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NC2x 631	Torque Limits _NC2x631_TorqueLimits					
Basic function	Outputs the torque limit signal.					
Symbol						
5	Always ON (P_On) (BOOL) (BOOL)					
	Unit No (INT) (BOOL) UnitNo Status - Output status					
	Avia (INT) (BOOL) Error					
	Torque limit - Enable ErrorID - Error code					
File name	Lib\FBL\omronlib\PositionController\NC2x\ NC2x631 TorqueLimits10.cxf					
Applicable	Position Control Units CJ1W-NC214/234/414/434					
models	CPU Unit CJ1*-CPU**H Version 3.0 or later					
	CJ1M-CPU** Version 3.0 or later					
	CP1H CJ2H-CPU**(-EIP)					
	CX-Programmer Version 5.0 or later					
Languages in	Ladder programming					
function block definitions						
Conditions for	None.					
usage Function	For the suis energified in White Ner (Heithle) and "Avia Ner (Avia)" the termus limit extruct signal will turn ON					
description	• For the axis specified in "Unit No. (UnitNo)" and "Axis No. (Axis)", the torque limit output signal will turn ON when "Torque limit (Enable)" is turned ON, and the signal will turn OFF when it's turned OFF.					
uccomption	"Output status (Status)" will reflect the torque limits signal status of the applicable axis.					
	 "Error (Error)" will be turned ON "Error code (ErrorID)" will be output if an error occurs for the FB. This will 					
	not occur for error in other FBs or other instances of the FB.					
	These statuses (Error/ErrorID) will be reset when "Torque limit (Enable)" turns OFF.					
	Status OFF					
	Error OFF					
	Torque limits ON signal OFF					
Kind of FB	Always execution type.					
definition	Connect the EN input to the Always ON Flag (P_On).					
	The same instance cannot be used in two or more places.					
EN input condition	 Connect the EN input to the Always ON Flag (P_On). If another bit is connected to EN, the FB outputs will be held when the connected bit turns OFF. 					
Restrictions	This FB does not recognize the existence of the axis specified in "Unit No. (UnitNo)" and "Axis (Axis)". If					
Other	these input variables have not been set correctly, the FB may not work normally.					
	This FB uses bits of the Position Control Unit. Therefore, do not turn these bits ON or OFF. For the same					
	reason, do not use these bits for coil outputs (OUT commands). Refer to the "∎Used bits list" for the bits used by this FB.					
Application	Turning ON bit A will enable the torque limit output signal of the axis (Axis1) connected to the Position Control					
example	Unit of unit number 0.					
	Unit No.: 0					
	CPU NC Servo motor					
	Axis 1					
	Sample					
	Always ON (P_On) (BOOL) (BOOL)					
	Unit No. (INT) (BOOL) Output status &0 UnitNo Done Bit B					
	Axis (INT) (BOOL) Error					
	81 Axis Error Bit C					
	Torque limit (BOOL) (WORD) Error code Bit A Enable ErrorID D0					
Related						
manuals	CJ-series Position Control Unit Operation Manual (W477) 9-4 Torque Limit					
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■Variable Tables

Name	Variable name	Data type	Default	Range	Description
EN	EN	BOOL			1(ON): FB started
					0(OFF): FB not started
Unit No.	UnitNo	INT	&0	&0 to &94	Specify the unit number.
Axis	Axis	INT	&1	&1 to &4	Specify the axis number.
Torque limit	Enable	BOOL	0(OFF)		
					✓: Torque limit disabled

Output Variables

Name	Variable name	Data type	Range	Description
ENO	ENO	BOOL		1(ON): FB operating normally
				0(OFF): FB not started / FB ended with error
Output	Status	BOOL		1(ON): The torque limits signal is output status.
status				0(OFF): The torque limits signal is stopping status.
Error	Error	BOOL		Turns ON when an error has occurred in the FB. Refer to "Error code
				(ErrorID)" for details.
Error code	ErrorID	WORD		Returns the error code when an error occurred in the FB. Refer to "Error
				code list" for details.

■Error code list

Error code list			
Error name	Error code	Probable cause	Clearing method
Input variable out of range	#0001	The value of input variable of this FB is out of valid range.	Set the value of input variable within the specified range.
Operating memory area allocation out of range	#0002	The allocation of Axis Operating Memory Area of Common Parameter is out of allowable setting range.	Correct the allocation of Axis Operating Memory Area of Common Parameter so that it falls within the allowable setting range of data.

∎Used bits list

Memory area	Name	Data type	Address	Note
Manual Operation Command Memory area	Torque limit output	BOOL	A+00.03	

■Version History

Version	Date	Contents		
1.00	2009.06.	Original production.		

∎Note

This document explains the function of the function block.

It does not provide information of restrictions on the use of Units and Components or combination of them. For actual applications, make sure to read the operation manuals of the applicable products.