ZXL -208	Read Low Threshold: _ZXL208_ReadLowThreshold

Basic function	Reads the low threshold value from the Smart Sensor.
Symbol	
File name	Lib\FBL\omronlib\LaserSensor\ZXL_ZXL208_ReadLowThreshold10.cxf

Applicable models	Laser Sensor	ZX-LDA-N
	CPU Unit	CS1*-CPU**H Unit version 3.0 or higher CJ1*-CPU**H Unit version 3.0 or higher CJ1M-CPU** Unit version 3.0 or higher CP1H CP1L (except 10 points CPU)
	Serial Communications Units/Boards	CS1W-SCU21-V1, CJ1W-SCU21-V1, CJ1W-SCU41-V1 Unit Version 1.2 or higher CS1W-SCB21-V1 and CS1W-SCB41-V1 Unit Version 1.2 or higher
	CX-Programmer	Version 5.0 or higher

Conditions for usage	External Connections
	• Can be used only for 1:1 connections.
	  (FB "_ZXLN***" can be used for 1:N connections)
	• Communications must be within one network and cannot cross to another network.
	Communications Settings
	  The communications settings of the serial port must be the same as those of the Laser Sensor.
	• The communications settings of the specified serial port can be set to the default Laser Sensor settings using the Set Communications Port (_ZXL600_SetComm) function block, and the other Laser Sensor settings using the Set Serial Gateway Mode (_SCx604_SetPortGATEWAY) function block.
	CPU Unit Settings
	  PLC Setup: Shared Settings for Communications Instructions in FBs
	• Communications Instruction Response Timeout Time (default: 2 s) 5 s recommended
	• Number of retries (default: 0)
	Shared Resources
	• Communications ports (internal logical ports)

Function description	When the Start Trigger turns ON, the low threshold value is read from the Smart Sensor connected to the Serial Port specified by the *Connection unit* and *Serial port No.* The threshold data read with this FB does not include the decimal point position. Use the Read Decimal Point Position FB (_ZXL202_ReadDecimalPoint) to read the decimal point.
FB precautions	• This FB is processed over multiple cycles. The BUSY output variable can be used to check whether the FB is being processed. • OK or NG will be turned ON only for one cycle after processing is completed. Use these flags to detect the end of the FB processing. **Time Chart** • When this FB is started, the output parameters are cleared. See the output parameters when the OK flag turns ON.
EN input condition	Connect EN to an OR between an upwardly differentiated condition for the start trigger and the BUSY output from the FB.
Restrictions Input variables	• Always use an upwardly differentiated condition for EN. • If the input variables are out of range, the ENO Flag will turn OFF and the FB will not be processed.
Output variables	• This FB requires multiple cycles to process. Always connect an OR including the BUSY output variable to the EN input variable to ensure that the FB is processed to completion (see *Symbol*). • Do not turn the BUSY output variable ON or OFF outside the FB.

Other	• Up to 3 seconds may be required for this FB to be completed (i.e., from EN turning ON until the OK or NG Flag turns ON).

Application example	A Smart Sensor is connected 1:1 to serial port 1 on a Serial Communications Board (SCB).
	 When bit A turns ON, the value of the low threshold of the Smart Sensor is stored in D0 and D1. If the stored value is &30000 and the decimal point position is &1, the actual value is 3.0000.
	
	 Connection unit: SCB (#BBBB)
	 Serial Port No.: 1
	
	 SCB CPU SCU
	
	 Smart Sensor 1:1 connection
	
	 Bit A ——— Processing to read decimal point position
	
	 Bit B ↑
	 Bit C
	
	 _ZXL208_ReadLowThreshold
	 (BOOL) EN ENO (BOOL)
	 Unit selection #BBBB — UnitSelect (INT) BUSY (BOOL) — *Busy flag* Bit C
	 Serial Port No. &1 — PortNo (INT) OK (BOOL) — *Normal end* Bit D
	                NG (BOOL) — *Error end* Bit E
	          Threshold (DINT) — *Threshold* D0

Related manuals	ZX-L-N Series Smart Sensors Laser Type User's Manual (Z197) ZX Series Smart Sensors Operation Manual (Z157)
Related FBs	Read Decimal Point FB (_ZXL202_ReadDecimalPoint) Read High Threshold (_ZXL207_ReadHighThreshold)

■ **Variable Tables**

Input Variables

Name	Variable name	Data type	Default	Range	Description
EN	EN	BOOL			1 (ON): FB started. 0 (OFF): FB not started.
Unit selection	UnitSelect	INT	&0	At right.	Specify the Unit and the serial port.
Serial Port No.	PortNo	INT	&1	&1 to &2	Only serial port 2 of CP1H/CP1L M-type CPU unit is possible to use this FB. ■ Connected to CPU Unit Unit selection #FFFF Serial port No. Not accessed. (CP1H/CP1L-M: Serial Port2 CP1L-L14/20: Serial Port1) ■ Connected to Serial Communication Board(SCB) Unit selection #BBBB Serial port No. &1: Serial Port 1 &2: Serial Port 2 ■ Connected to Serial Communication Unit(SCU) Unit selection SCU Unit No. (&0 to &15) Serial port No. &1: Serial Port 1 &2: Serial Port 2

Output Variables

Name	Variable name	Data type	Range	Description
ENO (May be omitted.)	ENO	BOOL		1 (ON): FB processed normally. 0 (OFF): FB not processed or ended in an error.
Busy Flag	BUSY	BOOL		Automatically turns OFF when processing is completed.
Normal end	OK	BOOL		Turns ON for one cycle when processing ends normally.
Error end	NG	BOOL		Turns ON for one cycle when processing ends in an error.
Threshold	Threshold	DINT	19999 to 59999	Outputs the value of the low threshold.

Internal Variables

Internal variables are not output from the FB.

If the NG Flag from the FB turns ON, the following internal variables can be monitored to obtain information on the error.

Name	Variable name	Data type	Range	Description
Error code	ErrorCode	WORD		The results information from the Smart Sensor is output to the Error Code. See below.

Error Code Details

Code	Contents	Meaning
#0000	Normal end	
#2203	Operation error	• A setting is incorrect. Refer to the *Smart Sensor Operation Manual* for setting error conditions for thresholds, hystereses, and other parameters.
#2204	Operation error	• The Sensor is not in RUN mode.

Version History

Version	Date	Contents
1.00	2004.6.	Original production

Note

This manual is a reference that explains the function block functions.

It does not explain the operational limitations of Units, components, or combinations of Units and components. Always read and understand the Operation Manuals for the system's Units and other components before using them.