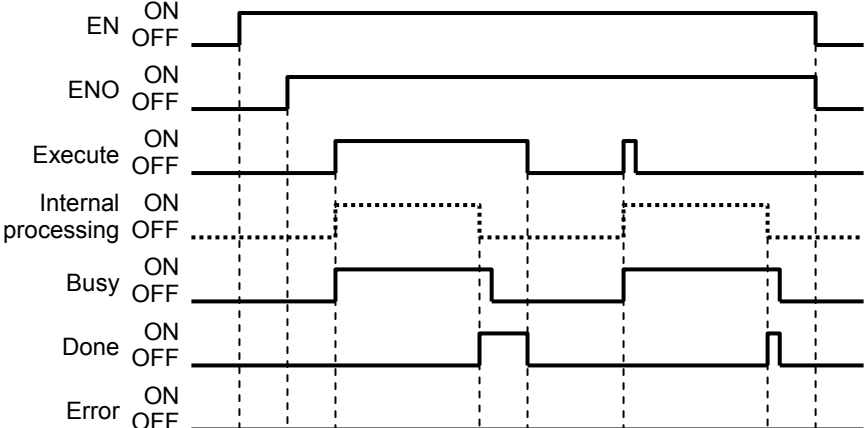
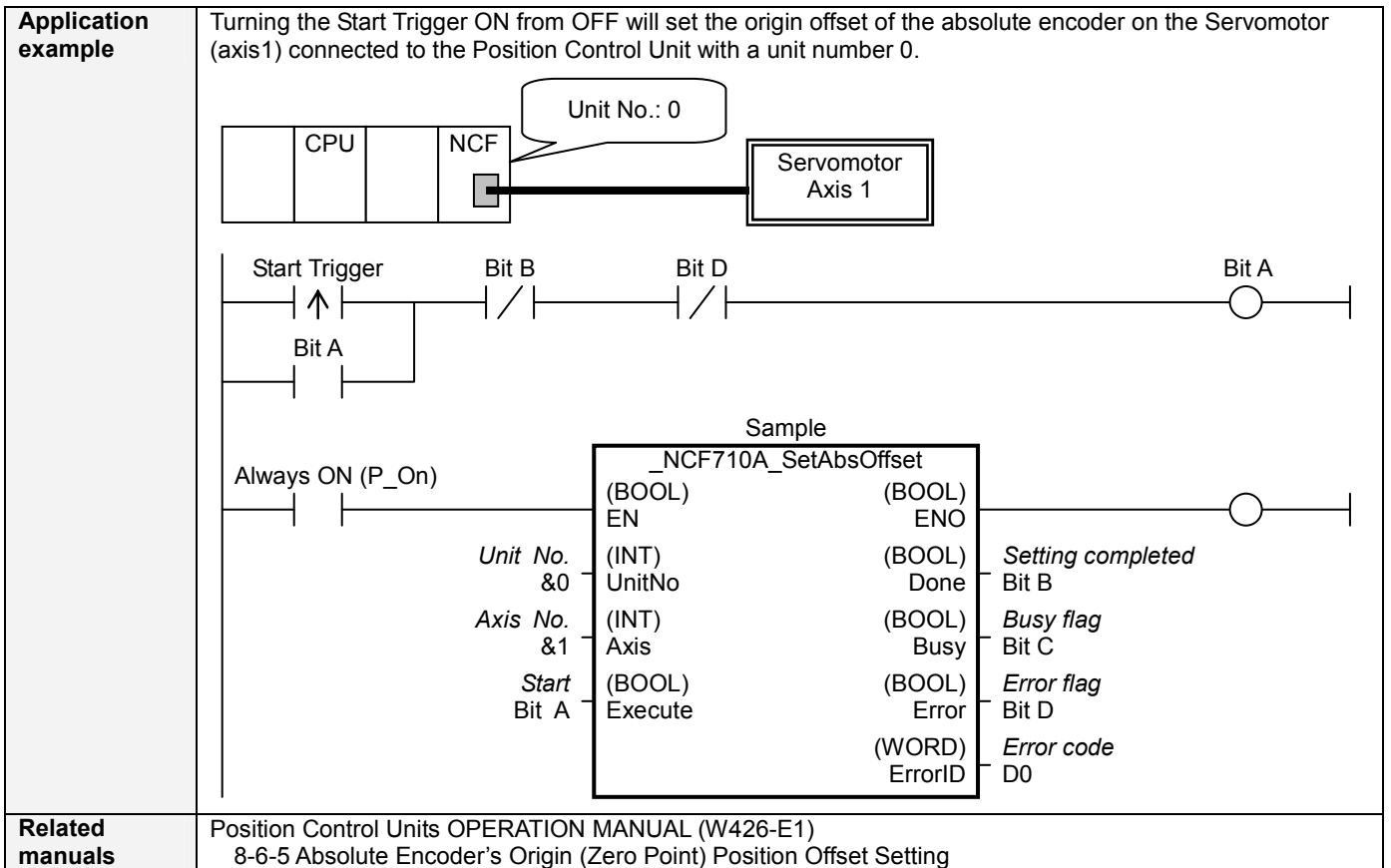


NCF 710A	Absolute Encoder's Origin Position Offset Setting _NCF710A_SetAbsOffset
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Basic function	Sets an origin position offset of the absolute encoder. (Busy attachment)																																								
Symbol	<div style="display: flex; justify-content: space-around; margin-top: 10px;"> <table border="1" style="border-collapse: collapse;"> <tr><td style="padding: 2px;">_NCF710A_SetAbsOffset</td></tr> <tr><td style="padding: 2px;">(BOOL) EN</td></tr> <tr><td style="padding: 2px;">(INT) UnitNo</td></tr> <tr><td style="padding: 2px;">(INT) Axis</td></tr> <tr><td style="padding: 2px;">(BOOL) Execute</td></tr> </table> <table border="1" style="border-collapse: collapse;"> <tr><td style="padding: 2px;">(BOOL) ENO</td></tr> <tr><td style="padding: 2px;">(BOOL) Done</td></tr> <tr><td style="padding: 2px;">(BOOL) Busy</td></tr> <tr><td style="padding: 2px;">(BOOL) Error</td></tr> <tr><td style="padding: 2px;">(WORD) ErrorID</td></tr> </table> </div>	_NCF710A_SetAbsOffset	(BOOL) EN	(INT) UnitNo	(INT) Axis	(BOOL) Execute	(BOOL) ENO	(BOOL) Done	(BOOL) Busy	(BOOL) Error	(WORD) ErrorID																														
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File name	Lib\FBL\omronlib\PositionController\NCF_NCF710A_SetAbsOffset11.cxf																																								
Applicable models	<table border="1" style="border-collapse: collapse; width: 100%;"> <tr> <td style="width: 30%;">Position Control Unit</td> <td>CJ1W-NCF71, CS1W-NCF71</td> </tr> <tr> <td>CPU Unit</td> <td>CS1*-CPU**H Unit Version 3.0 or later CJ1*-CPU**H Unit Version 3.0 or later CJ1M-CPU** Unit Version 3.0 or later CP1H</td> </tr> <tr> <td>CX-Programmer</td> <td>Version 5.0 or later</td> </tr> </table>	Position Control Unit	CJ1W-NCF71, CS1W-NCF71	CPU Unit	CS1*-CPU**H Unit Version 3.0 or later CJ1*-CPU**H Unit Version 3.0 or later CJ1M-CPU** Unit Version 3.0 or later CP1H	CX-Programmer	Version 5.0 or later																																		
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Languages in function block definitions	Ladder programming																																								
Conditions for usage	<p>The following conditions for usage should be the Position Control Unit version 1.2 or earlier. (It will not be required in the Position Control Unit version 1.3 or later)</p> <p>■CX-Programmer Setting</p> <p>The function blocks related to the Position Control Units will not operate if the area H512 or higher (default setting) is specified as the Non Retain Area through the Function block memory allocation. Make sure to change the memory area to unused area (DM or EM, for example) from the CX-Programmer. To change this value, click PLC/Function Block Memory/Function Block Memory Allocation from the Menu Bar.</p> <div style="display: flex; align-items: center;"> <table border="1" style="border-collapse: collapse; margin-right: 10px;"> <caption>Function Block Memory Allocation [NewPLC1]</caption> <thead> <tr><th>FB Instance Area</th><th>Start Address</th><th>End Address</th><th>Size</th></tr> </thead> <tbody> <tr><td>No Retain</td><td>H512</td><td>H1407</td><td>896</td></tr> <tr><td>Retain</td><td>H1408</td><td>H1535</td><td>128</td></tr> <tr><td>Timers</td><td>T3072</td><td>T4095</td><td>1024</td></tr> <tr><td>Counters</td><td>C3072</td><td>C4095</td><td>1024</td></tr> </tbody> </table> <div style="border: 1px solid black; padding: 5px; border-radius: 10px; width: fit-content;"> <p>Specify unused area. The required size varies depending on the used FB and the number of FBs. If an area being used in the ladder program is specified or sufficient free space cannot be found, the CX-Programmer will display a compile error.</p> </div> <table border="1" style="border-collapse: collapse; margin-left: 10px;"> <caption>Function Block Memory Allocation [NewPLC1]</caption> <thead> <tr><th>FB Instance Area</th><th>Start Address</th><th>End Address</th><th>Size</th></tr> </thead> <tbody> <tr><td>No Retain</td><td>D32020</td><td>D32767</td><td>748</td></tr> <tr><td>Retain</td><td>H1408</td><td>H1535</td><td>128</td></tr> <tr><td>Timers</td><td>T3072</td><td>T4095</td><td>1024</td></tr> <tr><td>Counters</td><td>C3072</td><td>C4095</td><td>1024</td></tr> </tbody> </table> <div style="margin-left: 20px;"> <p>For example, to use the memory area from D32020 to D32767 (748 words), specify the addresses as shown in the left.</p> </div> </div>	FB Instance Area	Start Address	End Address	Size	No Retain	H512	H1407	896	Retain	H1408	H1535	128	Timers	T3072	T4095	1024	Counters	C3072	C4095	1024	FB Instance Area	Start Address	End Address	Size	No Retain	D32020	D32767	748	Retain	H1408	H1535	128	Timers	T3072	T4095	1024	Counters	C3072	C4095	1024
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<p>Function description</p>	<p>The Busy Output is added to the _NCF710_SetAbsOffset in this FB.</p> <p>Sets the origin offset of the absolute encoder for the axis specified with Unit No. and Axis No. when Start (Execute) is turned ON. This FB processes the feedback present position to set the offset in the Servo Parameter Absolute encoder zero point position offset (Refer to the <i>Restrictions Other</i>).</p> <p>The Busy flag (Busy) will be set when the Start (Execute) is turned ON.</p> <p>The Busy flag (Busy) will be reset when any of the Setting completed (Done) or Error flag (Error) is turned ON. Even if an error occurs when the input variable is out of the range, etc., the Busy flag (Busy) will be set for at least one cycle.</p> <p>The Error flag (Error) will be turned ON and the Error code (ErrorID) will be output if an error occurs for the FB. This will not occur for error in other FBs or other instances of the FB.</p> <p>These statuses (Done/Error/ErrorID) will be reset when the Start (Execute) turns OFF. If the Start (Execute) turns OFF before the operation has been completed, the status will be set for at least one cycle when corresponding conditions have occurred.</p> <p>This FB should be used according to the following procedure:</p> <ul style="list-style-type: none"> • Set so that the absolute encoder is used as an absolute encoder. • Setup the absolute encoder. • Start MECHATROLINK communications (i.e., establish connection). • Stop the axis at the position to be set as a machine origin. • When executing this FB, the No Origin Flag turns ON meaning an origin is not established, and "Setting completed (Done)" turns ON. • By executing SERVO LOCK, the No Origin Flag turns OFF and the origin is established. <p>Reflecting the origin position offset, the present position is Clear to 0.</p> 																		
<p>Kind of FB definition</p>	<p>Always execution type.</p> <p>Connect the EN input to the Always ON Flag (P_On).</p> <p>The same instance cannot be used in two or more places.</p>																		
<p>EN input condition</p>	<ul style="list-style-type: none"> • Connect the EN input to the Always ON Flag (P_On). • If another bit is connected to EN, the FB outputs will be held when the connected bit turns OFF. 																		
<p>Restrictions Other</p>	<ul style="list-style-type: none"> • Following are Servo Parameters which this FB sets. <table border="1" data-bbox="391 1384 1465 1527"> <thead> <tr> <th>Drive</th> <th>PRM No.</th> <th>Parameter name</th> <th>Size</th> <th>Unit</th> <th>Setting range</th> </tr> </thead> <tbody> <tr> <td>W-Series</td> <td>Pn808</td> <td>Absolute encoder zero point position offset</td> <td>4</td> <td>command units</td> <td>-1073741823 to 1073741823</td> </tr> <tr> <td>G-Series</td> <td>Pn200 (808)</td> <td>Absolute origin offset</td> <td>4</td> <td>command units</td> <td>-1073741823 to 1073741823</td> </tr> </tbody> </table> <ul style="list-style-type: none"> • This FB uses Unit Error Reset, Write Data, Read Data and Save Data Bits of the Position Control Unit (see Note). Therefore, do not turn these bits ON or OFF between the period from the rising edge of EN to the rising edge of ENO. For the same reason, do not use these bits for coil outputs (OUT commands). • The output variable of FB may not change even if EN is turned ON. In that case, check if any of Unit Error Reset, Write Data, Read Data and Save Data Bit is left ON. • This FB uses the Device Setup/ Servo Unlock/ Read Servo Parameter/ Save Servo Parameter Bits in the Axis Operating Output Memory Areas. Therefore, do not turn these bits ON or OFF until the operation is completed. For the same reason, do not use these bits for coil outputs (OUT commands). <p>Note:</p> <p>For calculation of bit addresses, these bits are referenced in this FB in the first execution of each instance, and when changing "Unit No. (UnitNo)", "Axis No. (Axis)" of the input variable and set "Start (Execute)".</p>	Drive	PRM No.	Parameter name	Size	Unit	Setting range	W-Series	Pn808	Absolute encoder zero point position offset	4	command units	-1073741823 to 1073741823	G-Series	Pn200 (808)	Absolute origin offset	4	command units	-1073741823 to 1073741823
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■Variable Tables

Input Variables

Name	Variable name	Data type	Default	Range	Description
EN	EN	BOOL			1 (ON): FB started 0 (OFF): FB not started
Unit No.	UnitNo	INT	&0	&0 to &15	Specify the unit number.
Axis No.	Axis	INT	&0	&1 to &16	Specified value corresponds to the Axis No.
Start	Execute	BOOL	0(OFF)		↕ : Executes setting

Output Variables

Name	Variable name	Data type	Range	Description
ENO	ENO	BOOL		1 (ON): FB operating normally 0 (OFF): FB not operating normally <ul style="list-style-type: none"> •FB not started •Input variable out of the range •FB ended with error •Common Parameters could not be read
Setting completed	Done	BOOL		1 (ON) indicates that setting has been completed.
Busy flag	Busy	BOOL		1 (ON) indicates that the FB is in progress.
Error flag	Error	BOOL		1 (ON) indicates that an error has occurred in the FB.
Error code	ErrorID	WORD		Returns the error code when an error has occurred in the FB. Refer to the <i>Related Manuals</i> for details on errors. A code of #0000 will be returned if any of the following conditions is satisfied. <ul style="list-style-type: none"> •Input variable is out of range. •The common parameters of the Position Control Units are out of range. •Not established communications with a specified axis. •While either of Device Setup/Servo Unlock/Read Servo Parameter/Save Servo Parameter is in operation, a corresponding command bit has been changed by other FB.

■Version History

Version	Date	Contents
1.13	2006.01.	Original production

■Note

This document explains the function of the function block.

It does not provide information of restrictions on the use of Units and Components or combination of them. For actual applications, make sure to read the operation manuals of the applicable products.