# Read Power Tuning Target Value Setting: \_ExxDRT205\_ReadPTSV

Basic function	Reads the power tuning target value (set value) of a Digital Type Sensor in the DeviceNet network.					
Symbol	Start Trigger		ExxDRT205 Rea	adPTSV	]]	
			(BOOL)	(BOOL)		
			EN (INT)	ENO (BOOL)		
	Busy Flag Mast	er Unit number	MasterUnitNo	FB_BUSY	FB Busy Flag	
	Slave	e node address	(INT) NodeNo	(BOOL) FB_OK	FB Normal End	
			(INT)	(BOOL)	FB Error End	
	Sensor Amplif	ier unit number	SensorUnitNo	FB_NG (UINT)		
				PTSV	Power Tuning Target Value	
File name	Lib\FBL\omronlib\Digi	talTvpeSensor	ExxDRT\ ExxDRT2	05 ReadPT	SV10.cxf	
Applicable	Applicable Master		1(-V1) and CJ1W-D			
models	Units		-			
	Applicable Slave Units	E3X-DRT21-S	6			
	Applicable Sensor				/-S, and E3X-DARM-S	
	Amplifiers			models and	E3C-LDA input models	
	CPU Unit		Not supported. I Unit version 3.0 c	n higher		
			I Unit version 3.0 o			
			Unit version 3.0 or			
		CP1H		-		
Conditions	CX-Programmer Sensor	Version 5.0 or	r higher			
for usage		e is connected	when the power is t	urned ON the	e function cannot be used because	
iei acage			lished with the Sens			
	The Sensor must	be in RUN mod	le. The function canr	not be used w	when the Sensor is in another mode,	
	i.e., SET mode.					
	CPU Unit Settings	Catting of far Ca		unting in ED		
	<ul> <li>DeviceNet Response</li> </ul>		ommunications Instructions (default: 2 s)	uctions in FB	S	
	A Timeout time of					
	Number of retries					
	Shared Resources					
	Communications ports (internal logical ports)					
	Other • Communications r	must be within c	one network and car	not cross to	another network	
Function					viceNet network with the specified	
description	Master Unit number, S					
FB			e cycles. The FB_Bl	JSY output v	ariable can be used to check whether	
precautions	<ul> <li>the FB is being processed.</li> <li>FB_OK or FB_NG will be turned ON for one cycle only after processing is completed. Use these flags to</li> </ul>					
	• <i>PB_OK</i> of <i>PB_NG</i> detect the end of F			y aller proce	ssing is completed. Use these hags to	
	■ Timing Chart	_ p. 50000mg.				
	Start Trigger	ON OFF	<u></u>			
	FB Busy Flag (FB_BU	SY) ON				
		OFF	J L			
	FB Normal End (FB_					
	FB Error End (FB_NG)	OFF				
					al End Flag goes ON when the target en read and stored.	
		) h o t				
EN input condition	output from the FB.	-	-		or the start trigger and the FB_BUSY	
Restrictions	Always use an upwardly differentiated condition for EN.					
Input variables					and the FB will not be processed.	
Output					R including the FB_BUSY output	
variables					d to completion (see <i>Symbol</i> ).	
	Do not turn the FB_BUSY output variable ON or OFF outside the FB.					

Application example	A Digital Sensor Communication Unit (node 11) is connected to a DeviceNet Unit with Master unit number 10. When bit A turns ON, the function reads the power tuning target value of the Sensor Amplifier with unit number 2 and outputs the result to D00100.
	Start Trigger Bit A FB Busy Flag Bit B Slave node address Bit B Slave node address Bit B Slave node address & 11 Sensor Amplifier unit number & 22 & 22 Bit A C EXXDRT205_ReadPTSV (BOOL) EN (NT) (BOOL) EN (NT) (BOOL) EN (NT) (BOOL) EN (NT) (BOOL) EN (NT) (BOOL) EN (NT) (BOOL) EN (NT) (BOOL) (NT) (BOOL) MasterUnitNo FB_BUSY (INT) (BOOL) MasterUnitNo FB_BUSY (INT) (BOOL) MasterUnitNo FB_BUSY (INT) (BOOL) Bit B FB Busy Flag Bit B FB Normal End Bit D FB Error End Bit D Power Tuning Target Value D100
	Normal End Flag Bit C Processing after power tuning target value has been read
Related manuals	Communication Unit For Digital Fiber Sensor E3X-DRT21-S (DeviceNet) (Z223-E1) Section 2 E3X-DRT21 for Device Net Communications CS/CJ Series Communications Commands Reference Manual (W342-E1) 5-1 Command Lists

# Variable Tables

Name	Variable name	Data type	Default	Range	Description
EN	EN	BOOL			1 (ON): FB started 0 (OFF): FB not started.
Master Unit No.	MasterUnitNo	INT	&0	&0 to &15 #0 to #F	Specify the unit number of the DeviceNet Unit.
Slave node address	NodeNo	INT	&0	&0 to &63	Specify the node address of the slave.
Sensor Amplifier unit number	SensorUnitNo	INT	&1	&1 to &13 or &1 to &16	Depending on the communication mode setting, the maximum number of connectable Units is either 13 or 16 Units. Specify a unit number within the allowed range. Refer to the <i>Related Manuals</i> for details.

# **Output Variables**

Name	Variable name	Data type	Range	Description	
ENO	ENO	BOOL		1 (ON): FB processed normally.	
(May be omitted.)				0 (OFF): FB not processed or ended in an error.	
FB Busy Flag	FB_BUSY	BOOL		Automatically turns OFF when processing is completed.	
FB Normal End	FB_OK	BOOL		Turns ON for one cycle when processing ends normally.	
FB Error End	FB_NG	BOOL		Turns ON for one cycle when processing ends in an error.	
Power Tuning Target Value	PTSV	UINT		Outputs the power tuning target value.	

#### **Internal Variables**

Internal variables are not output from the FB.

If the FB\_NG Flag turns ON, the following internal variables can be monitored to obtain information on the error.

Name	Variable name	Data type	Range	Description
FINS error code	FINS_ErrorCode	WORD		The FINS error code is output. A code of #0000 is output for a normal end. Refer to the <i>Related Manuals</i> for details on the error codes.
Explicit message error code	Explicit_ErrorCode	WORD		Outputs the explicit message error code. A code of #0000 is output for a normal end. Refer to the <i>Related Manuals</i> for details on the error codes.

# **Explicit Error Code Details**

Code	Contents	Meaning
#0000	Normal end	
#16FF	No Sensor Amplifier	There is no Sensor Amplifier with the specified unit number.
#0CFF	Not executable	The specified command cannot be executed.
		A Mobile Console is connected.
		<ul> <li>There is an error in communications with the Sensor Amplifier.</li> </ul>
		• The Sensor Amplifier is in an operation mode other than RUN mode.
		• The FB was executed for a Sensor Amplifier that is not supported.

## Version History

Version	Date	Contents
1.00	2005.4.	Original production

## Note

This manual is a reference that explains the function block functions.

It does not explain the operational limitations of Units, components, or combinations of Units and components. Always read and understand the Operation Manuals for the system's Units and other components before using them.