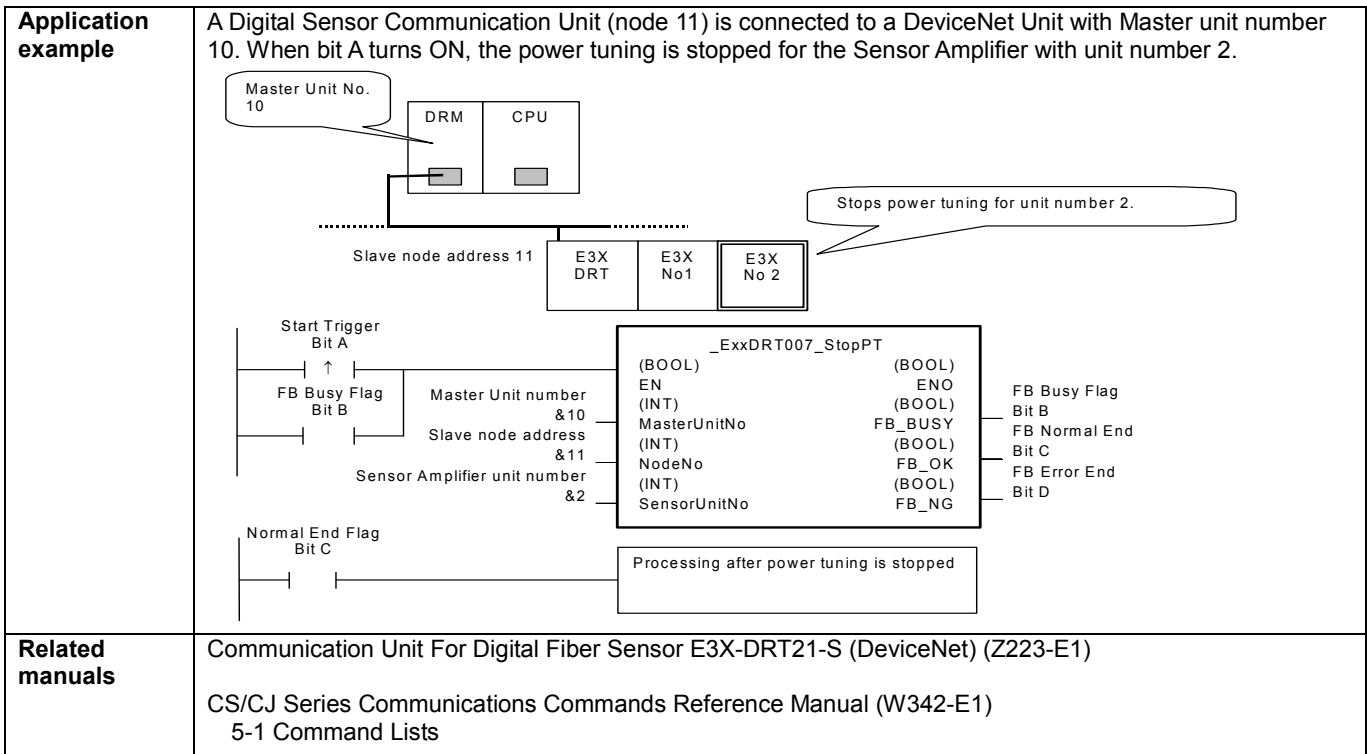| ExxDRT 007	Clearing Power Tuning: _ExxDRT007_StopPT

Basic function	Clearing power tuning in a Digital Type Sensor in the DeviceNet network.
Symbol	Start Trigger _ExxDRT007_StopPT Busy Flag Master Unit number (BOOL) EN ENO (BOOL) (INT) MasterUnitNo FB_BUSY (BOOL) — FB Busy Flag Slave node address — (INT) NodeNo FB_OK (BOOL) — FB Normal End Sensor Amplifier unit number — (INT) SensorUnitNo FB_NG (BOOL) — FB Error End
File name	Lib\FBL\omronlib\DigitalTypeSensor\ExxDRT_ExxDRT007_StopPT10.cxf
Applicable models	Applicable Master Units	CS1W-DRM21(-V1) and CJ1W-DRM21
	Applicable Slave Units	E3X-DRT21-S
	Applicable Sensor Amplifiers	E3X Series: E3X-DA-S, E3X-MDA, E3X-DATW-S, and E3X-DARM-S E3C Series: E3C-LDA two-output models and E3C-LDA input models E2C Series: E2C-EDA two-output models and E2C-EDA input models
	CPU Unit	CS1*-CPU**H Unit version 3.0 or higher CJ1*-CPU**H Unit version 3.0 or higher CJ1M-CPU** Unit version 3.0 or higher CP1H
	CX-Programmer	Version 5.0 or higher

Conditions for usage	Sensor
	• If a Mobile Console is connected when the power is turned ON, the function cannot be used because communications cannot be established with the Sensor.
	• The Sensor must be in RUN mode. The function cannot be used when the Sensor is in another mode, i.e., SET mode.
	CPU Unit Settings
	  PLC Setup: Shared Settings for Communications Instructions in FBs
	• DeviceNet Response Timeout Time (default: 2 s)
	  A Timeout time of 10 s or higher is recommended.
	• Number of retries (default: 0)
	Shared Resources
	• Communications ports (internal logical ports)
	Other
	• Communications must be within one network and cannot cross to another network.

Function description	Clearing power tuning for the Sensor Amplifier in the DeviceNet network with the specified Master Unit number, Slave node address, and Sensor Amplifier unit number.
FB precautions	• The FB is processed over multiple cycles. The FB_BUSY output variable can be used to check whether the FB is being processed. • *FB_OK* or *FB_NG* will be turned ON for one cycle only after processing is completed. Use these flags to detect the end of FB processing. ■ Timing Chart Start Trigger ON / OFF FB Busy Flag (FB_BUSY) ON / OFF FB Normal End (FB_OK) or ON FB Error End (FB_NG) OFF When the FB Normal End Flag goes ON, the results of the FB processing are reflected in the Sensor Amplifier.
EN input condition	Connect EN to an OR between an upwardly differentiated condition for the start trigger and the FB_BUSY output from the FB.
Restrictions Input variables	• Always use an upwardly differentiated condition for EN. • If the input variables are out of range, the ENO Flag will turn OFF and the FB will not be processed.
Output variables	• This FB requires multiple cycles to process. Always connect an OR including the FB_BUSY output variable to the EN input variable to ensure that the FB is processed to completion (see *Symbol*). • Do not turn the FB_BUSY output variable ON or OFF outside the FB.

Application example	A Digital Sensor Communication Unit (node 11) is connected to a DeviceNet Unit with Master unit number 10. When bit A turns ON, the power tuning is stopped for the Sensor Amplifier with unit number 2.
	Master Unit No. 10
	DRM CPU
	Stops power tuning for unit number 2.
	Slave node address 11 E3X DRT E3X No1 E3X No 2
	Start Trigger Bit A
	↑
	FB Busy Flag Bit B Master Unit number &10 _ExxDRT007_StopPT
	Slave node address &11
	(BOOL) (BOOL)
	EN ENO
	(INT) (BOOL) FB Busy Flag Bit B
	MasterUnitNo FB_BUSY FB Normal End Bit C
	(INT) (BOOL) FB Error End Bit D
	NodeNo FB_OK
	Sensor Amplifier unit number &2 (INT) (BOOL)
	SensorUnitNo FB_NG
	Normal End Flag Bit C
	Processing after power tuning is stopped
Related manuals	Communication Unit For Digital Fiber Sensor E3X-DRT21-S (DeviceNet) (Z223-E1) CS/CJ Series Communications Commands Reference Manual (W342-E1) 5-1 Command Lists

Variable Tables

Input Variables

Name	Variable name	Data type	Default	Range	Description
EN	EN	BOOL			1 (ON): FB started 0 (OFF): FB not started.
Master Unit No.	MasterUnitNo	INT	&0	&0 to &15 #0 to #F	Specify the unit number of the DeviceNet Unit.
Slave node address	NodeNo	INT	&0	&0 to &63	Specify the node address of the slave.
Sensor Amplifier unit number	SensorUnitNo	INT	&1	&1 to &13 or &1 to &16	Depending on the communication mode setting, the maximum number of connectable Units is either 13 or 16 Units. Specify a unit number within the allowed range. Refer to the *Related Manuals* for details.

Output Variables

Name	Variable name	Data type	Range	Description
ENO (May be omitted.)	ENO	BOOL		1 (ON): FB processed normally. 0 (OFF): FB not processed or ended in an error.
FB Busy Flag	FB_BUSY	BOOL		Automatically turns OFF when processing is completed.
FB Normal End	FB_OK	BOOL		Turns ON for one cycle when processing ends normally.
FB Error End	FB_NG	BOOL		Turns ON for one cycle when processing ends in an error.

Internal Variables

Internal variables are not output from the FB.

If the FB_NG Flag turns ON, the following internal variables can be monitored to obtain information on the error.

Name	Variable name	Data type	Range	Description
FINS error code	FINS_ErrorCode	WORD		The FINS error code is output. A code of #0000 is output for a normal end. Refer to the *Related Manuals* for details on the error codes.
Explicit message error code	Explicit_ErrorCode	WORD		Outputs the explicit message error code. A code of #0000 is output for a normal end. Refer to the *Related Manuals* for details on the error codes.

Explicit Error Code Details

Code	Contents	Meaning
#0000	Normal end	---
#16FF	No Sensor Amplifier	There is no Sensor Amplifier with the specified unit number.
#0CFF	Not executable	The specified command cannot be executed. • A Mobile Console is connected. • There is an error in communications with the Sensor Amplifier. • The Sensor Amplifier is in an operation mode other than RUN mode. • The FB was executed for a Sensor Amplifier that is not supported.
#20FF	Not supported.	The specified command is not supported.

Version History

Version	Date	Contents
1.00	2005.4.	Original production

Note

This manual is a reference that explains the function block functions.

It does not explain the operational limitations of Units, components, or combinations of Units and components. Always read and understand the Operation Manuals for the system's Units and other components before using them.