read another parameter.

· Press (SET) to show the setting again.

· Press (SET) twice to show the next parameter.

Setting	Description
0	Not executed.
1	Returns all parameters to the initial values except for *calibration parameters, terminal function selection parameters, etc.* Refer to the list of parameters on *page 368* for availability of parameter clear.

? 1 and Er4 are displayed alternately ... Why?

☞ The inverter is not in the PU operation mode.

1. Press (PU/EXT).

   PU is lit and the monitor (4-digit LED) displays "0" (*Pr. 79* = "0" (initial value)).
2. Carry out operation from step 6 again.

4

PARAMETERS

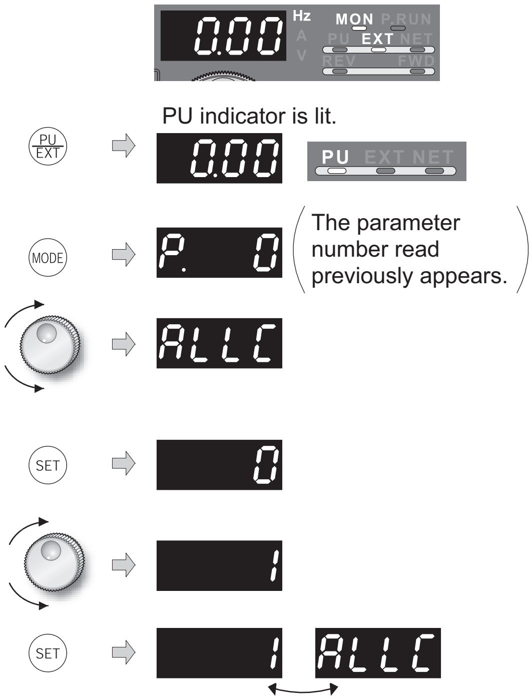
4.25 All parameter clear

POINT

· Set "1" in *ALLC all parameter clear* to initialize all parameters. (Parameters are not cleared when "1" is set in *Pr. 77 Parameter write selection*.)

Operation / **Display**

1. Screen at power-ON
   The monitor display appears.
2. Press (PU/EXT) to choose the PU operation mode.
3. Press (MODE) to choose the parameter setting mode.
4. Turn (dial) until ALLC (all parameter clear) appears.
5. Press (SET) to read the present set value.
   "0"(initial value) appears.
6. Turn (dial) to change it to the setting value "1".
7. Press (SET) to set.



Flicker ··· Parameter setting complete!!

· Press (dial) to read another parameter.

· Press (SET) to show the setting again.

· Press (SET) twice to show the next parameter.

Setting	Description
0	Not executed.
1	All parameters return to the initial values. Refer to the list of parameters on *page 368* for availability of parameter clear.

? 1 and Er4 are displayed alternately ... Why?

☞ The inverter is not in the PU operation mode.

1. Press (PU/EXT).

   PU is lit and the monitor (4-digit LED) displays "0" (*Pr. 79* = "0" (initial value)).
2. Carry out operation from step 6 again.

4.26 Parameter copy and parameter verification

PCPY Setting	Description
0	Cancel
1	Copy the source parameters to the operation panel.
2	Write the parameters copied to the operation panel into the destination inverter.
3	Verify parameters in the inverter and operation panel. *(Refer to page 302.)*

REMARKS

- When the copy destination inverter is not the FR-F700(P) series or parameter copy write is performed after parameter copy read is stopped, "model error (rE4)" is displayed.
- Refer to the parameter list on *page 368* and later for availability of parameter copy.
- When the power is turned OFF or an operation panel is disconnected, etc. during parameter copy write, perform write again or check the values by parameter verification.
- Initial settings of certain parameters are different for different capacities, so some parameter settings may be automatically changed when parameter copy is performed from a different-capacity inverter. After performing a parameter copy from a different-capacity inverter, check the parameter settings. Especially under IPM motor control, check the *Pr.80 Motor capacity* setting before starting the operation. (Refer to the parameter list *(page 64)* for the parameters with different initial settings for different capacities.)

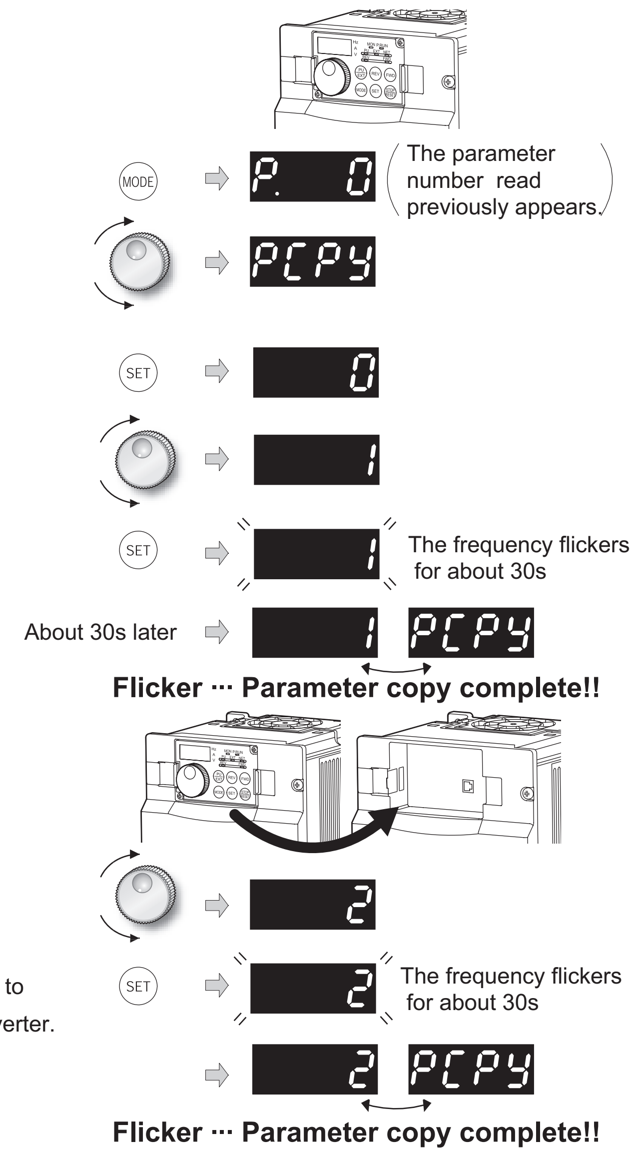
4.26.1 Parameter copy

Parameter settings can be copied to multiple inverters.

Operation

1. Connect the operation panel to the copy source inverter.
   - **Connect it during a stop.**
2. Press (MODE) to choose the parameter setting mode.
3. Turn (dial) until PCPY (parameter copy) appears.
4. Press (SET) to read the present set value. "0" (initial value) appears.
5. Turn (dial) to change it to the setting value "1".
6. Press (SET) to copy the source parameters to the operation panel.
7. Connect the operation panel to the copy source inverter.
8. After performing steps 2 to 5, turn (dial) to change it to "2".
9. Press (SET) to write the parameters copied to the operation panel to the destination inverter.
10. When copy is completed, "2" and "PCPY" flicker.
11. After writing the parameter values to the copy destination inverter, always reset the inverter, e.g. switch power OFF once, before starting operation.

Display



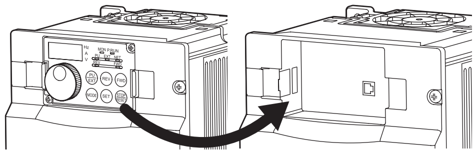
? rE1 appears...Why? ☞ Parameter read error. Perform operation from step 3 again.
? rE2 appears...Why? ☞ Parameter write error. Perform operation from step 8 again.
? CP and 0.00 flicker alternately
☞ Appears when parameters are copied between the inverter of 55K or lower and 75K or higher.
1. Set "0" in *Pr. 160 User group read selection*.
2. Set the following setting (initial value) in *Pr. 989 Parameter copy alarm release*.

	55K or lower	75K or higher
Pr. 989 Setting	10	100

3. Reset *Pr. 9, Pr. 30, Pr. 51, Pr. 52, Pr. 54, Pr. 56, Pr. 57, Pr. 70, Pr. 72, Pr. 80, Pr. 90, Pr. 158, Pr. 190 to Pr. 196, Pr. 557, Pr. 893*.

4.26.2 Parameter verification

Whether same parameter values are set in other inverters or not can be checked.

Operation	Display
1. Move the operation panel to the inverter to be verified. • **Move it during a stop.**	
2. Screen at power-ON The monitor display appears.	0.00 Hz MON EXT
3. Operation mode setting Press (PU/EXT) to choose the PU operation mode.	(PU/EXT) ⇨ 0.00 PU PU indicator is lit.
4. Press (MODE) to choose the parameter setting mode.	(MODE) ⇨ P. 0 The parameter number read previously appears.
5. Turn ◎ until PCPY (parameter copy) appears.	⇨ PCPY
6. Press (SET) to read the present set value. "0"(initial value) appears.	(SET) ⇨ 0
7. Turn ◎ to change it to the set value "3"(parameter copy verification mode).	⇨ 3
8. Press (SET) to read the parameter setting of the verified inverter to the operation panel.	(SET) ⇨ 3 The frequency flickers for about 30s
• If different parameters exist, different parameter numbers and rE3 flicker.	P 1 ⟷ rE3
• Hold down (SET) to verify.	(SET) ⇨ 3 Flickering
9. If there is no difference, PCPY and 3 flicker to complete verification.	3 ⟷ PCPY

Flicker ··· Parameter verification complete!!

? rE3 flickers ... Why?
☞ Set frequencies, etc. may be different. Check set frequencies.

4.27 Initial value change list

Displays and sets the parameters changed from the initial value.

Operation / **Display**

1. Screen at power-ON
   The monitor display appears.
   Display: 0.00 (Hz, MON, EXT)

2. Operation mode setting
   Press [PU/EXT] to choose the PU operation mode.
   PU indicator is lit.
   Display: 0.00 (PU)

3. Press [MODE] to choose the parameter setting mode.
   PRM indicator is lit.
   Display: P. 0
   (The parameter number read previously appears.)

4. Turn the dial until Pr.CH appears.
   Display: Pr.CH

5. Pressing [SET] changes to the initial value change list screen.
   Display: P.---

6. Turning the dial displays the parameter number changed.
   Display: P. 7

   - Press [SET] to read the present set value.
     Display: 3.0
   - Turn the dial and press [SET] to change the setting
     (refer to step 6 and 7 *on page 63)*
     Display: 4.0 ⇄ P. 7
     Flicker ··· Frequency setting complete!!
   - Turn the dial to read another parameter.
     Display: P. 11
   - The display returns to P.--- after all parameters are displayed.
     Display: P.---

7. Pressing [SET] in P.--- status returns to the parameter setting mode.
   Display: Pr.CH
   - Turning the dial sets other parameters.
   - Pressing [SET] displays the change list again.

REMARKS

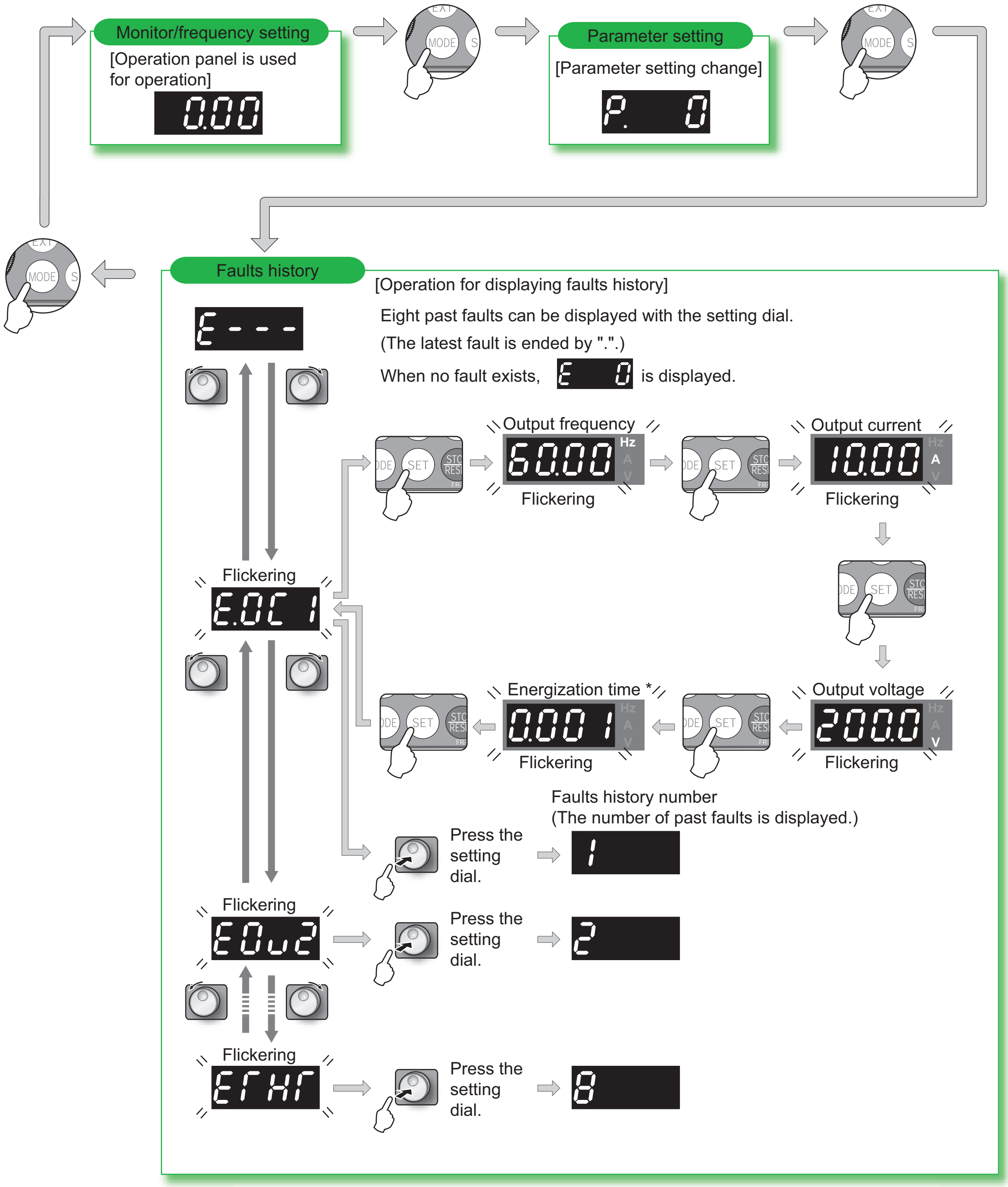
- Calibration parameters *(C0 (Pr. 900) to C7 (Pr. 905), C42 (Pr. 934) to C45 (Pr. 935))* are not displayed even they are changed from the initial settings.
- Only simple mode parameter is displayed when simple mode is set (*Pr. 160* = 9999 (initial value))
- Only user group is displayed when user group is set (*Pr. 160* = "1").
- *Pr. 160* is displayed independently of whether the setting value is changed or not.

♦Parameters referred to♦

Pr.160 User group read selection ☞ *Refer to page 201*
C0(Pr.900) FM terminal calibration ☞ *Refer to page 159*
C2(Pr.902) to 7(Pr.905) (Frequency setting bias/gain parameter) ☞ *Refer to page 193*

4.28 Check and clear of the faults history

(1) Check for the faults history



* The cumulative energization time and actual operation time are accumulated from 0 to 65535 hours, then cleared, and accumulated again from 0. When the operation panel (FR-DU07) is used, the time is displayed up to 65.53 (65530h) in the indication of 1h = 0.001, and thereafter, it is added up from 0.

(2) Clearing procedure

POINT

· The faults history can be cleared by setting "1" in *Er.CL Faults history clear*.

Operation — Display

1.Screen at power-ON
The monitor display appears.

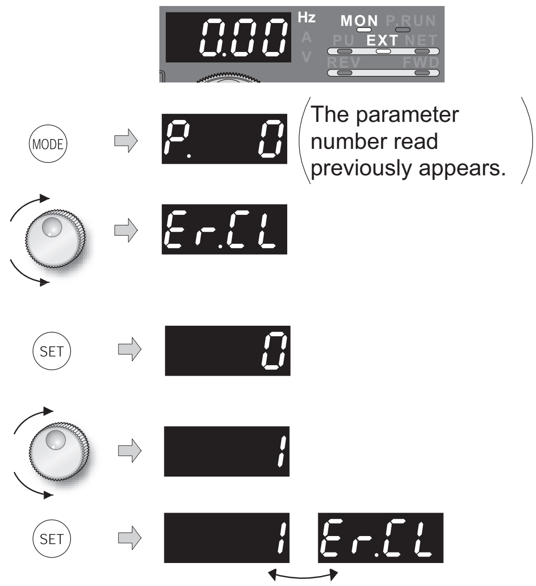
2.Press MODE to choose the parameter setting mode.

3.Turn until Er.CL (faults history clear) appears.

4.Press SET to read the present set value.
"0"(initial value) appears.

5.Turn to change it to the setting value "1".

6.Press SET to set.



Flicker ··· Faults history clear complete!!

· Press to read another parameter.

· Press SET to show the setting again.

· Press SET twice to show the next parameter.

4

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MEMO

5 PROTECTIVE FUNCTIONS

This chapter describes the basic "PROTECTIVE FUNCTION" for use of this product.
Always read the instructions before using the equipment.

When a fault occurs in the inverter, the inverter trips and the PU display automatically changes to one of the following fault or alarm indications.
If the fault does not correspond to any of the following faults or if you have any other problem, please contact your sales representative or distributor.

- Retention of fault output signal .... When the magnetic contactor (MC) provided on the input side of the inverter is opened when a fault occurs, the inverter's control power will be lost and the fault output will not be held.
- Fault or alarm indication .... When a fault or alarm occurs, the operation panel display automatically switches to the fault or alarm indication
- Resetting method .... When a fault occurs, the inverter output is kept stopped. Unless reset, therefore, the inverter cannot restart. *(Refer to page 308.)*
- When any fault occurs, take the appropriate corrective action, then reset the inverter, and resume operation. Not doing so may lead to the inverter fault and damage.

Inverter fault or alarm indications are roughly categorized as below.

(1) Error message
A message regarding operational fault and setting fault by the operation panel (FR-DU07) and parameter unit (FR-PU04/FR-PU07) is displayed. The inverter does not trip.

(2) Warning
The inverter does not trip even when a warning is displayed. However, failure to take appropriate measures will lead to a fault.

(3) Alarm
The inverter does not trip. You can also output an alarm signal by making parameter setting.

(4) Fault
When a fault occurs, the inverter trips and a fault signal is output.

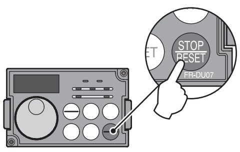
REMARKS

· Past eight faults can be displayed using the setting dial. (*Refer to page 304* for the operation.)

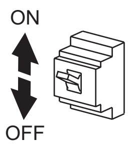
5.1 Reset method of protective function

The inverter can be reset by performing any of the following operations. Note that the internal thermal integrated value of the electronic thermal relay function and the number of retries are cleared (erased) by resetting the inverter.
Inverter recovers about 1s after the reset is released.

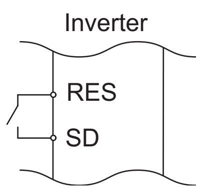
Operation 1:...... Using the operation panel, press STOP RESET to reset the inverter.
(This may only be performed when a fault occurs. (Refer to *page 314* for fault.))



Operation 2:...... Switch power OFF once. After the indicator of the operation panel turns OFF, switch it ON again.



Operation 3:...... Turn ON the reset signal (RES) for more than 0.1s. (If the RES signal is kept ON, "Err." appears (flickers) to indicate that the inverter is in a reset status.)



CAUTION

· OFF status of the start signal must be confirmed before resetting the inverter fault. Resetting inverter fault with the start signal ON restarts the motor suddenly.

5.2 List of fault or alarm display

	Operation Panel Indication		Name	Fault data code	Refer to page
Error message	E---	E---	Faults history	—	304
	HOLd	HOLD	Operation panel lock	—	310
	LOCd	LOCd	Password locked	—	310
	Er1 to Er4	Er1 to 4	Parameter write error	—	310
	rE1 to rE4	rE1 to 4	Copy operation error	—	311
	Err.	Err.	Error	—	311
Warning	OL	OL	Stall prevention (overcurrent)	—	312
	oL	oL	Stall prevention (overvoltage)	—	312
	rb	RB	Regenerative brake prealarm	—	313
	TH	TH	Electronic thermal relay function prealarm	—	313
	PS	PS	PU stop	—	312
	MT	MT	Maintenance signal output	—	313
	CP	CP	Parameter copy	—	313
Alarm	Fn	FN	Fan alarm	—	313
Fault	E.OC1	E.OC1	Overcurrent trip during acceleration	16 (H10)	314
	E.OC2	E.OC2	Overcurrent trip during constant speed	17 (H11)	314
	E.OC3	E.OC3	Overcurrent trip during deceleration or stop	18 (H12)	315
	E.Ou1	E.OV1	Regenerative overvoltage trip during acceleration	32 (H20)	315
	E.Ou2	E.OV2	Regenerative overvoltage trip during constant speed	33 (H21)	315
	E.Ou3	E.OV3	Regenerative overvoltage trip during deceleration or stop	34 (H22)	315
	E.THT	E.THT	Inverter overload trip (electronic thermal relay function)	48 (H30)	316
	E.THM	E.THM	Motor overload trip (electronic thermal relay function)	49 (H31)	316
	E.FIn	E.FIN	Heatsink overheat	64 (H40)	316
	E.IPF	E.IPF	Instantaneous power failure	80 (H50)	316
	E. bE	E.BE	Brake transistor alarm detection/internal circuit fault	112 (H70)	317
	E.UuT	E.UVT	Undervoltage	81 (H51)	317
	E.ILF	E.ILF*	Input phase loss	82 (H52)	317
	E.OLT	E.OLT	Stall prevention stop	96 (H60)	317
Fault	E.SOT	E.SOT* IPM	Loss of synchronism detection	97 (H61)	317
	E. GF	E.GF	Output side earth (ground) fault overcurrent	128 (H80)	318
	E. LF	E.LF	Output phase loss	129 (H81)	318
	E.OHT	E.OHT	External thermal relay operation *2	144 (H90)	318
	E.PTC	E.PTC*	PTC thermistor operation	145 (H91)	318
	E.OPT	E.OPT	Option fault	160 (HA0)	318
	E.OP1	E.OP1	Communication option fault	161 (HA1)	319
	E. 1	E. 1	Option fault	241 (HF1)	319
	E. PE	E.PE	Parameter storage device fault	176 (HB0)	319
	E.PUE	E.PUE	PU disconnection	177 (HB1)	319
	E.rET	E.RET	Retry count excess	178 (HB2)	319
	E.PE2	E.PE2*	Parameter storage device fault	179 (HB3)	319
	E. 5	E. 5	CPU fault	245 (HF5)	320
	E. 6	E. 6		246 (HF6)	
	E. 7	E. 7		247 (HF7)	
	E.CPU	E.CPU		192 (HC0)	
	E.CTE	E.CTE	Operation panel power supply short circuit, RS-485 terminal power supply short circuit	193 (HC1)	320
	E.P24	E.P24	24VDC power output short circuit	194 (HC2)	320
	E.CdO	E.CDO*	Output current detection value exceeded	196 (HC4)	320
	E.IOH	E.IOH*	Inrush current limit circuit fault	197 (HC5)	320
	E.SEr	E.SER*	Communication fault (inverter)	198 (HC6)	321
	E.AIE	E.AIE*	Analog input fault	199 (HC7)	321
	E.PId	E.PID*	PID signal fault	230 (HE6)	321
	E. 13	E.13	Internal circuit fault	253 (HFD)	321

* If an error occurs when using FR-PU04/FR-PU07, "Fault 14" is displayed on FR-PU04/FR-PU07.

5.3 Causes and corrective actions

(1) Error Message

A message regarding operational troubles is displayed. Output is not shut off.

Operation Panel Indication	**HOLD**	HOLd
Name	Operation panel lock	
Description	Operation lock mode is set. Operation other than STOP RESET is invalid. *(Refer to page 298.)*	
Check point	——	
Corrective action	Press MODE for 2s to release lock.	

Operation panel indication	**LOCd**	LOCd
Name	Password locked	
Description	Password function is active. Display and setting of parameter is restricted.	
Check point	——	
Corrective action	Enter the password in *Pr. 297 Password lock/unlock* to unlock the password function before operating. *(Refer to page 203).*	

Operation Panel Indication	**Er1**	Er 1
Name	Write disable error	
Description	· You attempted to make parameter setting when *Pr. 77 Parameter write selection* has been set to disable parameter writing. · Frequency jump setting range overlapped. · Adjustable 5 points V/F settings overlapped. · The PU and inverter cannot make normal communication. · Appears if IPM parameter initialization is attempted in the parameter setting mode while *Pr.72* = "25."	
Check point	· Check the setting of *Pr. 77 Parameter write selection (Refer to page 200.)* · Check the settings of *Pr. 31 to 36 (frequency jump). (Refer to page 97.)* · Check the settings of *Pr. 100 to Pr. 109 (Adjustable 5 points V/F). (Refer to page 101.)* · Check the connection of the PU and inverter. · Check the *Pr.72 PWM frequency selection* setting. A sine wave filter cannot be used under IPM motor control.	

Operation Panel Indication	**Er2**	Er 2
Name	Write error during operation	
Description	When parameter writing was performed during operation with a value other than "2" (writing is enabled independently of operating status in any operation mode) is set in *Pr. 77* and the STF (STR) is ON.	
Check point	· Check the *Pr. 77* setting. *(Refer to page 200.)* · Check that the inverter is not operating.	
Corrective action	· Set "2" in *Pr. 77*. · After stopping the operation, make parameter setting.	

Operation Panel Indication	**Er3**	Er 3
Name	Calibration error	
Description	Analog input bias and gain calibration values are too close.	
Check point	Check the settings of C3, C4, C6 and C7 (calibration functions). *(Refer to page 193.)*	

Operation Panel Indication	Er4	E r - 4
Name	Mode designation error	
Description	· You attempted to make parameter setting in the NET operation mode when *Pr. 77* is not "2". · If a parameter write was performed when the command source is not at the operation panel (FR-DU07).	
Check point	· Check that operation mode is "PU operation mode". · Check the *Pr. 77* setting. *(Refer to page 200.)* · Check the *Pr. 551* setting.	
Corrective action	· After setting the operation mode to the "PU operation mode", make parameter setting. *(Refer to page 200.)* · After setting "2" in *Pr. 77*, make parameter setting. · Set *Pr.551* = "2 (initial setting)". *(Refer to page 219.)*	

Operation Panel Indication	rE1	r E 1
Name	Parameter read error	
Description	An error occurred in the EEPROM on the operation panel side during parameter copy reading.	
Check point	—	
Corrective action	· Make parameter copy again. *(Refer to page 301.)* · Check for an operation panel (FR-DU07) failure. Please contact your sales representative.	

Operation Panel Indication	rE2	r E 2
Name	Parameter write error	
Description	· You attempted to perform parameter copy write during operation. · An error occurred in the EEPROM on the operation panel side during parameter copy writing.	
Check point	Is the FWD or REV LED of the operation panel (FR-DU07) lit or flickering?	
Corrective action	· After stopping the operation, make parameter copy again. *(Refer to page 301.)* · Check for an operation panel (FR-DU07) failure. Please contact your sales representative.	

Operation Panel Indication	rE3	r E 3
Name	Parameter verification error	
Description	· Data on the operation panel side and inverter side are different. · An error occurred in the EEPROM on the operation panel side during parameter verification.	
Check point	Check for the parameter setting of the source inverter and inverter to be verified.	
Corrective action	· Press SET to continue verification. Make parameter verification again. *(Refer to page 302.)* · Check for an operation panel (FR-DU07) failure. Please contact your sales representative.	

Operation Panel Indication	rE4	r E 4
Name	Model error	
Description	· A different model was used for parameter writing and verification during parameter copy. · When parameter copy write is stopped after parameter copy read is stopped.	
Check point	· Check that the verified inverter is the same model. · Check that the power is not turned OFF or an operation panel is not disconnected, etc. during parameter copy read.	
Corrective action	· Use the same model (FR-F700(P) series) for parameter copy and verification. · Perform parameter copy read again.	

Operation Panel Indication	Err.	E r r.
Description	· The RES signal is ON. · The PU and inverter cannot make normal communication (contact fault of the connector). · When the voltage drops in the inverter's input side. · While the control circuit power (R1/L11, S1/L21) and the main circuit power (R/L1, S/L2, T/L3) are connected to separate power sources, the error may appear when turning ON the main circuit. This is not a fault though.	
Corrective action	· Turn OFF the RES signal. · Check the connection of PU and the inverter. · Check the voltage on the inverter's input side.	

PROTECTIVE FUNCTIONS

5

(2) Warning

When the protective function is activated, the output is not shut off.

<table>
<tr><th>Operation Panel Indication</th><th>OL</th><th>OL</th><th>FR-PU04
FR-PU07</th><th>OL</th></tr>
<tr><td>Name</td><td colspan="4">Stall prevention (overcurrent)</td></tr>
<tr><td rowspan="3">Description</td><td>During acceleration</td><td colspan="3">When the output current of the inverter exceeds the stall prevention operation level (Pr. 22 Stall prevention operation level, etc.), this function stops the increase in frequency until the overload current decreases to prevent the inverter from resulting in overcurrent trip. When the overload current has decreased below stall prevention operation level, this function increases the frequency again.</td></tr>
<tr><td>During constant speed operation</td><td colspan="3">When the output current of the inverter exceeds the stall prevention operation level (Pr. 22 Stall prevention operation level, etc.), this function lowers the frequency until the overload current decreases to prevent overcurrent trip. When the overload current has decreased below stall prevention operation level, this function increases the frequency up to the set value.</td></tr>
<tr><td>During deceleration</td><td colspan="3">When the output current of the inverter exceeds the stall prevention operation level (Pr. 22 Stall prevention operation level, etc.), this function stops the decrease in frequency until the overload current decreases to prevent the inverter from resulting in overcurrent trip. When the overload current has decreased below stall prevention operation level, this function decreases the frequency again.</td></tr>
<tr><td>Check point</td><td colspan="4">· Check that the Pr. 0 Torque boost setting is not too large.(V/F control)
· Check that the Pr. 7 Acceleration time and Pr. 8 Deceleration time settings are not too small.
· Check that the load is not too heavy.
· Are there any failure in peripheral devices?
· Check that the Pr. 13 Starting frequency is not too large.(V/F control, Simple magnetic flux vector control)
· Check that the Pr. 22 Stall prevention operation level is appropriate.
· Check if the operation was performed without connecting a motor under IPM motor control.</td></tr>
<tr><td>Corrective action</td><td colspan="4">· Increase or decrease the Pr. 0 Torque boost value by 1% and check the motor status. (V/F control) (Refer to page 87.)
· Set a larger value in Pr. 7 Acceleration time and Pr. 8 Deceleration time. (Refer to page 109.)
· Reduce the load weight. Try Simple magnetic flux vector control (Pr. 80).
· Check the peripheral devices
· Adjust the Pr.13 setting. Change the Pr. 14 Load pattern selection setting. (V/F control)
· Set stall prevention operation current in Pr. 22 Stall prevention operation level. (The initial value is 120%.) The acceleration/deceleration time may change. Increase the stall prevention operation level with Pr. 22 Stall prevention operation level, or disable stall prevention with Pr. 156 Stall prevention operation selection. (Use Pr. 156 to set either operation continued or not at OL operation.)
· Check the connection of the IPM motor.</td></tr>
</table>

<table>
<tr><th>Operation Panel Indication</th><th>oL</th><th>oL</th><th>FR-PU04
FR-PU07</th><th>oL</th></tr>
<tr><td>Name</td><td colspan="4">Stall prevention (overcurrent)</td></tr>
<tr><td>Description</td><td>During deceleration</td><td colspan="3">· If the regenerative energy of the motor becomes excessive and exceeds the regenerative energy consumption capability, this function stops the decrease in frequency to prevent overvoltage trip. As soon as the regenerative energy has decreased, deceleration resumes.
· If the regenerative energy of the motor becomes excessive when regeneration avoidance function is selected (Pr. 882 = 1), this function increases the speed to prevent overvoltage trip. (Refer to page 200.)</td></tr>
<tr><td>Check point</td><td colspan="4">· Check for sudden speed reduction.
· Regeneration avoidance function (Pr. 882 to Pr. 886) is being used? (Refer to page 279.)</td></tr>
<tr><td>Corrective action</td><td colspan="4">The deceleration time may change.
Increase the deceleration time using Pr. 8 Deceleration time.</td></tr>
</table>

<table>
<tr><th>Operation Panel Indication</th><th>PS</th><th>PS</th><th>FR-PU04
FR-PU07</th><th>PS</th></tr>
<tr><td>Name</td><td colspan="4">PU stop</td></tr>
<tr><td>Description</td><td colspan="4">Stop with STOP RESET of PU is set in Pr. 75 Reset selection/disconnected PU detection/PU stop selection. (For Pr. 75, refer to page 198.)</td></tr>
<tr><td>Check point</td><td colspan="4">Check for a stop made by pressing STOP RESET of the operation panel.</td></tr>
<tr><td>Corrective action</td><td colspan="4">Turn the start signal OFF and release with PU EXT.</td></tr>
</table>

Operation Panel Indication	RB		FR-PU04 FR-PU07	RB
Name	Regenerative brake prealarm			
Description	Appears if the regenerative brake duty reaches or exceeds 85% of the *Pr. 70 Special regenerative brake duty* value. When the setting of *Pr. 70 Special regenerative brake duty* is the initial value (*Pr. 70* ="0"), this warning does not occur. If the regenerative brake duty reaches 100%, a regenerative overvoltage (E. OV_) occurs. The RBP signal can be simultaneously output with the [RB] display. For the terminal used for the RBP signal output, assign the function by setting "7" (positive logic) or "107" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*. *(Refer to page 140)* Appears only for the 75K or higher.			
Check point	• Check that the brake resistor duty is not high. • Check that the *Pr. 30 Regenerative function selection* and *Pr. 70 Special regenerative brake duty* values are correct.			
Corrective action	• Increase the deceleration time. • Check the *Pr. 30 Regenerative function selection* and *Pr. 70 Special regenerative brake duty* values.			

Operation Panel Indication	TH		FR-PU04 FR-PU07	TH
Name	Electronic thermal relay function prealarm			
Description	Appears if the cumulative value of the *Pr. 9 Electronic thermal O/L relay* reaches or exceeds 85% of the preset level. If it reaches 100% of the *Pr. 9 Electronic thermal O/L relay* setting, a motor overload trip (E. THM) occurs. The THP signal can be simultaneously output with the [TH] display. For the terminal used for the THP signal output, assign the function by setting "8" (positive logic) or "108" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*. *(Refer to page 140)*			
Check point	· Check for large load or sudden acceleration. · Is the *Pr. 9 Electronic thermal O/L relay* setting is appropriate? *(Refer to page 117.)*			
Corrective action	· Reduce the load weight or the number of operation times. · Set an appropriate value in *Pr. 9 Electronic thermal O/L relay*. *(Refer to page 117.)*			

Operation Panel Indication	MT		FR-PU04 FR-PU07	——— MT
Name	Maintenance signal output			
Description	Indicates that the cumulative energization time of the inverter has reached a given time. When the setting of *Pr. 504 Maintenance timer alarm output set time* is the initial value (*Pr. 504* = "9999"), this protective function does not function.			
Check point	The *Pr. 503 Maintenance timer* setting is larger than the *Pr. 504 Maintenance timer alarm output set time* setting. *(Refer to page 285.)*			
Corrective action	Setting "0" in *Pr. 503 Maintenance timer* erases the signal.			

Operation Panel Indication	CP		FR-PU04 FR-PU07	——— CP
Name	Parameter copy			
Description	Appears when parameters are copied between models with capacities of 55K or lower and 75K or higher.			
Check point	Resetting of *Pr.9, Pr.30, Pr.51, Pr.52, Pr.54, Pr.56, Pr.57, Pr.70, Pr.72, Pr.80, Pr.90, Pr.158, Pr.190 to Pr.196, Pr.557* and *Pr.893* is necessary.			
Corrective action	Set the initial value in *Pr. 989 Parameter copy alarm release*.			

(3) Alarm

When an alarm occurs, the output is not shut off. You can also output an alarm signal by making parameter setting. (Set "98" in any of *Pr. 190 to Pr. 196 (output terminal function selection)*. *(Refer to page 140.)*

Operation Panel Indication	FN		FR-PU04 FR-PU07	FN
Name	Fan alarm			
Description	For the inverter that contains a cooling fan, FN appears on the operation panel when the cooling fan stops due to a fault or different operation from the setting of *Pr. 244 Cooling fan operation selection*.			
Check point	Check the cooling fan for an alarm.			
Corrective action	Check for fan failure. Please contact your sales representative.			

(4) Fault

When a fault occurs, the inverter trips and a fault signal is output.

Operation Panel Indication	E.OC1	E.OC 1	FR-PU04 FR-PU07	OC During Acc
Name	Overcurrent trip during acceleration			
Description	When the inverter output current reaches or exceeds approximately 170% of the rated current during acceleration, the protective circuit is activated to stop the inverter output.			
Check point	· Check for sudden acceleration. · Check that the downward acceleration time is not long in vertical lift application. · Check for output short circuit. · Check that the *Pr. 3 Base frequency* setting is not 60Hz when the motor rated frequency is 50Hz.(V/F control, Simple magnetic flux vector control) · Check if the stall prevention operation level is set too high. · Check if the fast-response current limit operation is disabled. (V/F control, Simple magnetic flux vector control) · Check that the regeneration is not performed frequently. (Check that the output voltage becomes larger than the V/F reference voltage at regeneration and overcurrent occurs due to the high voltage.) (V/F control, Simple magnetic flux vector control) · Check that the inverter capacity matches with the motor capacity. (IPM motor control) · Check if a start command is given to the inverter while the motor is coasting.			
Corrective action	· Increase the acceleration time. (Shorten the downward acceleration time in vertical lift application.) · When "E.OC1" is always lit at starting, disconnect the motor once and start the inverter. If "E.OC1" is still lit, contact your sales representative. · Check the wiring to make sure that output short circuit does not occur. · Set the *Pr. 3 Base frequency* to 50Hz. (V/F control, Simple magnetic flux vector control) *(Refer to page 98.)* · Lower the setting of stall prevention operation level. *(Refer to page 91.)* · Activate the fast-response current limit operation. (V/F control, Simple magnetic flux vector control) · Set base voltage (rated voltage of the motor, etc.) in *Pr. 19 Base frequency voltage*.(V/F control, Simple magnetic flux vector control) *(Refer to page 98.)* · Choose inverter and motor capacities that match. (IPM motor control) · Input a start command after the motor stops. Alternatively, set the automatic restart after instantaneous power failure/flying start function. *(Refer to page 162.)*			

Operation Panel Indication	E.OC2	E.OC 2	FR-PU04 FR-PU07	Stedy Spd OC
Name	Overcurrent trip during constant speed			
Description	When the inverter output current reaches or exceeds approximately 170% of the rated current during constant speed operation, the protective circuit is activated to stop the inverter output.			
Check point	· Check for sudden load change. · Check for output short circuit. · Check if the stall prevention operation level is set too high · Check if the fast-response current limit operation is disabled. (V/F control, Simple magnetic flux vector control) · Check that the inverter capacity matches with the motor capacity. (IPM motor control) · Check if a start command is given to the inverter while the motor is coasting.			
Corrective action	· Keep load stable. · Check the wiring to avoid output short circuit. · Lower the setting of stall prevention operation level *(Refer to page 91.)* · Activate the fast-response current limit operation. (V/F control, Simple magnetic flux vector control) · Choose inverter and motor capacities that match. (IPM motor control) · Input a start command after the motor stops. Alternatively, set the automatic restart after instantaneous power failure/flying start function. *(Refer to page 162.)*			

Operation Panel Indication	E.OC3	E.OC 3	FR-PU04 FR-PU07	OC During Dec
Name	Overcurrent trip during deceleration or stop			
Description	When the inverter output current reaches or exceeds approximately 170% of the rated inverter current during deceleration (other than acceleration or constant speed), the protective circuit is activated to stop the inverter output.			
Check point	· Check for sudden speed reduction. · Check for output short circuit. · Check for too fast operation of the motor's mechanical brake. · Check if the stall prevention operation level is set too high · Check if the fast-response current limit operation is disabled. (V/F control, Simple magnetic flux vector control) · Check that the inverter capacity matches with the motor capacity. (IPM motor control) · Check if a start command is given to the inverter while the motor is coasting.			
Corrective action	· Increase the deceleration time. · Check the wiring to avoid output short circuit. · Check the mechanical brake operation. · Lower the setting of stall prevention operation level *(Refer to page 91.)* · Activate the fast-response current limit operation. (V/F control, Simple magnetic flux vector control) · Choose inverter and motor capacities that match. (IPM motor control) · Input a start command after the motor stops. Alternatively, set the automatic restart after instantaneous power failure/flying start function. *(Refer to 162 page .)*			

Operation Panel Indication	E.OV1	E.Ov 1	FR-PU04 FR-PU07	OV During Acc
Name	Regenerative overvoltage trip during acceleration			
Description	If regenerative energy causes the inverter's internal main circuit DC voltage to reach or exceed the specified value, the protective circuit is activated to stop the inverter output. The circuit may also be activated by a surge voltage produced in the power supply system.			
Check point	· Check for too slow acceleration. (e.g. during descending acceleration with lifting load) · Check if *Pr.22 Stall prevention operation level* is set too low like the no-load current.			
Corrective action	· Decrease the acceleration time. · Use regeneration avoidance function *(Pr. 882 to Pr. 886)*. *(Refer to page 279.)* · Set a value larger than the no load current in *Pr. 22 Stall prevention operation level*.			

Operation Panel Indication	E.OV2	E.Ov2	FR-PU04 FR-PU07	Stedy Spd OV
Name	Regenerative overvoltage trip during constant speed			
Description	If regenerative energy causes the inverter's internal main circuit DC voltage to reach or exceed the specified value, the protective circuit is activated to stop the inverter output. The circuit may also be activated by a surge voltage produced in the power supply system.			
Check point	· Check for sudden load change. · Check if *Pr.22 Stall prevention operation level* is set too low like the no-load current.			
Corrective action	· Keep load stable. · Use regeneration avoidance function *(Pr. 882 to Pr. 886)*. *(Refer to page 279.)* · Use the brake unit or power regeneration common converter (FR-CV) as required. · Set a value larger than the no load current in *Pr. 22 Stall prevention operation level.*			

Operation Panel Indication	E.OV3	E.Ov 3	FR-PU04 FR-PU07	OV During Dec
Name	Regenerative overvoltage trip during deceleration or stop			
Description	If regenerative energy causes the inverter's internal main circuit DC voltage to reach or exceed the specified value, the protective circuit is activated to stop the inverter output. The circuit may also be activated by a surge voltage produced in the power supply system.			
Check point	Check for sudden speed reduction.			
Corrective action	· Increase the deceleration time. (Set the deceleration time which matches the moment of inertia of the load) · Longer the brake cycle. · Use regeneration avoidance function *(Pr. 882 to Pr. 886)*. *(Refer to page 279.)* · Use the brake unit or power regeneration common converter (FR-CV) as required.			

Operation Panel Indication	E.THT	E.THT	FR-PU04 FR-PU07	Inv. Overload
Name	Inverter overload trip (electronic thermal relay function) *1			
Description	If a current not less than 120% of the rated output current flows and overcurrent trip does not occur (170% or less), the electronic thermal relay activates to stop the inverter output in order to protect the output transistors. (Overload capacity 120% 60s inverse-time characteristic)			
Check point	· Check that acceleration/deceleration time is not too short. · Check that *Pr. 0 Torque boost* setting is not too large (small). (V/F control) · Check that *Pr. 14 Load pattern selection* setting is appropriate for the load pattern of the using machine. (V/F control) · Check the motor for use under overload.			
Corrective action	· Increase acceleration/deceleration time. · Adjust the *Pr. 0 Torque boost* setting. (V/F control) · Set the *Pr. 14 Load pattern selection* setting according to the load pattern of the using machine. (V/F control) · Reduce the load weight.			

*1 Resetting the inverter initializes the internal thermal integrated data of the electronic thermal relay function.

Operation Panel Indication	E.THM	E.THM	FR-PU04 FR-PU07	Motor Ovrload
Name	Motor overload trip (electronic thermal relay function) *1			
Description	The electronic thermal relay function in the inverter detects motor overheat due to overload or reduced cooling capability during constant-speed operation and pre-alarm (TH display) is output when the integrated value reaches 85% of the *Pr. 9 Electronic thermal O/L relay* setting and the protection circuit is activated to stop the inverter output when the integrated value reaches the specified value. When running a special motor such as a multi-pole motor or multiple motors, provide a thermal relay on the inverter output side since such motor(s) cannot be protected by the electronic thermal relay function.			
Check point	· Check the motor for use under overload. · Check that the setting of *Pr. 71 Applied motor* for motor selection is correct. (V/F control, Simple magnetic flux vector control) *(Refer to page 122.)* · Check that stall prevention operation setting is correct.			
Corrective action	· Reduce the load weight. · For a constant-torque motor, set the constant-torque motor in *Pr. 71 Applied motor*. (V/F control, Simple magnetic flux vector control) · Check that stall prevention operation setting is correct. *(Refer to page 91.)*			

*1 Resetting the inverter initializes the internal thermal integrated data of the electronic thermal relay function.

Operation Panel Indication	E.FIN	E.FIn	FR-PU04 FR-PU07	H/Sink O/Temp
Name	Heatsink overheat			
Description	If the heatsink overheats, the temperature sensor is actuated to stop the inverter output. The FIN signal can be output when the temperature becomes approximately 85% of the heatsink overheat protection operation temperature. For the terminal used for the FIN signal output, assign the function by setting "26" (positive logic) or "126" (negative logic) in any of *Pr. 190 to Pr. 196 (output terminal function selection)*. *(Refer to page 140)*			
Check point	· Check for too high surrounding air temperature. · Check for heatsink clogging. · Check that the cooling fan is stopped. (Check that Fn is displayed on the operation panel.)			
Corrective action	· Set the surrounding air temperature to within the specifications. · Clean the heatsink. · Replace the cooling fan.			

Operation Panel Indication	E.IPF	E.IPF	FR-PU04 FR-PU07	Inst. Pwr. Loss
Name	Instantaneous power failure			
Description	If a power failure occurs for longer than 15ms (this also applies to inverter input shut-off), the instantaneous power failure protective function is activated to trip the inverter in order to prevent the control circuit from malfunctioning. If a power failure persists for longer than 100ms, the fault output is not provided, and the inverter restarts if the start signal is ON upon power restoration. (The inverter continues operating if an instantaneous power failure is within 15ms.) In some operating status (load magnitude, acceleration/ deceleration time setting, etc.), overcurrent or other protection may be activated upon power restoration. When instantaneous power failure protection is activated, the IPF signal is output. *(Refer to page 162)*			
Check point	Find the cause of instantaneous power failure occurrence.			
Corrective action	· Remedy the instantaneous power failure. · Prepare a backup power supply for instantaneous power failure. · Set the function of automatic restart after instantaneous power failure (*Pr. 57*). *(Refer to page 162.)*			

Operation Panel Indication	**E.BE**		**FR-PU04 FR-PU07**	**Br. Cct. Fault**
Name	Brake transistor alarm detection/internal circuit fault			
Description	This function stops the inverter output if a fault occurs in the brake circuit, e.g. damaged brake transistors when using functions of the 75K or higher. In this case, the inverter must be powered OFF immediately. For the 55K or lower, it appears when an internal circuit error occurred.			
Check point	· Reduce the load inertia. · Check that the frequency of using the brake is proper. · Check that the brake resistor selected is correct.			
Corrective action	For the 75K or higher, when the protective function is activated even if the above measures are taken, replace the brake unit with a new one. For the 55K or lower, replace the inverter.			

Operation Panel Indication	**E.UVT**		**FR-PU04 FR-PU07**	**Under Voltage**
Name	Undervoltage			
Description	If the power supply voltage of the inverter decreases, the control circuit will not perform normal functions. In addition, the motor torque will be insufficient and/or heat generation will increase. To prevent this, if the power supply voltage decreases below about 150V (300VAC for the 400V class), this function stops the inverter output. When a jumper is not connected across P/+ and P1, the undervoltage protective function is activated. When undervoltage protection is activated, the IPF signal is output. *(Refer to page 162)*			
Check point	· Check for start of large-capacity motor. · Check that a jumper or DC reactor is connected across terminals P/+ and P1.			
Corrective action	· Check the power supply system equipment such as the power supply. · Connect a jumper or DC reactor across terminals P/+ and P1. · If the problem still persists after taking the above measure, please contact your sales representative.			

Operation Panel Indication	**E.ILF**		**FR-PU04**	**Fault 14**
			FR-PU07	**Input phase loss**
Name	Input phase loss			
Description	This fault is output when function valid setting (=1) is set in *Pr. 872 Input phase loss protection selection* and one phase of the three phase power input is lost. When the setting of *Pr. 872 Input phase loss protection selection* is the initial value (*Pr. 872* = "0"), this fault does not occur. *(Refer to page 175.)*			
Check point	Check for a break in the cable for the three-phase power supply input.			
Corrective action	· Wire the cables properly. · Repair a break portion in the cable. · Check the *Pr. 872 Input phase loss protection selection* setting.			

Operation Panel Indication	**E.OLT**		**FR-PU04 FR-PU07**	**Stll Prev STP**
Name	Stall prevention stop			
Description	If the frequency has fallen to 0.5Hz(1.5Hz under IPM motor control) by stall prevention operation and remains for 3s, a fault (E.OLT) appears and trips the inverter. OL appears while stall prevention is being activated.			
Check point	· Check the motor for use under overload. *(Refer to page 92.)* · Check that a motor is connected during IPM motor control. (IPM motor control)			
Corrective action	· Reduce the load weight. · Check the connection of the IPM motor. (IPM motor control) · Set the IPM motor test operation. *(Refer to page 92)*			

Operation Panel Indication	**E.SOT** IPM		**FR-PU04**	**Fault 14**
			FR-PU07	**Motor step out**
Name	Loss of synchronism detection			
Description	Stops the output when the operation is not synchronized. (This function is only available under IPM motor control.)			
Check point	· Check that the IPM motor is not driven overloaded. · Check if a start command is given to the inverter while the IPM motor is coasting. · Check if a motor other than the IPM motor (MM-EFS series or MM-EF series) is driven.			
Corrective action	· Set the acceleration time longer. · Reduce the load. · If the inverter restarts during coasting, set *Pr.57 Restart coasting time* ≠ "9999," and select the automatic restart after instantaneous power failure. · Drive the IPM motor (MM-EFS series or MM-EF series).			

Operation Panel Indication	E.GF		FR-PU04 FR-PU07	Ground Fault
Name	Output side earth (ground) fault overcurrent			
Description	This function stops the inverter output if an earth (ground) fault overcurrent flows due to an earth (ground) fault that occurred on the inverter's output (load) side.			
Check point	Check for an earth (ground) fault in the motor and connection cable.			
Corrective action	Remedy the earth (ground) fault portion.			

Operation Panel Indication	E.LF		FR-PU04 FR-PU07	E. LF
Name	Output phase loss			
Description	This function stops the inverter output if one of the three phases (U, V, W) on the inverter's output side (load side) is lost.			
Check point	· Check the wiring (Check that the motor is normal.) · Check that the capacity of the motor used is not smaller than that of the inverter. · Check if a start command is given to the inverter while the motor is coasting.			
Corrective action	· Wire the cables properly. · Choose inverter and motor capacities that match. · Input a start command after the motor stops. Alternatively, use automatic restart after instantaneous power failure/flying start function. *(Refer to page 162)*			

Operation Panel Indication	E.OHT		FR-PU04 FR-PU07	OH Fault
Name	External thermal relay operation			
Description	If the external thermal relay provided for motor overheat protection, or the internally mounted temperature relay in the motor, etc. switches ON (contacts open), the inverter output is stopped. This function is available when "7" (OH signal) is set to any of *Pr. 178 to Pr. 189 (input terminal function selection)*. When the initial value (without OH signal assigned) is set, this protective function is not available.			
Check point	· Check for motor overheating. · Check that the value of 7 (OH signal) is set correctly in any of *Pr. 178 to Pr. 189 (input terminal function selection)*.			
Corrective action	· Reduce the load and operating duty. · Even if the relay contacts are reset automatically, the inverter will not restart unless it is reset.			

Operation Panel Indication	E.PTC		FR-PU04	Fault 14
			FR-PU07	PTC activated
Name	PTC thermistor operation			
Description	Trips when the motor overheat status is detected for 10s or more by the external PTC thermistor input connected to the terminal AU. This fault is available when "63" is set in *Pr. 184 AU terminal function selection* and AU/PTC switchover switch is set in PTC side. When the initial value (*Pr. 184* = "4") is set, this protective function is not available.			
Check point	· Check the connection between the PTC thermistor switch and thermal relay protector. · Check the motor for operation under overload. · Is valid setting (= 63) selected in *Pr. 184 AU terminal function selection* ? *(Refer to page 121, 133.)*			
Corrective action	Reduce the load weight.			

Operation Panel Indication	E.OPT		FR-PU04 FR-PU07	Option Fault
Name	Option fault			
Description	· Appears when the AC power supply is connected to the terminal R/L1, S/L2, T/L3 accidentally when a high power factor converter is connected. · Appears when the switch for the manufacturer setting of the plug-in option is changed. · Appears when a communication option is connected while *Pr. 296 Password lock level* = "0 or 100."			
Check point	· Check that the AC power supply is not connected to the terminal R/L1, S/L2, T/L3 when a high power factor converter (FR-HC, MT-HC) or power regeneration common converter (FR-CV) is connected. · Check if password lock is activated by setting *Pr. 296* = "0, 100"			
Corrective action	· Check the parameter *(Pr. 30)* setting and wiring. · The inverter may be damaged if the AC power supply is connected to the terminal R/L1, S/L2, T/L3 when a high power factor converter is connected. Please contact your sales representative. · Return the switch for the manufacturer setting of the plug-in option to the initial status. *(Refer to page 203.)* · To apply the password lock when installing a communication option, set *Pr.296* ≠ "0,100". *(Refer to page 203.)*. · If the problem still persists after taking the above measure, please contact your sales representative.			

Operation Panel Indication	E.OP1		FR-PU04 FR-PU07	Option 1 Fault
Name	Communication option fault			
Description	Stops the inverter output when a communication line fault occurs in the communication option.			
Check point	· Check for a wrong option function setting and operation. · Check that the plug-in option is plugged into the connector securely. · Check for a break in the communication cable. · Check that the terminating resistor is fitted properly.			
Corrective action	· Check the option function setting, etc. · Connect the plug-in option securely. · Check the connection of communication cable.			

Operation Panel Indication	E. 1		FR-PU04 FR-PU07	Fault 1
Name	Option fault			
Description	Stops the inverter output if a contact fault or the like of the connector between the inverter and communication option occurs. Appears when the switch for the manufacturer setting of the plug-in option is changed.			
Check point	· Check that the plug-in option is plugged into the connector securely. · Check for excess electrical noises around the inverter.			
Corrective action	· Connect the plug-in option securely. · Take measures against noises if there are devices producing excess electrical noises around the inverter. If the problem still persists after taking the above measure, please contact your sales representative or distributor. · Return the switch position for the manufacturer setting of the plug-in option to the initial status. *(Refer to instruction manual of each option)*			

Operation Panel Indication	E.PE		FR-PU04 FR-PU07	Corrupt Memry
Name	Parameter storage device fault (control circuit board)			
Description	Trips when a fault occurred in the parameter stored. (EEPROM failure)			
Check point	Check for too many number of parameter write times.			
Corrective action	Please contact your sales representative. When performing parameter write frequently for communication purposes, set "1" in *Pr. 342* to enable RAM write. Note that powering OFF returns the inverter to the status before RAM write.			

Operation Panel Indication	E.PE2		FR-PU04	Fault 14
			FR-PU07	PR storage alarm
Name	Parameter storage device fault (main circuit board)			
Description	Trips when a fault occurred in the parameter stored. (EEPROM failure)			
Check point	——————			
Corrective action	Please contact your sales representative.			

Operation Panel Indication	E.PUE		FR-PU04 FR-PU07	PU Leave Out
Name	PU disconnection			
Description	· This function stops the inverter output if communication between the inverter and PU is suspended, e.g. the operation panel and parameter unit is disconnected, when "2", "3", "16" or "17" was set in *Pr. 75 Reset selection/disconnected PU detection/PU stop selection*. This protective function is not available in the initial setting (*Pr. 75* = "14"). · This function stops the inverter output when communication errors occurred consecutively for more than permissible number of retries when a value other than "9999" is set in *Pr. 121 Number of PU communication retries* during the RS-485 communication with the PU connector. · This function stops the inverter output if communication is broken for the period of time set in *Pr. 122 PU communication check time interval* during the RS-485 communication with the PU connector.			
Check point	· Check that the FR-DU07 or parameter unit (FR-PU04/FR-PU07) is fitted tightly. · Check the *Pr. 75* setting.			
Corrective action	Fit the FR-DU07 or parameter unit (FR-PU04/FR-PU07) securely.			

Operation Panel Indication	E.RET		FR-PU04 FR-PU07	Retry No Over
Name	Retry count excess			
Description	If operation cannot be resumed properly within the number of retries set, this function trips the inverter. This function is available only when *Pr. 67 Number of retries at fault occurrence* is set. When the initial value (*Pr. 67* = "0") is set, this protective function is not available.			
Check point	Find the cause of fault occurrence.			
Corrective action	Eliminate the cause of the fault preceding this error indication.			

Operation Panel Indication	**E. 5**	E. 5	**FR-PU04** **FR-PU07**	**Fault 5**
	E. 6	E. 6		**Fault 6**
	E. 7	E. 7		**Fault 7**
	E.CPU	E.CPU		**CPU Fault**
Name	CPU fault			
Description	Stops the inverter output if the communication fault of the built-in CPU occurs.			
Check point	Check for devices producing excess electrical noises around the inverter.			
Corrective action	· Take measures against noises if there are devices producing excess electrical noises around the inverter. · Please contact your sales representative.			

Operation Panel Indication	**E.CTE**	E.CTE	**FR-PU04**	**———**
			FR-PU07	**E.CTE**
Name	Operation panel power supply short circuit, RS-485 terminal power supply short circuit			
Description	When the operation panel power supply (PU connector) is shorted, this function shuts off the power output and stops the inverter output. At this time, the operation panel (parameter unit) cannot be used and RS-485 communication from the PU connector cannot be made. When the internal power supply for RS-485 terminals are shorted, this function shuts off the power output. At this time, communication from the RS-485 terminals cannot be made. To reset, enter the RES signal or switch power OFF, then ON again.			
Check point	· Check for a short circuit in the PU connector cable. · Check that the RS-485 terminals are connected correctly.			
Corrective action	· Check the PU and cable. · Check the connection of the RS-485 terminals			

Operation Panel Indication	**E.P24**	E.P24	**FR-PU04** **FR-PU07**	**E.P24**
Name	24VDC power output short circuit			
Description	When the 24VDC power output from the PC terminal is shorted, this function shuts off the power output. At this time, all external contact inputs switch OFF. The inverter cannot be reset by entering the RES signal. To reset it, use the operation panel or switch power OFF, then ON again.			
Check point	· Check for a short circuit in the PC terminal output.			
Corrective action	· Remedy the earth (ground) fault portion.			

Operation Panel Indication	**E.CDO**	E.CdO	**FR-PU04**	**Fault 14**
			FR-PU07	**OC detect level**
Name	Output current detection value exceeded			
Description	This function stops the inverter output when the output current exceeds the setting of *Pr.150 Output current detection level*, or the output current falls below the setting of *Pr.152 Zero current detection level*. This function is active when *Pr. 167 Output current detection operation selection* is set to "1, 10, 11". When the initial value (*Pr. 167* = "0") is set, this fault does not occur.			
Check point	Check the settings of *Pr. 150 Output current detection level*, *Pr. 151 Output current detection signal delay time*, *Pr. 152 Zero current detection level*, *Pr. 153 Zero current detection time, Pr. 166 Output current detection signal retention time*, *Pr. 167 Output current detection operation selection*. *(Refer to page 146.)*			

Operation Panel Indication	**E.IOH**	E.IOH	**FR-PU04**	**Fault 14**
			FR-PU07	**Inrush overheat**
Name	Inrush current limit circuit fault			
Description	Trips when the resistor of the inrush current limit circuit overheats. The inrush current limit circuit fault			
Check point	· Check that frequent power ON/OFF is not repeated. · Check that no meltdown is found in the input side fuse (5A) in the power supply circuit of the inrush current suppression circuit contactor (FR-F740P-132K or higher) or no fault is found in the power supply circuit of the contactor. · Check that the power supply circuit of inrush current limit circuit contactor is not damaged.			
Corrective action	Configure a circuit where frequent power ON/OFF is not repeated. If the problem still persists after taking the above measure, please contact your sales representative.			

Operation Panel Indication	E.SER	E.SEr	FR-PU04 FR-PU07	Fault 14 VFD Comm error
Name	Communication fault (inverter)			
Description	This function stops the inverter output when communication error occurs consecutively for more than permissible retry count when a value other than "9999" is set in *Pr. 335 RS-485 communication retry count* during RS-485 communication from the RS-485 terminals. This function also stops the inverter output if communication is broken for the period of time set in *Pr. 336 RS-485 communication check time interval*.			
Check point	Check the RS-485 terminal wiring.			
Corrective action	Perform wiring of the RS-485 terminals properly.			

Operation Panel Indication	E.AIE	E.AI E	FR-PU04 FR-PU07	Fault 14 Analog in error
Name	Analog input fault			
Description	Stops the inverter output when a 30mA or higher current or a 7.5V or higher voltage is input to terminal 2 while the current input is selected by *Pr.73 Analog input selection*, or to terminal 4 while the current input is selected by *Pr.267 Terminal 4 input selection*.			
Check point	Check the setting of *Pr. 73 Analog input selection* and *Pr. 267 Terminal 4 input selection*. *(Refer to page 185.)*			
Corrective action	Either give a frequency command by current input or set *Pr. 73 Analog input selection* or *Pr. 267 Terminal 4 input selection* to voltage input.			

Operation Panel Indication	E.PID	E.PI d	FR-PU04 FR-PU07	Fault 14 Fault PID Signal Error
Name	PID signal fault			
Description	If any of PID upper limit (FUP), PID lower limit (FDN), and PID deviation limit (Y48) turns ON during PID control, inverter shuts off the output. This function is active under the following parameter settings: *Pr.554 PID signal operation selection* ≠ "0,10", *Pr.131 PID upper limit* ≠ "9999", *Pr.132 PID lower limit* ≠ "9999", and *Pr.553 PID deviation limit* ≠ "9999". This protective function is not active in the initial setting (*Pr.554* = "0", *Pr.131* = "9999", *Pr.132* = "9999", *Pr.553* = "9999").			
Check Point	· Check if the measured PID value is greater than the upper limit *(Pr.131)* or smaller than the lower limit *(Pr.132)*. · Check if the absolute PID deviation value is greater than the limit value *(Pr.553)*.			
Corrective Action	Make correct settings for *Pr.131 PID upper limit*, *Pr.132 PID lower limit*, *Pr.553 PID deviation limit*. *(Refer to page 261)*			

Operation Panel Indication	E.13	E. 13	FR-PU04 FR-PU07	Fault 13
Name	Internal circuit fault			
Description	Trips when an internal circuit error occurred.			
Corrective action	Please contact your sales representative.			

CAUTION

- If protective functions of E.ILF, E.SOT, E.PTC, E.PE2, E.CDO, E.IOH, E.SER, E.AIE, E.PID are activated when using the FR-PU04, "Fault 14" appears.
  Also when the faults history is checked on the FR-PU04, the display is "E.14".
- If faults other than the above appear, contact your sales representative.

5.4 Correspondences between digital and actual characters

There are the following correspondences between the actual alphanumeric characters and the digital characters displayed on the operation panel.

Actual	Digital
0	
1	
2	
3	
4	
5	
6	
7	
8	
9	

Actual	Digital
A	
B	
C	
D	
E	
F	
G	
H	
I	
J	
L	

Actual	Digital
M	
N	
O	
o	
P	
S	
T	
U	
V	
r	
-	

5.5 Check first when you have a trouble

POINT

- If the cause of malfunction is still unknown after performing applicable checks, initialization of parameter settings is recommended. Reset the parameter settings and set the required parameters again, then perform the checks again.

5.5.1 Motor does not start

Check points	Possible Cause	Countermeasures	Refer to page
Main Circuit	Appropriate power supply voltage is not applied. (Operation panel display is not provided.)	Power ON a moulded case circuit breaker (MCCB), an earth leakage circuit breaker (ELB), or a magnetic contactor (MC).	—
		Check for the decreased input voltage, input phase loss, and wiring.	
		If only the control power is ON when using a separate power source for the control circuit, turn ON the main circuit power.	*24*
	Motor is not connected properly.	Check the wiring between the inverter and the motor. If commercial power supply-inverter switchover function is active, check the wiring of the magnetic contactor connected between the inverter and the motor. (V/F control, Simple magnetic flux vector control)	*16*
	The jumper across P/+ and P1 is disconnected. (55K or lower)	Securely fit a jumper across P/+ and P1. When using a DC reactor (FR-HEL), remove the jumper across P/+ and P1, and then connect the DC reactor.	*16*
Input Signal	Start signal is not input.	Check the start command source, and input a start signal. PU operation mode: FWD / REV External operation mode : STF/STR signal	*208*
	Both the forward and reverse rotation start signals (STF, STR) are input simultaneously.	Turn ON only one of the forward and reverse rotation start signals (STF or STR). If STF and STR signals are turned ON simultaneously in the initial setting, a stop command is given.	*26*
	Frequency command is zero. (FWD or REV LED on the operation panel is flickering.)	Check the frequency command source and enter a frequency command.	*208*
	AU signal is not ON when terminal 4 is used for frequency setting. (FWD or REV LED on the operation panel is flickering.)	Turn ON the AU signal. Turning ON the AU signal activates terminal 4 input.	*185*
	Output stop signal (MRS) or reset signal (RES) is ON. (FWD or REV LED on the operation panel is flickering.)	Turn MRS or RES signal OFF. Inverter starts the operation with a given start command and a frequency command after turning OFF MRS or RES signal. Before turning OFF, ensure the safety.	*162*
	CS signal is OFF when automatic restart after instantaneous power failure function is selected (*Pr. 57* ≠ "9999"). (FWD or REV LED on the operation panel is flickering.)	Turn ON the CS signal. Restart operation is enabled when restart after instantaneous power signal (CS) is ON.	*162*
	Jumper connector of sink - source is wrongly selected. (FWD or REV LED on the operation panel is flickering.)	Check that the control logic switchover jumper connector is correctly installed. If it is not installed correctly, input signal is not recognized.	*29*
	Voltage/current input switch is not correctly set for analog input signal (0 to 5V/0 to 10V, 4 to 20mA). (FWD or REV LED on the operation panel is flickering.)	Set *Pr. 73, Pr. 267*, and a voltage/current input switch correctly, then input an analog signal in accordance with the setting.	*26*

Check points	Possible Cause	Countermeasures	Refer to page
Input Signal	STOP/RESET was pressed. (Operation panel indication is PS (PS).)	During the External operation mode, check the method of restarting from a STOP/RESET input stop from PU.	*312*
	Two-wire or three-wire type connection is wrong.	Check the connection. Connect STOP signal when three-wire type is used.	*138*
Parameter Setting	*Pr. 0 Torque boost* setting is improper when V/F control is used.	Increase *Pr. 0* setting by 0.5% increments while observing the rotation of a motor. If that makes no difference, decrease the setting.	*87*
	Pr. 78 Reverse rotation prevention selection is set.	Check the *Pr. 78* setting. Set *Pr. 78* when you want to limit the motor rotation to only one direction.	*201*
	Pr. 79 Operation mode selection setting is wrong.	Select the operation mode which corresponds with input methods of start command and frequency command.	*206*
	Bias and gain *(calibration parameter C2 to C7)* settings are improper.	Check the bias and gain *(calibration parameter C2 to C7)* settings.	*193*
	Pr. 13 Starting frequency setting is greater than the running frequency.	Set running frequency higher than *Pr. 13*. The inverter does not start if the frequency setting signal is less than the value set in *Pr. 13*.	*113*
	Frequency settings of various running frequency (such as multi-speed operation) are zero. Especially, *Pr. 1 Maximum frequency* is zero.	Set the frequency command according to the application. Set *Pr. 1* higher than the actual frequency used.	*96*
	Pr. 15 Jog frequency setting is lower than *Pr. 13 Starting frequency*.	Set *Pr. 15 Jog frequency* higher than *Pr. 13 Starting frequency.*	*104*
	Operation mode and a writing device do not match.	Check *Pr. 79, Pr. 338, Pr. 339, Pr. 550, Pr. 551,* and select an operation mode suitable for the purpose.	*206, 219*
	Start signal operation selection is set by the *Pr. 250 Stop selection*	Check *Pr. 250* setting and connection of STF and STR signals.	*138*
	Inverter decelerated to a stop when power failure deceleration stop function is selected.	When power is restored, ensure the safety, and turn OFF the start signal once, then turn ON again to restart. Inverter restarts when *Pr. 261*="2, 22".	*169*
	Automatic restart after instantaneous power failure function or power failure stop function is activated. (Performing overload operation during input phase loss may cause voltage insufficiency, and that may result in detection of power failure.)	• Set *Pr. 872 Input phase loss protection selection* = "1" (input phase failure protection active). • Disable the automatic restart after instantaneous power failure function and power failure stop function. • Reduce the load. • Increase the acceleration time if the automatic restart after instantaneous power failure function or power failure stop function occurred during acceleration.	*162, 169, 175*
	DC feeding mode 1 or mode 2 is not selected in *Pr.30 Regenerative function selection* even though the DC is fed through terminal P and N.	Set the DC feeding mode in *Pr.30 Regenerative function selection*.	*125*
	IPM motor test operation is selected under IPM motor control.	Set "20" in *Pr.800 Control method selection*.	*82*
Load	Load is too heavy.	Reduce the load.	—
	Shaft is locked.	Inspect the machine (motor).	—

5.5.2 Motor or machine is making abnormal acoustic noise

When operating the inverter with the carrier frequency of 3kHz (6kHz during IPM motor control) or more set in *Pr. 72*, the carrier frequency will automatically decrease if the output current of the inverter exceeds the value in parenthesis of the rated output current on *page 346*. This may cause the motor noise to increase. But it is not a fault.

Check points	Possible Cause	Countermeasures	Refer to page
Input signal	Disturbance due to EMI when frequency command is given from analog input (terminal 1, 2, 4).	Take countermeasures against EMI.	44
Parameter Setting		Increase the *Pr. 74 Input filter time constant* if steady operation cannot be performed due to EMI.	192
Parameter Setting	No carrier frequency noises (metallic noises) are generated.	In the initial setting, *Pr. 240 Soft-PWM operation selection* is enabled to change motor noise to an unoffending complex tone. Therefore, no carrier frequency noises (metallic noises) are generated. Set *Pr. 240* = "0" to disable this function.	182
	Resonance occurs. (output frequency)	Set *Pr. 31 to Pr. 36 (Frequency jump)*. When it is desired to avoid resonance attributable to the natural frequency of a mechanical system, these parameters allow resonant frequencies to be jumped.	97
	Resonance occurs. (carrier frequency)	Change *Pr. 72 PWM frequency selection* setting. Changing the PWM carrier frequency produces an effect on avoiding the resonance frequency of a mechanical system or a motor.	182
	Gain adjustment during PID control is insufficient.	To stabilize the measured value, change the proportional band (*Pr. 129*) to a larger value, the integral time (*Pr. 130*) to a slightly longer time, and the differential time (*Pr. 134*) to a slightly shorter time. Check the calibration of set point and measured value.	261
Others	Mechanical looseness	Adjust machine/equipment so that there is no mechanical looseness.	—
	Contact the motor manufacturer.		
Motor	Operating with output phase loss	Check the motor wiring.	—

5.5.3 Inverter generates abnormal noise

Check points	Possible Cause	Countermeasures	Refer to page
Fan	Fan cover was not correctly installed when a cooling fan was replaced.	Install a fan cover correctly.	336

5.5.4 Motor generates heat abnormally

Check points	Possible Cause	Countermeasures	Refer to page
Motor	Motor fan is not working (Dust is accumulated.)	Clean the motor fan. Improve the environment.	—
	Phase to phase insulation of the motor is insufficient.	Check the insulation of the motor.	—
Main Circuit	The inverter output voltage (U, V, W) are unbalanced.	Check the output voltage of the inverter. Check the insulation of the motor.	333
Parameter Setting	The *Pr. 71 Applied motor* setting is wrong. (V/F control, Simple magnetic flux vector control)	Check the *Pr. 71 Applied motor* setting. (V/F control, Simple magnetic flux vector control)	122
—	Motor current is large.	Refer to "5.5.11 Motor current is too large"	328

5.5.5 Motor rotates in the opposite direction

Check points	Possible Cause	Countermeasures	Refer to page
Main Circuit	Phase sequence of output terminals U, V and W is incorrect.	Connect phase sequence of the output cables (terminal U, V, W) to the motor correctly	*16*
Input signal	The start signals (forward rotation, reverse rotation) are connected improperly.	Check the wiring. (STF: forward rotation , STR: reverse rotation)	*26*
	The polarity of the frequency command is negative during the polarity reversible operation set by *Pr. 73 Analog input selection*.	Check the polarity of the frequency command.	*185*

5.5.6 Speed greatly differs from the setting

Check points	Possible Cause	Countermeasures	Refer to page
Input signal	Frequency setting signal is incorrectly input.	Measure the input signal level.	—
	The input signal lines are affected by external EMI.	Take countermeasures against EMI such as using shielded wires for input signal lines.	*46*
Parameter Setting	*Pr. 1, Pr. 2, Pr. 18, calibration parameter C2 to C7* settings are improper.	Check the settings of *Pr. 1 Maximum frequency, Pr. 2 Minimum frequency, Pr. 18 High speed maximum frequency.*	*96*
		Check the *calibration parameter C2 to C7* settings.	*193*
		During IPM motor control, maximum frequency is limited to the maximum motor speed (frequency) of the IPM motor.	*360*
	Pr. 31 to Pr. 36 (frequency jump) settings are improper.	Narrow down the range of frequency jump.	*97*
Load	Stall prevention function is activated due to a heavy load.	Reduce the load weight.	—
Parameter Setting		Set *Pr. 22 Stall prevention operation level* higher according to the load. (Setting *Pr. 22* too large may result in frequent overcurrent trip (E.OC□).)	*91*
Motor		Check the capacities of the inverter and the motor.	—

5.5.7 Acceleration/deceleration is not smooth

Check points	Possible Cause	Countermeasures	Refer to page
Parameter Setting	Acceleration/deceleration time is too short.	Increase acceleration/deceleration time.	*109*
	Torque boost (*Pr. 0, Pr. 46*) setting is improper under V/F control, so the stall prevention function is activated.	Increase/decrease *Pr. 0 Torque boost* setting value by 0.5% increments to the setting.	*87*
	The base frequency does not match the motor characteristics under V/F control or Simple magnetic flux vector control.	Set *Pr. 3 Base frequency and Pr. 47 Second V/F (base frequency)*.	*98*
	Regeneration avoidance operation is performed	If the frequency becomes unstable during regeneration avoidance operation, decrease the setting of *Pr. 886 Regeneration avoidance voltage gain*.	*279*
Load	Stall prevention function is activated due to a heavy load.	Reduce the load weight.	—
Parameter Setting		Set *Pr. 22 Stall prevention operation level* higher according to the load. (Setting *Pr. 22* too large may result in frequent overcurrent trip (E.OC□).)	*91*
Motor		Check the capacities of the inverter and the motor.	—

5.5.8 Speed varies during operation

Check points	Possible Cause	Countermeasures	Refer to page
Load	Load varies during an operation. (V/F control)	Select Simple magnetic flux vector control	89
Input signal	Frequency setting signal is varying.	Check the frequency setting signal.	—
	The frequency setting signal is affected by EMI.	Set filter to the analog input terminal using *Pr. 74 Input filter time constant*.	192
		Take countermeasures against EMI, such as using shielded wires for input signal lines.	46
	Malfunction is occurring due to the undesirable current generated when the transistor output unit is connected.	Use terminal PC (terminal SD when source logic) as a common terminal to prevent a malfunction caused by undesirable current.	30
	Multi-speed command signal is chattering.	Take countermeasures to suppress chattering.	—
Parameter Setting	Fluctuation of power supply voltage is too large.	Change the *Pr. 19 Base frequency voltage* setting (about 3%) under V/F control.	98
	The *Pr.80 Motor capacity* setting is inappropriate for the inverter and motor capacities under Simple magnetic flux vector control and IPM motor control.	Check the *Pr. 80 Motor capacity* setting.	89
	Wiring length is too long for V/F control, and a voltage drop occurs.	Adjust *Pr. 0 Torque boost* by increasing with 0.5% increments for low-speed operation.	87
		Change to Simple magnetic flux vector control.	89
	Hunting occurs by the generated vibration, for example, when structural rigidity at load side is insufficient.	Disable automatic control functions, such as energy saving operation, fast-response current limit function, regeneration avoidance function, Simple magnetic flux vector control and stall prevention. For PID control, set smaller values to *Pr.129 PID proportional band* and *Pr.130 PID integral time*. Lower the control gain, and adjust to increase the stability.	—
		Change *Pr. 72 PWM frequency selection* setting.	182

5.5.9 Operation mode is not changed properly

Check points	Possible Cause	Countermeasures	Refer to page
Input signal	Start signal (STF or STR) is ON.	Check that the STF and STR signals are OFF. When either is ON, the operation mode cannot be changed.	206
Parameter Setting	*Pr. 79* setting is improper.	When *Pr. 79 Operation mode selection* setting is "0" (initial value), the inverter is placed in the External operation mode at input power ON. To switch to the PU operation mode, press PU/EXT on the operation panel (press PU when the parameter unit (FR-PU04/FR-PU07) is used) . At other settings (1 to 4, 6, 7), the operation mode is limited accordingly.	206
	Operation mode and a writing device do not correspond.	Check *Pr. 79, Pr. 338, Pr. 339, Pr. 550, Pr. 551,* and select an operation mode suitable for the purpose.	206, 219

5.5.10 Operation panel (FR-DU07) display is not operating

<table>
<tr><th>Check points</th><th>Possible Cause</th><th>Countermeasures</th><th>Refer to page</th></tr>
<tr><td>Main Circuit, Control Circuit</td><td>Power is not input.</td><td>Input the power.</td><td>14</td></tr>
<tr><td>Front cover</td><td>Operation panel is not properly connected to the inverter.</td><td>Check if the inverter front cover is installed securely.
The inverter cover may not fit properly when using wires whose size are 1.25mm^2 or larger, or when using many wires, and this could cause a contact fault of the operation panel.</td><td>6</td></tr>
</table>

5.5.11 Motor current is too large

<table>
<tr><th>Check points</th><th>Possible Cause</th><th>Countermeasures</th><th>Refer to page</th></tr>
<tr><td rowspan="7">Parameter Setting</td><td>Torque boost (Pr. 0, Pr. 46) setting is improper under V/F control, so the stall prevention function is activated.</td><td>Increase/decrease Pr. 0 Torque boost setting value by 0.5% increments to the setting.</td><td>87</td></tr>
<tr><td rowspan="2">V/F pattern is improper when V/F control or Simple magnetic flux vector control is performed.
(Pr. 3, Pr. 14, Pr. 19)</td><td>Set rated frequency of the motor to Pr. 3 Base frequency.
(V/F control, Simple magnetic flux vector control)
Use Pr. 19 Base frequency voltage to set the base voltage (e.g. rated motor voltage). (V/F control, Simple magnetic flux vector control)</td><td>98</td></tr>
<tr><td>Change Pr. 14 Load pattern selection according to the load characteristic. (V/F control)</td><td>100</td></tr>
<tr><td rowspan="3">Stall prevention function is activated due to a heavy load.</td><td>Reduce the load weight.</td><td>—</td></tr>
<tr><td>Set Pr. 22 Stall prevention operation level higher according to the load. (Setting Pr. 22 too large may result in frequent overcurrent trip (E.OC□).)</td><td>91</td></tr>
<tr><td>Check the capacities of the inverter and the motor.</td><td>—</td></tr>
</table>

5.5.12 Speed does not accelerate

Check points	Possible Cause	Countermeasures	Refer to page
Input signal	Start command and frequency command are chattering.	Check if the start command and the frequency command are correct.	—
	The wiring length used for analog frequency command is too long, and it is causing a voltage (current) drop.	Perform analog input bias/gain calibration.	*193*
	Input signal lines are affected by external EMI.	Take countermeasures against EMI, such as using shielded wires for input signal lines.	*46*
Parameter Setting	*Pr. 1, Pr. 2, Pr. 18, calibration parameter C2 to C7* settings are improper.	Check the settings of *Pr. 1 Maximum frequency and Pr. 2 Minimum frequency*. If you want to run the motor at 120Hz or higher, set *Pr. 18 High speed maximum frequency.*	*96*
		Check the *calibration parameter C2 to C7* settings.	*193*
		During IPM motor control, maximum frequency is limited to the maximum motor speed (frequency) of the IPM motor.	*360*
	The maximum voltage (current) input value is not set during the external operation. *(Pr.125, Pr.126, Pr.18)*	Check the *Pr.125 Terminal 2 frequency setting gain frequency* and *Pr.126 Terminal 4 frequency setting gain frequency* settings. To operate at 120Hz or higher, set *Pr.18 High speed maximum frequency*.	*96, 193*
	Torque boost (*Pr. 0, Pr. 46*) setting is improper under V/F control, so the stall prevention function is activated.	Increase/decrease *Pr. 0 Torque boost* setting value by 0.5% increments so that stall prevention does not occur.	*87*
	V/F pattern is improper when V/F control or Simple magnetic flux vector control is performed. *(Pr. 3, Pr. 14, Pr. 19)*	Set rated frequency of the motor to *Pr. 3 Base frequency*. (V/F control, Simple magnetic flux vector control) Use *Pr. 19 Base frequency voltage* to set the base voltage (e.g. rated motor voltage). (V/F control, Simple magnetic flux vector control)	*98*
		Change *Pr. 14 Load pattern selection* according to the load characteristic. (V/F control)	*100*
	Stall prevention function is activated due to a heavy load.	Reduce the load weight.	—
		Set *Pr. 22 Stall prevention operation level* higher according to the load. (Setting *Pr. 22* too large may result in frequent overcurrent trip (E.OC□).)	*91*
		Check the capacities of the inverter and the motor.	—
	During PID control, output frequency is automatically controlled to make measured value = set point.		*261*

5.5.13 Unable to write parameter setting

Check points	Possible Cause	Countermeasures	Refer to page
Input signal	Operation is being performed (signal STF or STR is ON).	Stop the operation. When *Pr. 77* = "0" (initial value), write is enabled only during a stop.	*200*
Parameter Setting	You are attempting to set the parameter in the External operation mode.	Choose the PU operation mode. Or, set *Pr. 77* = "2" to enable parameter write regardless of the operation mode.	*200*
	Parameter is disabled by the *Pr. 77 Parameter write selection* setting.	Check *Pr. 77 Parameter write selection* setting.	*200*
	Key lock is activated by the *Pr. 161 Frequency setting/key lock operation selection* setting.	Check *Pr. 161 Frequency setting/key lock operation selection* setting.	*295*
	Operation mode and a writing device do not correspond.	Check *Pr. 79, Pr. 338, Pr. 339, Pr. 550, Pr. 551,* and select an operation mode suitable for the purpose.	*206, 219*
	Attempted to set "25" in *Pr.72 PWM frequency selection* under IPM motor control. Attempted to perform IPM motor control while *Pr.72* ="25."	*Pr.72* cannot be set to "25" during the IPM motor control. (The sine wave filter (MT-BSL/BSC) cannot be used under IPM motor control.)	*183*

5.5.14 Power lamp is not lit

Check points	Possible Cause	Countermeasures	Refer to page
Main Circuit, Control Circuit	Wiring or installation is improper.	Check for the wiring and the installation. Power lamp is lit when power supply is input to the control circuit (R1/L11, S1/L21).	*16*

MEMO

6 PRECAUTIONS FOR MAINTENANCE AND INSPECTION

This chapter describes the "PRECAUTIONS FOR MAINTENANCE AND INSPECTION" of this product.
Always read the instructions before using the equipment.

The inverter is a static unit mainly consisting of semiconductor devices. Daily inspection must be performed to prevent any fault from occurring due to the adverse effects of the operating environment, such as temperature, humidity, dust, dirt and vibration, changes in the parts with time, service life, and other factors.

• Precautions for maintenance and inspection

For some short time after the power is switched OFF, a high voltage remains in the smoothing capacitor. When accessing the inverter for inspection, wait for at least 10 minutes after the power supply has been switched OFF, and then make sure that the voltage across the main circuit terminals P/+ and N/– of the inverter is not more than 30VDC using a tester, etc.

6.1 Inspection item

6.1.1 Daily inspection

Basically, check for the following faults during operation.
(1) Motor operation fault
(2) Improper installation environment
(3) Cooling system fault
(4) Unusual vibration and noise
(5) Unusual overheat and discoloration

6.1.2 Periodic inspection

Check the areas inaccessible during operation and requiring periodic inspection.
Consult us for periodic inspection.
1) Check for cooling system fault...............Clean the air filter, etc.
2) Tightening check and retightening.........The screws and bolts may become loose due to vibration, temperature changes, etc.
Tighten them according to the specified tightening torque.
(Refer to page 20.)
3) Check the conductors and insulating materials for corrosion and damage.
4) Measure insulation resistance.
5) Check and change the cooling fan and relay.

6.1.3 Daily and periodic inspection

Area of Inspection	Inspection Item	Inspection Item	Interval: Daily	Interval: Periodic *2	Corrective Action at Alarm Occurrence	Customer's Check
General	Surrounding environment	Check the surrounding air temperature, humidity, dirt, corrosive gas, oil mist , etc	○		Improve environment	
	Overall unit	Check for unusual vibration and noise	○		Check alarm location and retighten	
	Power supply voltage	Check that the main circuit voltages and control voltages are normal *1	○		Inspect the power supply	
Main circuit	General	(1)Check with megger (across main circuit terminals and earth (ground) terminal).		○	Contact the manufacturer	
		(2)Check for loose screws and bolts.		○	Retighten	
		(3)Check for overheat traces on the parts.		○	Contact the manufacturer	
		(4)Check for stain		○	Clean	
	Conductors, cables	(1)Check conductors for distortion.		○	Contact the manufacturer	
		(2)Check cable sheaths for breakage and deterioration (crack, discoloration, etc.)		○	Contact the manufacturer	
	Transformer/reactor	Check for unusual odor and abnormal increase in whining sound.	○		Stop the device and contact the manufacturer.	
	Terminal block	Check for damage.		○	Stop the device and contact the manufacturer.	
	Smoothing aluminum electrolytic capacitor	(1)Check for liquid leakage.		○	Contact the manufacturer	
		(2)Check for safety valve projection and bulge.		○	Contact the manufacturer	
		(3)Visual check and judge by the life check of the main circuit capacitor *(Refer to page 334)*		○		
	Relay/contactor	Check that the operation is normal and no chatter is heard.		○	Contact the manufacturer	
Control circuit protective circuit	Operation check	(1)Check that the output voltages across phases with the inverter operated alone is balanced		○	Contact the manufacturer	
		(2)Check that no fault is found in protective and display circuits in a sequence protective operation test.		○	Contact the manufacturer	
	Parts check: Overall	(1)Check for unusual odor and discoloration.		○	Stop the device and contact the manufacturer.	
		(2)Check for serious rust development		○	Contact the manufacturer	
	Parts check: Aluminum electrolytic capacitor	(1)Check for liquid leakage in a capacitor and deformation trace		○	Contact the manufacturer	
		(2)Visual check and judge by the life check of the control circuit capacitor. *(Refer to page 334.)*		○		
Cooling system	Cooling fan	(1)Check for unusual vibration and noise.	○		Replace the fan	
		(2)Check for loose screws and bolts		○	Fix with the fan cover fixing screws	
		(3)Check for stain		○	Clean	
	Heatsink	(1)Check for clogging		○	Clean	
		(2)Check for stain		○	Clean	
	Air filter, etc.	(1)Check for clogging		○	Clean or replace	
		(2)Check for stain		○	Clean or replace	
Display	Indication	(1)Check that display is normal.	○		Contact the manufacturer	
		(2)Check for stain		○	Clean	
	Meter	Check that reading is normal	○		Stop the device and contact the manufacturer.	
Load motor	Operation check	Check for vibration and abnormal increase in operation noise	○		Stop the device and contact the manufacturer.	

*1 It is recommended to install a device to monitor voltage for checking the power supply voltage to the inverter.

*2 One to two years of periodic inspection cycle is recommended. However, it differs according to the installation environment. Consult us for periodic inspection.

6.1.4 Display of the life of the inverter parts

The self-diagnostic alarm is output when the life span of the control circuit capacitor, cooling fan, each parts of the inrush current limit circuit is near its end. It gives an indication of replacement time .

The life alarm output can be used as a guideline for life judgement.

Parts	Judgement level
Main circuit capacitor	85% of the initial capacity
Control circuit capacitor	Estimated 10% life remaining
Inrush current limit circuit	Estimated 10% life remaining (Power ON: 100,000 times left)
Cooling fan	Less than 50% of the predetermined speed

Refer to page 282 to perform the life check of the inverter parts.

6.1.5 Checking the inverter and converter modules

<Preparation>

(1) Disconnect the external power supply cables (R/L1, S/L2, T/L3) and motor cables (U, V, W).

(2) Prepare a tester. (Use 100Ω range.)

<Checking method>

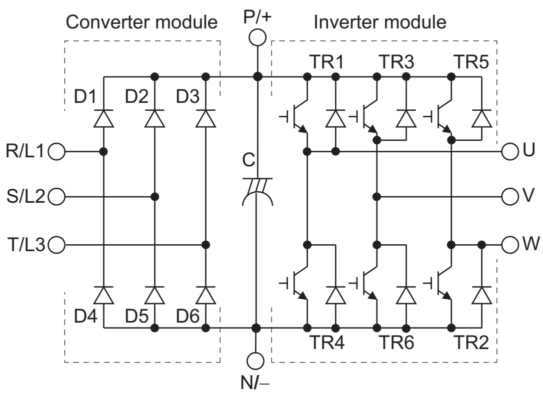
Change the polarity of the tester alternately at the inverter terminals R/L1, S/L2, T/L3, U, V, W, P/+ and N/–, and check for electric continuity.

CAUTION

1. Before measurement, check that the smoothing capacitor is discharged.
2. At the time of electric discontinuity, due to the smoothing capacitor, the tester may not indicate ∞. At the time of electric continuity, the measured value is several to several ten-of ohms depending on the module type, circuit tester type, etc. If all measured values are almost the same, the modules are without fault.

<Module device numbers and terminals to be checked>

		Tester Polarity		Measured Value		Tester Polarity		Measured Value
		⊕	⊖			⊕	⊖	
Converter module	D1	R/L1	P/+	Discontinuity	D4	R/L1	N/–	Continuity
		P/+	R/L1	Continuity		N/–	R/L1	Discontinuity
	D2	S/L2	P/+	Discontinuity	D5	S/L2	N/–	Continuity
		P/+	S/L2	Continuity		N/–	S/L2	Discontinuity
	D3	T/L3	P/+	Discontinuity	D6	T/L3	N/–	Continuity
		P/+	T/L3	Continuity		N/–	T/L3	Discontinuity
Inverter module	TR1	U	P/+	Discontinuity	TR4	U	N/–	Continuity
		P/+	U	Continuity		N/–	U	Discontinuity
	TR3	V	P/+	Discontinuity	TR6	V	N/–	Continuity
		P/+	V	Continuity		N/–	V	Discontinuity
	TR5	W	P/+	Discontinuity	TR2	W	N/–	Continuity
		P/+	W	Continuity		N/–	W	Discontinuity



(Assumes the use of an analog meter.)

6.1.6 Cleaning

Always run the inverter in a clean status.
When cleaning the inverter, gently wipe dirty areas with a soft cloth immersed in neutral detergent or ethanol.

CAUTION

Do not use solvent, such as acetone, benzene, toluene and alcohol, as they will cause the inverter surface paint to peel off.
The display, etc. of the operation panel (FR-DU07) and parameter unit (FR-PU04/FR-PU07) are vulnerable to detergent and alcohol. Therefore, avoid using them for cleaning.

6.1.7 Replacement of parts

The inverter consists of many electronic parts such as semiconductor devices.
The following parts may deteriorate with age because of their structures or physical characteristics, leading to reduced performance or fault of the inverter. For preventive maintenance, the parts must be replaced periodically.
Use the life check function as a guidance of parts replacement.

Part Name	Estimated lifespan *1	Description
Cooling fan	10 years	Replace (as required)
Main circuit smoothing capacitor	10 years *2	Replace (as required)
On-board smoothing capacitor	10 years	Replace the board (as required)
Relays	–	as required
Fuse (185K or higher)	10 years	Replace the fuse (as required)

*1 Estimated lifespan for when the yearly average surrounding air temperature is 40°C (without corrosive gas, flammable gas, oil mist, dust and dirt etc)
*2 Output current : 80% of the inverter rated current

CAUTION

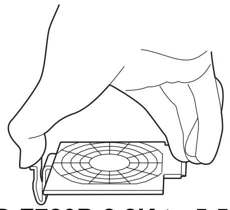
For parts replacement, consult the nearest Mitsubishi FA Center.

(1) Cooling fan

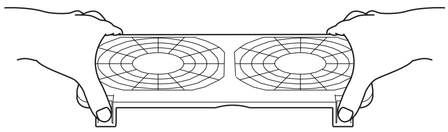
The replacement interval of the cooling fan used for cooling the parts generating heat such as the main circuit semiconductor is greatly affected by the surrounding air temperature. When unusual noise and/or vibration is noticed during inspection, the cooling fan must be replaced immediately.

• Removal (FR-F720P-2.2K to 110K, FR-F740P-3.7K to 160K)

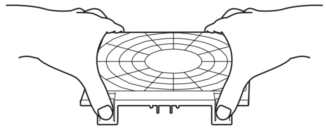
1) Push the hooks from above and remove the fan cover.



FR-F720P-2.2K to 5.5K
FR-F740P-3.7K, 5.5K

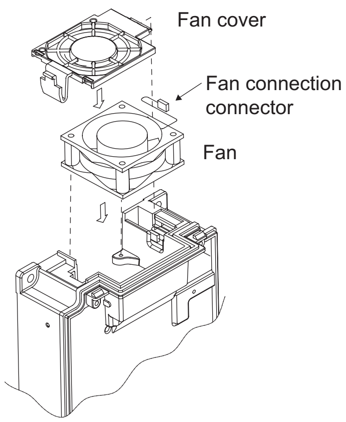


FR-F720P-7.5K to 30K
FR-F740P-7.5K to 30K

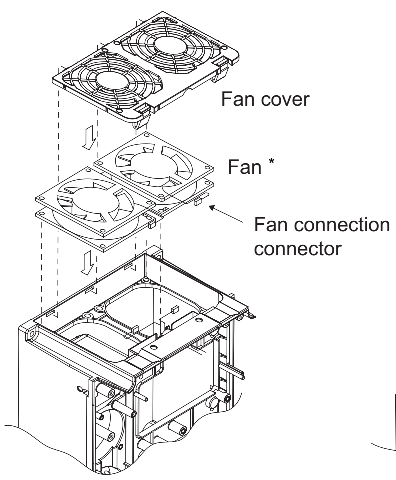


FR-F720P-37K or higher
FR-F740P-37K to 160K

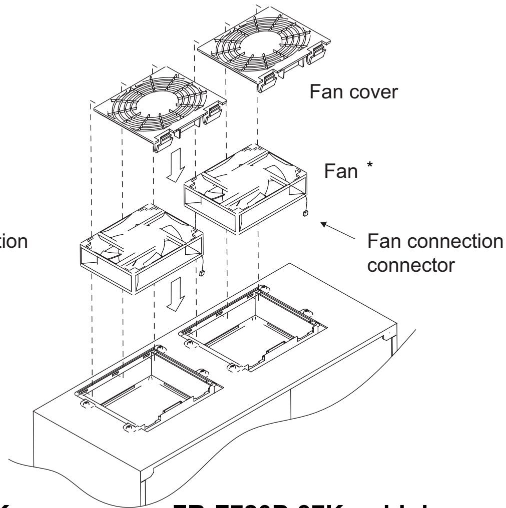
2) Disconnect the fan connectors.
3) Remove the fan.



FR-F720P-2.2K to 5.5K
FR-F740P-3.7K, 5.5K



FR-F720P-7.5K to 30K
FR-F740P-7.5K to 30K

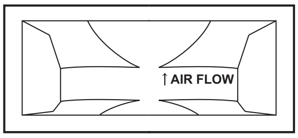


FR-F720P-37K or higher
FR-F740P-37K to 160K

* The number of cooling fans differs according to the inverter capacity.

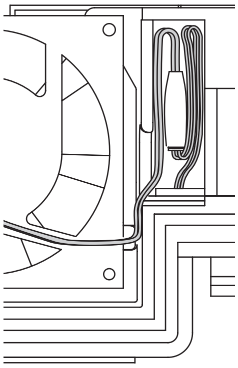
• Reinstallation (FR-F720P-2.2K to 110K, FR-F740P-3.7K to 160K)

1)After confirming the orientation of the fan, reinstall the fan so that the arrow on the left of "AIR FLOW" faces up.

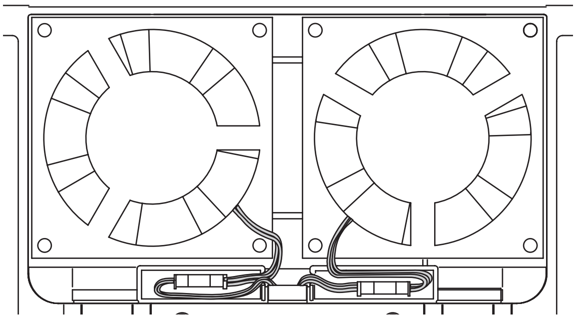


<Fan side face>

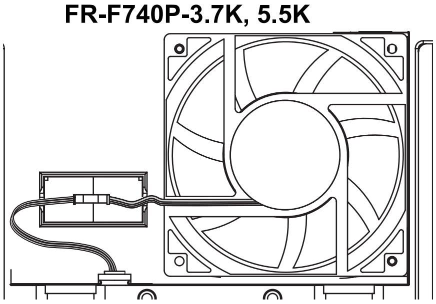
2)Reconnect the fan connectors.



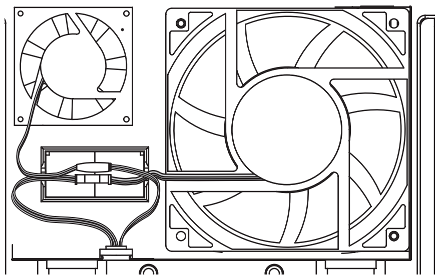
FR-F720P-2.2K to 5.5K
FR-F740P-3.7K, 5.5K



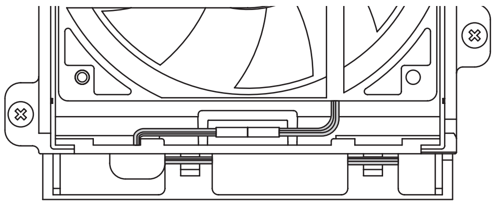
FR-F720P-7.5K to 15K
FR-F740P-7.5K to 18.5K



FR-F720P-18.5K, 22K
FR-F740P-22K, 30K

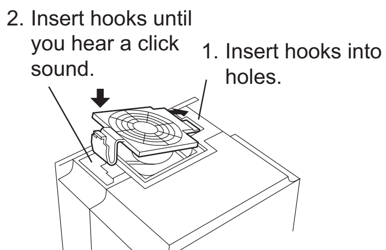


FR-F720P-30K

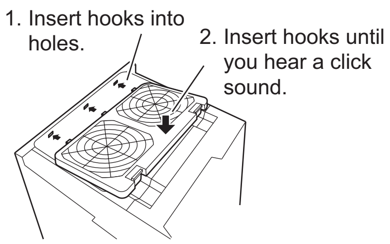


FR-F720P-37K to 110K
FR-F740P-37K to 160K

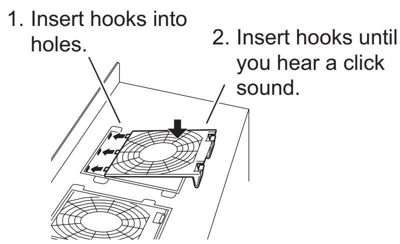
3)Reinstall the fan cover.



FR-F720P-2.2K to 5.5K
FR-F740P-3.7K, 5.5K



FR-F720P-7.5K to 30K
FR-F740P-7.5K to 30K

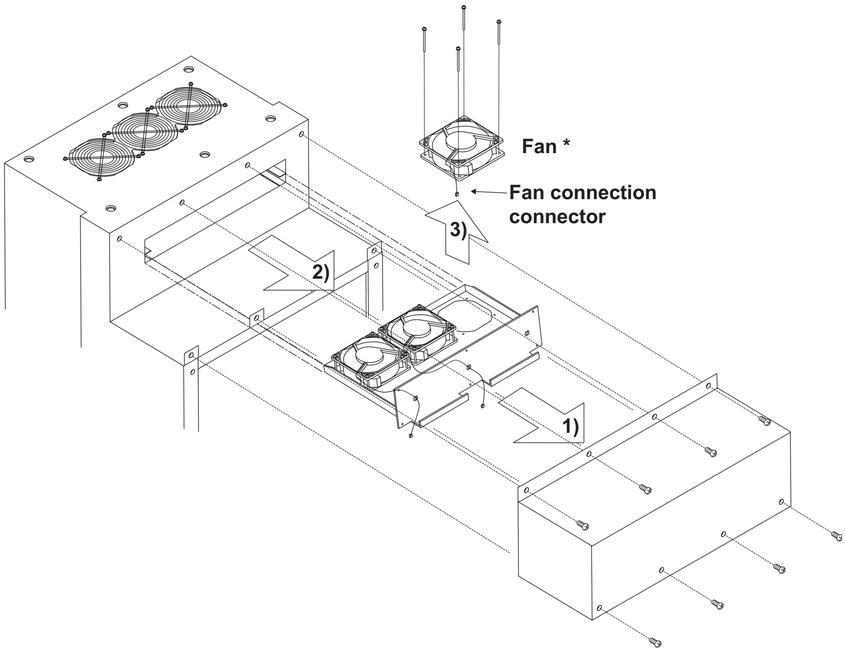


FR-F720P-37K to 110K
FR-F740P-37K to 160K

CAUTION

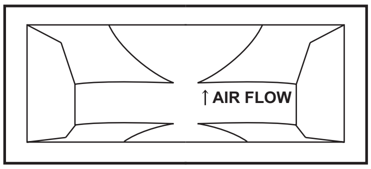
• Installing the fan in the opposite of air flow direction can cause the inverter life to be shorter.
• When installing the fan, use care to prevent wires from being caught between the inverter and fan.
• Switch the power OFF before replacing fans. Since the inverter circuits are charged with voltage even after power OFF, replace fans only when the inverter cover is on the inverter to prevent an electric shock accident.

• Removal (FR-F740P-185K or higher)
1) Remove a fan cover.
2) After removing a fan connector, remove a fan block.
3) Remove a fan. (Make sure to remove the fan cable from the clamp of the fan block beforehand.)



* The number of cooling fans differs according to the inverter capacity.

• Reinstallation (FR-F740P-185K or higher)
1) After confirming the orientation of the fan, reinstall the fan so that the arrow on the left of "AIR FLOW" faces up.



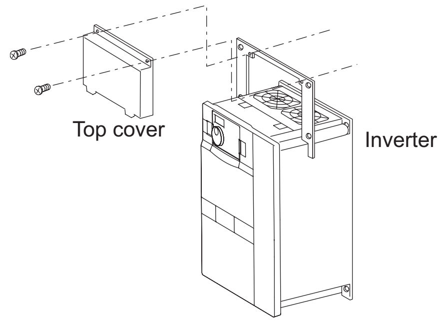
<Fan side face>

2) Install fans referring to the above figure.

CAUTION
- Installing the fan in the opposite of air flow direction can cause the inverter life to be shorter.
- When installing the fan, use care to prevent wires from being caught between the inverter and fan.
- Switch the power OFF before replacing fans. Since the inverter circuits are charged with voltage even after power OFF, replace fans only when the inverter cover is on the inverter to prevent an electric shock accident.

(2) Replacement procedure of the cooling fan when using a heatsink protrusion attachment (FR-A7CN)

When replacing a cooling fan, remove a top cover of the heatsink protrusion attachment and perform replacement. After replacing the cooling fan, replace the top cover in the original position.



(3) Smoothing capacitors

A large-capacity aluminum electrolytic capacitor is used for smoothing in the main circuit DC section, and an aluminum electrolytic capacitor is used for stabilizing the control power in the control circuit. Their characteristics are deteriorated by the adverse effects of ripple currents, etc.
The replacement intervals greatly vary with the surrounding air temperature and operating conditions. When the inverter is operated in air-conditioned, normal environment conditions, replace the capacitors about every 10 years.
The appearance criteria for inspection are as follows:
1) Case: Check the side and bottom faces for expansion
2) Sealing plate: Check for remarkable warp and extreme crack.
3) Check for external crack, discoloration, fluid leakage, etc. Judge that the capacitor has reached its life when the measured capacitance of the capacitor reduced below 80% of the rating.

Refer to page 335 to perform the life check of the main circuit capacitor.

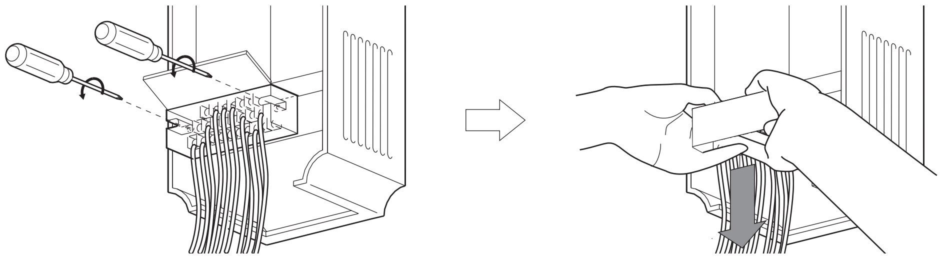
(4) Relays

To prevent a contact fault, etc., relays must be replaced according to the cumulative number of switching times (switching life).

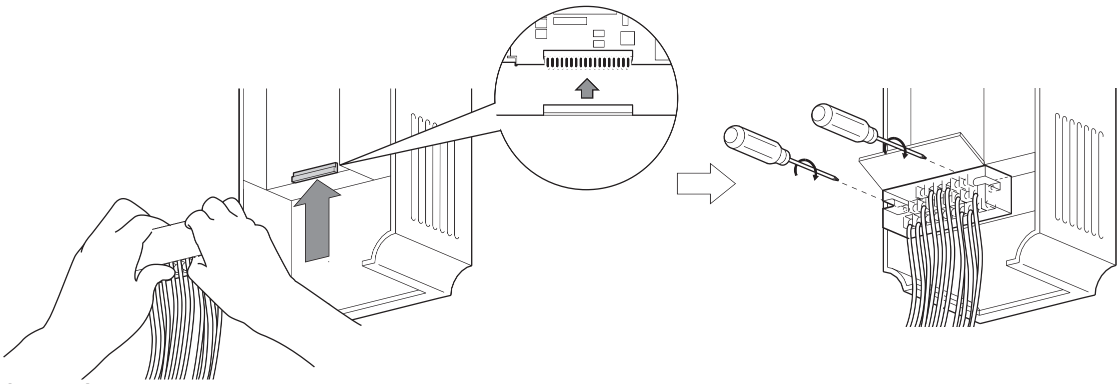
6.1.8 Inverter replacement

The inverter can be replaced with the control circuit wiring kept connected. Before replacement, remove the wiring cover of the inverter.

1) Loosen the two installation screws in both ends of the control circuit terminal block. (These screws cannot be removed.) Pull down the terminal block from behind the control circuit terminals.



2) Using care not to bend the pins of the inverter's control circuit connector, reinstall the control circuit terminal block and fix it with the mounting screws.



CAUTION

Before starting inverter replacement, switch power OFF, wait for at least 10 minutes, and then check the voltage with a tester and such to ensure safety.

PRECAUTIONS FOR MAINTENANCE AND INSPECTION

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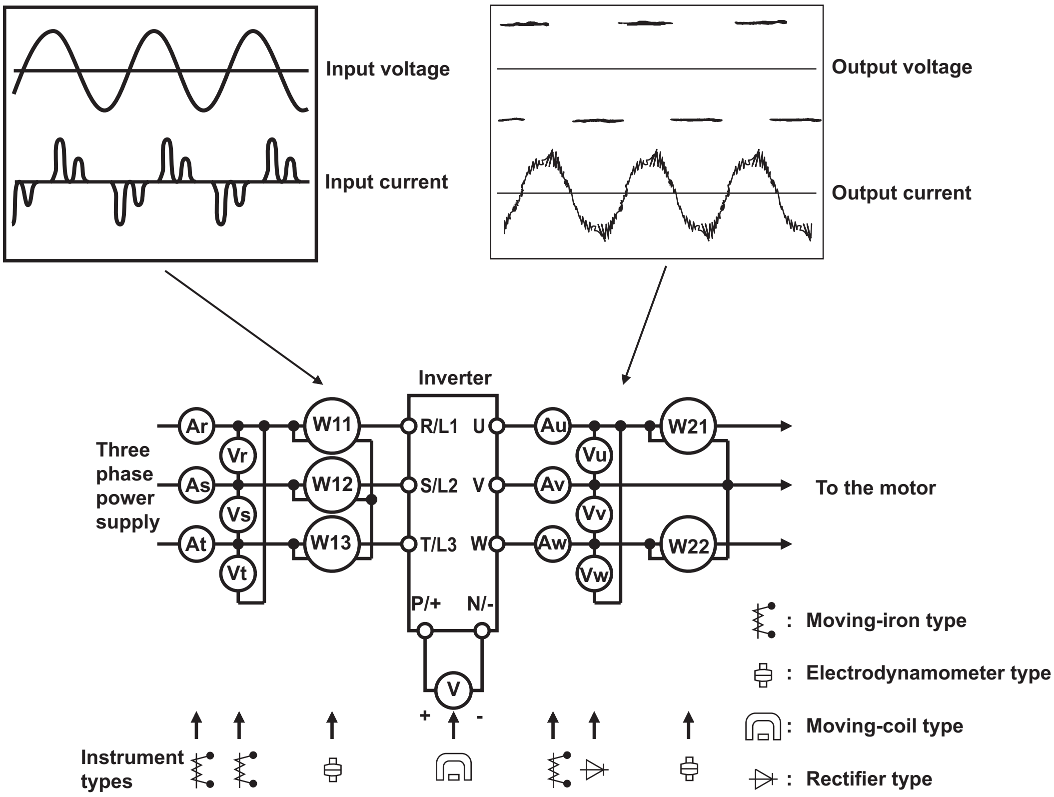
6.2 Measurement of main circuit voltages, currents and powers

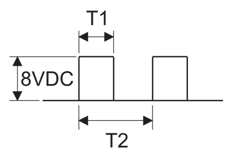
Since the voltages and currents on the inverter power supply and output sides include harmonics, measurement data depends on the instruments used and circuits measured.
When instruments for commercial frequency are used for measurement, measure the following circuits with the instruments given on the next page.

- When installing meters etc. on the inverter output side
  When the inverter-to-motor wiring length is large, especially in the 400V class, small-capacity models, the meters and CTs may generate heat due to line-to-line leakage current. Therefore, choose the equipment which has enough allowance for the current rating.
  When measuring and indicating the output voltage and output current of the inverter, it is recommended to utilize the AM and FM terminal output function of the inverter.



Examples of Measuring Points and Instruments

Measuring Points and Instruments

Item	Measuring Point	Measuring Instrument	Remarks (Reference Measured Value)	
Power supply voltage V_1	Across R/L1 and S/L2, S/L2 and T/L3, T/L3 and R/L1	Moving-iron type AC voltmeter *4	Commercial power supply Within permissible AC voltage fluctuation Refer to *page 346*.	
Power supply side current I_1	R/L1, S/L2, and T/L3 line currents	Moving-iron type AC ammeter *4		
Power supply side power P_1	R/L1, S/L2, T/L3 and R/L1 and S/L2, S/L2 and T/L3, T/L3 and R/L1	Digital power meter (designed for inverter) or electrodynamic type single-phase wattmeter	$P_1=W_{11}+W_{12}+W_{13}$ (3-wattmeter method)	
Power supply side power factor Pf_1	Calculate after measuring power supply voltage, power supply side current and power supply side power. $Pf_1 = \frac{P_1}{\sqrt{3}\,V_1 \times I_1} \times 100\%$			
Output side voltage V_2	Across U and V, V and W and W and U	Rectifier type AC voltage meter *1 *4 (Moving-iron type cannot measure)	Difference between the phases is within ±1% of the maximum output voltage.	
Output side current I_2	U, V and W line currents	Moving-iron type AC ammeter *2 *4	Difference between the phases is 10% or lower of the rated inverter current.	
Output side power P_2	U, V, W and U and V, V and W	Digital power meter (designed for inverter) or electrodynamic type single-phase wattmeter	$P_2 = W_{21} + W_{22}$ 2-wattmeter method (or 3-wattmeter method)	
Output side power factor Pf_2	Calculate in similar manner to power supply side power factor. $Pf_2 = \frac{P_2}{\sqrt{3}\,V_2 \times I_2} \times 100\%$			
Converter output	Across P/+ and N/−	Moving-coil type (such as tester)	Inverter LED display is lit. 1.35 × V1	
Frequency setting signal	Across 2 and 5 Across 4(+) and 5	Moving-coil type (Tester and such may be used) (Internal resistance: 50kΩ or larger)	0 to 10VDC, 4 to 20mA	"5" is common
	Across 1(+) and 5		0 to ±5VDC, 0 to ±10VDC	
Frequency setting power supply	Across 10 (+) and 5		5.2VDC	
	Across 10E(+) and 5		10VDC	
Frequency meter signal	Across AM(+) and 5		Approximately 10VDC at maximum frequency (without frequency meter)	
	Across FM(+) and SD		Approximately 5VDC at maximum frequency (without frequency meter)  Pulse width T1: Adjusted by *C0 (Pr. 900)* Pulse cycle T2: Set by *Pr. 55* (Valid for frequency monitoring only)	"SD" is common
Start signal Select signal	Across SD and the following: STF, STR, RH, RM, RL, JOG, RT, AU, STOP, CS (+)		When open 20 to 30VDC ON voltage: 1V or less	
Reset	Across RES (+) and SD			
Output stop	Across MRS (+) and SD			
Fault signal	Across A1 and C1 Across B1 and C1	Moving-coil type (such as tester)	Electric continuity check*3 <Normal> <Fault> Across A1 and C1: Discontinuity / Continuity Across B1 and C1: Continuity / Discontinuity	

*1 Use an FFT to measure the output voltage accurately. A tester or general measuring instrument cannot measure accurately.
*2 When the carrier frequency exceeds 5kHz, do not use this instrument since using it may increase eddy-current losses produced in metal parts inside the instrument, leading to burnout. If the wiring length between the inverter and motor is long, the instrument and CT may generate heat due to line-to-line leakage current.
*3 When the setting of *Pr. 195 ABC1 terminal function selection* is positive logic
*4 A digital power meter (designed for inverter) can also be used to measure.

PRECAUTIONS FOR MAINTENANCE AND INSPECTION

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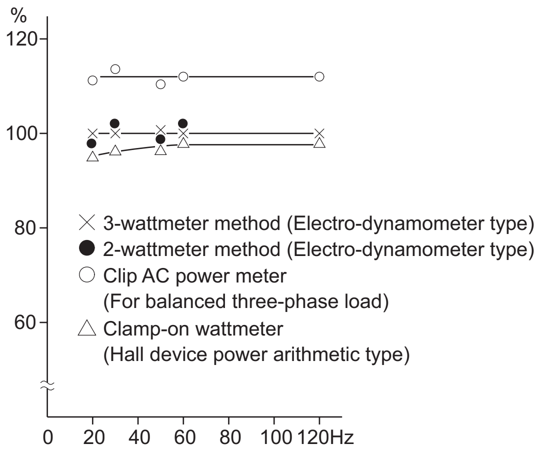
6.2.1 Measurement of powers

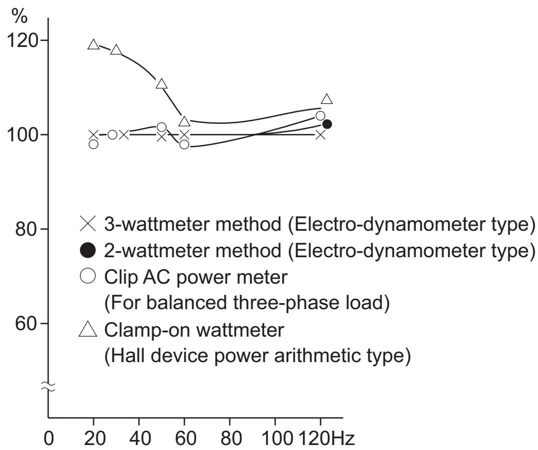
Use digital power meters (for inverter) for the both of inverter input and output side. Alternatively, measure using electrodynamic type single-phase wattmeters for the both of inverter input and output side in two-wattmeter or three-wattmeter method. As the current is liable to be imbalanced especially in the input side, it is recommended to use the three-wattmeter method.
Examples of measured value differences produced by different measuring meters are shown below.
An error will be produced by difference between measuring instruments, e.g. power calculation type and two- or three-wattmeter type three-phase wattmeter. When a CT is used in the current measuring side or when the meter contains a PT on the voltage measurement side, an error will also be produced due to the frequency characteristics of the CT and PT.

[Measurement conditions]
Constant-torque (100%) load, constant-power at 60Hz or more.
3.7kW, 4-pole motor, value indicated in 3-wattmeter method is 100%.



Example of measuring inverter input power

[Measurement conditions]
Constant-torque (100%) load, constant-power at 60Hz or more.
3.7kW, 4-pole motor, value indicated in 3-wattmeter method is 100%.



Example of measuring inverter output power

6.2.2 Measurement of voltages and use of PT

(1) Inverter input side

As the input side voltage has a sine wave and it is extremely small in distortion, accurate measurement can be made with an ordinary AC meter.

(2) Inverter output side

Since the output side voltage has a PWM-controlled rectangular wave, always use a rectifier type voltmeter. A needle type tester cannot be used to measure the output side voltage as it indicates a value much greater than the actual value. A moving-iron type meter indicates an effective value which includes harmonics and therefore the value is larger than that of the fundamental wave. The value monitored on the operation panel is the inverter controlled voltage itself. Hence, that value is accurate and it is recommended to monitor values (provide analog output) using the operation panel.

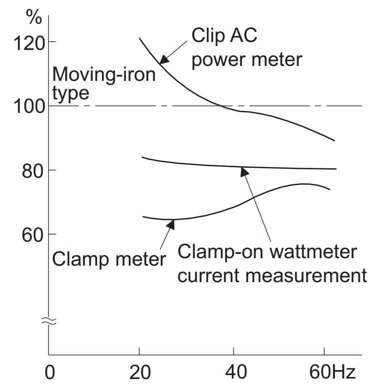
(3) PT

No PT can be used in the output side of the inverter. Use a direct-reading meter. (A PT can be used in the input side of the inverter.)

6.2.3 Measurement of currents

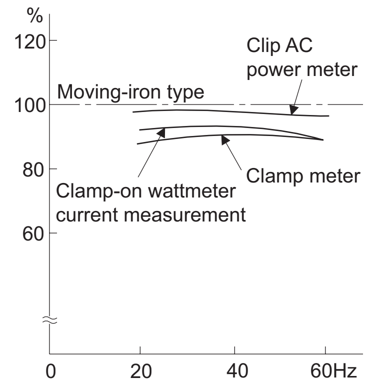
Use moving-iron type meters on both the input and output sides of the inverter. However, if the carrier frequency exceeds 5kHz, do not use that meter since an overcurrent losses produced in the internal metal parts of the meter will increase and the meter may burn out. In this case, use an approximate-effective value type.
As the inverter input side current is easily imbalanced, measurement of currents in all three phases is recommended. Correct values cannot be measured in one or two phases. On the other hand, the phase imbalanced ratio of the output side current must be within 10%.
When a clamp ammeter is used, always use an effective value detection type. A mean value detection type produces a large error and may indicate an extremely smaller value than the actual value. The value monitored on the operation panel is accurate if the output frequency varies, and it is recommended to monitor values (provide analog output) using the operation panel.
An example of the measured value difference produced by different measuring meters is shown below.

[Measurement conditions]
Value indicated by moving-iron type ammeter is 100%.



Example of measuring Inverter Input Current

[Measurement conditions]
Value indicated by moving-iron type ammeter is 100%.



Example of measuring Inverter Output Current

6.2.4 Use of CT and transducer

A CT may be used in both the input and output sides of the inverter, but the one used should have the largest possible VA ability because an error will increase if the frequency gets lower.
When using a transducer, use the effective value calculation type which is immune to harmonics.

6.2.5 Measurement of inverter input power factor

Use the effective power and apparent power to calculate the inverter input power factor. A power-factor meter cannot indicate an exact value.

$$\text{Total power factor of the inverter} = \frac{\text{Effective power}}{\text{Apparent power}}$$

$$= \frac{\text{Three-phase input power found by 3-wattmeter method}}{\sqrt{3} \times \text{V (power supply voltage)} \times \text{I (input current effective value)}}$$

6.2.6 Measurement of converter output voltage (across terminals P/+ and N/-)

The output voltage of the converter is developed across terminals P/+ and N/- and can be measured with a moving-coil type meter (tester). Although the voltage varies according to the power supply voltage, approximately 270V to 300V (approximately 540V to 600V for the 400V class) is output when no load is connected and voltage decreases when a load is connected.
When regenerative energy is returned from the motor during deceleration, for example, the converter output voltage rises to nearly 400V to 450V (800V to 900V for the 400V class) maximum.

6.2.7 Measurement of inverter output frequency

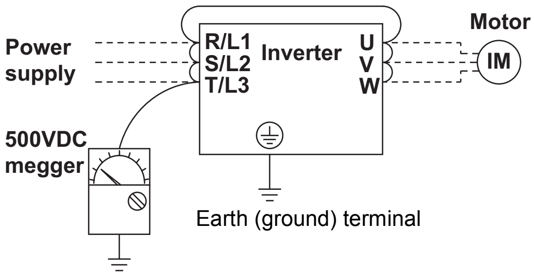
A pulse train proportional to the output frequency is output across the frequency meter signal output terminal FM and SD of the inverter. This pulse train output can be counted by a frequency counter, or a meter (moving-coil type voltmeter) can be used to read the mean value of the pulse train output voltage. When a meter is used to measure the output frequency, approximately 5VDC is indicated at the maximum frequency.
For detailed specifications of the frequency meter signal output terminal FM, refer to *page 159*.

6.2.8 Insulation resistance test using megger

For the inverter, conduct the insulation resistance test on the main circuit only as shown below and do not perform the test on the control circuit. (Use a 500VDC megger.)

CAUTION

- Before performing the insulation resistance test on the external circuit, disconnect the cables from all terminals of the inverter so that the test voltage is not applied to the inverter.
- For the electric continuity test of the control circuit, use a tester (high resistance range) and do not use the megger or buzzer.



6.2.9 Pressure test

Do not conduct a pressure test. Deterioration may occur.

7 SPECIFICATIONS

This chapter provides the "SPECIFICATIONS" of this product.
Always read the instructions before using the equipment.

7.1 Rating

•200V class

Type FR-F720P-□□K			0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110
Applicable motor capacity (kW)*1			0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110
Output	Rated capacity (kVA)*2		1.6	2.7	3.7	5.8	8.8	11.8	17.1	22.1	27	32	43	53	65	81	110	132	165
Output	Rated current (A)*3		4.2 (3.6)	7.0 (6.0)	9.6 (8.2)	15.2 (13)	23 (20)	31 (26)	45 (38)	58 (49)	70.5 (60)	85 (72)	114 (97)	140 (119)	170 (145)	212 (180)	288 (244)	346 (294)	432 (367)
Output	Overload current rating*4		120% for 60s, 150% for 3s (inverse-time characteristics)																
Output	Rated voltage*5		Three-phase 200 to 240V																
Power supply	Rated input AC voltage/frequency		Three-phase 200 to 220V 50Hz, 200 to 240V 60Hz																
Power supply	Permissible AC voltage fluctuation		170 to 242V 50Hz, 170 to 264V 60Hz																
Power supply	Permissible frequency fluctuation		±5%																
Power supply	Power supply system capacity (kVA)*6	Without DC reactor	2.1	4.0	4.8	8.0	11.5	16	20	27	32	41	52	65	79	99	-	-	-
Power supply	Power supply system capacity (kVA)*6	With DC reactor	1.2	2.6	3.3	5.0	8.1	10	16	19	24	31	41	50	61	74	110	132	165
Protective structure (JEM 1030)*8			Enclosed type (IP20)*7										Open type (IP00)						
Cooling system			Self-cooling		Forced air cooling														
Approx. mass (kg)			1.8	2.2	3.5	3.5	3.5	6.5	6.5	7.8	13	13	14	23	35	35	67	70	70

*1 The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor. To use a dedicated IPM motor, *refer to page 359 and 360.*
*2 The rated output capacity indicated assumes that the output voltage is 220V.
*3 When operating the inverter with the carrier frequency set to 3kHz or more, the carrier frequency automatically decreases if the inverter output current exceeds the value in parenthesis of the rated current. This may cause the motor noise to increase.
*4 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.
*5 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the pulse voltage value of the inverter output side voltage remains unchanged at about $\sqrt{2}$ that of the power supply.
*6 The power supply capacity varies with the value of the power supply side inverter impedance (including those of the input reactor and cables).
*7 When the hook of the inverter front cover is cut off for installation of the plug-in option, the inverter changes to an open type (IP00).
*8 FR-DU07: IP40 (except for the PU connector)

•400V class

Type FR-F740P-□□K			0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
Applicable motor capacity (kW)*1			0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
Output	Rated capacity (kVA)*2		1.6	2.7	3.7	5.8	8.8	12.2	17.5	22.1	26.7	32.8	43.4	53.3	64.8	80.8
	Rated current (A)*3		2.1 (1.8)	3.5 (3.0)	4.8 (4.1)	7.6 (6.4)	11.5 (9.8)	16 (13)	23 (19)	29 (24)	35 (30)	43 (36)	57 (48)	70 (60)	85 (72)	106 (90)
	Overload current rating*4		120% 60s, 150% 3s (inverse-time characteristics)													
	Rated voltage*5		Three-phase 380 to 480V													
Power supply	Rated input AC voltage/ frequency		Three-phase 380 to 480V 50Hz/60Hz													
	Permissible AC voltage fluctuation		323 to 528V 50Hz/60Hz													
	Permissible frequency fluctuation		±5%													
	Power supply system capacity (kVA)*6	Without DC reactor	2.1	4.0	4.8	8.0	11.5	16	20	27	32	41	52	65	79	99
		With DC reactor	1.2	2.6	3.3	5.0	8.1	10	16	19	24	31	41	50	61	74
Protective structure (JEM 1030)*8			Enclosed type (IP20)*7											Open type (IP00)		
Cooling system			Self-cooling			Forced air cooling										
Approx. mass (kg)			3.5	3.5	3.5	3.5	3.5	6.5	6.5	7.5	7.5	13	13	23	35	35

Type FR-F740P-□□K			75	90	110	132	160	185	220	250	280	315	355	400	450	500	560
Applicable motor capacity (kW)*1			75	90	110	132	160	185	220	250	280	315	355	400	450	500	560
Output	Rated capacity (kVA)*2		110	137	165	198	247	275	329	366	416	464	520	586	659	733	833
	Rated current (A)*3		144 (122)	180 (153)	216 (183)	260 (221)	325 (276)	361 (306)	432 (367)	481 (408)	547 (464)	610 (518)	683 (580)	770 (654)	866 (736)	962 (817)	1094 (929)
	Overload current rating*4		120% 60s, 150% 3s (inverse-time characteristics)														
	Rated voltage*5		Three-phase 380 to 480V														
Power supply	Rated input AC voltage/ frequency		Three-phase 380 to 480V 50Hz/60Hz														
	Permissible AC voltage fluctuation		323 to 528V 50Hz/60Hz														
	Permissible frequency fluctuation		±5%														
	Power supply system capacity (kVA)*6	Without DC reactor	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
		With DC reactor	110	137	165	198	247	275	329	366	416	464	520	586	659	733	833
Protective structure (JEM 1030)*8			Open type (IP00)														
Cooling system			Forced air cooling														
Approx. mass (kg)			37	50	57	72	72	110	110	175	175	175	260	260	370	370	370

*1 The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor. To use a dedicated IPM motor, *refer to page 359 and 360*.

*2 The rated output capacity indicated assumes that the output voltage is 440V.

*3 When operating the inverter with the carrier frequency set to 3kHz or more, the carrier frequency automatically decreases if the inverter output current exceeds the value in parenthesis of the rated current. This may cause the motor noise to increase.

*4 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

*5 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the pulse voltage value of the inverter output side voltage remains unchanged at about $\sqrt{2}$ that of the power supply.

*6 The power supply capacity varies with the value of the power supply side inverter impedance (including those of the input reactor and cables).

*7 When the hook of the inverter front cover is cut off for installation of the plug-in option, protective structure of the inverter changes to an open type (IP00).

*8 FR-DU07: IP40 (except for the PU connector)

7.2 Common specifications

Control specifications	Control method		High carrier frequency PWM control (V/F control)/Optimum excitation control/Simple magnetic flux vector control/IPM motor control
Control specifications	Output frequency range		0.5 to 400Hz
Control specifications	Frequency setting resolution	Analog input	0.015Hz/60Hz (terminal 2 and 4: 0 to 10V/12-bit) 0.03Hz/60Hz (terminal 2 and 4: 0 to 5V/11bit, 0 to 20mA/approx.11-bit, terminal 1: 0 to ±10V/12-bit) 0.06Hz/60Hz (terminal 1: 0 to ±5V/11-bit)
Control specifications	Frequency setting resolution	Digital input	0.01Hz
Control specifications	Frequency accuracy	Analog input	Within ±0.2% of the maximum output frequency (25°C ±10°C)
Control specifications	Frequency accuracy	Digital input	Within 0.01% of the set output frequency
Control specifications	Speed control range		1:10 under V/F control, 1:15 under Simple magnetic flux vector control, 1:10 under IPM motor control
Control specifications	Voltage/frequency characteristics		Base frequency can be set from 0 to 400Hz. Constant-torque/variable-torque pattern or adjustable 5 points V/F can be selected.
Control specifications	Starting torque	General-purpose motor control	Under Simple magnetic flux vector control and slip compensation: 120% (at 3Hz)
Control specifications	Starting torque	IPM motor control	50%
Control specifications	Acceleration/deceleration time setting		0 to 3600s (acceleration and deceleration can be set individually), linear or S-pattern acceleration/deceleration modes are available.
Control specifications	DC injection brake		General-purpose motor control: Operation frequency (0 to 120Hz), operation time (0 to 10s), operation voltage (0 to 30%) can be changed.
Control specifications	Stall prevention operation level		Operation current level can be set (0 to 150% variable). Whether to use the function or not can be set.
Operation specifications	Frequency setting signal	Analog input	Terminal 2 and 4: 0 to 10V, 0 to 5V, and 4 to 20mA are available. Terminal 1: -10 to +10V and -5 to 5V are available.
Operation specifications	Frequency setting signal	Digital input	4-digit BCD or 16-bit binary using the setting dial of the operation panel or parameter unit (when used with the option FR-A7AX)
Operation specifications	Start signal		Forward and reverse rotation or start signal automatic self-holding input (3-wire input) can be selected.
Operation specifications	Input signals (twelve terminals)		The following signals can be assigned to *Pr. 178 to Pr.189 (input terminal function selection)*: multi-speed selection, remote setting, second function selection, terminal 4 input selection, JOG operation selection, automatic restart after instantaneous power failure/flying start, external thermal relay input, inverter run enable signal (FR-HC/FR-CV connection), FR-HC connection (instantaneous power failure detection), PU operation external interlock signal, PID control enable terminal, PU-External operation switchover, output stop, start self-holding selection, forward rotation command, reverse rotation command, inverter reset, PTC thermistor input, PID forward/reverse action switchover, PU/NET operation switchover, External/NET operation switchover, command source switchover, DC feeding operation permission, DC feeding cancel, and PID integral value reset.
Operation specifications	Operational functions		Maximum and minimum frequency settings, frequency jump operation, external thermal relay input selection, polarity reversible operation, automatic restart after instantaneous power failure operation, original operation continuation at an instantaneous power failure, electronic bypass operation, forward/reverse rotation prevention, remote setting, second and third function, multi-speed setting, regenerative avoidance, slip compensation, operation mode selection, PID control, and computer link operation (RS-485)
Operation specifications	Output signal Open collector output (five terminals) Relay output (two terminals)	Operating status	The following signals can be assigned to *Pr.190 to Pr.196 (output terminal function selection)*: inverter running, up to frequency, instantaneous power failure/undervoltage, overload warning, output frequency detection, second output frequency detection, regenerative brake prealarm*1, electronic thermal relay function pre-alarm, PU operation mode, inverter operation ready, output current detection, zero current detection, PID lower limit, PID upper limit, PID forward/reverse rotation output, electronic bypass MC1*2, electronic bypass MC2*2, electronic bypass MC3*2, fan fault output, heatsink overheat pre-alarm, inverter running start command is ON, during deceleration at occurrence of power failure, during PID control activated, PID deviation limit, IPM motor control*6, during retry, PID output interruption, pulse train output of output power, DC feeding, life alarm, fault output 3 (power-off signal), energy saving average value updated timing, current average value monitor, fault output 2, maintenance timer alarm, remote output, alarm output, and fault output. Fault code of the inverter can be output (4-bit) from the open collector.
Operation specifications	Output signal	Operating status: When used with the FR-A7AY, FR-A7AR (option)	In addition to above, the following signals can be assigned to *Pr.313 to Pr.319 (extension output terminal function selection)*: control circuit capacitor life, main circuit capacitor life, cooling fan life, and inrush current limit circuit life. (Only positive logic can be set to the extension terminals of FR-A7AR.)
Operation specifications	Output signal	For meter Pulse train output (Max. 2.4kHz: one terminal) Analog output (Max. 10VDC: one terminal)	The following signals can be assigned to *Pr.54 FM terminal function selection(pulse train output) and Pr. 158 AM terminal function selection (analog output)*: output frequency, motor current (steady or peak value), output voltage, frequency setting value, running speed, converter output voltage (steady or peak value), electronic thermal relay load factor, input power, output power, load meter, reference voltage output, motor load factor, energy saving effect, regenerative brake duty*1, PID set point, and PID measured value.
Indication	Operation panel (FR-DU07) Parameter unit (FR-PU07)	Operating status	Output frequency, motor current (steady or peak value), output voltage, fault display, frequency setting value, running speed, converter output voltage (steady or peak value), electronic thermal relay load factor, input power, output power, load meter, cumulative energization time, actual operation time, motor load factor, cumulative power, energy saving effect, cumulative energy savings, regenerative brake duty*1, PID set point, PID measured value, PID deviation, inverter I/O terminal monitor, input terminal option monitor*3, output terminal option monitor*3, option fitting status monitor*4, and terminal assignment status*4.
Indication	Operation panel (FR-DU07) Parameter unit (FR-PU07)	Fault record	Fault record is displayed when a fault occurs. Past 8 fault records (output voltage/current/frequency/cumulative energization time right before the fault occurs) are stored.
Indication	Operation panel (FR-DU07) Parameter unit (FR-PU07)	Interactive guidance	Function (help) for operation guide and troubleshooting*4

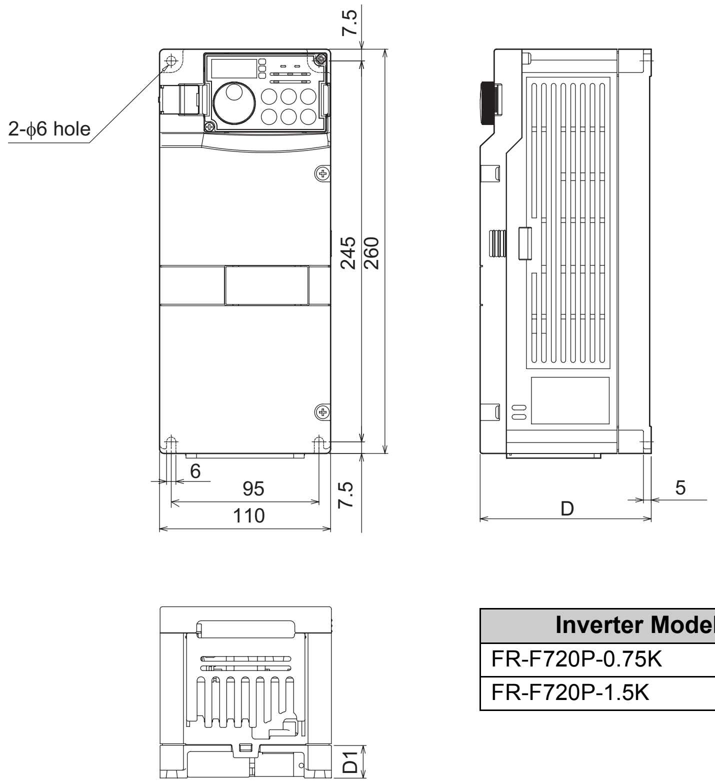
Protective/ warning function		Protective function	Overcurrent during acceleration, overcurrent during constant speed, overcurrent during deceleration/stop, overvoltage during acceleration, overvoltage during constant speed, overvoltage during deceleration/stop, inverter protection thermal operation, motor protection thermal operation, heatsink overheat, instantaneous power failure occurrence, undervoltage, input phase loss*5, stall prevention stop, output side earth (ground) fault overcurrent, output phase loss, external thermal relay operation*5, PTC thermistor operation*5, option fault, parameter error, PU disconnection*5, retry count excess*5, CPU fault, operation panel power supply short circuit, 24VDC power output short circuit, output current detection value excess*5, inrush current limit circuit fault, communication fault (inverter), analog input fault, PID signal fault*5, internal circuit fault (15V power supply), brake transistor alarm detection*1, loss of synchronism detection*6.
		Warning function	Fan alarm, overcurrent stall prevention, overvoltage stall prevention, regenerative brake prealarm*5, electronic thermal relay function prealarm, PU stop, maintenance timer alarm*3*5, parameter write error, copy operation error, operation panel lock, parameter copy warning, password locked *5
Environment	Surrounding air temperature		-10×C to +50×C (non-freezing)
	Ambient humidity		90% RH or less (non-condensing)
	Storage temperature*7		-20°C to 65°C
	Atmosphere		Indoors (without corrosive gas, flammable gas, oil mist, dust and dirt etc.)
	Altitude/vibration		Maximum 1000m above sea level, 5.9m/s ^{2} or less *8 at 10 to 55Hz (directions of X, Y, Z axes)

*1 This function is only available for 75K or higher.
*2 This function is only available under general-purpose motor control.
*3 This can be displayed only on the operation panel (FR-DU07).
*4 This can be displayed only on the option parameter unit (FR-PU07).
*5 This protective function is not available in the initial status.
*6 This function is available only when an IPM motor is connected.
*7 Temperature applicable for a short time, e.g. in transit.
*8 2.9m/s^2 or less for 185K or higher.

7.3 Outline dimension drawings

7.3.1 Inverter outline dimension drawings

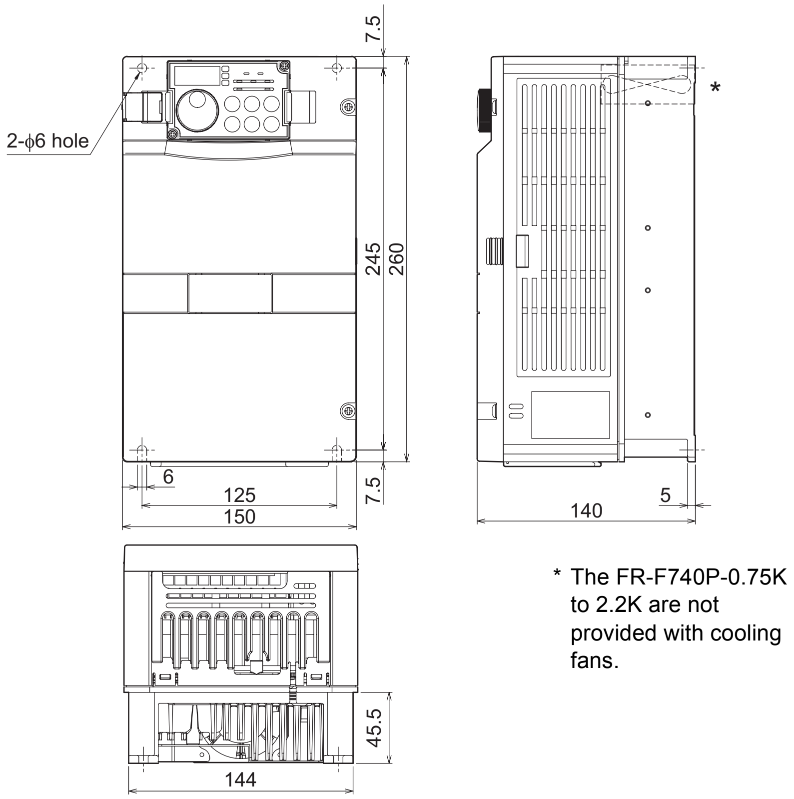
- **FR-F720P-0.75K, 1.5K**



Inverter Model	D	D1
FR-F720P-0.75K	110	21
FR-F720P-1.5K	125	36

(Unit: mm)

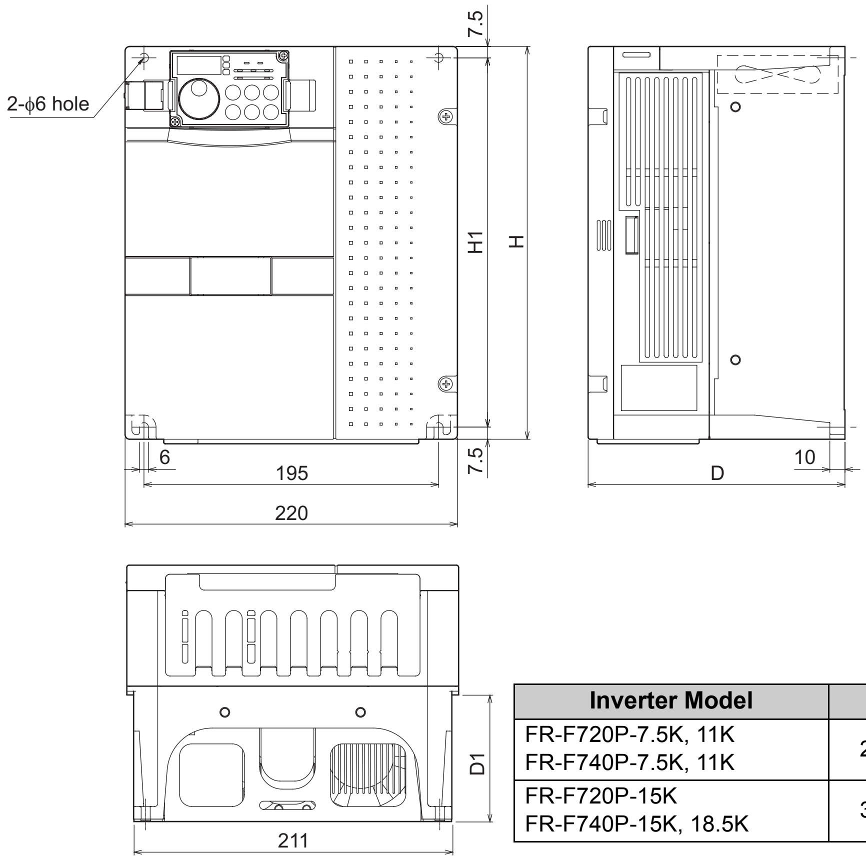
- **FR-F720P-2.2K, 3.7K, 5.5K**
- **FR-F740P-0.75K, 1.5K, 2.2K, 3.7K, 5.5K**



* The FR-F740P-0.75K to 2.2K are not provided with cooling fans.

(Unit: mm)

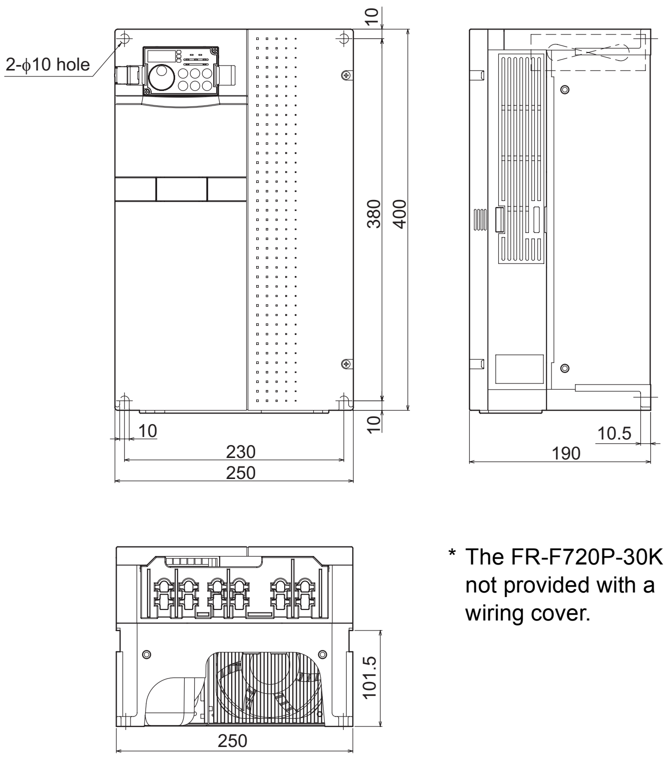
- **FR-F720P-7.5K, 11K, 15K**
- **FR-F740P-7.5K, 11K, 15K, 18.5K**



Inverter Model	H	H1	D	D1
FR-F720P-7.5K, 11K FR-F740P-7.5K, 11K	260	245	170	84
FR-F720P-15K FR-F740P-15K, 18.5K	300	285	190	101.5

(Unit: mm)

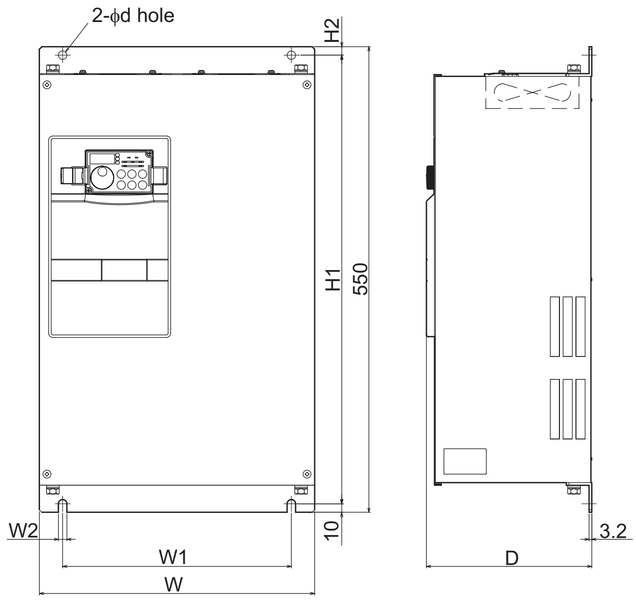
- **FR-F720P-18.5K, 22K, 30K**
- **FR-F740P-22K, 30K**



* The FR-F720P-30K is not provided with a wiring cover.

(Unit: mm)

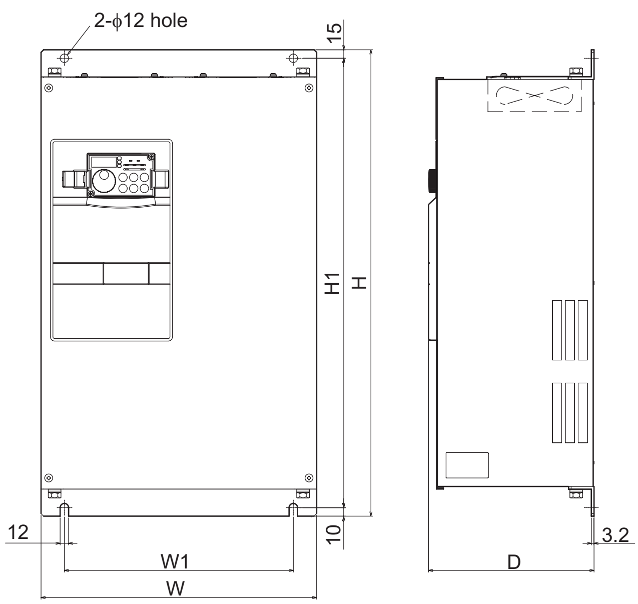
- **FR-F720P-37K, 45K, 55K**
- **FR-F740P-37K, 45K, 55K**



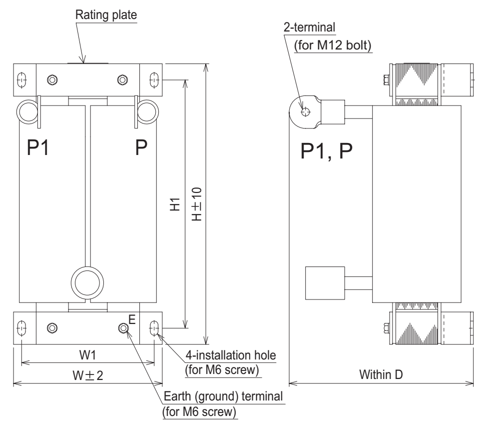
Inverter Model	W	W1	W2	H1	H2	d	D
FR-F720P-37K FR-F740P-37K	325	270	10	530	10	10	195
FR-F720P-45K, 55K FR-F740P-45K, 55K	435	380	12	525	15	12	250

(Unit: mm)

- **FR-F740P-75K, 90K**



- **DC reactor supplied**

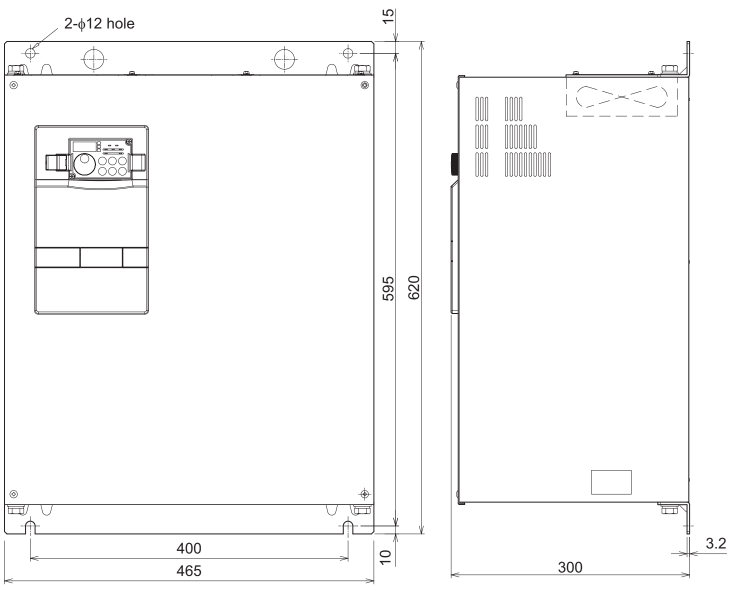


Inverter Model	W	W1	H	H1	D
FR-F740P-75K	435	380	550	525	250
FR-F740P-90K	465	400	620	595	300

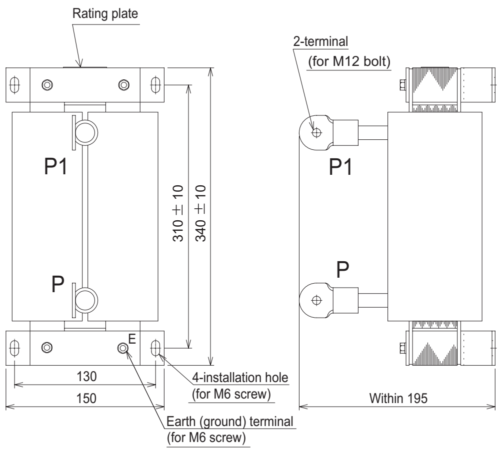
DC reactor Model	W	W1	H	H1	D	Mass (kg)
FR-HEL-H75K (FR-F740P-75K)	140	120	320	295	185	16
FR-HEL-H90K (FR-F740P-90K)	150	130	340	310	190	20

(Unit: mm)

- **FR-F740P-110K**



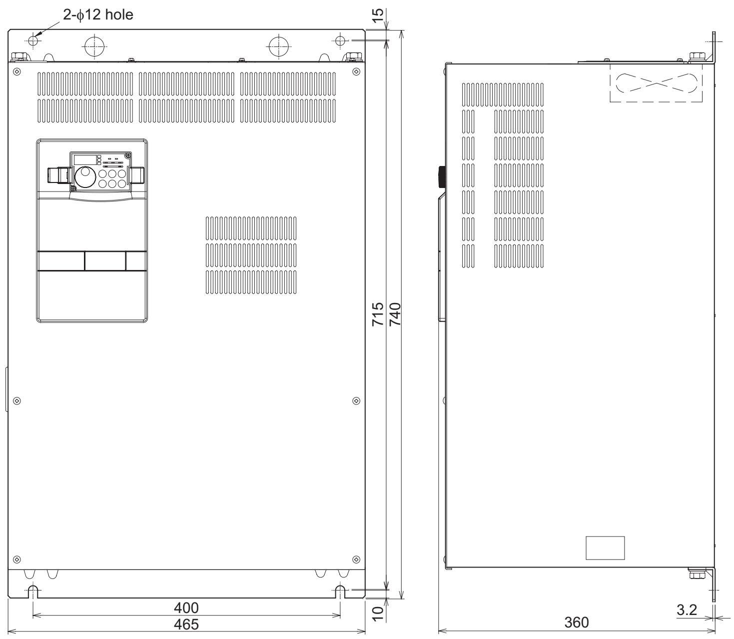
- **DC reactor supplied**



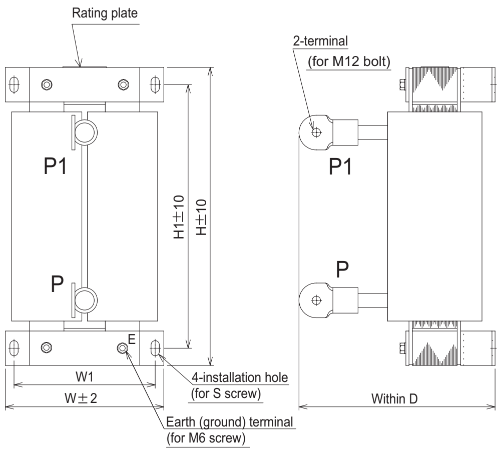
DC reactor Model	Mass (kg)
FR-HEL-H110K(FR-F740P-110K)	22

(Unit: mm)

- **FR-F720P-75K, 90K, 110K**
- **FR-F740P-132K, 160K**



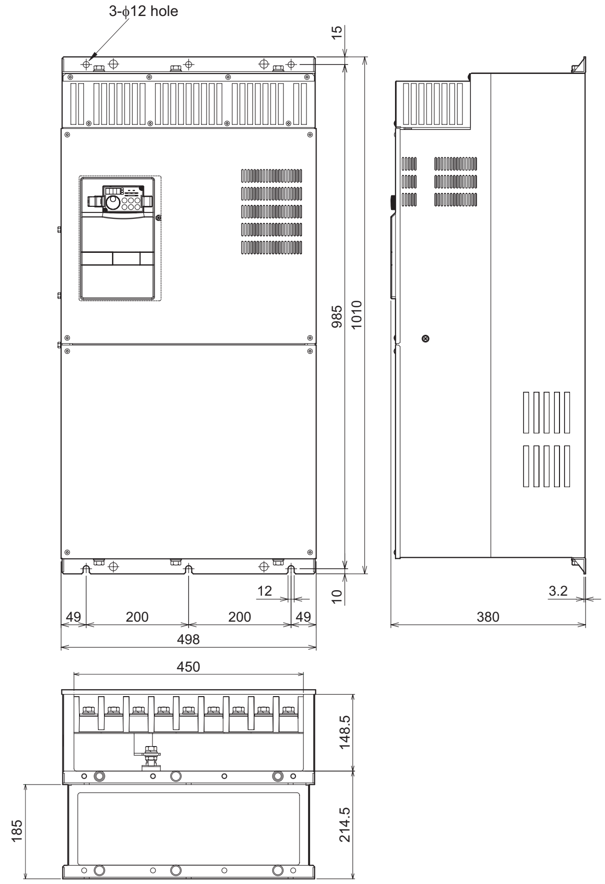
- **DC reactor supplied**



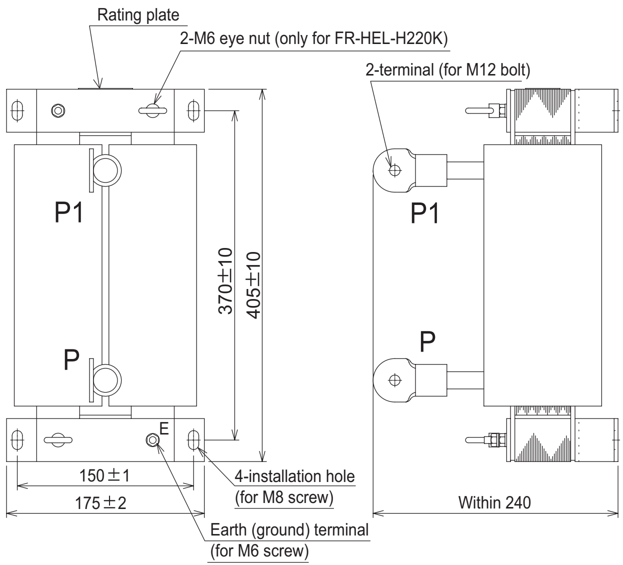
DC reactor Model	W	W1	H	H1	D	S	Mass (kg)
FR-HEL-75K(FR-F720P-75K)	150	130	340	310	190	M6	17
FR-HEL-90K(FR-F720P-90K)	150	130	340	310	200	M6	19
FR-HEL-110K(FR-F720P-110K)	175	150	400	365	200	M8	20
FR-HEL-H132K(FR-F740P-132K)	175	150	405	370	200	M8	26
FR-HEL-H160K(FR-F740P-160K)	175	150	405	370	205	M8	28

(Unit: mm)

- **FR-F740P-185K, 220K**



- **DC reactor supplied**

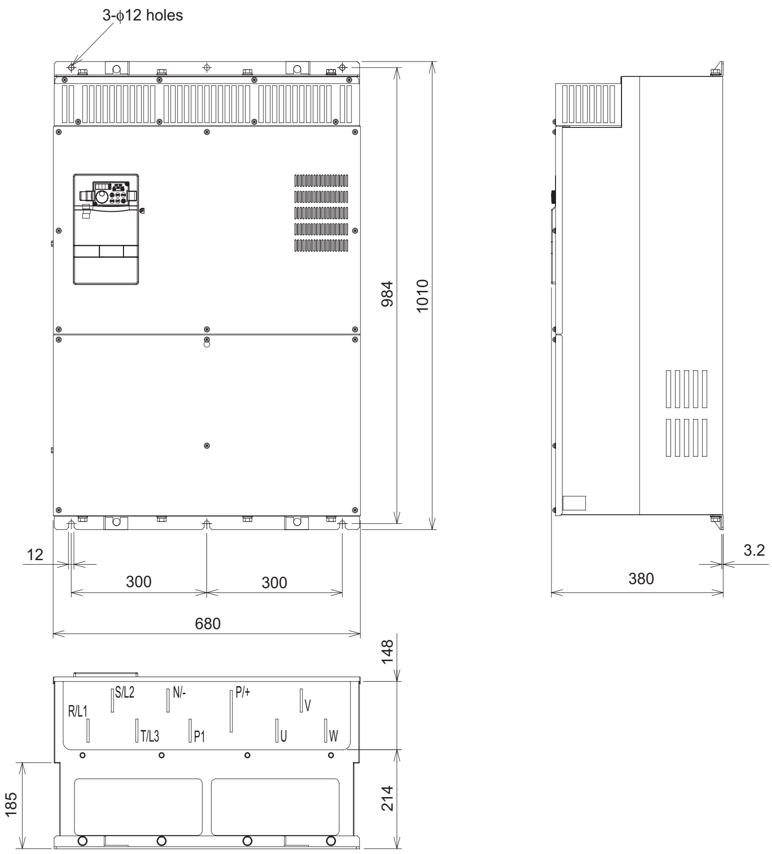


* Remove the eye nut after installation of the product.

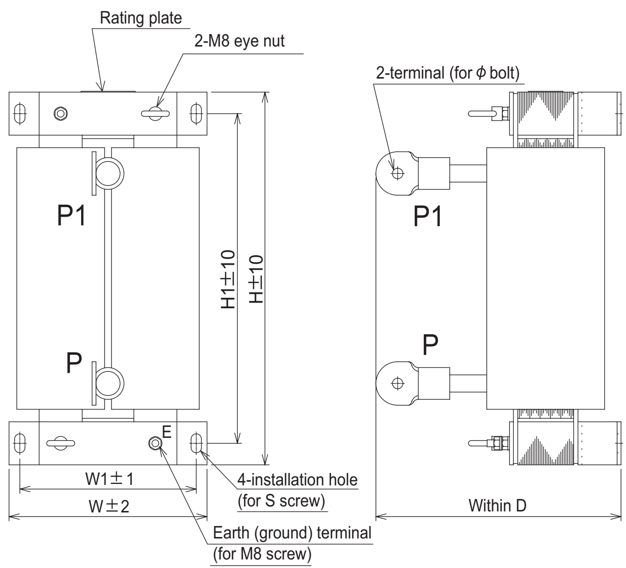
DC reactor Model	Mass (kg)
FR-HEL-H185K (FR-F740P-185K)	29
FR-HEL-H220K (FR-F740P-220K)	30

(Unit: mm)

- **FR-F740P-250K, 280K, 315K**



- **DC reactor supplied**

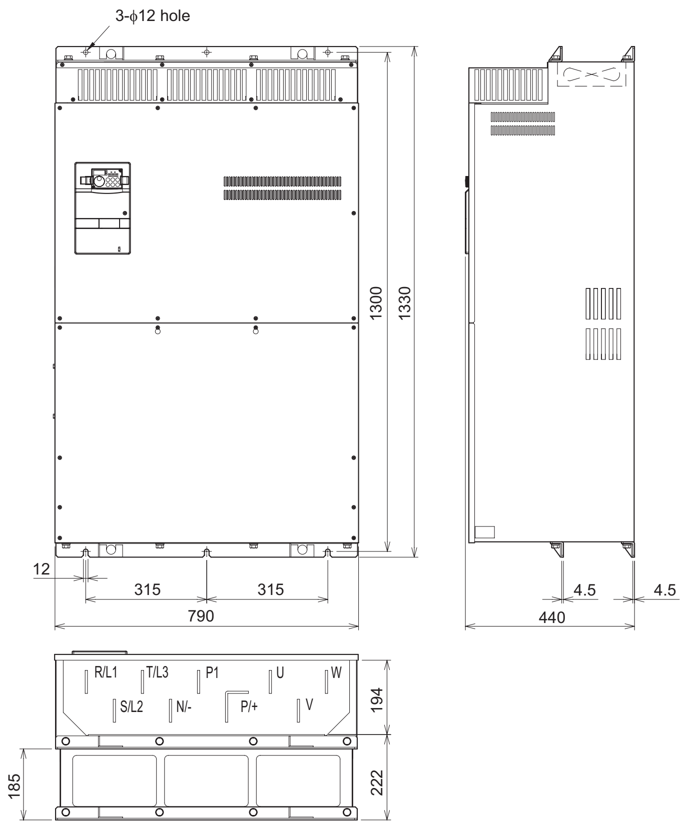


* Remove the eye nut after installation of the product.

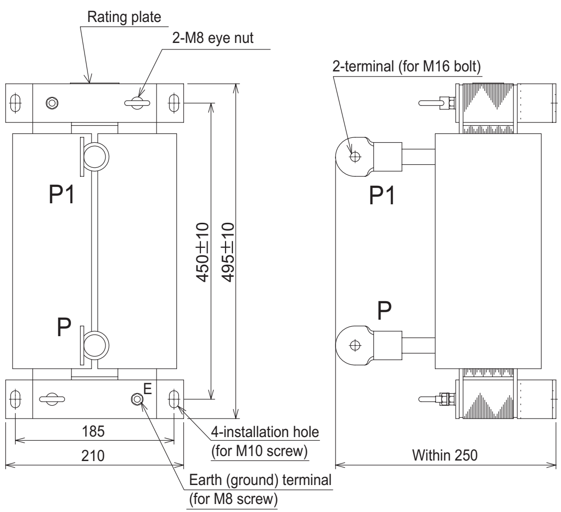
DC reactor Model	W	W1	H	H1	D	S	ϕ	Mass (kg)
FR-HEL-H250K (FR-F740P-250K)	190	165	440	400	250	M8	M12	35
FR-HEL-H280K (FR-F740P-280K)	190	165	440	400	255	M8	M16	38
FR-HEL-H315K (FR-F740P-315K)	210	185	495	450	250	M10	M16	42

(Unit: mm)

• FR-F740P-355K, 400K



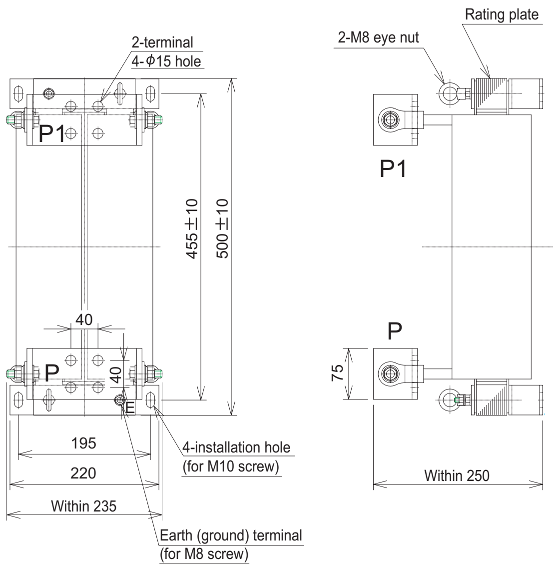
• DC reactor supplied



* Remove the eye nut after installation of the product.

DC reactor Model	Mass (kg)
FR-HEL-H355K (FR-F740P-355K)	46

• DC reactor supplied

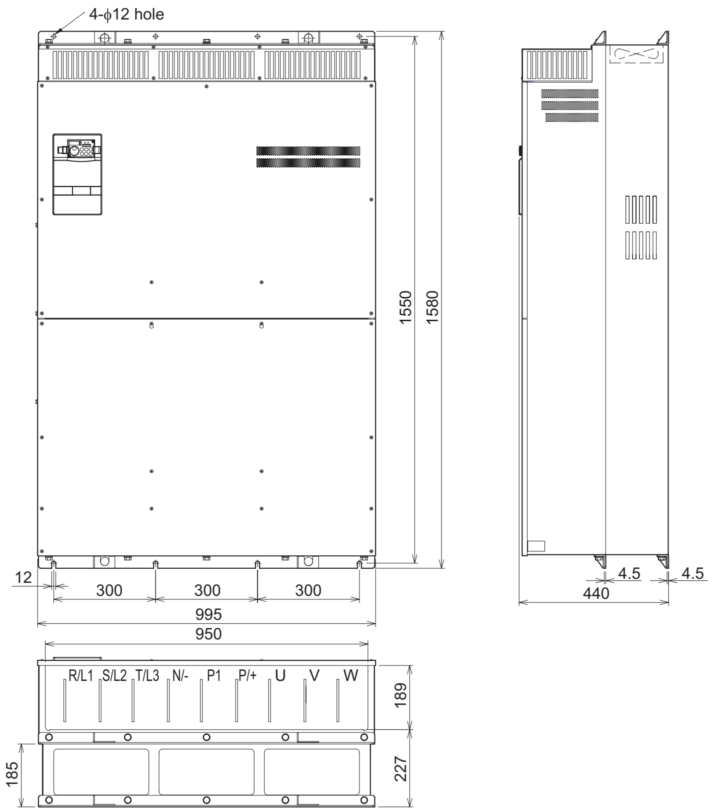


* Remove the eye nut after installation of the product.

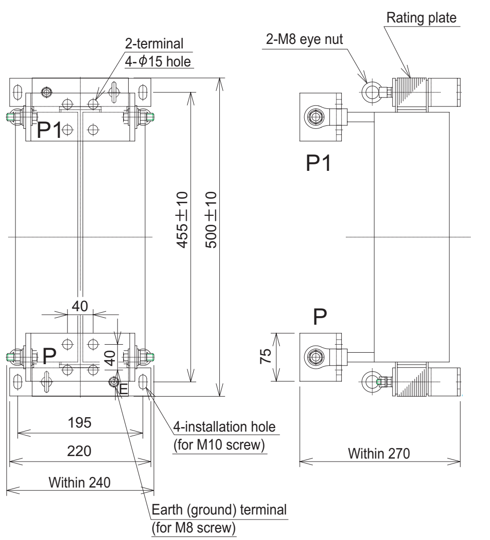
DC reactor Model	Mass (kg)
FR-HEL-H400K (FR-F740P-400K)	50

(Unit: mm)

• FR-F740P-450K, 500K, 560K



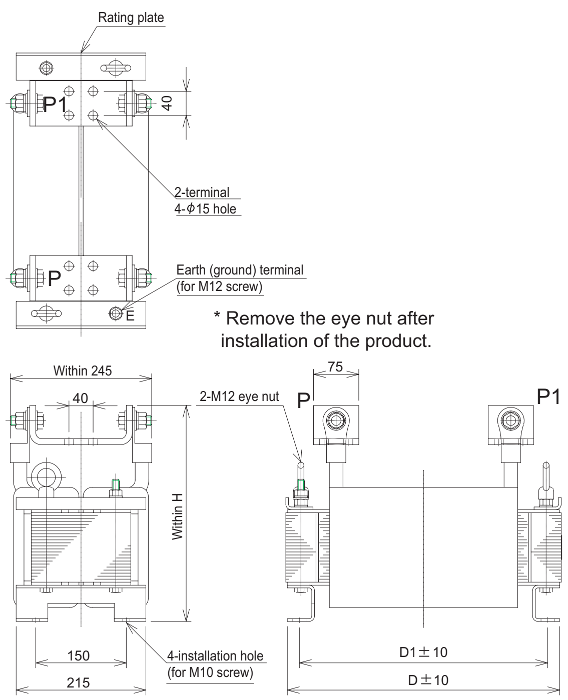
• DC reactor supplied



* Remove the eye nut after installation of the product.

DC reactor Model	Mass (kg)
FR-HEL-H450K (FR-F740P-450K)	57

• DC reactor supplied

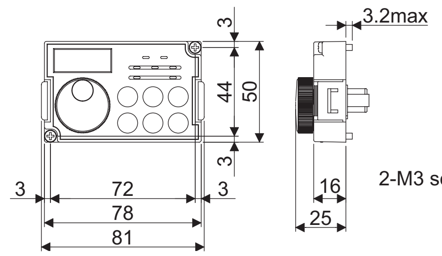


DC reactor Model	H	D	D1	Mass (kg)
FR-HEL-H500K (FR-F740P-500K)	345	455	405	67
FR-HEL-H560K (FR-F740P-560K)	360	460	410	85

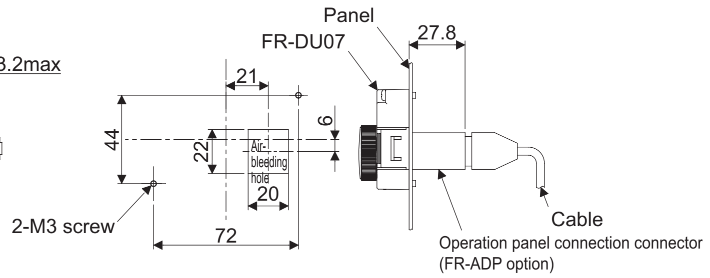
(Unit: mm)

• Operation panel (FR-DU07)

<Outline drawing>



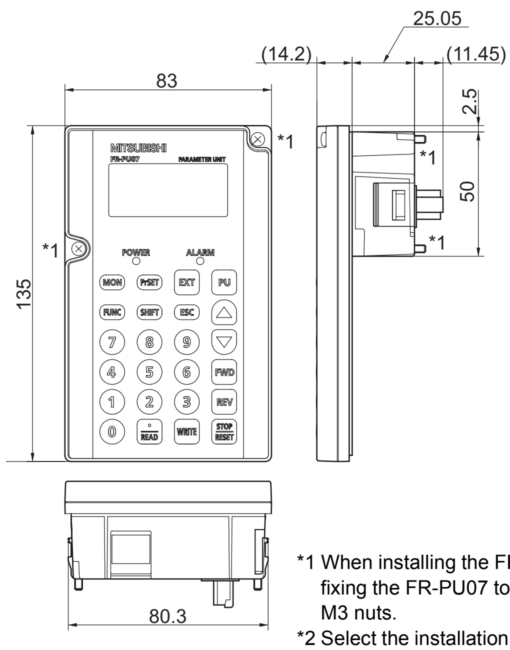
<Panel cutting dimension drawing>



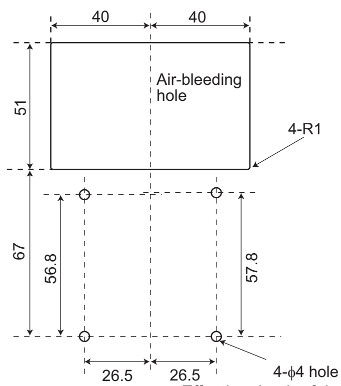
(Unit: mm)

• Parameter unit (option) (FR-PU07(-L)

<Outline drawing>



<Panel cutting dimension drawing>



4-ϕ4 hole
(Effective depth of the installation screws hole 5.0)
M3 screw *2

*1 When installing the FR-PU07 on the enclosure, etc., remove screws for fixing the FR-PU07 to the inverter or fix the screws to the FR-PU07 with M3 nuts.

*2 Select the installation screws whose length will not exceed the effective depth of the installation screw hole.

(Unit: mm)

7.4 Specification of premium high-efficiency IPM motor [MM-EFS (1500r/min) series]

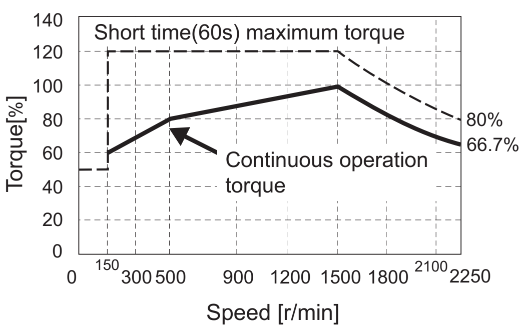
Motor specification

MM-EFS□1M4		7	15	22	37	55	75	11K	15K	18K	22K	30K	37K	45K	55K
Compatible inverter	FR-F740P-□K	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
Continuous characteristic *1	Rated output (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
	Rated torque (N·m)	4.77	9.55	14	23.6	35	47.7	70	95.5	118	140	191	236	286	350
Rated speed (r/min)		1500													
Maximum speed (r/min)		2250													
Number of poles		6								8					
Maximum torque		120% 60s													
Frame number		80M	90L	100L	112M	132S	132M	160M	160L	180M		180L	200L		225S
Moment of inertia ($\times 10^{-4}$kg·m^2)		20	40	55	110	275	280	760	770	1700	1700	1900	3400	3850	6500
Rated current (A)	400V class	1.5	2.8	4	6.5	10	13.5	20	27	33	39.5	55	64	78.5	97
Structure		Totally-enclosed fan-cooled motor. With steel framed legs. (protective structure IP44 *2)													
Insulation class		F class													
Vibration class		V-15													
Environment	Surrounding air temperature and humidity	-10°C to +40°C (non-freezing) · 90%RH or less (non-condensing)													
	Storage temperature and humidity	-20°C to +70°C (non-freezing) · 90%RH or less (non-condensing)													
	Atmosphere	Indoors (not under direct sunlight), and free from corrosive gas, flammable gas, oil mist, dust and dirt.													
	Altitude	Maximum 1,000m above sea level													
	Vibration	4.9m/s^2													
Mass(kg)		11	15	22	31	50	53	95	100	135		155	215	230	285

*1 The above characteristics apply when the rated AC voltage is input from the inverter. (*Refer to page 346.*) Output and rated motor speed are not guaranteed when the power supply voltage drops.
*2 This excludes the part where the axis passes through.

Motor torque characteristic

The following figure shows the torque characteristic of the premium high-efficiency IPM motor [MM-EFS (1500r/min) series] when used with an inverter.



REMARKS

· The motor can also be used for applications which require the rated speed of 1800r/min.

CAUTION

- The torque characteristic is when the armature winding temperature is 20°C, and the input voltage to the inverter is 400VAC.
- Constant-speed operation cannot be performed for the speed of 150r/min or less.

7.5 Specification of high-efficiency IPM motor [MM-EF (1800r/min) series]

Motor specification

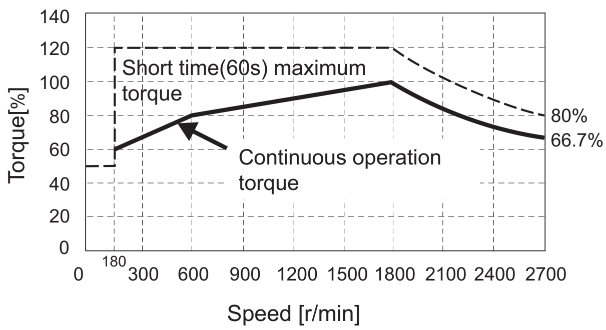
Motor model																			
Motor model	200V class MM-EF□2	4	7	15	22	37	55	75	11K	15K	18K	22K	30K	37K	45K	55K	75K	-	-
	400V class MM-EF□24	4	7	15	22	37	55	75	11K	15K	18K	22K	30K	37K	45K	55K	75K	90K	110K
Compatible inverter	200V class FR-F720P-□K	0.75	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	-	-
	400V class FR-F740P-□K	0.75	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110
Continuous characteristic *1	Rated output (kW)	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110
	Rated torque (N·m)	2.12	3.98	7.96	11.7	19.6	29.2	39.8	58.4	79.6	98.1	117	159	196	239	292	398	477	584
Rated speed (r/min)		1800 (90Hz)												1800 (120Hz)					
Maximum speed (r/min)		2700 (135Hz)												2700 (180Hz)				2400 (160Hz)	
Number of poles		6												8					
Maximum torque		120% 60s																	
Frame number		80M			90L	100L	112M		132S		160M		160L	180L		200L		225S	
Moment of inertia ($\times 10^{-4}$kg·m^2)		10.4	10.4	18.4	36.9	51.2	125	153	274	354	815	815	1050	2215	2400	4300	5200	8700	9500
Rated current (A)	200V class	1.6	3.0	5.9	8.7	14.4	22	29	43	55	70.5	83.5	109	136	162	195	272	-	-
	400V class	0.8	1.5	3.0	4.4	7.2	11	14.5	21.5	27.5	35	42	57	68	81	96.5	136	160	197
Structure		Totally-enclosed fan-cooled motor (protective structure IP44*2)																	
Insulation class		B class									F class								
Environment	Surrounding air temperature and humidity	-10°C to +40°C (non-freezing) · 90%RH or less (non-condensing)																	
	Storage temperature and humidity	-20°C to +70°C (non-freezing) · 90%RH or less (non-condensing)																	
	Atmosphere	Indoors (not under direct sunlight), and free from corrosive gas, flammable gas, oil mist, dust and dirt.																	
	Altitude	Maximum 1,000m above sea level																	
	Vibration	4.9m/s^2																	
Mass(kg)		8.5	9.0	11	15	23	33	38	52	60	105	105	119	167	178	240	290	360	390

*1 The above characteristics apply when the rated AC voltage is input from the inverter. *(Refer to page 346.)* Output and rated motor speed are not guaranteed when the power supply voltage drops.
*2 This excludes the part where the axis passes through.

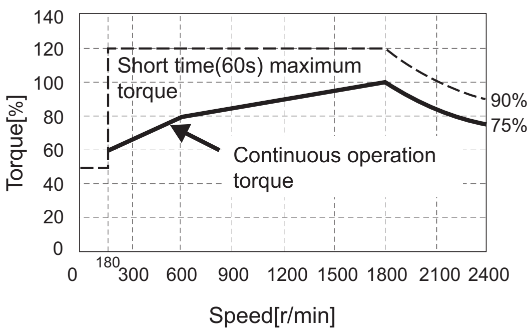
Motor torque characteristic

The following figures show the torque characteristics of high-efficiency IPM motors [MM-EF (1800r/min) series] when used with inverters.

• 75K or lower



• 90K or higher



CAUTION

- The torque characteristic is when the armature winding temperature is 20°C, and the input voltage to the inverter is 200VAC or 400VAC.
- Constant-speed operation cannot be performed for the speed of 180r/min or less.

7.6 Heatsink protrusion attachment procedure

When encasing the inverter in an enclosure, the generated heat amount in an enclosure can be greatly reduced by installing the heatsink portion of the inverter outside the enclosure. When installing the inverter in a compact enclosure, etc., this installation method is recommended.

7.6.1 When using a heatsink protrusion attachment (FR-A7CN)

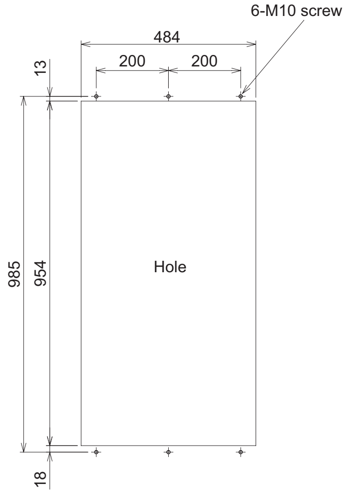
For the FR-F720P-2.2K to 110K, FR-F740P-0.75K to 160K, a heatsink can be protruded outside the enclosure using a heatsink protrusion attachment (FR-A7CN). (Attachment is not required when protruding the heatsink for 185K or higher.) For a panel cut dimension drawing and an installation procedure of the heatsink protrusion attachment (FR-A7CN) to the inverter, refer to a manual of "heatsink protrusion attachment (FR-A7CN)".

7.6.2 Protrusion of heatsink of the FR-F740P-185K or higher

(1) Panel cutting

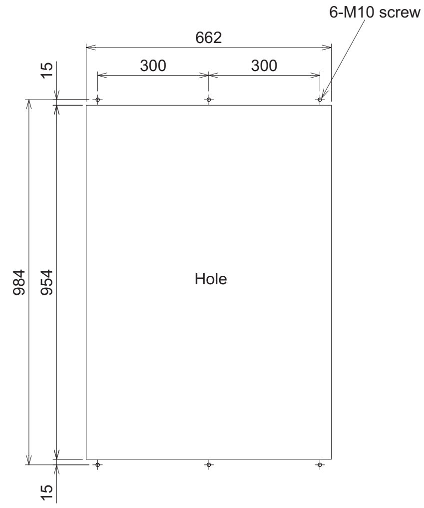
Cut the panel of the enclosure according to the inverter capacity.

• FR-F740P-185K, 220K



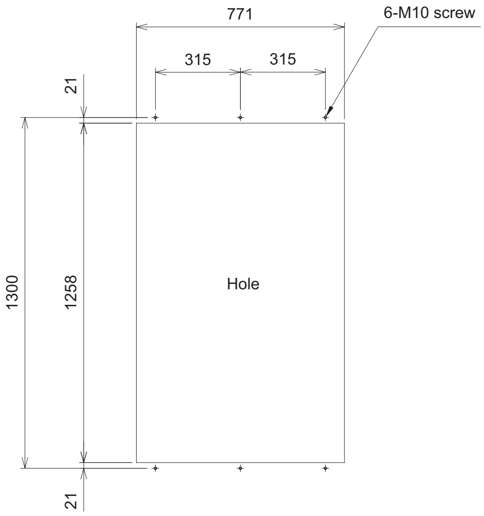
(Unit: mm)

• FR-F740P-250K, 280K, 315K



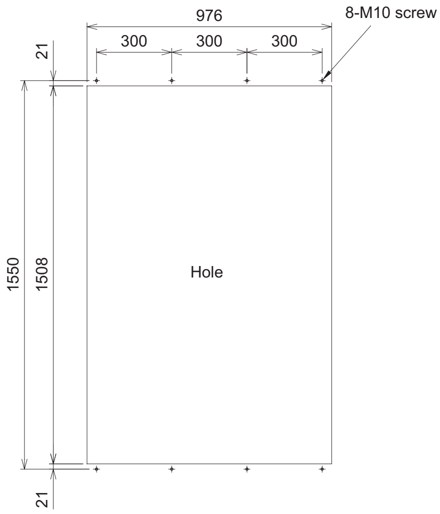
(Unit: mm)

• FR-F740P-355K, 400K



(Unit: mm)

• FR-F740P-450K, 500K, 560K



(Unit: mm)

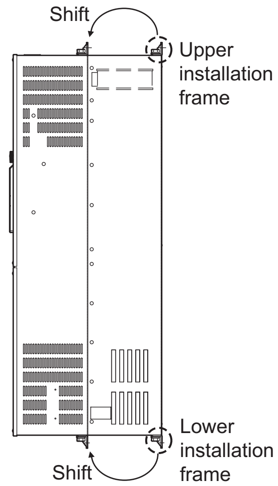
SPECIFICATIONS

7

(2) Shift and removal of a rear side installation frame

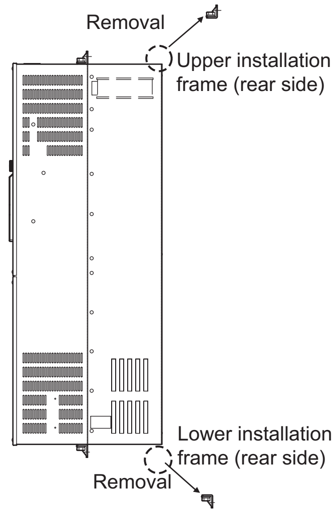
- **FR-F740P-250K to 315K**

  One installation frame is attached to each of the upper and lower part of the inverter. Change the position of the rear side installation frame on the upper and lower side of the inverter to the front side as shown on the right. When changing the installation frames, make sure that the installation orientation is correct.



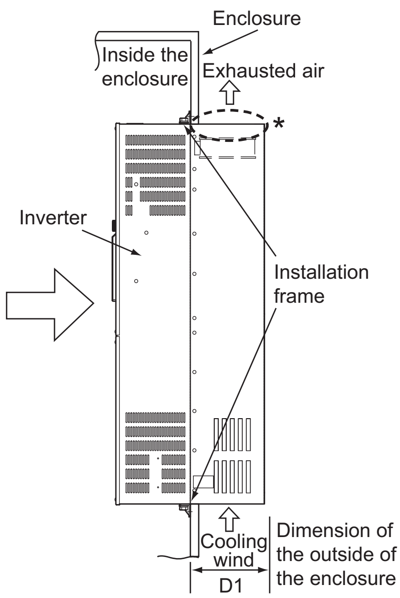
- **FR-F740P-185K/220K, 355K or higher**

  Two installation frames each are attached to the upper and lower parts of the inverter. Remove the rear side installation frame on the upper and lower side of the inverter as shown on the right.

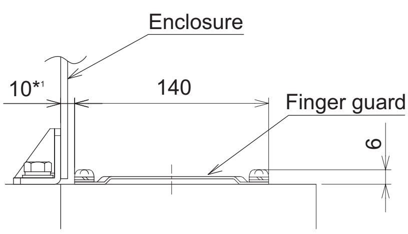


(3) Installation of the inverter

Push the inverter heatsink portion outside the enclosure and fix the enclosure and inverter with upper and lower installation frame.



* For the FR-F740P-250K or higher, there are finger guards behind the enclosure. Therefore, the thickness of the panel should be less than 10mm(*1) and also do not place anything around finger guards to avoid contact with the finger guards.



(Unit: mm)

Inverter Model	D1(mm)
FR-F740P-185K, 220K	185
FR-F740P-250K to 560K	184

CAUTION

- Having a cooling fan, the cooling section which comes out of the enclosure cannot be used in the environment of water drops, oil, mist, dust, etc.
- Be careful not to drop screws, dust etc. into the inverter and cooling fan section.

7 APPENDICES

This chapter provides the "APPENDICES" of this product.
Always read the instructions before using the equipment.

Appendix 1 For customers who are replacing the conventional model with this inverter

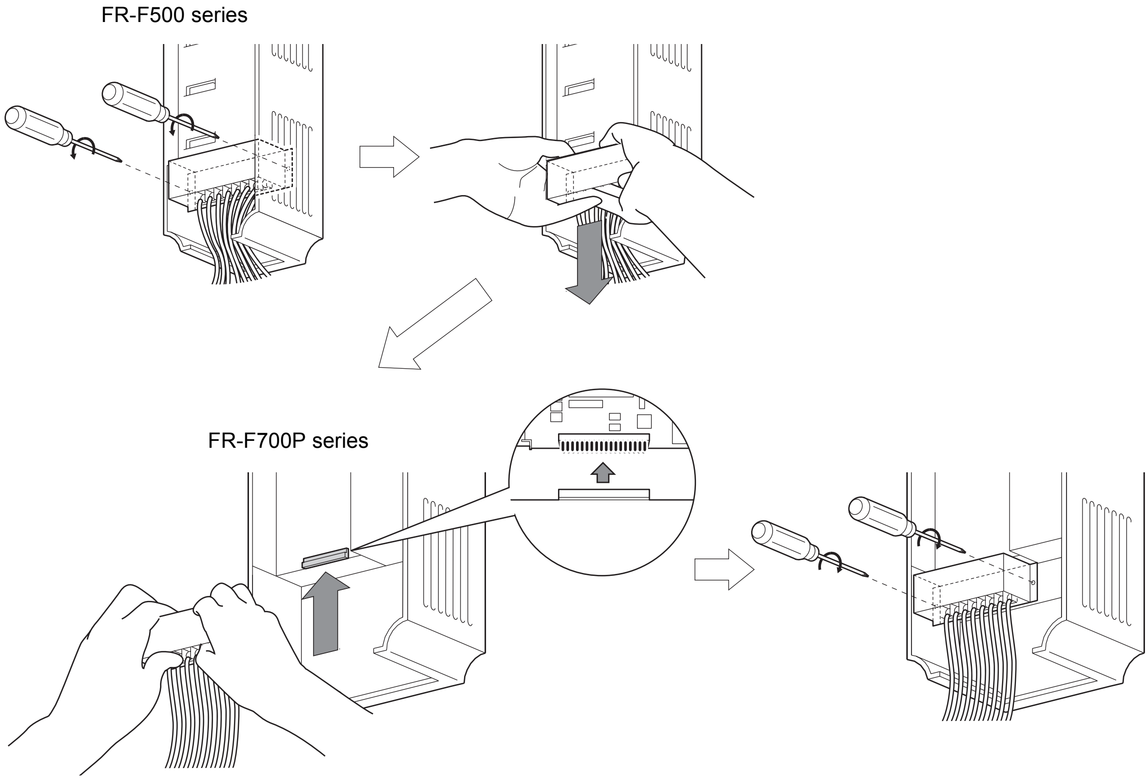
Appendix 1-1 Replacement of the FR-F500 series

(1) Instructions for installation

1)Removal procedure of the front cover was changed. (with screws) Please note. *(Refer to page 6.)*
2)Removal procedure of the operation panel was changed. (with screws) Please note. *(Refer to page 6.)*
3)Plug-in options of the F500 series are not compatible
4)Operation panel (FR-DU04) cannot be used.
5)Setup software (FR-SW0-SETUP) cannot be used.

(2) Wiring instructions

1)The control circuit terminal block can be used for the FR-F700P series without removing wiring.
Note that the wiring cover (0.75K to 22K) is not compatible.



(Note that the relay output 2 (A2, B2, C2) specific for the FR-F700P series cannot be used with the FR-F500 series terminals.)

(3) Instructions for continuous use of the FR-PU04 (parameter unit)

1) For the FR-F700P series, many functions (parameters) have been added. When setting these parameters, the parameter name and setting range are not displayed. Parameter list, change list, initial value list, initial value list 2 and parameter clear of the HELP function cannot be used.
2) For the FR-F700P series, many protective functions have been added. These functions activate, but all faults are displayed as "Fault 14". When the faults history has been checked, "E.14" appears. Added faults display will not appear on the parameter unit.
3) User initial value setting cannot be used.
4) User registration/clear (user group 2) cannot be used.
5) Parameter copy/verification function cannot be used.

(4) Main differences and compatibilities with the FR-F500(L) series

Item		FR-F500(L)	FR-F700P
Changed function	Simple mode parameter	61 parameters	17 parameters
	User group	User group 1 (16 parameters), User group 2 (16 parameters) (*Pr.160*, *Pr.173 to Pr.175*)	User group (16 parameters) only Setting methods were partially changed (*Pr.160*, *Pr.172 to Pr.173*)
	Communication option	Performing the parameter clear or all parameter clear (H5A96 or HAA99) from the DeviceNet communication option (FR-A5ND) clears the *Pr. 345* and *Pr. 346* settings.	Performing the parameter clear or all parameter clear (H5A96 or HAA99) from the DeviceNet communication option (FR-A7ND) does not clear the *Pr. 345* and *Pr. 346* settings.
Changed initial value	*Pr.0* Torque boost	2% for 11K to 55K	2% for 11K to 37K, 1.5% for 45K and 55K (If the torque boost setting was being used in the initial setting in the FR-F500 series, the setting does not need to be changed from the initial setting after the inverter is replaced with the FR-F700P series.)
Deleted function	User initial value setting (*Pr.199*)	Available	Not available Substitutable with the copy function of the operation panel (FR-DU07)
	DC injunction function with terminal	With a terminal (X13 signal) (Setting value "8888" for *Pr.11*, setting value "13" for *Pr.180* to *Pr.186*)	Not available Start in the reverse rotation is possible with the flying start function (frequency search of the automatic restart after instantaneous power failure function)
	Long wire mode	Setting values "10 and 11" for *Pr.240*	Setting is not necessary (Setting values "10 and 11" for *Pr.240* are deleted.)
	Intelligent optimum acceleration/ deceleration	Available (*Pr.60* setting "3" and *Pr.61* to *Pr.63)*	Not available For deceleration time, overvoltage fault can be avoided with the regeneration avoidance function (*Pr.882 to Pr.885*).
	Automatic torque boost	*Pr.38, Pr.39*	The automatic torque boost is deleted because the Simple magnetic flux vector (*Pr.80*) has been added.
Terminal block		Removable terminal block	Removable terminal block Upward compatibility (Terminal block of the F500 can be mounted)
PU		FR-PU04, DU04	FR-PU07 FR-DU07 FR-DU04 unavailable (Partly restricted when the FR-PU04 is used. *Refer to page 364.*)
Plug-in option		Dedicated plug-in option (not compatible)	
		Computer link, relay output option FR-A5NR	Built into the inverter (RS-485 terminal, relay output 2 points)
		Three boards can be mounted	One board can be mounted
Installation size		FR-F720P-0.75K, 2.2K, 3.7K, 7.5K, 18.5K, 22K, 37K, 45K, FR-F740P-0.75K to 3.7K, 7.5K, 11K, 22K, 37K to 55K are compatible in mounting dimensions For other capacities, an optional intercompatibility attachment (FR-AAT) is necessary.	

Appendix 1-2 Replacement of the FR-A100 <EXCELENT> series

Instructions for installation

- When using the installation holes of the FR-A100(E) series, FR-A5AT (intercompatibility attachment) is necessary.

Appendix 2 Options and products available on the market

By fitting the following options to the inverter, the inverter is provided with more functions.

	Name	Model	Applications, Specifications, etc.	Applicable Inverter
Stand-alone type	Parameter unit (Eight languages)	FR-PU07 FR-PU04	Interactive parameter unit with LCD display	Applicable for all models
	Parameter unit with battery pack	FR-PU07BB(-L)	Parameter unit that enables parameter setting without connecting the power supply to the inverter.	Applicable for all models
	Parameter unit connection cable	FR-CB20□	Cable for connection of operation panel or parameter unit. □ indicates a cable length.(1m, 3m, 5m)	Applicable for all models
	Operation panel connection connector	FR-ADP	Connector to connect the operation panel (FR-DU07) and connection cable	
	Heatsink protrusion attachment	FR-A7CN	Attachment for protruding the inverter heatsink at the back of the enclosure.	Applicable for the following capacities: FR-F720P-2.2K to 110K FR-F740P-0.75K to 160K
	Intercompatibility attachment	FR-AAT	Attachment for replacing with the FR-F700P series using the installation holes of the FR-F500.	Applicable for the certain capacities
		FR-A5AT	Attachment for replacing with the FR-F700P series using the installation holes of the FR-A100[Excellent] and FR-A200[Excellent]	
	AC reactor	FR-HAL	For harmonic current reduction and inverter input power factor improvement (total power factor approx. 88%)	Applicable for the certain capacities
	DC reactor	FR-HEL	For harmonic current reduction and inverter input power factor improvement (total power factor approx. 93%)	For the 55K or lower
	Brake unit Resistor unit	FR-BU2	For increasing the braking capability of the inverter (for high inertia load or negative load) Brake unit and resistor unit are used in combination	Applicable for the certain capacities
		FR-BR		For the 55K or lower
		MT-BR5		For the 75K or higher
	Power regeneration common converter Dedicated stand-alone reactor for FR-CV	FR-CV/FR-CVL	Unit which can return motor-generated braking energy back to the power supply in common converter system	For the 55K or lower
	Power regeneration common converter	MT-RC	Energy-efficient and high-performance brake unit which regenerates the braking energy generated by the motor to the power supply.	For the 75K or higher
	High power factor converter	FR-HC	The high power factor converter switches the converter section on/off to reshape an input current waveform into a sine wave, greatly suppressing harmonics. (Used in combination with the standard accessory.)	For the 55K or lower
		MT-HC		For the 75K or higher
	Line noise filter	FR-BSF01 FR-BLF	For line noise reduction	Applicable for all models
	Surge voltage suppression filter	FR-ASF	Filter for suppressing surge voltage on motor	For the 55K or lower in the 400V class
		FR-BMF		Applicable for the following capacities: FR-F740P-5.5K to 37K
	Sine wave filter — Reactor	MT-BSL	For reducing the motor noise while the motor is driven by an inverter. Use a reactor and a capacitor in combination.	For the 75K or higher
	Sine wave filter — Capacitor	MT-BSC		

	Name	Model	Applications, Specifications, etc.	Applicable Inverter
FR Series Manual Controller/Speed controller	Manual controller	FR-AX	For independent operation. With frequency meter, frequency setting potentiometer and start switch.	Applicable for all models
	DC tach. follower	FR-AL	For synchronous operation (1VA) by external signal (0 to 5V, 0 to 10V DC) *	
	Three speed selector	FR-AT	For three speed switching among high, middle and low speed operation (1.5VA)*	
	Motorized speed setter	FR-FK	For remote operation. Allows operation to be controlled from several places (5VA)*	
	Ratio setter	FR-FH	For ratio operation. Allows ratios to be set to five inverters. (3VA)*	
	Speed follower	FR-FP	For tracking operation by a pilot generator (PG) signal (3VA)*	
	Master controller	FR-FG	Master controller (5VA) for parallel operation of multiple (maximum 35) inverters.*	
	Soft starter	FR-FC	For soft start and stop. Enables acceleration/deceleration in parallel operation (3VA)*	
	Deviation detector	FR-FD	For continuous speed control operation. Used in combination with a deviation sensor or synchro (5VA)*	
	Preamplifier	FR-FA	Used as an A/V converter or arithmetic amplifier (3VA)*	
Others	Pilot generator	QVAH-10	For tracking operation. 70V/35VAC 500Hz (at 2500r/min)	
	Deviation sensor	YVGC-500W-NS	For continuous speed control operation (mechanical deviation detection). Output 90VAC/90°	
	Frequency setting potentiometer	WA2W 1kΩ	For frequency setting. Wirewound 2W 1k B characteristic	
	Frequency meter (64mm × 60mm)	YM206NRI 1mA	Dedicated frequency meter (graduated to 120Hz). Moving-coil type DC ammeter	
	Calibration resistor	RV24YN 10kΩ	For frequency meter calibration. Carbon film type B characteristic	
	FR Configurator SW3 (Inverter setup software)	FR-SW3-SETUP-W☐	Supports an inverter startup to maintenance. FR-SW1-SETUP-W☐ is also available for installation.	Applicable for all models

* Rated power consumption. The power supply specifications of the FR series manual controllers and speed controllers are 200VAC 50Hz, 220/220VAC 60Hz, and 115VAC 60Hz.

Commercially available products (as of Jan. 2010)

Name	Model	Manufacturer	Applications, Specifications, etc.
Communication connector	5-554720-3	Tyco Electronics	RJ-45 connector
Communication cable	SGLPEV-T (Cat5e/300m) 24AWG × 4	Mitsubishi Cable Industries, Ltd.	Cat.5e cable that is compatible with TIA/EIA standards. (10BASE-T/100BASE-T/1000BASE-T)

•Blade terminals

Commercially available products (as of Jan. 2010)
·Phoenix Contact Co.,Ltd.

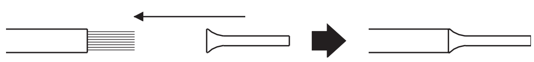
Terminal Screw Size	Wire Size (mm^2)	Blade Terminal Model (with insulation sleeve)	Blade Terminal Model (without insulation sleeve)	Blade Terminal Crimping Tool
M2	0.3, 0.5	AI 0,5-6WH	A 0,5-6	CRIMPFOX 6

·NICHIFU Co.,Ltd.

Terminal Screw Size	Wire Size (mm^2)	Blade Terminal Product Number	Insulation Product Number	Blade Terminal Crimping Tool
M2	0.3 to 0.75	BT 0.75-7	VC 0.75	NH 67

Use shielded or twisted cable as the connection cable for the control circuit terminals. Separate the cable from the main circuit and the high-power circuits (including the 200V relay sequence circuit).

When using a blade terminal (without insulation sleeve), take caution that the twisted wires do not come out.



Appendix 3 Parameter clear, parameter copy and instruction code list

*1 These instruction codes are used for parameter read and write by using Mitsubishi inverter protocol with the RS-485 communication. (Refer to *page 229* for RS-485 communication)
*2 Validity and invalidity according to operation mode are as follows:
○:Usable parameter
×:Unusable parameter
*3 "○" indicates valid and "×" indicates invalid of "parameter copy", "parameter clear", and "all parameter clear".
*4 These parameters are communication parameters that are not cleared when parameter clear (all clear) is executed from RS-485 communication. (Refer to *page 229* for RS-485 communication)
*5 When a communication option is installed, parameter clear (lock release) during password lock (*Pr. 297* ≠ 9999) can be performed only from the communication option.

Symbols in the table indicate parameters which function when an option is mounted.

AX ....FR-A7AX, AY .... FR-A7AY, AR .... FR-A7AR, NC ....FR-A7NC, ND FR-A7ND,
NL ....FR-A7NL, NP .... FR-A7NP, NF FR-A7NF

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
0	Torque boost	00	80	0	○	×	×	○	○	○
1	Maximum frequency	01	81	0	○	○	○	○	○	○
2	Minimum frequency	02	82	0	○	○	○	○	○	○
3	Base frequency	03	83	0	○	○	×	○	○	○
4	Multi-speed setting (high speed)	04	84	0	○	○	○	○	○	○
5	Multi-speed setting (middle speed)	05	85	0	○	○	○	○	○	○
6	Multi-speed setting (low speed)	06	86	0	○	○	○	○	○	○
7	Acceleration time	07	87	0	○	○	○	○	○	○
8	Deceleration time	08	88	0	○	○	○	○	○	○
9	Electronic thermal O/L relay	09	89	0	○	○	○	○	○	○
10	DC injection brake operation frequency	0A	8A	0	○	○	○	○	○	○
11	DC injection brake operation time	0B	8B	0	○	○	○	○	○	○
12	DC injection brake operation voltage	0C	8C	0	○	○	×	○	○	○
13	Starting frequency	0D	8D	0	○	○	○	○	○	○
14	Load pattern selection	0E	8E	0	○	×	×	○	○	○
15	Jog frequency	0F	8F	0	○	○	○	○	○	○
16	Jog acceleration/deceleration time	10	90	0	○	○	○	○	○	○
17	MRS input selection	11	91	0	○	○	○	○	○	○
18	High speed maximum frequency	12	92	0	○	○	○	○	○	○
19	Base frequency voltage	13	93	0	○	○	×	○	○	○
20	Acceleration/deceleration reference frequency	14	94	0	○	○	○	○	○	○
21	Acceleration/deceleration time increments	15	95	0	○	○	○	○	○	○
22	Stall prevention operation level (Torque limit level)	16	96	0	○	○	○	○	○	○
23	Stall prevention operation level compensation factor at double speed	17	97	0	○	○	×	○	○	○
24	Multi-speed setting (speed 4)	18	98	0	○	○	○	○	○	○
25	Multi-speed setting (speed 5)	19	99	0	○	○	○	○	○	○
26	Multi-speed setting (speed 6)	1A	9A	0	○	○	○	○	○	○
27	Multi-speed setting (speed 7)	1B	9B	0	○	○	○	○	○	○

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
28	Multi-speed input compensation selection	1C	9C	0	○	○	○	○	○	○
29	Acceleration/deceleration pattern selection	1D	9D	0	○	○	○	○	○	○
30	Regenerative function selection	1E	9E	0	○	○	○	○	○	○
31	Frequency jump 1A	1F	9F	0	○	○	○	○	○	○
32	Frequency jump 1B	20	A0	0	○	○	○	○	○	○
33	Frequency jump 2A	21	A1	0	○	○	○	○	○	○
34	Frequency jump 2B	22	A2	0	○	○	○	○	○	○
35	Frequency jump 3A	23	A3	0	○	○	○	○	○	○
36	Frequency jump 3B	24	A4	0	○	○	○	○	○	○
37	Speed display	25	A5	0	○	○	○	○	○	○
41	Up-to-frequency sensitivity	29	A9	0	○	○	○	○	○	○
42	Output frequency detection	2A	AA	0	○	○	○	○	○	○
43	Output frequency detection for reverse rotation	2B	AB	0	○	○	○	○	○	○
44	Second acceleration/ deceleration time	2C	AC	0	○	○	○	○	○	○
45	Second deceleration time	2D	AD	0	○	○	○	○	○	○
46	Second torque boost	2E	AE	0	○	×	×	○	○	○
47	Second V/F (base frequency)	2F	AF	0	○	×	×	○	○	○
48	Second stall prevention operation current	30	B0	0	○	○	○	○	○	○
49	Second stall prevention operation frequency	31	B1	0	○	○	○	○	○	○
50	Second output frequency detection	32	B2	0	○	○	○	○	○	○
51	Second electronic thermal O/L relay	33	B3	0	○	○	×	○	○	○
52	DU/PU main display data selection	34	B4	0	○	○	○	○	○	○
54	FM terminal function selection	36	B6	0	○	○	○	○	○	○
55	Frequency monitoring reference	37	B7	0	○	○	○	○	○	○
56	Current monitoring reference	38	B8	0	○	○	○	○	○	○
57	Restart coasting time	39	B9	0	○	○	○	○	○	○
58	Restart cushion time	3A	BA	0	○	○	×	○	○	○
59	Remote function selection	3B	BB	0	○	○	○	○	○	○
60	Energy saving control selection	3C	BC	0	○	×	×	○	○	○
65	Retry selection	41	C1	0	○	○	○	○	○	○
66	Stall prevention operation reduction starting frequency	42	C2	0	○	○	×	○	○	○
67	Number of retries at fault occurrence	43	C3	0	○	○	○	○	○	○
68	Retry waiting time	44	C4	0	○	○	○	○	○	○
69	Retry count display erase	45	C5	0	○	○	○	○	○	○
70	Special regenerative brake duty	46	C6	0	○	○	○	○	○	○
71	Applied motor	47	C7	0	○	○	○	○	○	○
72	PWM frequency selection	48	C8	0	○	○	○	○	○	○
73	Analog input selection	49	C9	0	○	○	○	○	○	○
74	Input filter time constant	4A	CA	0	○	○	○	○	○	○

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
75	Reset selection/disconnected PU detection/PU stop selection	4B	CB	0	○	○	○	○	×	×
76	Fault code output selection	4C	CC	0	○	○	○	○	○	○
77 *	Parameter write selection	4D	CD	0	○	○	○	○	○	○
78	Reverse rotation prevention selection	4E	CE	0	○	○	○	○	○	○
79 *	Operation mode selection	4F	CF	0	○	○	○	○	○	○
80	Motor capacity	50	D0	0	×	○	○	○	○	○
90	Motor constant (R1)	5A	DA	0	×	○	×	○	×	○
100	V/F1(first frequency)	00	80	1	○	×	×	○	○	○
101	V/F1(first frequency voltage)	01	81	1	○	×	×	○	○	○
102	V/F2(second frequency)	02	82	1	○	×	×	○	○	○
103	V/F2(second frequency voltage)	03	83	1	○	×	×	○	○	○
104	V/F3(third frequency)	04	84	1	○	×	×	○	○	○
105	V/F3(third frequency voltage)	05	85	1	○	×	×	○	○	○
106	V/F4(fourth frequency)	06	86	1	○	×	×	○	○	○
107	V/F4(fourth frequency voltage)	07	87	1	○	×	×	○	○	○
108	V/F5(fifth frequency)	08	88	1	○	×	×	○	○	○
109	V/F5(fifth frequency voltage)	09	89	1	○	×	×	○	○	○
117	PU communication station number	11	91	1	○	○	○	○	○*4	○*4
118	PU communication speed	12	92	1	○	○	○	○	○*4	○*4
119	PU communication stop bit length	13	93	1	○	○	○	○	○*4	○*4
120	PU communication parity check	14	94	1	○	○	○	○	○*4	○*4
121	Number of PU communication retries	15	95	1	○	○	○	○	○*4	○*4
122	PU communication check time interval	16	96	1	○	○	○	○	○*4	○*4
123	PU communication waiting time setting	17	97	1	○	○	○	○	○*4	○*4
124	PU communication CR/LF selection	18	98	1	○	○	○	○	○*4	○*4
125	Terminal 2 frequency setting gain frequency	19	99	1	○	○	○	○	×	○
126	Terminal 4 frequency setting gain frequency	1A	9A	1	○	○	○	○	×	○
127	PID control automatic switchover frequency	1B	9B	1	○	○	○	○	○	○
128	PID action selection	1C	9C	1	○	○	○	○	○	○
129	PID proportional band	1D	9D	1	○	○	○	○	○	○
130	PID integral time	1E	9E	1	○	○	○	○	○	○
131	PID upper limit	1F	9F	1	○	○	○	○	○	○
132	PID lower limit	20	A0	1	○	○	○	○	○	○
133	PID action set point	21	A1	1	○	○	○	○	○	○
134	PID differential time	22	A2	1	○	○	○	○	○	○

* Read and write from communication with PU connector only is enabled.

Parameter	Name	Instruction Code *1 Read	Instruction Code *1 Write	Instruction Code *1 Extended	Control Mode-based Correspondence Table *2 V/F control V/F	Control Mode-based Correspondence Table *2 Simple magnetic flux vector control S MFVC	Control Mode-based Correspondence Table *2 IPM motor control IPM	Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
135	Electronic bypass sequence selection	23	A3	1	○	○	×	○	○	○
136	MC switchover interlock time	24	A4	1	○	○	×	○	○	○
137	Start waiting time	25	A5	1	○	○	×	○	○	○
138	Bypass selection at a fault	26	A6	1	○	○	×	○	○	○
139	Automatic switchover frequency from inverter to bypass operation	27	A7	1	○	○	×	○	○	○
140	Backlash acceleration stopping frequency	28	A8	1	○	○	○	○	○	○
141	Backlash acceleration stopping time	29	A9	1	○	○	○	○	○	○
142	Backlash deceleration stopping frequency	2A	AA	1	○	○	○	○	○	○
143	Backlash deceleration stopping time	2B	AB	1	○	○	○	○	○	○
144	Speed setting switchover	2C	AC	1	○	○	○	○	○	○
145	PU display language selection	2D	AD	1	○	○	○	○	×	×
147	Acceleration/deceleration time switching frequency	2F	AF	1	○	○	○	○	○	○
148	Stall prevention level at 0V input	30	B0	1	○	○	○	○	○	○
149	Stall prevention level at 10V input	31	B1	1	○	○	○	○	○	○
150	Output current detection level	32	B2	1	○	○	○	○	○	○
151	Output current detection signal delay time	33	B3	1	○	○	○	○	○	○
152	Zero current detection level	34	B4	1	○	○	○	○	○	○
153	Zero current detection time	35	B5	1	○	○	○	○	○	○
154	Voltage reduction selection during stall prevention operation	36	B6	1	○	○	×	○	○	○
155	RT signal function validity condition selection	37	B7	1	○	○	○	○	○	○
156	Stall prevention operation selection	38	B8	1	○	○	○	○	○	○
157	OL signal output timer	39	B9	1	○	○	○	○	○	○
158	AM terminal function selection	3A	BA	1	○	○	○	○	○	○
159	Automatic switchover frequency range from bypass to inverter operation	3B	BB	1	○	○	×	○	○	○
160	User group read selection	00	80	2	○	○	○	○	○	○
161	Frequency setting/key lock operation selection	01	81	2	○	○	○	○	×	○
162	Automatic restart after instantaneous power failure selection	02	82	2	○	○	○	○	○	○
163	First cushion time for restart	03	83	2	○	○	×	○	○	○
164	First cushion voltage for restart	04	84	2	○	○	×	○	○	○
165	Stall prevention operation level for restart	05	85	2	○	○	×	○	○	○
166	Output current detection signal retention time	06	86	2	○	○	○	○	○	○
167	Output current detection operation selection	07	87	2	○	○	○	○	○	○

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
168	Parameter for manufacturer setting. Do not set.									
169										
170	Watt-hour meter clear	0A	8A	2	○	○	○	○	×	○
171	Operation hour meter clear	0B	8B	2	○	○	○	×	×	×
172	User group registered display/ batch clear	0C	8C	2	○	○	○	○	×	×
173	User group registration	0D	8D	2	○	○	○	×	×	×
174	User group clear	0E	8E	2	○	○	○	×	×	×
178	STF terminal function selection	12	92	2	○	○	○	○	×	○
179	STR terminal function selection	13	93	2	○	○	○	○	×	○
180	RL terminal function selection	14	94	2	○	○	○	○	×	○
181	RM terminal function selection	15	95	2	○	○	○	○	×	○
182	RH terminal function selection	16	96	2	○	○	○	○	×	○
183	RT terminal function selection	17	97	2	○	○	○	○	×	○
184	AU terminal function selection	18	98	2	○	○	○	○	×	○
185	JOG terminal function selection	19	99	2	○	○	○	○	×	○
186	CS terminal function selection	1A	9A	2	○	○	○	○	×	○
187	MRS terminal function selection	1B	9B	2	○	○	○	○	×	○
188	STOP terminal function selection	1C	9C	2	○	○	○	○	×	○
189	RES terminal function selection	1D	9D	2	○	○	○	○	×	○
190	RUN terminal function selection	1E	9E	2	○	○	○	○	×	○
191	SU terminal function selection	1F	9F	2	○	○	○	○	×	○
192	IPF terminal function selection	20	A0	2	○	○	○	○	×	○
193	OL terminal function selection	21	A1	2	○	○	○	○	×	○
194	FU terminal function selection	22	A2	2	○	○	○	○	×	○
195	ABC1 terminal function selection	23	A3	2	○	○	○	○	×	○
196	ABC2 terminal function selection	24	A4	2	○	○	○	○	×	○
232	Multi-speed setting (speed 8)	28	A8	2	○	○	○	○	○	○
233	Multi-speed setting (speed 9)	29	A9	2	○	○	○	○	○	○
234	Multi-speed setting (speed 10)	2A	AA	2	○	○	○	○	○	○
235	Multi-speed setting (speed 11)	2B	AB	2	○	○	○	○	○	○
236	Multi-speed setting (speed 12)	2C	AC	2	○	○	○	○	○	○
237	Multi-speed setting (speed 13)	2D	AD	2	○	○	○	○	○	○
238	Multi-speed setting (speed 14)	2E	AE	2	○	○	○	○	○	○
239	Multi-speed setting (speed 15)	2F	AF	2	○	○	○	○	○	○
240	Soft-PWM operation selection	30	B0	2	○	○	○	○	○	○
241	Analog input display unit switchover	31	B1	2	○	○	○	○	○	○
242	Terminal 1 added compensation amount (terminal 2)	32	B2	2	○	○	○	○	○	○
243	Terminal 1 added compensation amount (terminal 4)	33	B3	2	○	○	○	○	○	○

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
244	Cooling fan operation selection	34	B4	2	○	○	○	○	○	○
245	Rated slip	35	B5	2	○	○	×	○	○	○
246	Slip compensation time constant	36	B6	2	○	○	×	○	○	○
247	Constant-power range slip compensation selection	37	B7	2	○	○	×	○	○	○
250	Stop selection	3A	BA	2	○	○	○	○	○	○
251	Output phase loss protection selection	3B	BB	2	○	○	○	○	○	○
252	Override bias	3C	BC	2	○	○	○	○	○	○
253	Override gain	3D	BD	2	○	○	○	○	○	○
255	Life alarm status display	3F	BF	2	○	○	○	×	×	×
256	Inrush current limit circuit life display	40	C0	2	○	○	○	×	×	×
257	Control circuit capacitor life display	41	C1	2	○	○	○	×	×	×
258	Main circuit capacitor life display	42	C2	2	○	○	○	×	×	×
259	Main circuit capacitor life measuring	43	C3	2	○	○	○	○	○	○
260	PWM frequency automatic switchover	44	C4	2	○	○	○	○	○	○
261	Power failure stop selection	45	C5	2	○	○	○	○	○	○
262	Subtracted frequency at deceleration start	46	C6	2	○	○	○	○	○	○
263	Subtraction starting frequency	47	C7	2	○	○	○	○	○	○
264	Power-failure deceleration time 1	48	C8	2	○	○	○	○	○	○
265	Power-failure deceleration time 2	49	C9	2	○	○	○	○	○	○
266	Power failure deceleration time switchover frequency	4A	CA	2	○	○	○	○	○	○
267	Terminal 4 input selection	4B	CB	2	○	○	○	○	×	○
268	Monitor decimal digits selection	4C	CC	2	○	○	○	○	○	○
269	Parameter for manufacturer setting. Do not set.									
296	Password lock level	68	E8	2	○	○	○	○	×	○
297	Password lock/unlock	69	E9	2	○	○	○	○	○*5	○
299	Rotation direction detection selection at restarting	6B	EB	2	○	○	×	○	○	○
300	BCD input bias AX	00	80	3	○	○	○	○	○	○
301	BCD input gain AX	01	81	3	○	○	○	○	○	○
302	BIN input bias AX	02	82	3	○	○	○	○	○	○
303	BIN input gain AX	03	83	3	○	○	○	○	○	○
304	Digital input and analog input compensation enable/disable selection AX	04	84	3	○	○	○	○	○	○
305	Read timing operation selection AX	05	85	3	○	○	○	○	○	○
306	Analog output signal selection AY	06	86	3	○	○	○	○	○	○
307	Setting for zero analog output AY	07	87	3	○	○	○	○	○	○

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
308	Setting for maximum analog output AY	08	88	3	○	○	○	○	○	○
309	Analog output signal voltage/ current switchover AY	09	89	3	○	○	○	○	○	○
310	Analog meter voltage output selection AY	0A	8A	3	○	○	○	○	○	○
311	Setting for zero analog meter voltage output AY	0B	8B	3	○	○	○	○	○	○
312	Setting for maximum analog meter voltage output AY	0C	8C	3	○	○	○	○	○	○
313	DO0 output selection AY NC	0D	8D	3	○	○	○	○	○	○
314	DO1 output selection AY NC	0E	8E	3	○	○	○	○	○	○
315	DO2 output selection AY NC	0F	8F	3	○	○	○	○	○	○
316	DO3 output selection AY	10	90	3	○	○	○	○	○	○
317	DO4 output selection AY	11	91	3	○	○	○	○	○	○
318	DO5 output selection AY	12	92	3	○	○	○	○	○	○
319	DO6 output selection AY	13	93	3	○	○	○	○	○	○
320	RA1 output selection AR	14	94	3	○	○	○	○	○	○
321	RA2 output selection AR	15	95	3	○	○	○	○	○	○
322	RA3 output selection AR	16	96	3	○	○	○	○	○	○
323	AM0 0V adjustment AY	17	97	3	○	○	○	○	×	○
324	AM1 0mA adjustment AY	18	98	3	○	○	○	○	×	○
329	Digital input unit selection AX	1D	9D	3	○	○	○	○	×	○
331	RS-485 communication station	1F	9F	3	○	○	○	○	○*4	○*4
332	RS-485 communication speed	20	A0	3	○	○	○	○	○*4	○*4
333	RS-485 communication stop bit length	21	A1	3	○	○	○	○	○*4	○*4
334	RS-485 communication parity check selection	22	A2	3	○	○	○	○	○*4	○*4
335	RS-485 communication retry count	23	A3	3	○	○	○	○	○*4	○*4
336	RS-485 communication check time interval	24	A4	3	○	○	○	○	○*4	○*4
337	RS-485 communication waiting time setting	25	A5	3	○	○	○	○	○*4	○*4
338	Communication operation command source	26	A6	3	○	○	○	○	○*4	○*4
339	Communication speed command source	27	A7	3	○	○	○	○	○*4	○*4
340	Communication startup mode selection	28	A8	3	○	○	○	○	○*4	○*4
341	RS-485 communication CR/ LF selection	29	A9	3	○	○	○	○	○*4	○*4
342	Communication EEPROM write selection	2A	AA	3	○	○	○	○	○	○
343	Communication error count	2B	AB	3	○	○	○	×	×	×
345	DeviceNet address ND	2D	AD	3	○	○	○	○	○*4	○*4
346	DeviceNet baud rate ND	2E	AE	3	○	○	○	○	○*4	○*4
349	Communication reset selection NC ND NL NP	31	B1	3	○	○	○	○	○*4	○*4

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
387	Initial communication delay time NL	57	D7	3	○	○	○	○	○	○
388	Send time interval at heart beat NL	58	D8	3	○	○	○	○	○	○
389	Minimum sending time at heart beat NL	59	D9	3	○	○	○	○	○	○
390	% setting reference frequency NL	5A	DA	3	○	○	○	○	○	○
391	Receive time interval at heart beat NL	5B	DB	3	○	○	○	○	○	○
392	Event driven detection width NL	5C	DC	3	○	○	○	○	○	○
495	Remote output selection	5F	DF	4	○	○	○	○	○	○
496	Remote output data 1	60	E0	4	○	○	○	×	×	×
497	Remote output data 2	61	E1	4	○	○	○	×	×	×
500	Communication error execution waiting time NC ND NL NP NF	00	80	5	○	○	○	○	○*4	○*4
501	Communication error occurrence count display NC ND NL NP NF	01	81	5	○	○	○	×	○	○
502	Stop mode selection at communication error	02	82	5	○	○	○	○	○*4	○*4
503	Maintenance timer	03	83	5	○	○	○	×	×	×
504	Maintenance timer alarm output set time	04	84	5	○	○	○	○	×	○
505	Speed setting reference	05	85	5	○	○	○	○	○	○
522	Output stop frequency	16	96	5	○	○	○	○	○	○
539	Modbus-RTU communication check time interval	27	A7	5	○	○	○	○	○*4	○*4
542	Communication station number (CC-Link) NC	2A	AA	5	○	○	○	○	○*4	○*4
543	Baud rate selection (CC-Link)	2B	AB	5	○	○	○	○	○*4	○*4
544	CC-Link extended setting NC	2C	AC	5	○	○	○	○	○*4	○*4
549	Protocol selection	31	B1	5	○	○	○	○	○*4	○*4
550	NET mode operation command source selection	32	B2	5	○	○	○	○	○*4	○*4
551	PU mode operation command source selection	33	B3	5	○	○	○	○	○*4	○*4
553	PID deviation limit	35	B5	5	○	○	○	○	○	○
554	PID signal operation selection	36	B6	5	○	○	○	○	○	○
555	Current average time	37	B7	5	○	○	○	○	○	○
556	Data output mask time	38	B8	5	○	○	○	○	○	○
557	Current average value monitor signal output reference current	39	B9	5	○	○	○	○	○	○
563	Energization time carrying-over times	3F	BF	5	○	○	○	×	×	×
564	Operating time carrying-over times	40	C0	5	○	○	○	×	×	×
571	Holding time at a start	47	C7	5	○	○	×	○	○	○
575	Output interruption detection time	4B	CB	5	○	○	○	○	○	○

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
576	Output interruption detection level	4C	CC	5	○	○	○	○	○	○
577	Output interruption cancel level	4D	CD	5	○	○	○	○	○	○
611	Acceleration time at a restart	0B	8B	6	○	○	○	○	○	○
653	Speed smoothing control	35	B5	6	○	○	×	○	○	○
654	Speed smoothing cutoff frequency	36	B6	6	○	○	×	○	○	○
665	Regeneration avoidance frequency gain	41	C1	6	○	○	○	○	○	○
779	Operation frequency during communication error	4F	CF	7	○	○	○	○	○	○
791	Acceleration time in low-speed range	5B	DB	7	×	×	○	○	○	○
792	Deceleration time in low-speed range	5C	DC	7	×	×	○	○	○	○
799	Pulse increment setting for output power	63	E3	7	○	○	○	○	○	○
800	Control method selection	00	80	8	×	×	○	○	○	○
820	Speed control P gain 1	14	94	8	×	×	○	○	○	○
821	Speed control integral time 1	15	95	8	×	×	○	○	○	○
867	AM output filter	43	C3	8	○	○	○	○	○	○
870	Speed detection hysteresis	46	C6	8	○	○	○	○	○	○
872	Input phase loss protection selection	48	C8	8	○	○	○	○	○	○
882	Regeneration avoidance operation selection	52	D2	8	○	○	○	○	○	○
883	Regeneration avoidance operation level	53	D3	8	○	○	○	○	○	○
884	Regeneration avoidance at deceleration detection sensitivity	54	D4	8	○	○	○	○	○	○
885	Regeneration avoidance compensation frequency limit value	55	D5	8	○	○	○	○	○	○
886	Regeneration avoidance voltage gain	56	D6	8	○	○	○	○	○	○
888	Free parameter 1	58	D8	8	○	○	○	○	×	×
889	Free parameter 2	59	D9	8	○	○	○	○	×	×
891	Cumulative power monitor digit shifted times	5B	DB	8	○	○	○	○	○	○
892	Load factor	5C	DC	8	○	○	○	○	○	○
893	Energy saving monitor reference (motor capacity)	5D	DD	8	○	○	○	○	○	○
894	Control selection during commercial power-supply operation	5E	DE	8	○	○	○	○	○	○
895	Power saving rate reference value	5F	DF	8	○	○	○	○	○	○
896	Power unit cost	60	E0	8	○	○	○	○	○	○
897	Power saving monitor average time	61	E1	8	○	○	○	○	○	○
898	Power saving cumulative monitor clear	62	E2	8	○	○	○	○	×	○
899	Operation time rate (estimated value)	63	E3	8	○	○	○	○	○	○

Parameter	Name	Instruction Code *1			Control Mode-based Correspondence Table *2			Parameter Copy *3	Parameter Clear *3	All Parameter Clear *3
		Read	Write	Extended	V/F control V/F	Simple magnetic flux vector control S MFVC	IPM motor control IPM			
C0 (900)	FM terminal calibration	5C	DC	1	○	○	○	○	×	○
C1 (901)	AM terminal calibration	5D	DD	1	○	○	○	○	×	○
C2 (902)	Terminal 2 frequency setting bias frequency	5E	DE	1	○	○	○	○	×	○
C3 (902)	Terminal 2 frequency setting bias	5E	DE	1	○	○	○	○	×	○
125 (903)	Terminal 2 frequency setting gain frequency	5F	DF	1	○	○	○	○	×	○
C4 (903)	Terminal 2 frequency setting gain	5F	DF	1	○	○	○	○	×	○
C5 (904)	Terminal 4 frequency setting bias frequency	60	E0	1	○	○	○	○	×	○
C6 (904)	Terminal 4 frequency setting bias	60	E0	1	○	○	○	○	×	○
126 (905)	Terminal 4 frequency setting gain frequency	61	E1	1	○	○	○	○	×	○
C7 (905)	Terminal 4 frequency setting gain	61	E1	1	○	○	○	○	×	○
C42 (934)	PID display bias coefficient	22	A2	9	○	○	○	○	×	○
C43 (934)	PID display bias analog value	22	A2	9	○	○	○	○	×	○
C44 (935)	PID display gain coefficient	23	A3	9	○	○	○	○	×	○
C45 (935)	PID display gain analog value	23	A3	9	○	○	○	○	×	○
989	Parameter copy alarm release	59	D9	9	○	○	○	○	×	○
990	PU buzzer control	5A	DA	9	○	○	○	○	○	○
991	PU contrast adjustment	5B	DB	9	○	○	○	○	×	○
997	Fault initiation	61	E1	9	○	○	○	○	○	○
998	IPM parameter initialization	62	E2	9	○	○	○	○	○	○
999	Automatic parameter setting	63	E3	9	○	○	○	×	×	×

Appendix 4 Specification change

Appendix 4-1 SERIAL number check

Refer to page 2 for the location of the rating plate.

Rating plate example

□	○	○	○○○○○○
Symbol	Year	Month	Control number

SERIAL (Serial No.)

The SERIAL consists of one symbol, two characters indicating production year and month, and six characters indicating control number.
The last digit of the production year is indicated as the Year, and the Month is indicated by 1 to 9, X (October), Y (November), or Z (December.)

Appendix 4-2 Changed functions

(1) The following functions are available for the 400V class inverters, and the 200V class inverters manufactured in May 2010 or later. Check the SERIAL on the rating plate of the inverter or on the package.

Item	Changed functions
Added parameters	*Pr. 502 Stop mode selection at communication error* (*Refer to page 231*) *Pr. 779 Operation frequency during communication error* (*Refer to page 231*) *Pr. 997 Fault initiation* (*Refer to page 289)*
Changed parameter setting value	*Pr. 885 Regeneration avoidance compensation frequency limit value* (*Refer to page 279*)
Added model information monitor (*Refer to page 259*)	Modbus-RTU register 44001 to 44013
Added special monitors (*Refer to page 244*)	H4D 32-bit cumulative power (lower 16-bit) H4E 32-bit cumulative power (upper 16-bit) H4F 32-bit cumulative power (lower 16-bit) H50 32-bit cumulative power (upper 16-bit)
Added real-time monitors (*Refer to page 256*)	40277 32-bit cumulative power (lower 16-bit) 40278 32-bit cumulative power (upper 16-bit) 40279 32-bit cumulative power (lower 16-bit) 40280 32-bit cumulative power (upper 16-bit)

(2) The following functions are available with the products bearing the SERIAL shown below or later. Check the SERIAL on the rating plate of the inverter or on the package.

Model	SERIAL (Serial No.)
FR-F720P-0.75K to 110K FR-F740P-0.75K to 160K	○08○○○○○○ (August 2010 or later)
FR-F740P-185K or higher	○07○○○○○○ (July 2010 or later)

Item	Changed functions
Specification change of the IPM parameter initialization	*Pr. 893 Energy saving monitor reference (motor capacity)* is initialized for IPM control when the IPM motor control is selected with the operation panel or IPM parameter initialization is performed with *Pr. 998 IPM parameter initialization*. (*Refer to page 81*)
LF signal operation while *Pr. 502 Stop mode selection at communication error* = "3."	While *Pr. 502 Stop mode selection at communication error* = "3," the alarm output signal (LF) is output from an inverter terminal at a detection of a communication error. (*Refer to page 232*)
Added parameter setting value	Setting value “4” for *Pr. 17 MRS input selection*

(3) The following functions are available with the products bearing the SERIAL shown below or later. Check the SERIAL on the rating plate of the inverter or on the package.

Model	SERIAL (Serial No.)
FR-F740P-1.5K to 45K	○11○○○○○○ (January 2011 or later)
FR-F740P-0.75K, 55K	○13○○○○○○ (March 2011 or later)

Item	Changed functions
Added parameter setting values	Setting value "210" for *Pr. 71 Applied motor* (*Refer to page 122*)
	Setting values "12 and 112" for *Pr. 998 IPM parameter initialization* (*Refer to page 80*)
	Setting value "12" for *IPM (IPM parameter initialization)* (*Refer to page 77*)

Appendix 5 Index

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REVISIONS

*The manual number is given on the bottom left of the back cover.

Print Date	*Manual Number	Revision
Oct. 2010	IB(NA)-0600412ENG-A	First edition
Apr 2011	IB(NA)-0600412ENG-B	Addition · MM-EFS71M4 to 55K1M4 · Setting value "210" for *Pr. 71 Applied motor* · Setting values "12, 112" for *Pr. 998 IPM parameter initialization* · Setting value "12" for IPM (IPM parameter initialization)

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