

<b>2DCR -401</b>	<b>Execute Read: _2DCR401_ExecRead</b>
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<b>Basic function</b>	Executes one read for a 2D Code Reader.								
<b>Symbol</b>									
<b>File name</b>	Lib\FBL\omronlib\Barcode Scanner\2DCR\_2DCR401_ExecRead10.cfx								
<b>Applicable models</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 20%;">2D Code Reader</td> <td>V530-R2000 Series, V530-R160 Series, and V530-R150V3 Series</td> </tr> <tr> <td>CPU Unit</td> <td>                     CS1*-CPU**H Unit version 3.0 or higher                      CJ1*-CPU**H Unit version 3.0 or higher                      CJ1M-CPU** Unit version 3.0 or higher                      CP1H                      CP1L (except 10 points CPU)                 </td> </tr> <tr> <td>Serial Communications Units/Boards</td> <td>                     CS1W-SCU21-V1, CJ1W-SCU21-V1, CJ1W-SCU41-V1 Unit Version 1.2 or higher                      CS1W-SCB21-V1 and CS1W-SCB41-V1 Unit Version 1.2 or higher                 </td> </tr> <tr> <td>CX-Programmer</td> <td>Version 5.0 or higher</td> </tr> </table>	2D Code Reader	V530-R2000 Series, V530-R160 Series, and V530-R150V3 Series	CPU Unit	CS1*-CPU**H Unit version 3.0 or higher CJ1*-CPU**H Unit version 3.0 or higher CJ1M-CPU** Unit version 3.0 or higher CP1H CP1L (except 10 points CPU)	Serial Communications Units/Boards	CS1W-SCU21-V1, CJ1W-SCU21-V1, CJ1W-SCU41-V1 Unit Version 1.2 or higher CS1W-SCB21-V1 and CS1W-SCB41-V1 Unit Version 1.2 or higher	CX-Programmer	Version 5.0 or higher
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<b>Conditions for usage</b>	<p>External Connections</p> <ul style="list-style-type: none"> <li>• Can be used only for 1:1 connections.</li> <li>• Communications must be within one network and cannot cross to another network.</li> <li>• This FB is invalid when the serial port error is happend.</li> <li>• Multiple FBs cannot simultaneously perform processing for one Code Reader.</li> <li>• When the PLC system is turned ON, the serial port may receive unexpected data, resulting in a communication error. It is recommended to restart the serial port one time after starting up the PLC system.</li> </ul> <p>Communications Settings</p> <p>The communications settings(No-protocol Mode) of the serial port must be the same as those of the 2D Code Reader.</p> <ul style="list-style-type: none"> <li>• The communications settings of the specified serial port can be set to the default 2D Code Reader settings using the Set Communications Port (_2DCR600_SetComm) function block, and the other 2D Code Reader settings using the Set No-protocol Mode (_SCx603_SetPortNOPRTCL) function block.</li> </ul> <p>Shared Resources</p> <ul style="list-style-type: none"> <li>• When a Serial Communications Unit is specified: Communications ports (internal logical ports)</li> </ul> <p>Code Reader Settings</p> <ul style="list-style-type: none"> <li>• Always set the 2D Code Reader scene number before using this FB.</li> <li>• This FB can be used only when the trigger input mode is set to the one-shot mode or the level mode.</li> </ul>								
<b>Function description</b>	<p>When the Start Trigger turns ON, one read is executed and the specified number of read data reception bytes are stored in the measurement results storage words for the 2D Code Reader connected to the specified serial port for the specified Unit Selection and serial port number.</p> <p>The word designation for storing the measurement results is specified using the area type and beginning word address. For example, for D1000, the area type is set to P_DM and the beginning word address is set to &amp;1000.</p>								
<b>FB precautions</b>	<ul style="list-style-type: none"> <li>• The FB is processed over multiple cycles. The BUSY output variable can be used to check whether the FB is being processed.</li> <li>• OK or NB will be turned ON for one cycle only after processing is completed. Use these flags to detect the end of FB processing.</li> </ul> <p>Timechart</p> <p style="text-align: center;">↑ FB execution completed. At normal end: Data is stored in measurement results storage are</p>								

<b>EN input condition</b>	Connect EN to an OR between an upwardly differentiated condition for the start trigger and the BUSY output from the FB.
<b>Restrictions Input variables</b>	<ul style="list-style-type: none"> <li>• Always use an upwardly differentiated condition for EN.</li> <li>• If the input variables are out of range, the ENO Flag will turn OFF and the FB will not be processed.</li> <li>• Up to 256 read data reception bytes can be read.</li> </ul>
<b>Output variables</b>	<ul style="list-style-type: none"> <li>• This FB requires multiple cycles to process. Always connect an OR including the BUSY output variable to the EN input variable to ensure that the FB is processed to completion (see <i>Symbol</i>).</li> <li>• Do not turn the BUSY output variable ON or OFF outside the FB.</li> </ul>
<b>Application example</b>	<p>A 2D Code Reader is connected 1:1 to serial port 1 on a Serial Communications Board (SCB).</p> <p>When bit A turns ON, one read is executed by the 2D Code Reader. When the read has been completed, 128 bytes of read data is received at serial port 1 of the Serial Communications Board and stored in D1000.</p> <p>The diagram illustrates the hardware and logic for the application example. It shows a PLC rack with SCB, CPU, and SCU modules. A 2D Code Reader is connected to the SCB. A callout indicates 'Unit selection: SCB (#BBBB)'. Below, a ladder logic diagram shows Bit A triggering the <code>_2DCR401_ExecRead</code> function block. Bit B is used for Unit selection (#BBBB) and Serial Port No. (&amp;1). Bit C is used for processing to set analysis function. The function block has various inputs and outputs including EN, ENO, BUSY, OK, and NG.</p>
<b>Related manuals</b>	2D Code Reader V530-R2000 User's Manual (Q134) Section 7 Host Communications, Serial Interface 2D Code Reader V530-R160E/V530-R160EP User's Manual (Z169) Section 8 Communications with the Host, Serial Interface (Normal) V530-R150E-3, V530-R150EP-3 2-Dimensional Code Reader (Fixed Type) Operation Manual (Z155) Section 4 RS-232C

■ Variable Tables

Input Variables

Name	Variable name	Data type	Default	Range	Description																														
EN	EN	BOOL			1 (ON): FB started. 0 (OFF): FB not started.																														
Unit selection Serial Port No.	UnitSelect PortNo	INT INT	&0 &1	At right. &1 to &2	Specify the Unit and the serial port. Only serial port 2 of CP1H/CP1L M-type CPU unit is possible to use this FB. <ul style="list-style-type: none"> <li>■ Connected to CPU Unit Unit selection #FFFF Serial port No. Not accessed. (CP1H/CP1L-M: Serial Port2 CP1L-L14/20: Serial Port1)</li> <li>■ Connected to Serial Communication Board(SCB) Unit selection #BBBB Serial port No. &amp;1: Serial Port 1 &amp;2: Serial Port 2</li> <li>■ Connected to Serial Communication Unit(SCU) Unit selection SCU Unit No. (&amp;0 to &amp;15) Serial port No. &amp;1: Serial Port 1 &amp;2: Serial Port 2</li> </ul>																														
Storage order designation	BytesOrder	INT	&0	&0 to &1	Storage order for read data &0: Upper byte to lower byte &1: Lower byte to upper byte  0: Upper to lower <table style="margin-left: 20px; border-collapse: collapse;"> <tr> <td style="padding-right: 5px;">Address</td> <td style="padding-right: 5px;">Read data</td> <td style="padding-right: 10px;">CPU Unit memory</td> </tr> <tr> <td>0010</td> <td style="border: 1px solid black; text-align: center;">01</td> <td style="border: 1px solid black; text-align: center;">01 02</td> </tr> <tr> <td>0011</td> <td style="border: 1px solid black; text-align: center;">02</td> <td style="border: 1px solid black; text-align: center;">03 04</td> </tr> <tr> <td>0012</td> <td style="border: 1px solid black; text-align: center;">03</td> <td style="border: 1px solid black; text-align: center;">←→</td> </tr> <tr> <td>0013</td> <td style="border: 1px solid black; text-align: center;">04</td> <td style="border: 1px solid black; text-align: center;">04</td> </tr> </table> 1: Lower to upper <table style="margin-left: 20px; border-collapse: collapse;"> <tr> <td style="padding-right: 5px;">Address</td> <td style="padding-right: 5px;">Read data</td> <td style="padding-right: 10px;">CPU Unit memory</td> </tr> <tr> <td>0010</td> <td style="border: 1px solid black; text-align: center;">01</td> <td style="border: 1px solid black; text-align: center;">02 01</td> </tr> <tr> <td>0011</td> <td style="border: 1px solid black; text-align: center;">02</td> <td style="border: 1px solid black; text-align: center;">04 03</td> </tr> <tr> <td>0012</td> <td style="border: 1px solid black; text-align: center;">03</td> <td style="border: 1px solid black; text-align: center;">←→</td> </tr> <tr> <td>0013</td> <td style="border: 1px solid black; text-align: center;">04</td> <td style="border: 1px solid black; text-align: center;">04</td> </tr> </table>	Address	Read data	CPU Unit memory	0010	01	01 02	0011	02	03 04	0012	03	←→	0013	04	04	Address	Read data	CPU Unit memory	0010	01	02 01	0011	02	04 03	0012	03	←→	0013	04	04
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Area for read results	RecvAreaID	WORD	#0082	At left.	P_CIO (#00B0): CIO Area P_WR (#00B1): Work Area P_HR (#00B2): Holding Area P_DM (#0082): DM Area P_EM0 (#0050) to P EMC (#005C): EM Area bank 0 to C																														
Beginning word for read results	RecvAreaNo	INT	&0																																
No. of read results bytes to receive	RecvBytes	INT	&0	&0 to &256																															
Response monitor time	TimeOut	INT	&0	&0 to &990	Specify the response monitor time (unit: 100 ms). &0: Default (99 seconds)																														

Output Variables

Name	Variable name	Data type	Range	Description
ENO (May be omitted.)	ENO	BOOL		1 (ON): FB processed normally. 0 (OFF): FB not processed or ended in an error.
Busy Flag	BUSY	BOOL		Automatically turns OFF when processing is completed.
Normal end	OK	BOOL		Turns ON for one cycle when processing ends normally.
Error end	NG	BOOL		Turns ON for one cycle when processing ends in an error.

Version History

Version	Date	Contents
1.00	2004.6.	Original production

Note

This manual is a reference that explains the function block functions.

It does not explain the operational limitations of Units, components, or combinations of Units and components. Always read and understand the Operation Manuals for the system's Units and other components before using them.