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ABB Engineering (Shanghai)
No.4528, Kangxin Highway, Kangqiao Town
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P.R.China

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Customer	:	
	:	
Drawing number	:	
Drawing version	:	
Manufacture	:	
Type	:	
Type of installation	:	
Control cabinet	:	
Mains voltage	:	
Supply	:	
Control voltage	:	
Year of construction	:	
Project start	:	
Project manager	:	
Last revision	:	
Designed by	:	
Designed date	:	
Number of pages	:	

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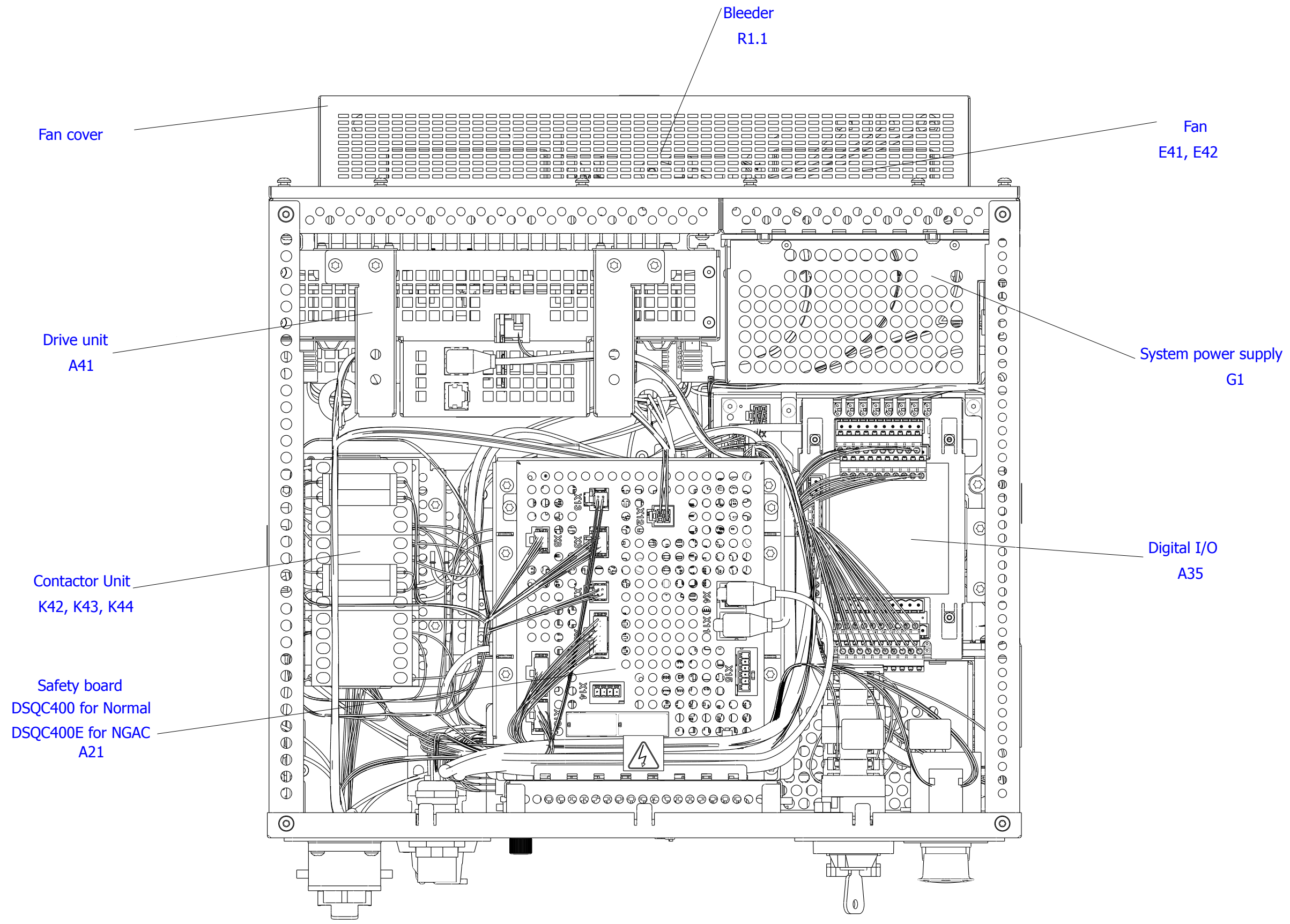
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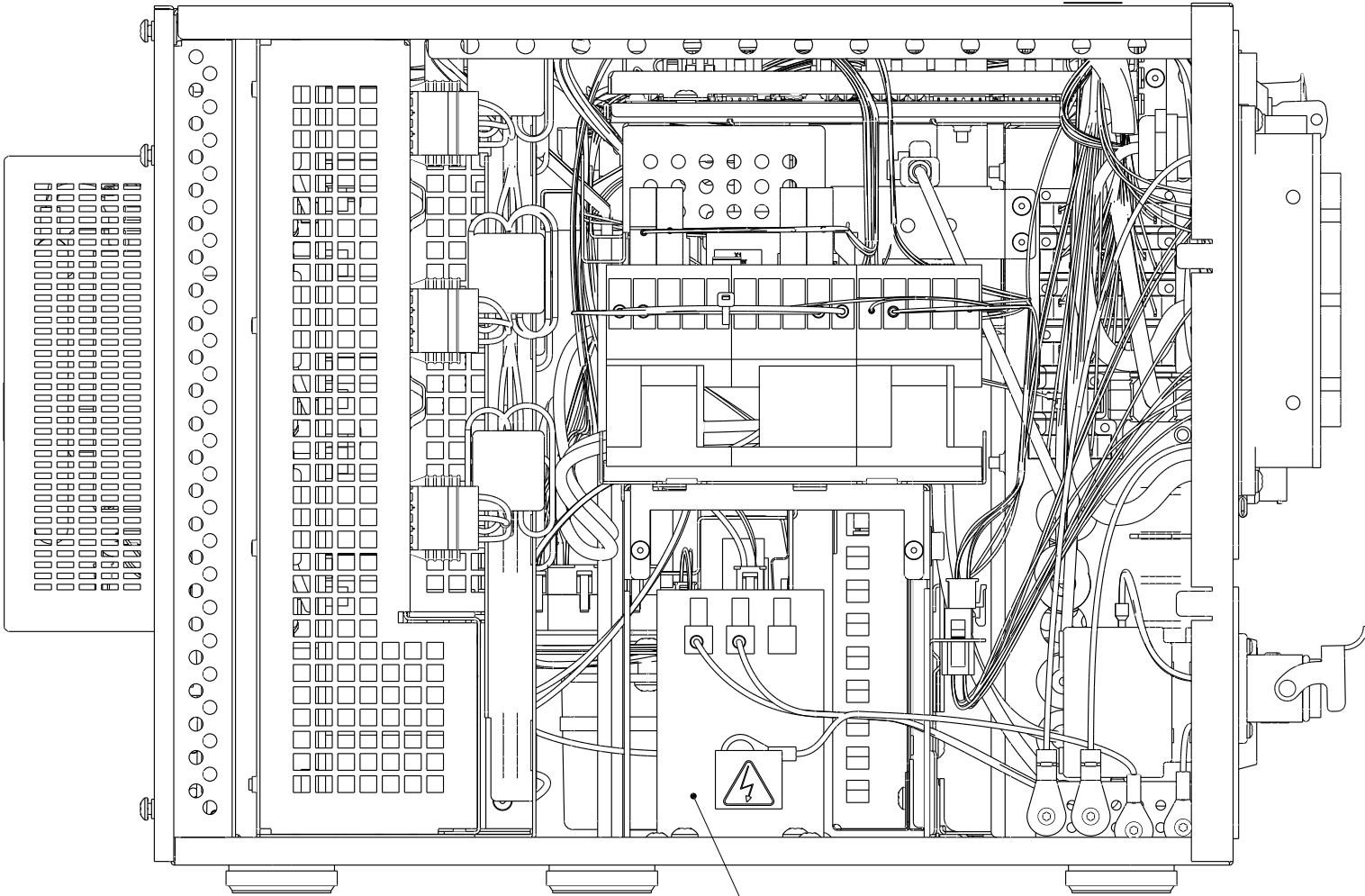


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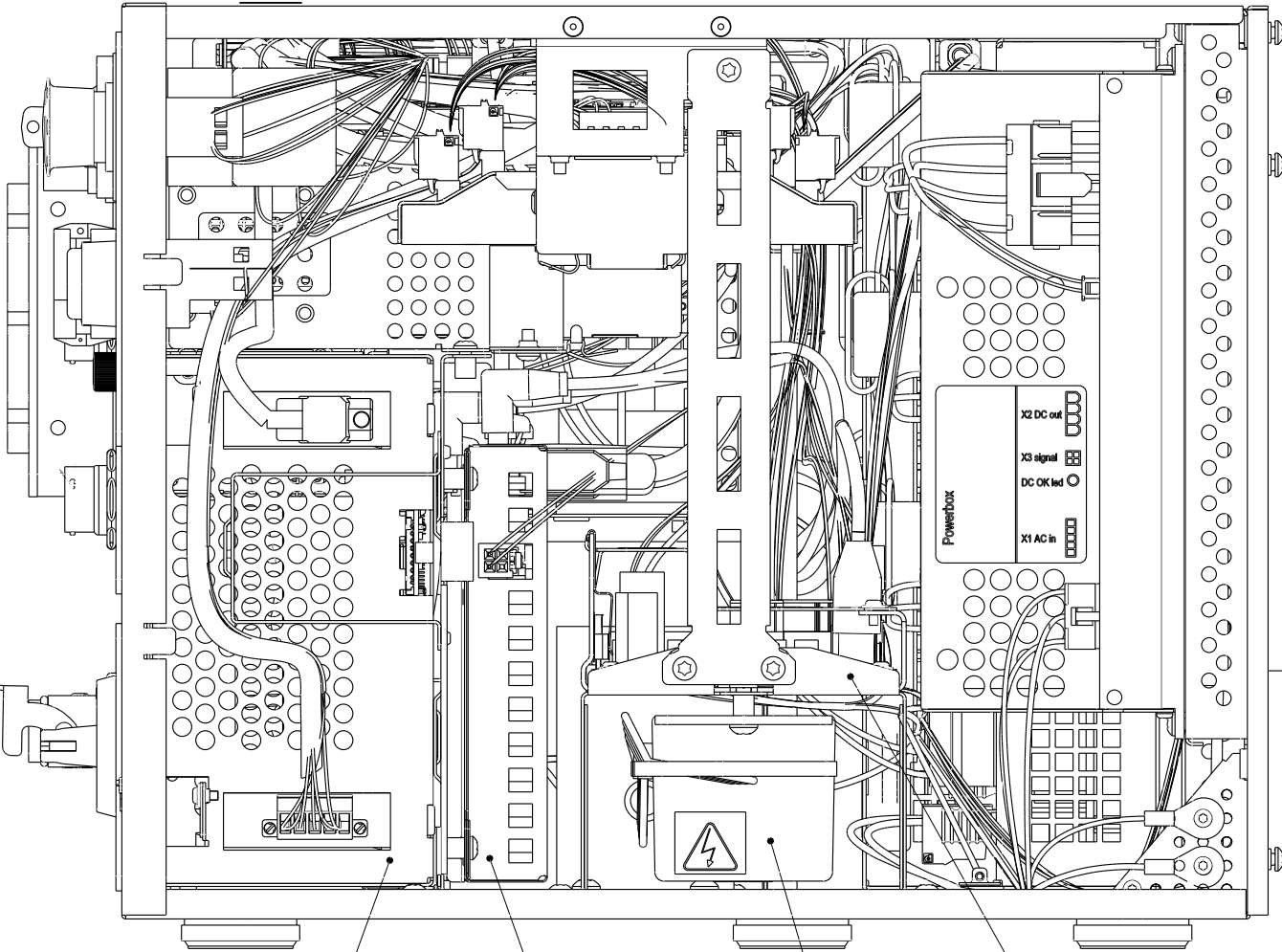
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Leftside View



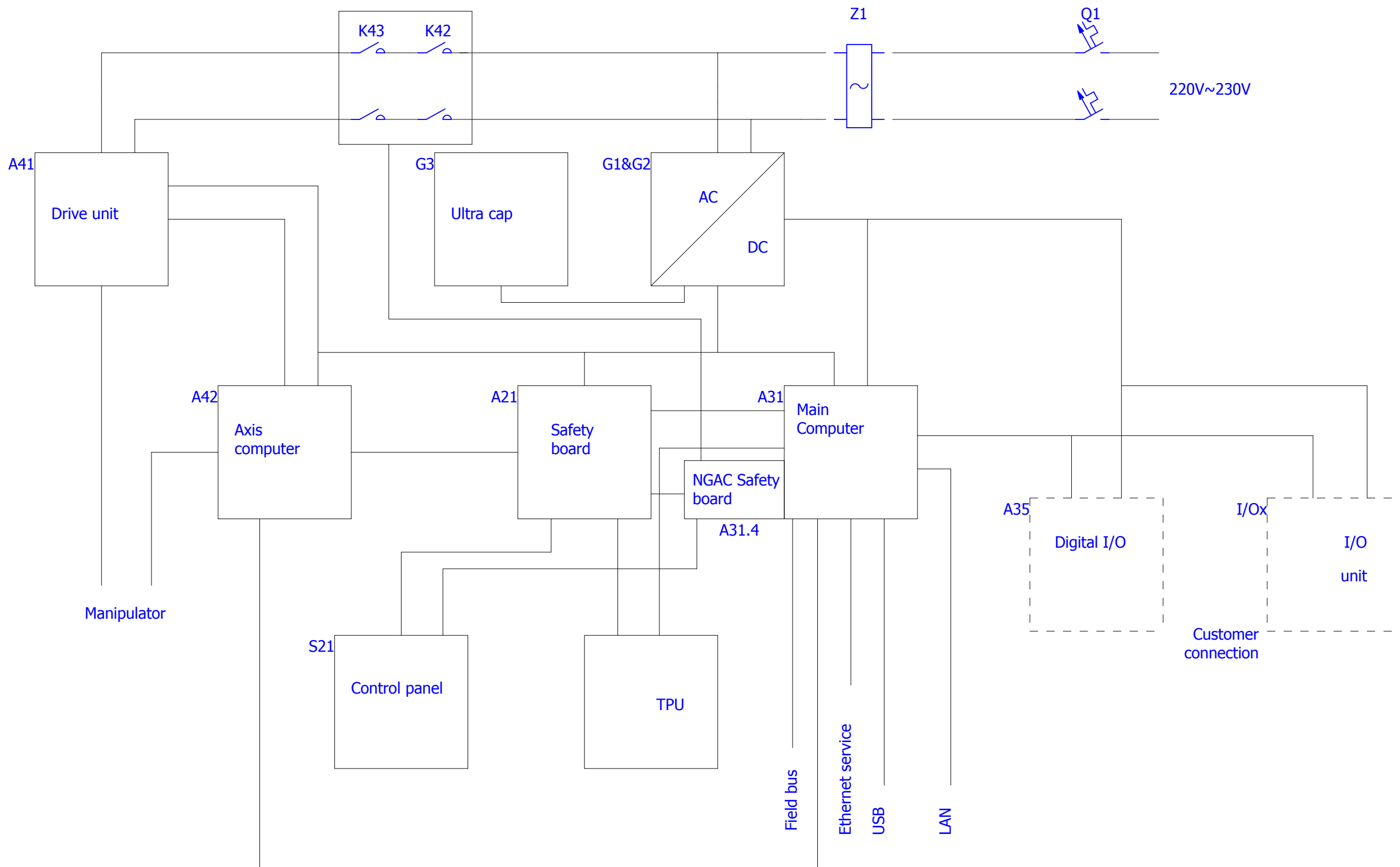
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Rightside View

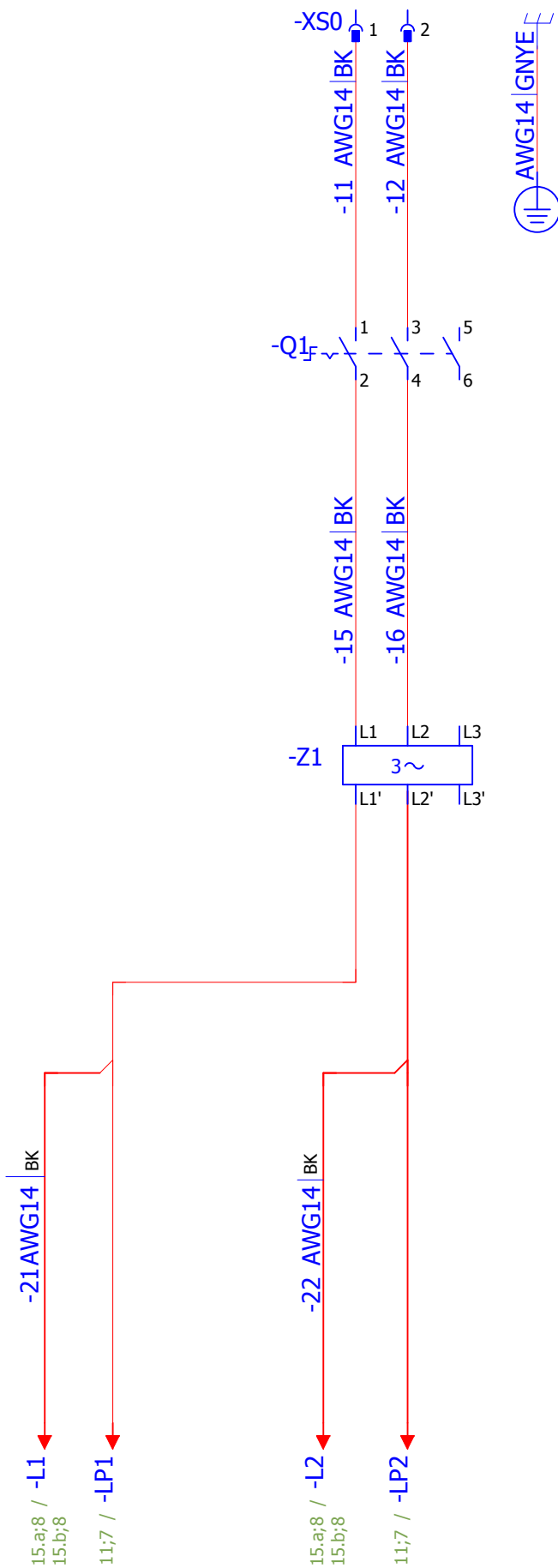


Main computer Axis computer Ultra cap bank Power distribution
A31 A42 G3 G2

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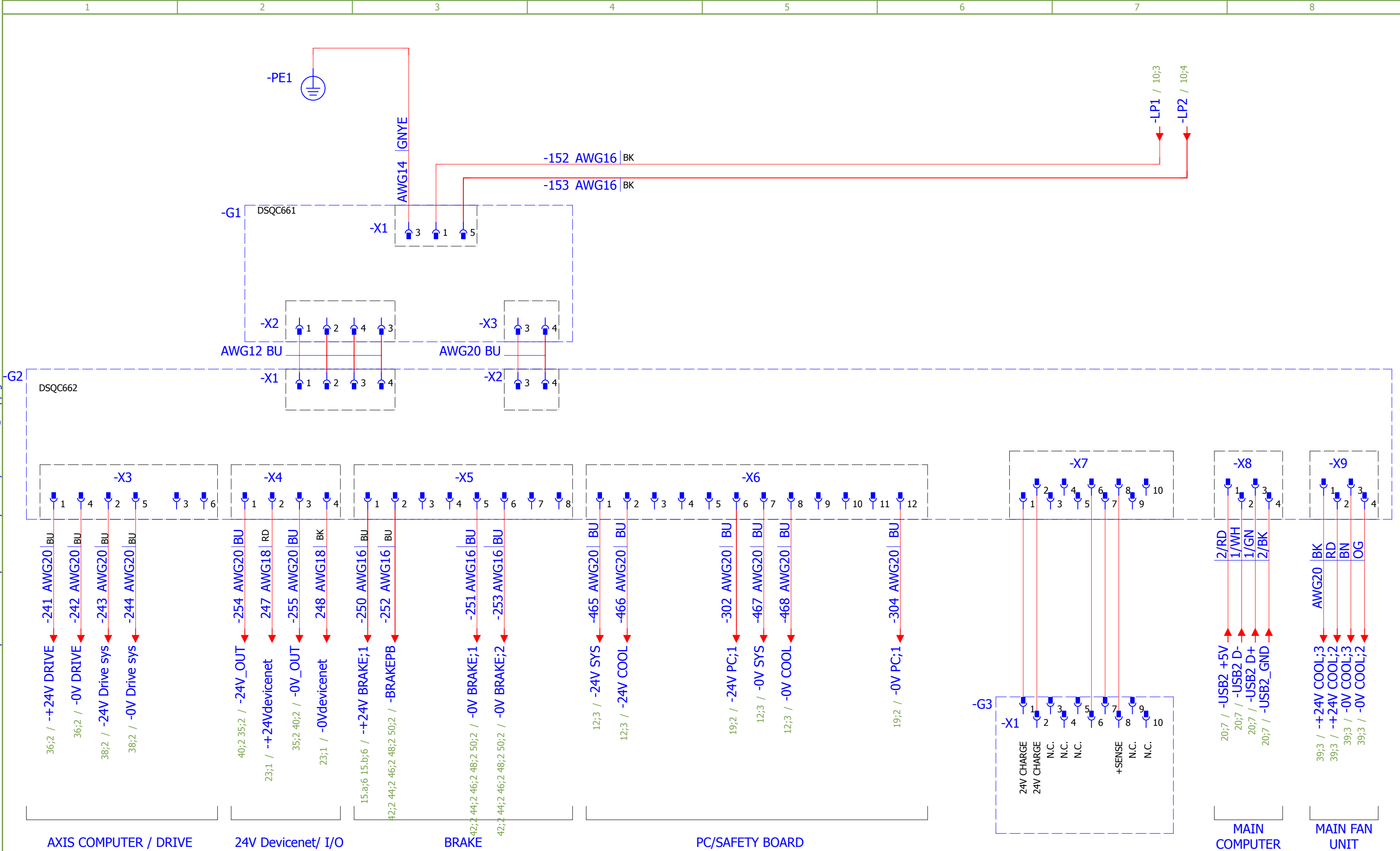


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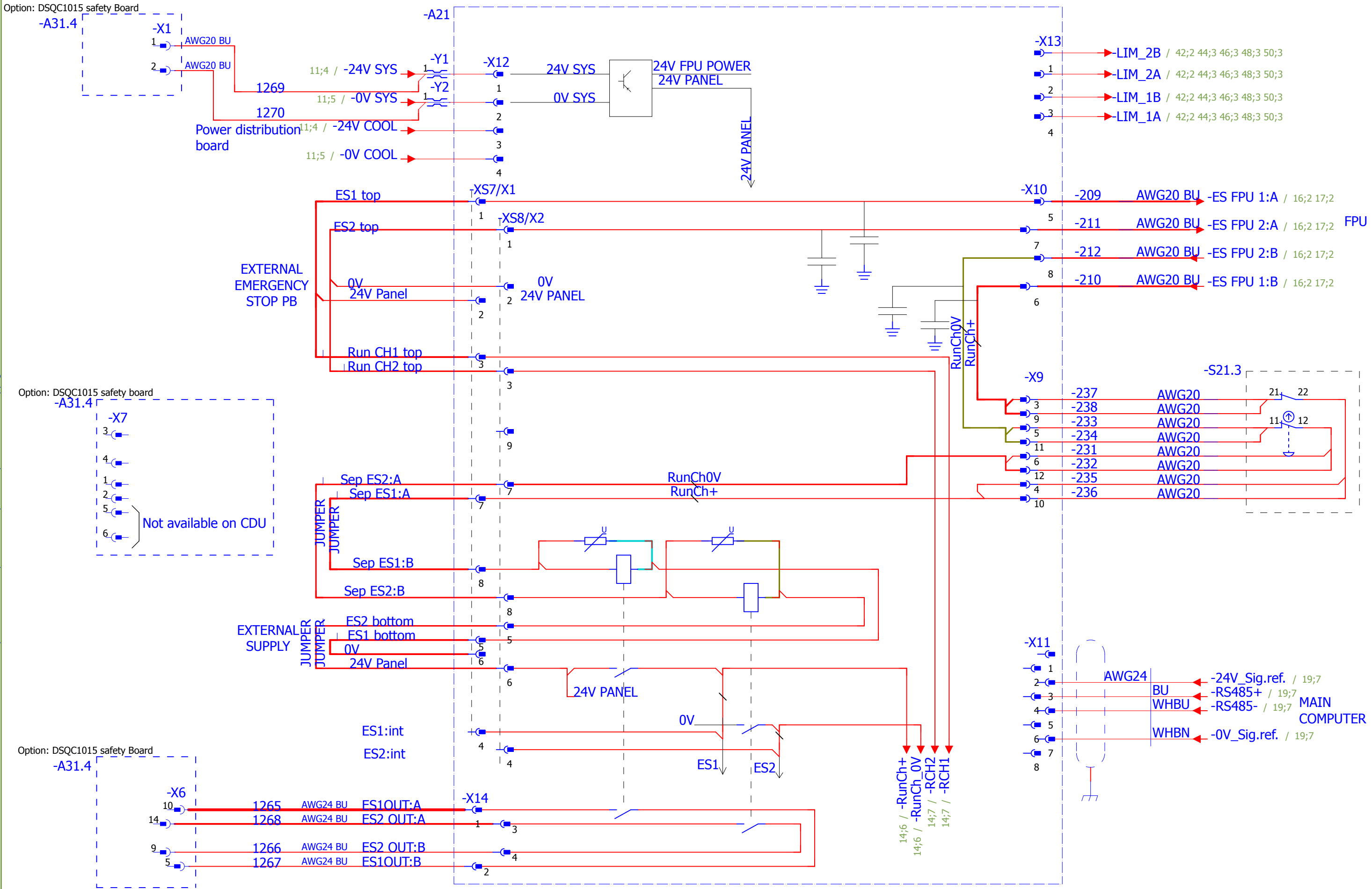
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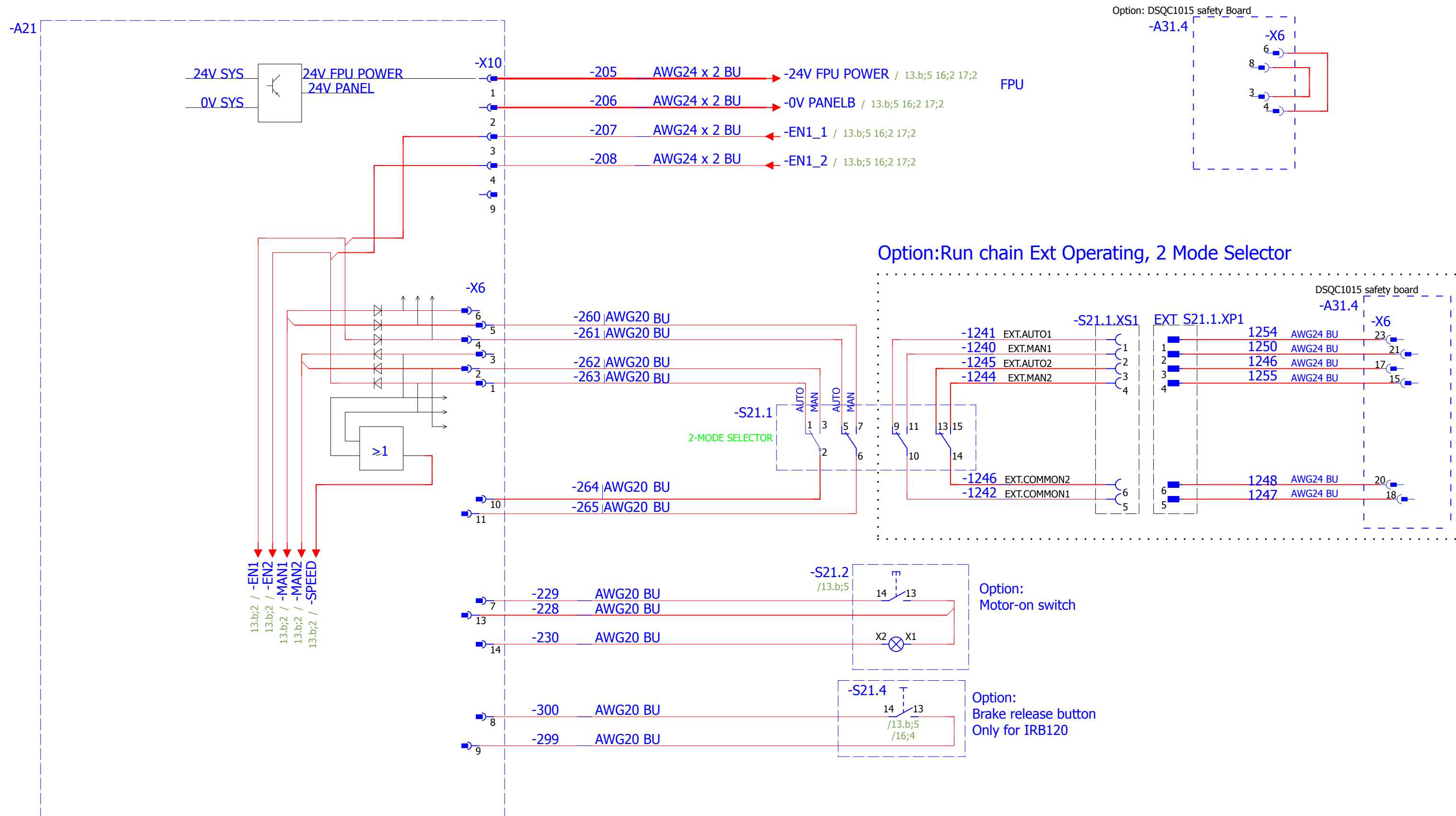


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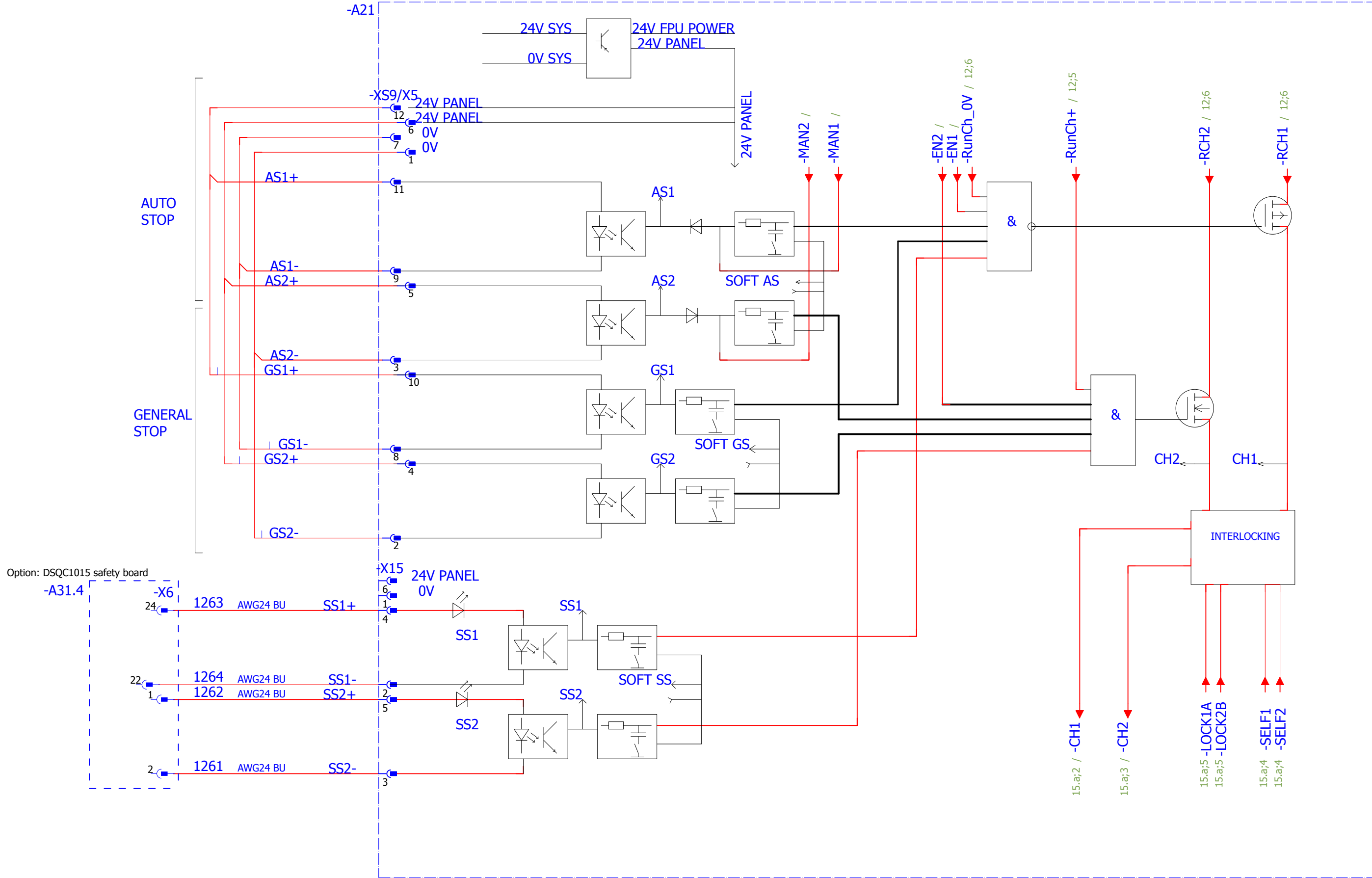


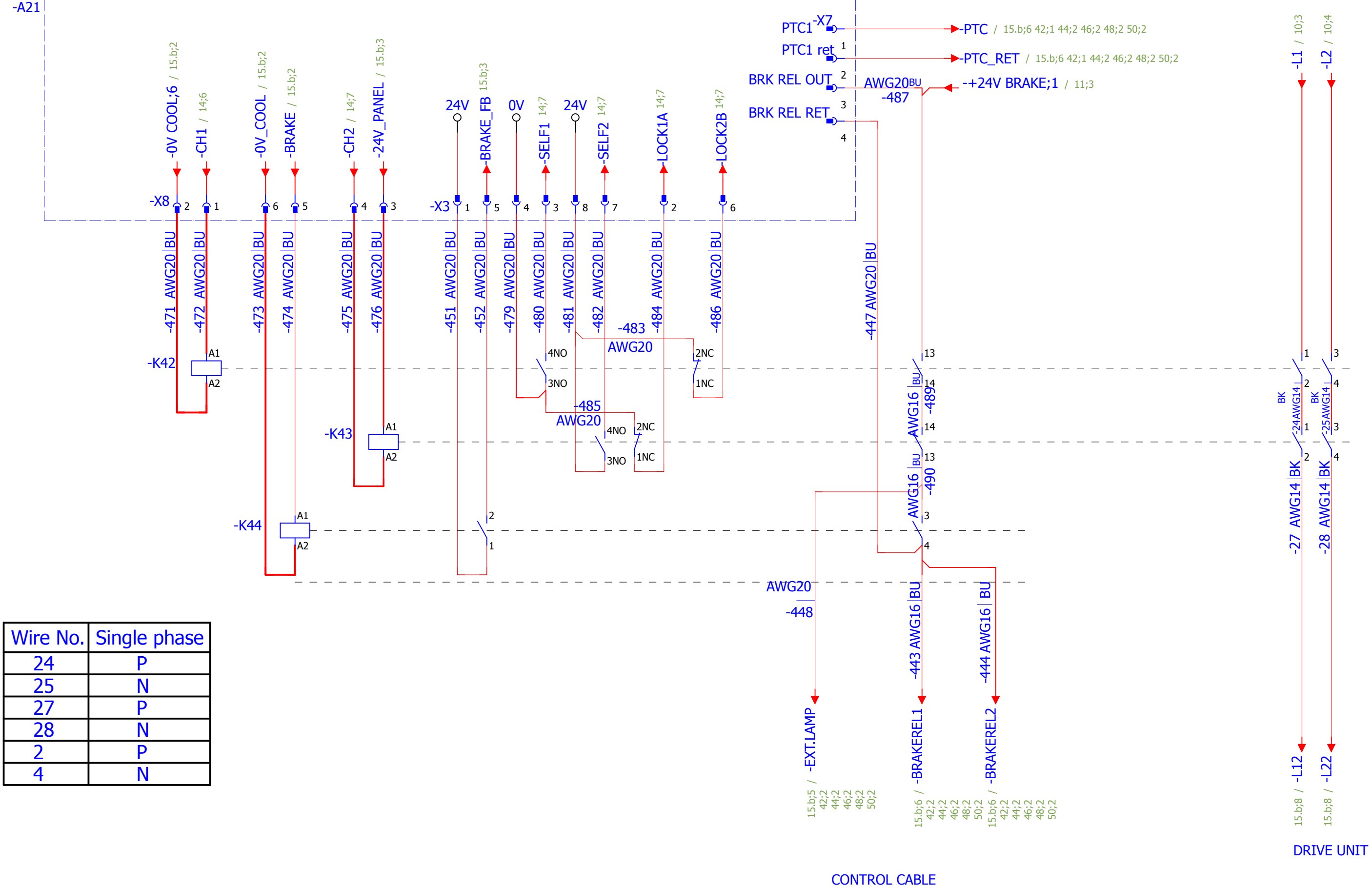
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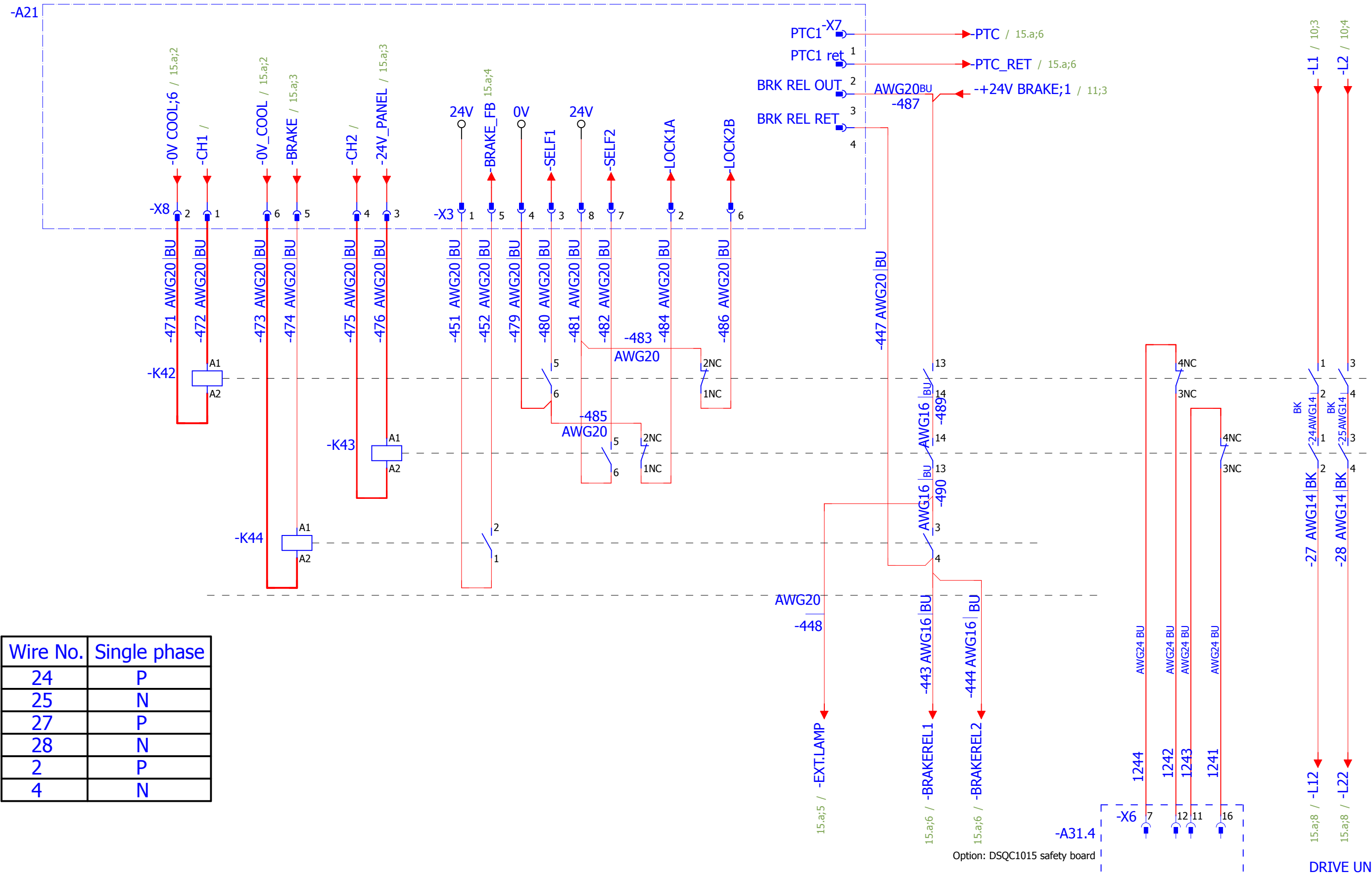
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4	N

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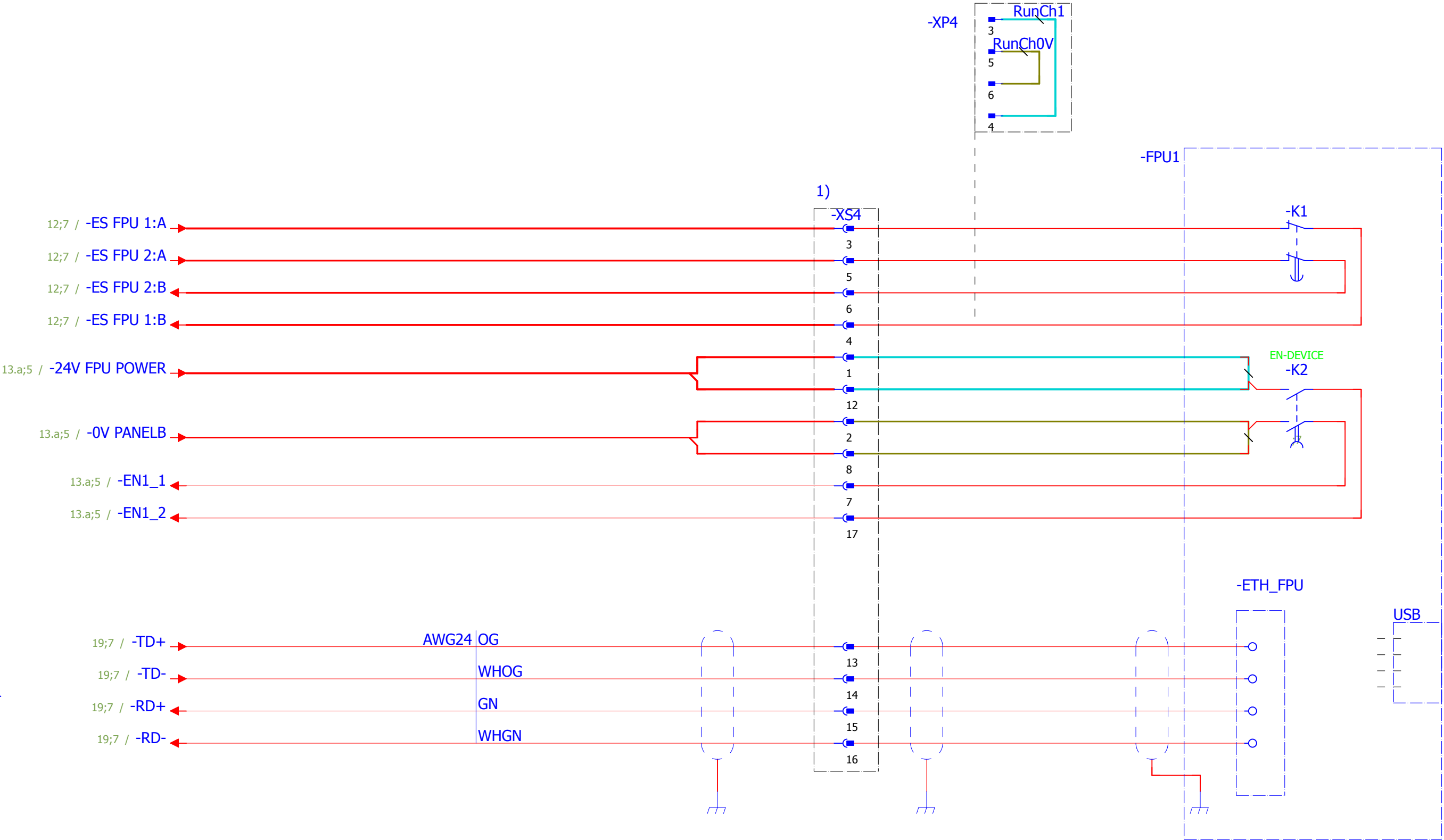




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SAFETY
BOARD
A21-X10

MAIN
COMPUTER
A31-A8



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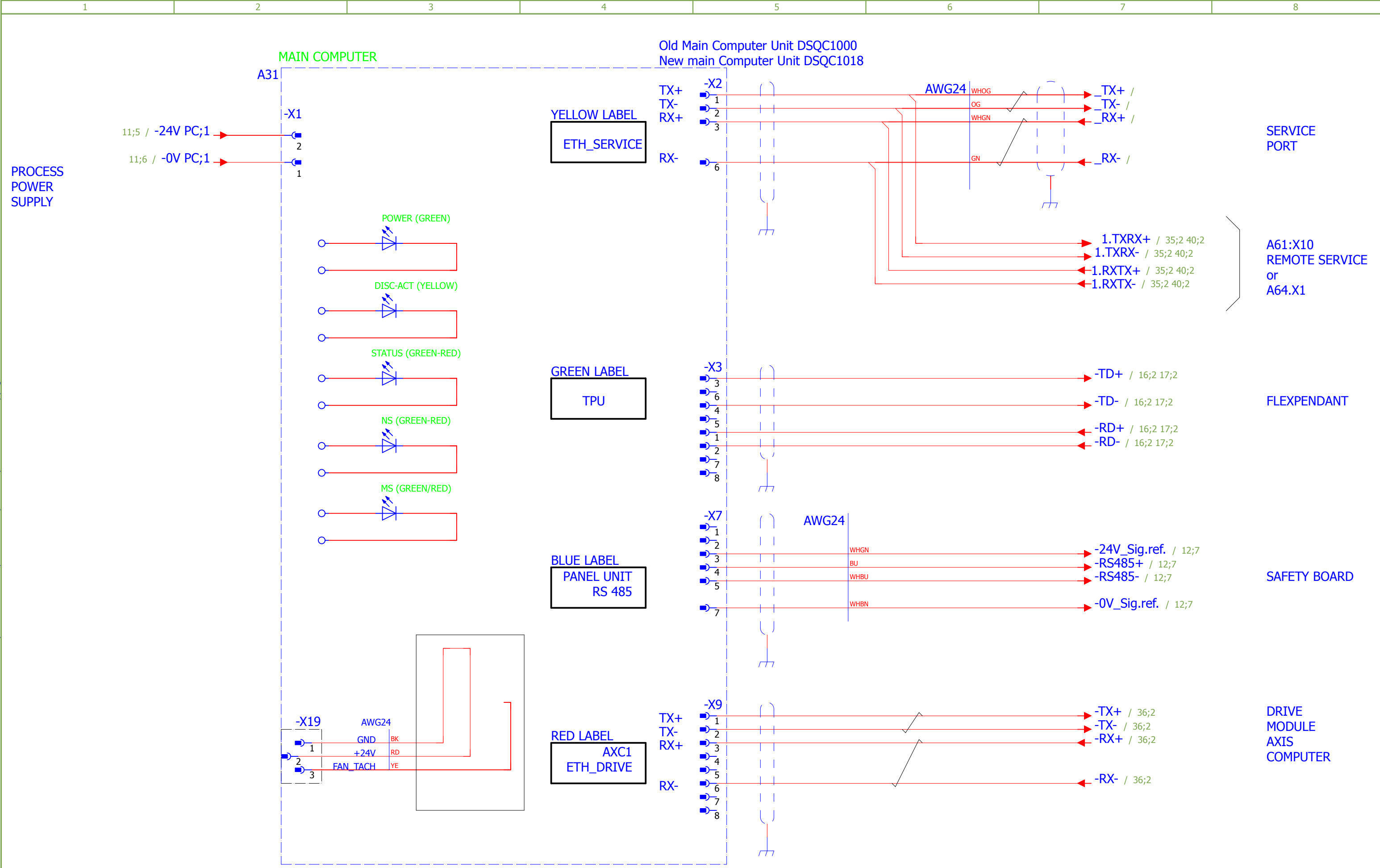
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Old Main Computer Unit DSQC1000
New main Computer Unit DSQC1018



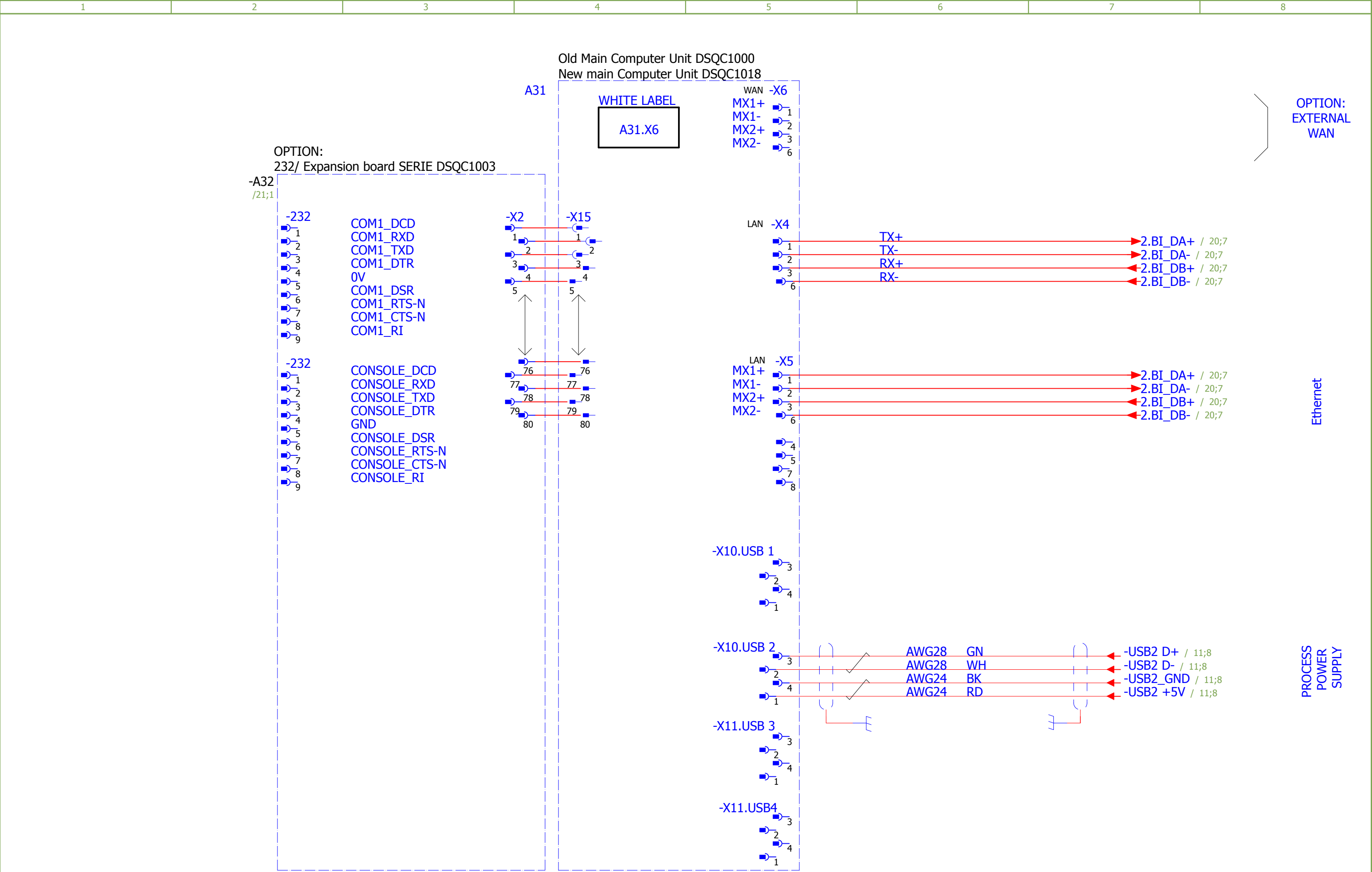
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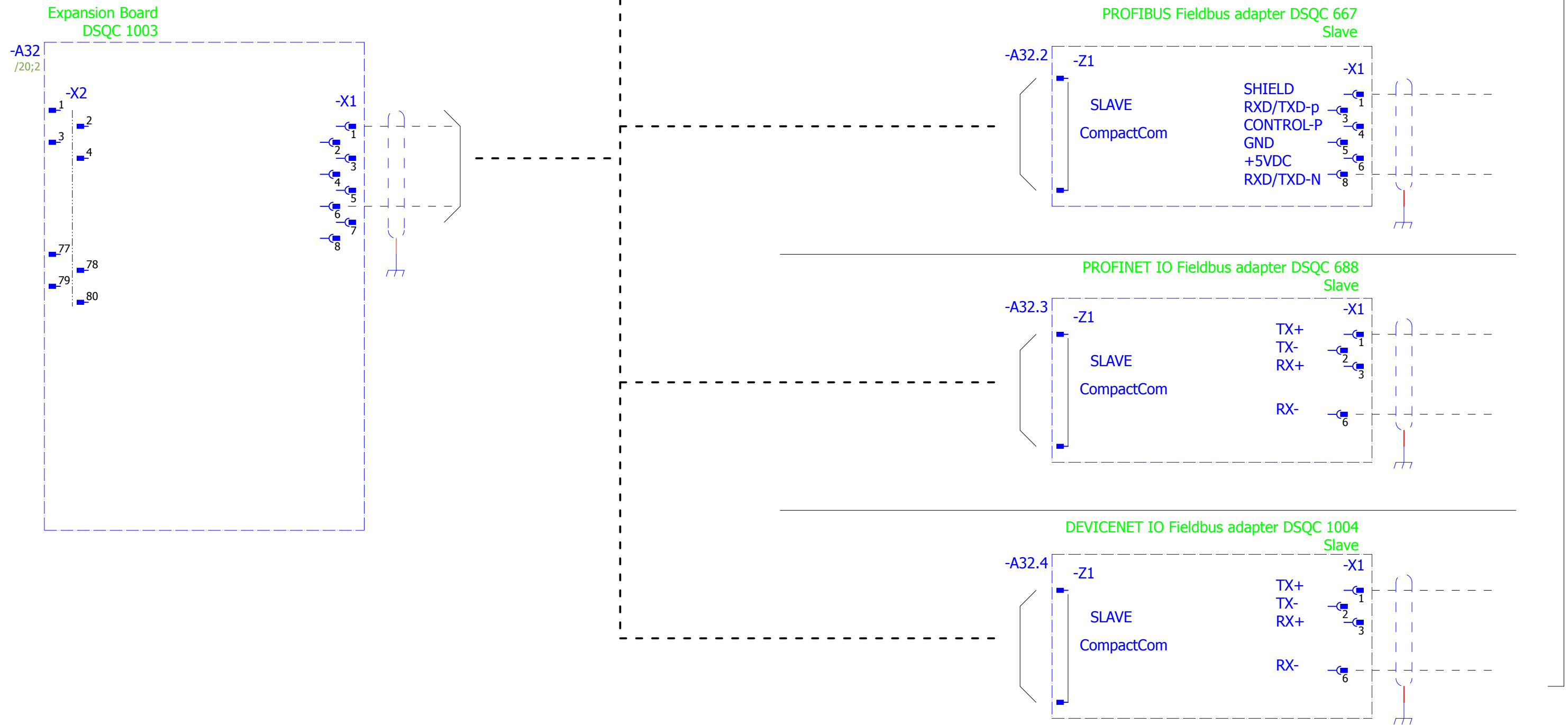
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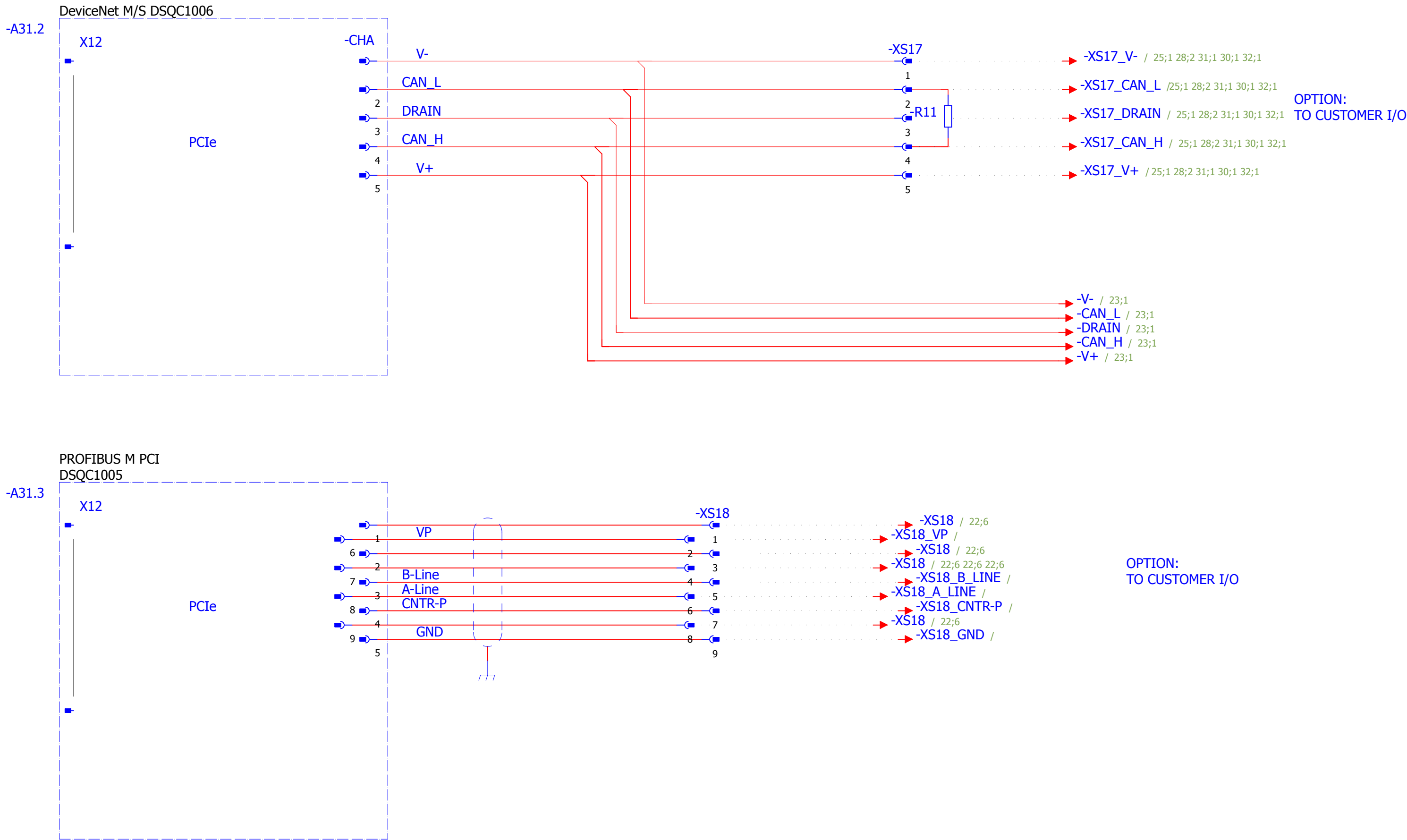
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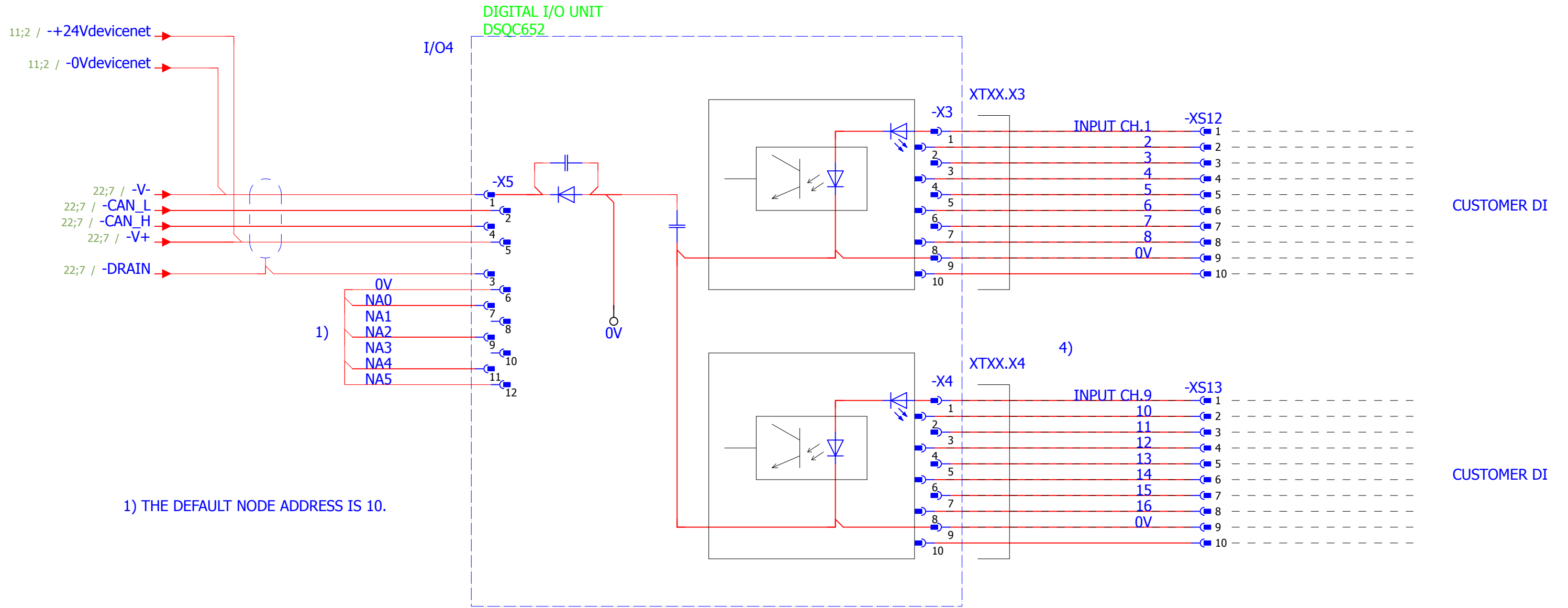


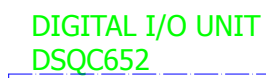
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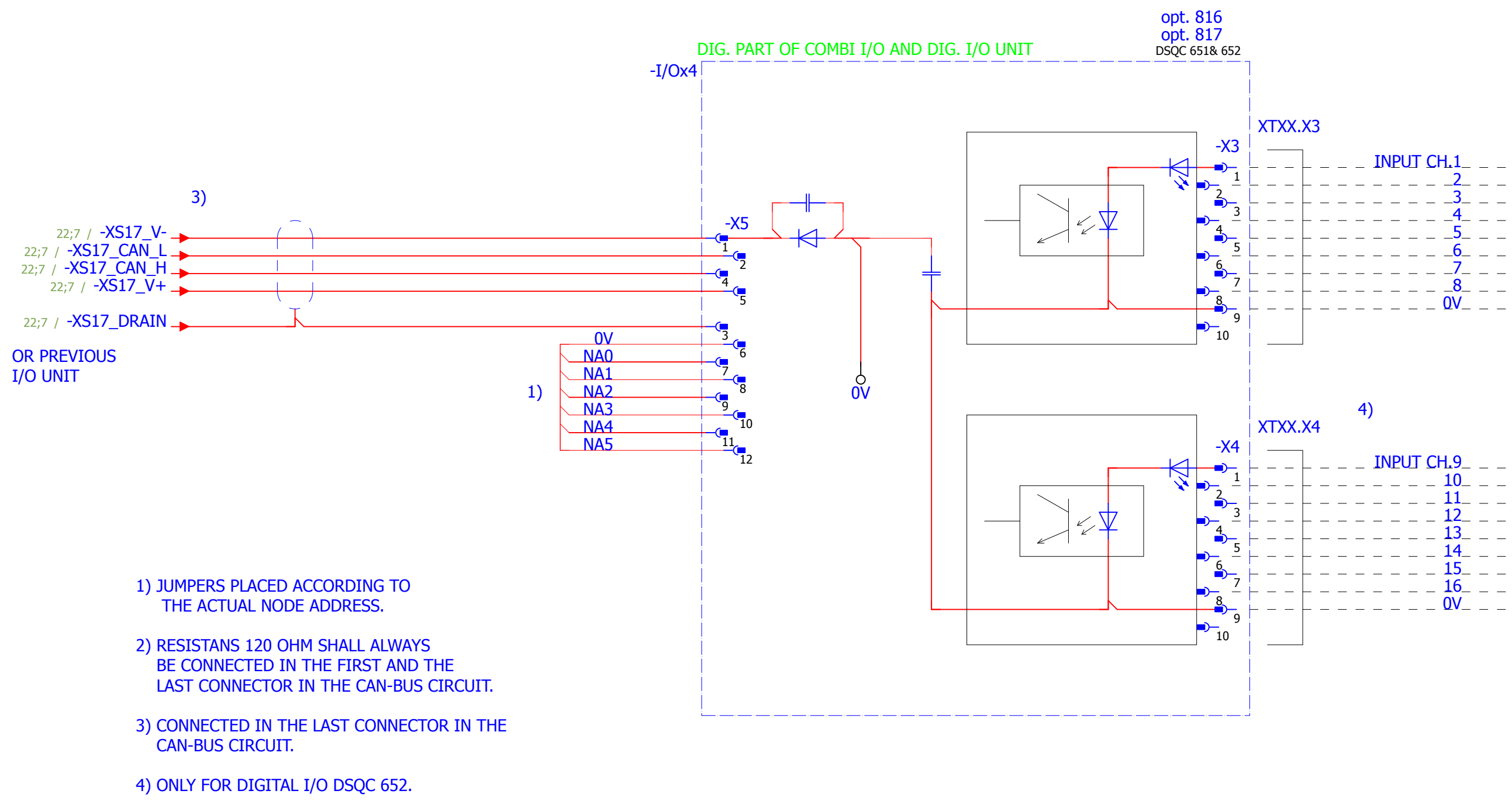


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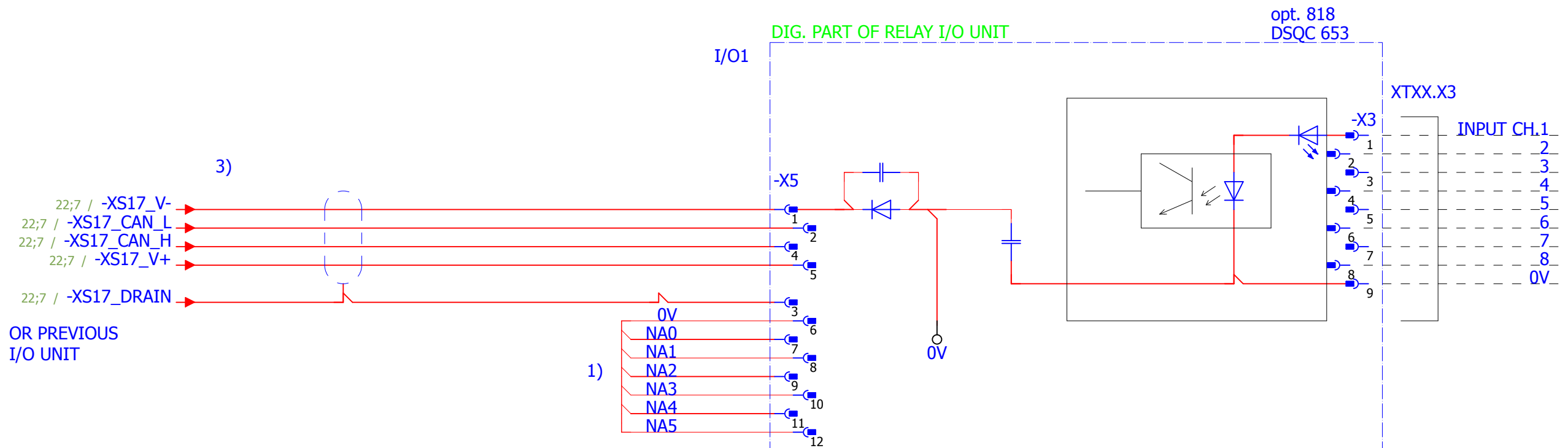


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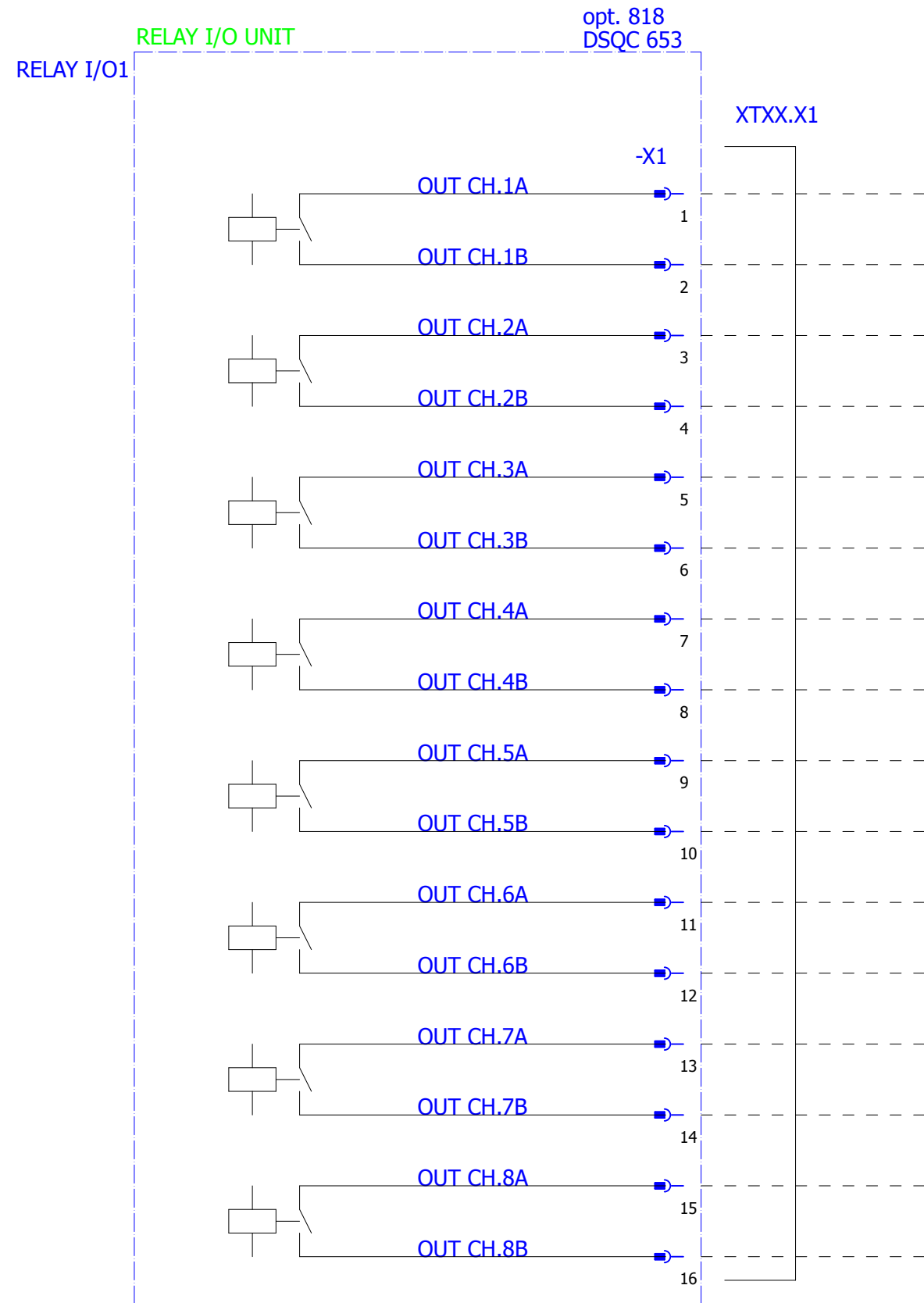


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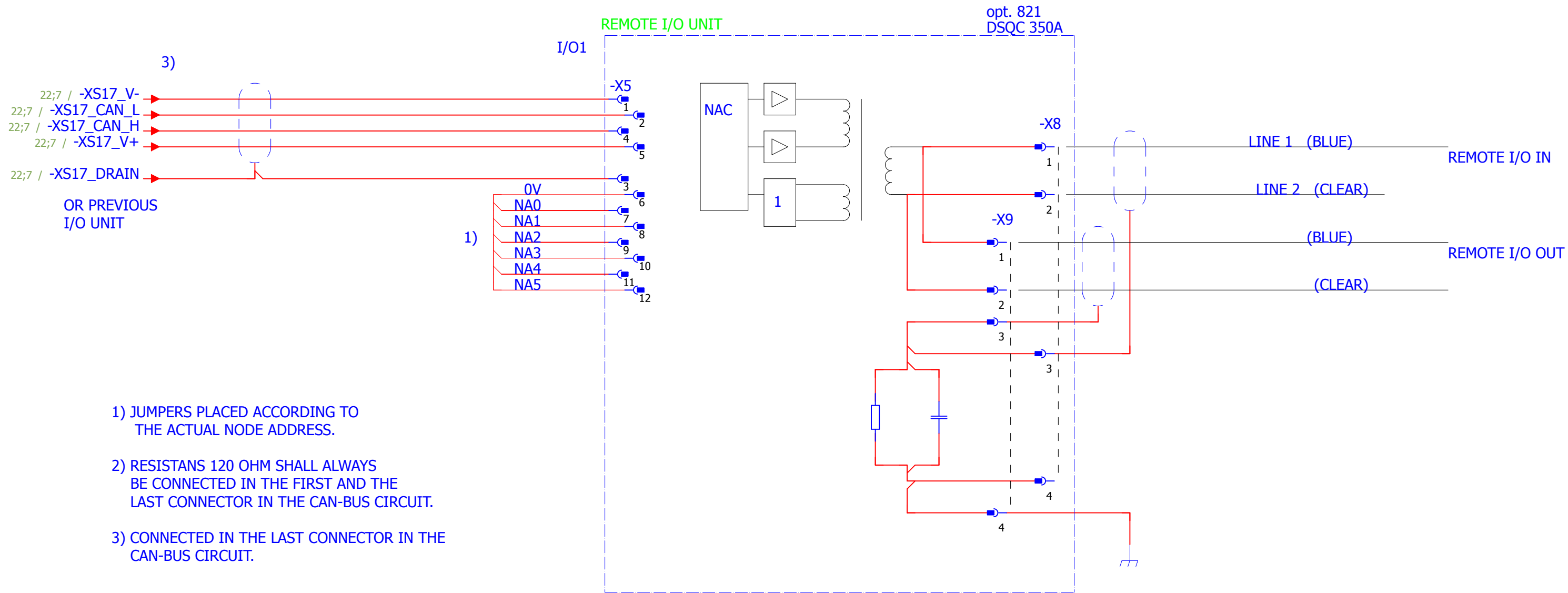
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- 2) RESISTANS 120 OHM SHALL ALWAYS BE CONNECTED IN THE FIRST AND THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT.
- 3) CONNECTED IN THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT.

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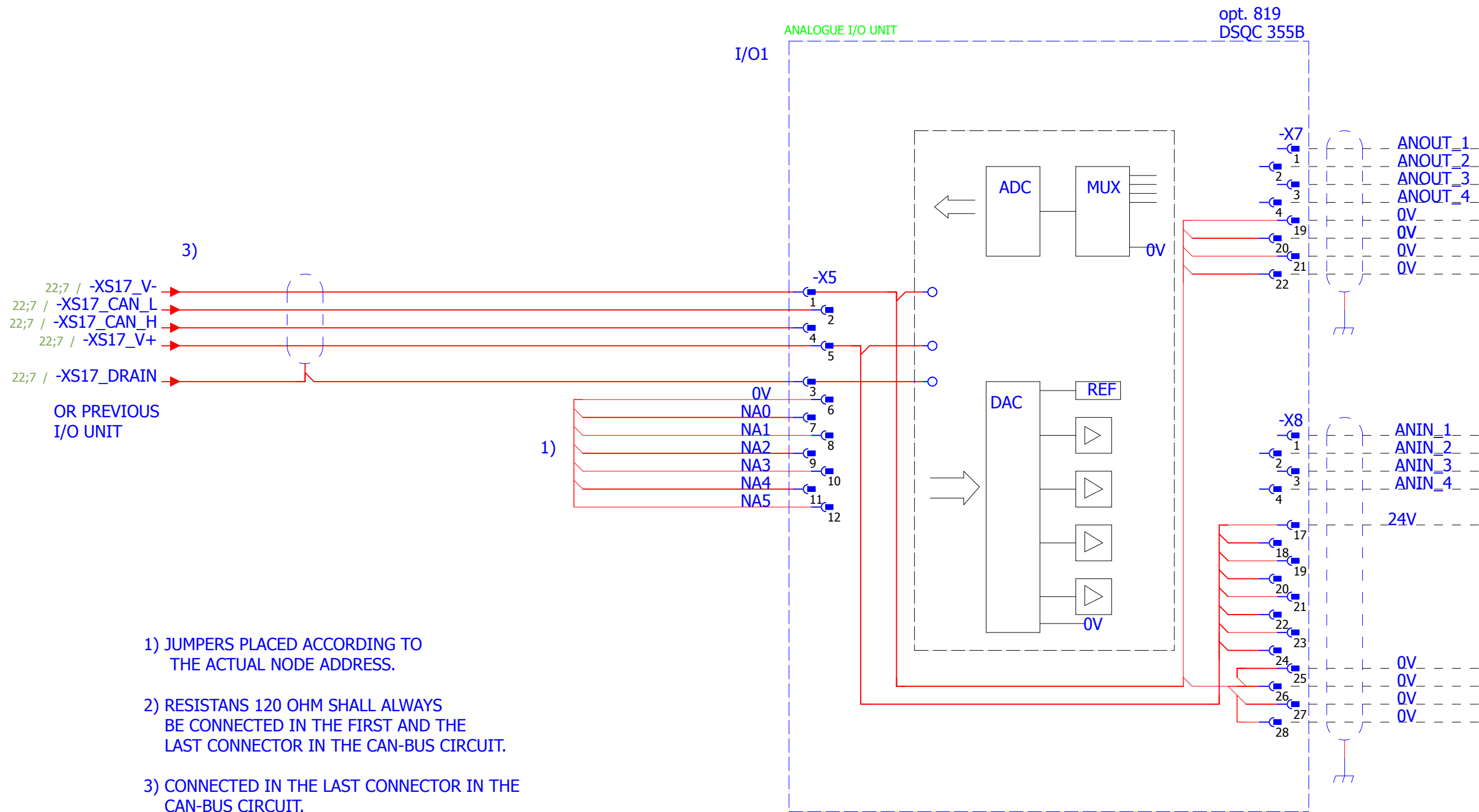
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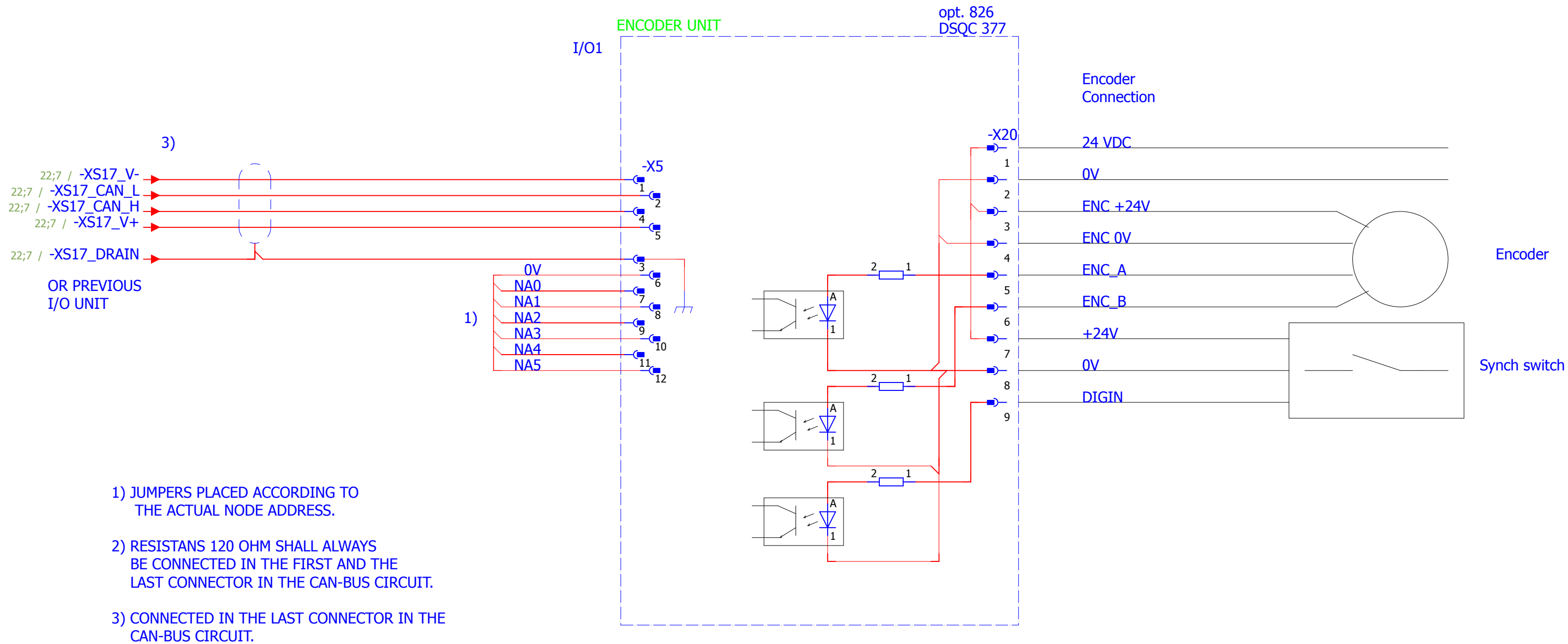


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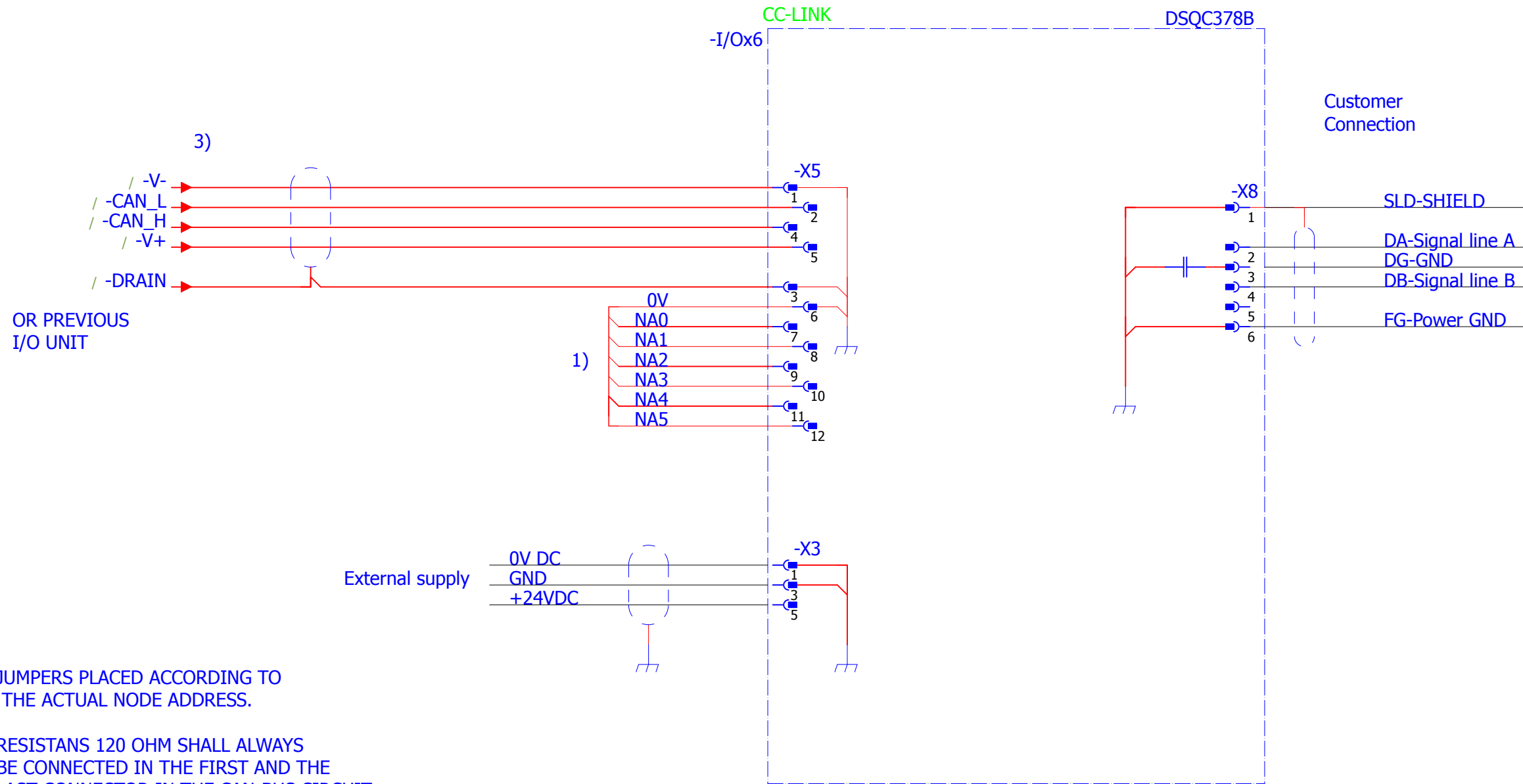
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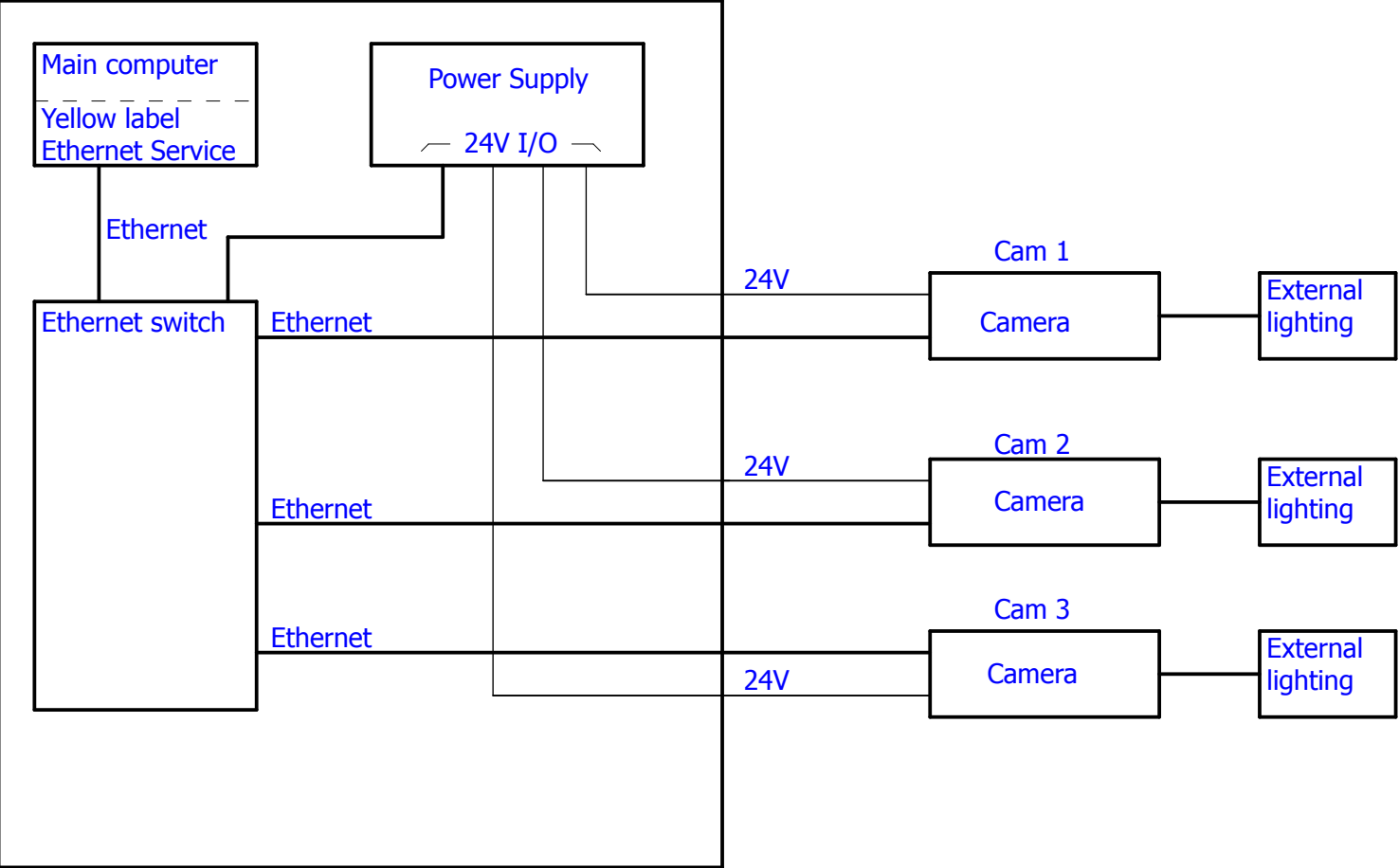
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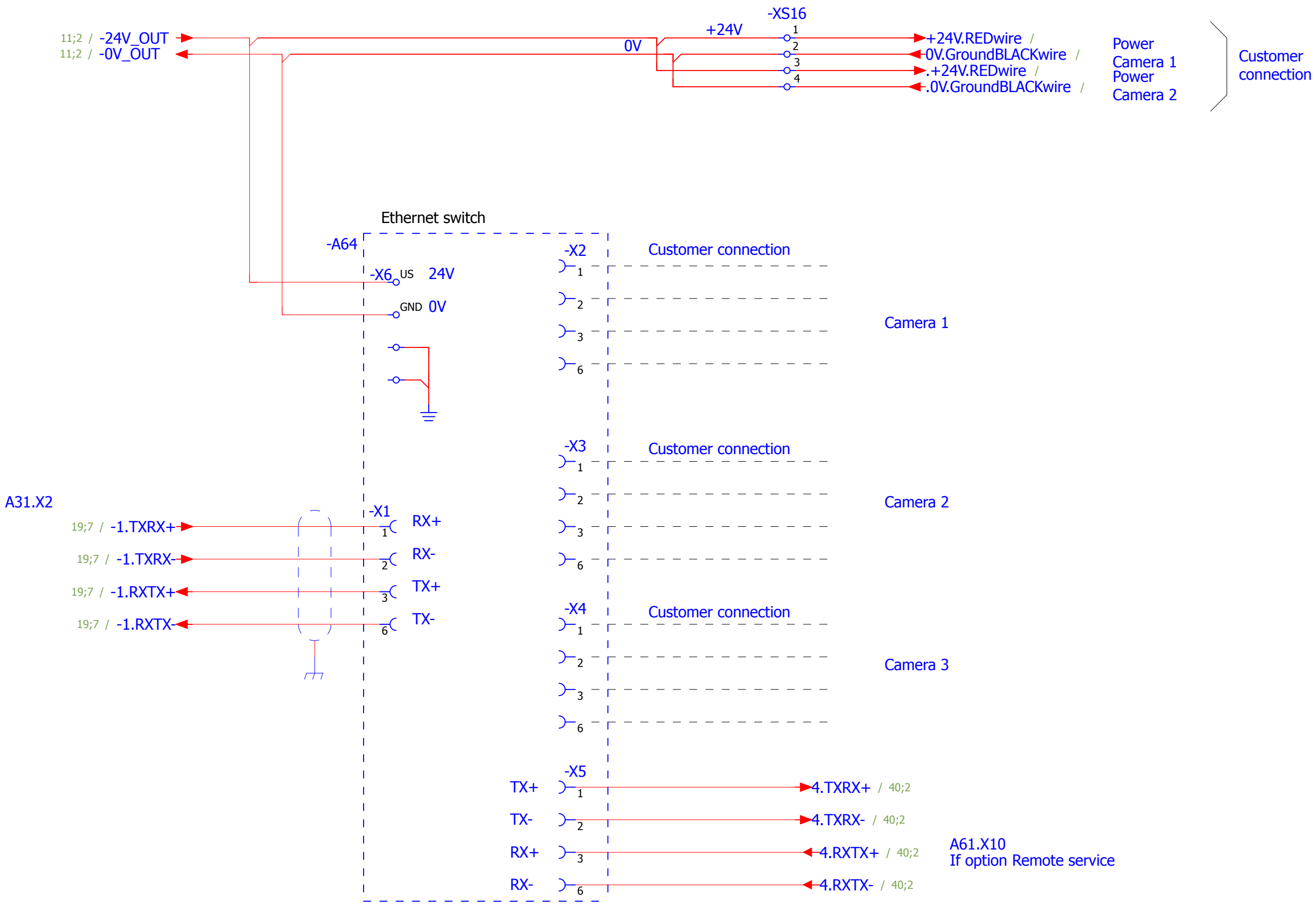
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- 2) RESISTANS 120 OHM SHALL ALWAYS BE CONNECTED IN THE FIRST AND THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT.
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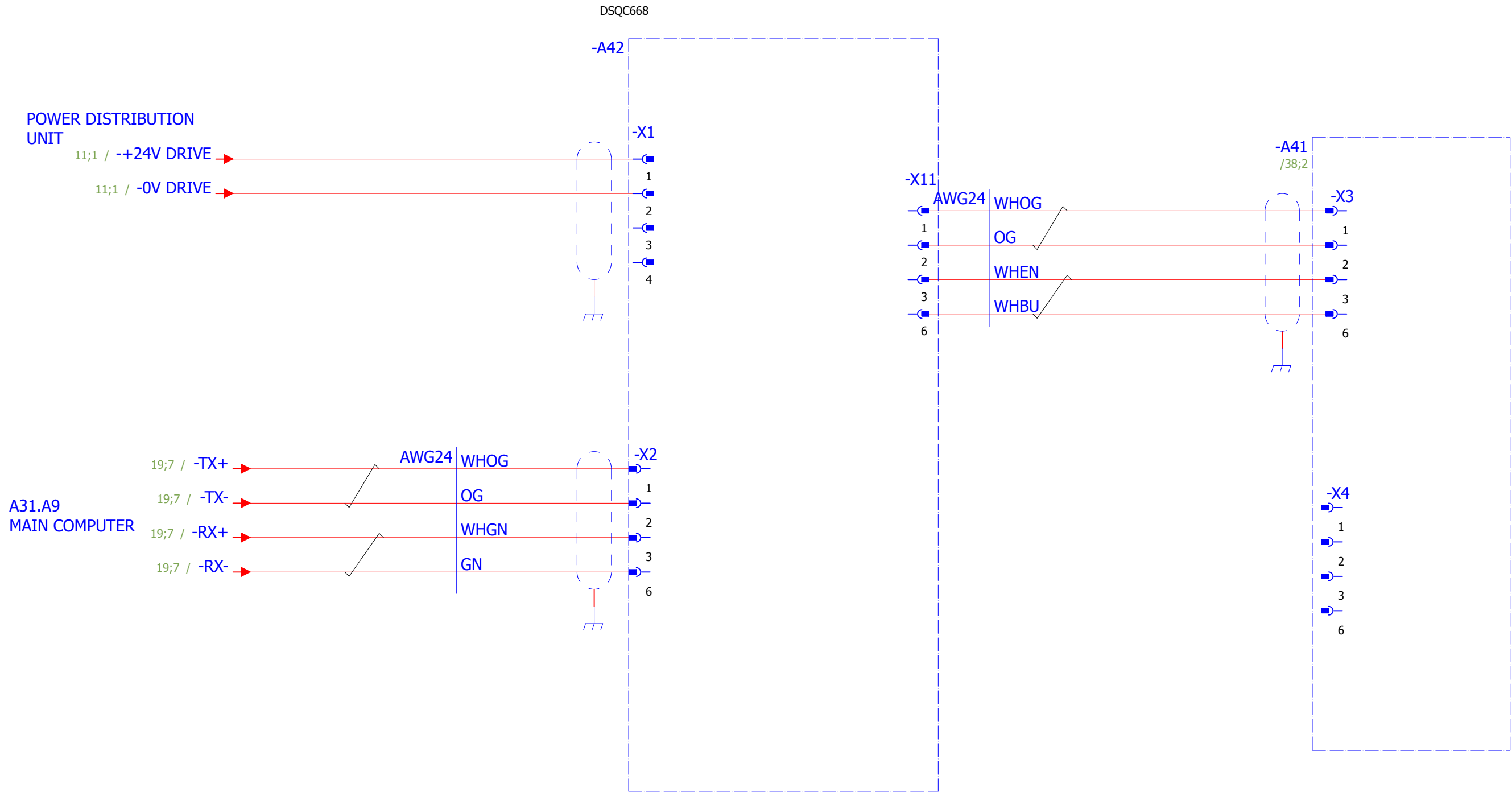
Robot controller



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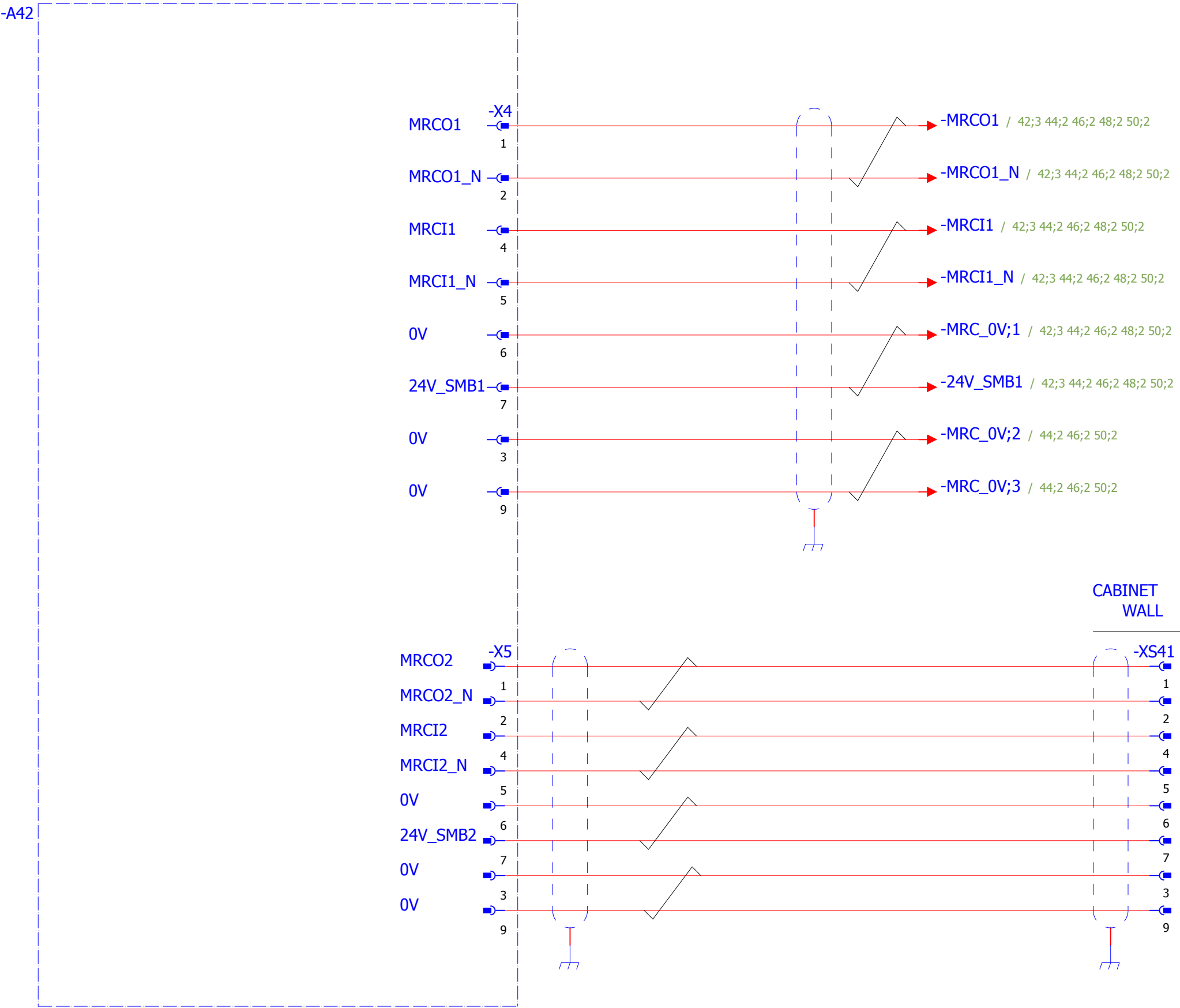


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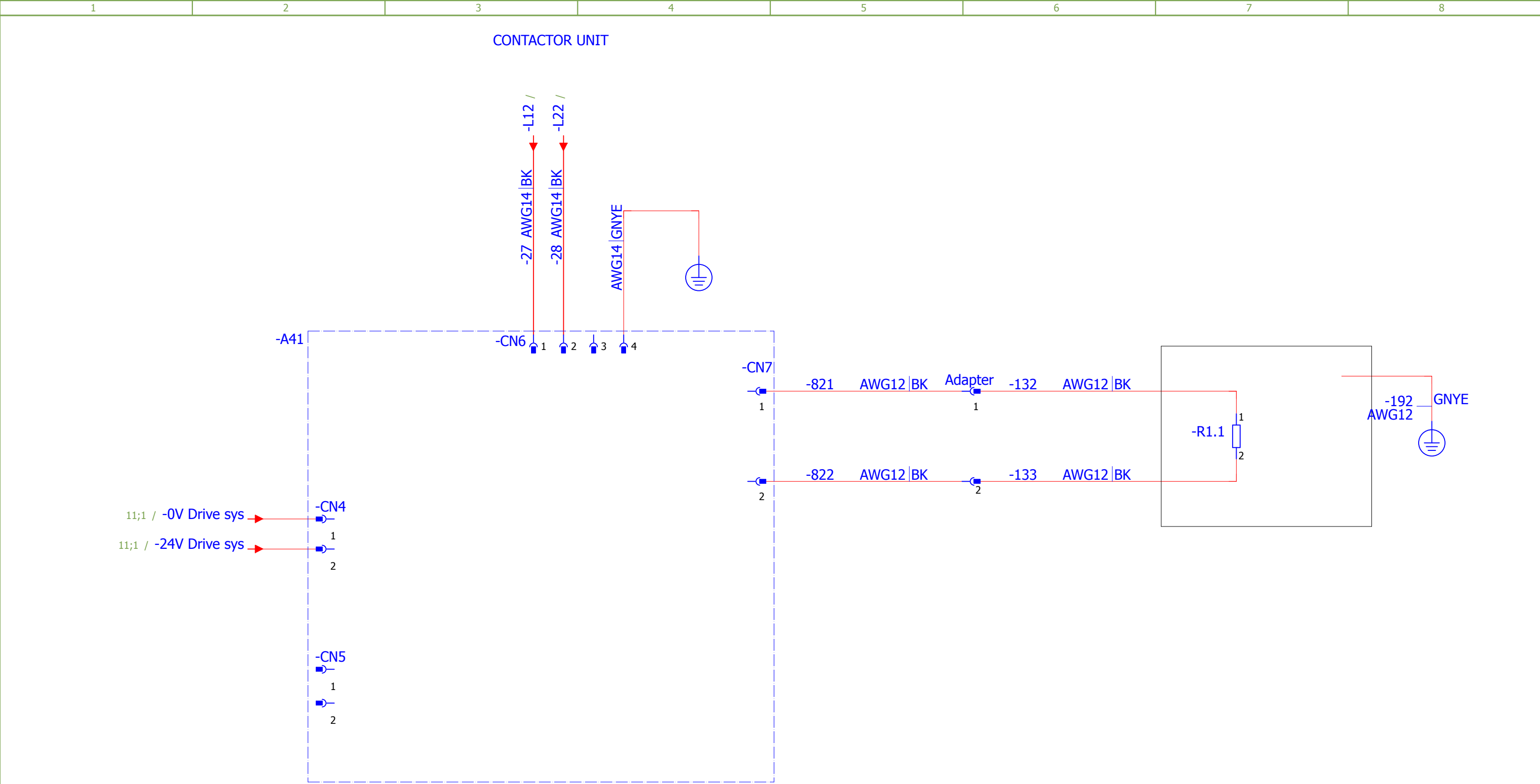


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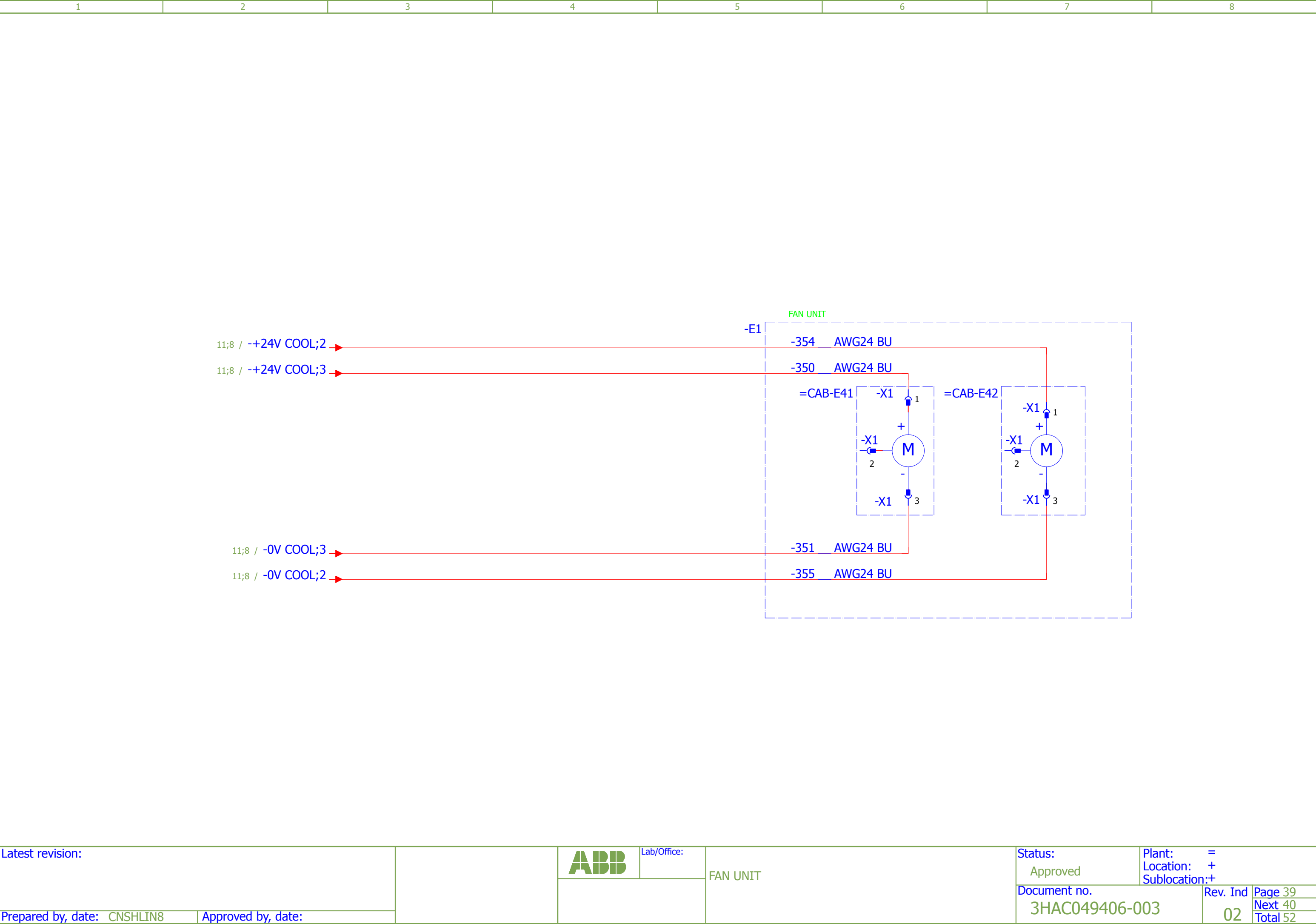


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Wire No.	Single phase
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28	N
29	

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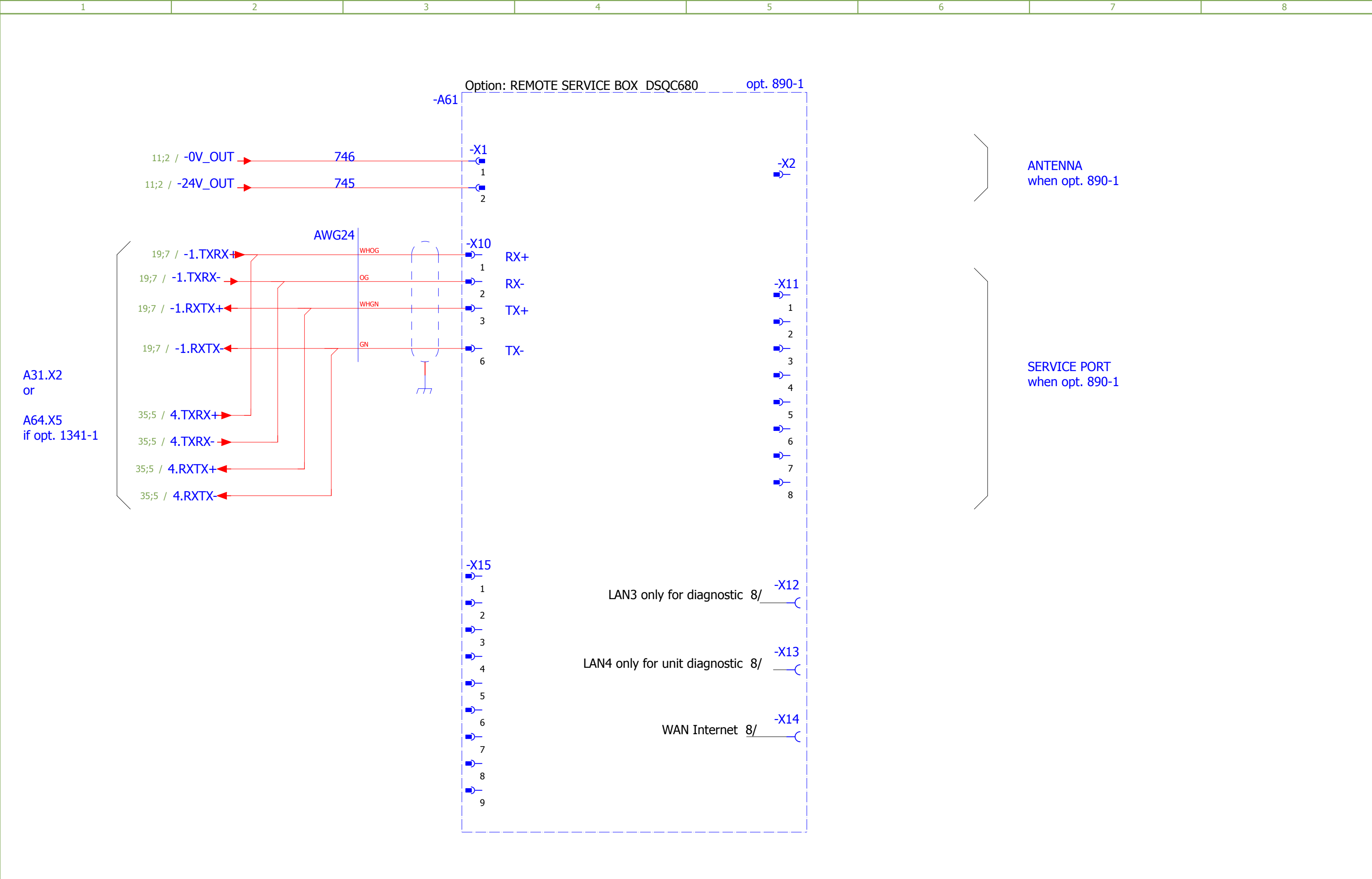
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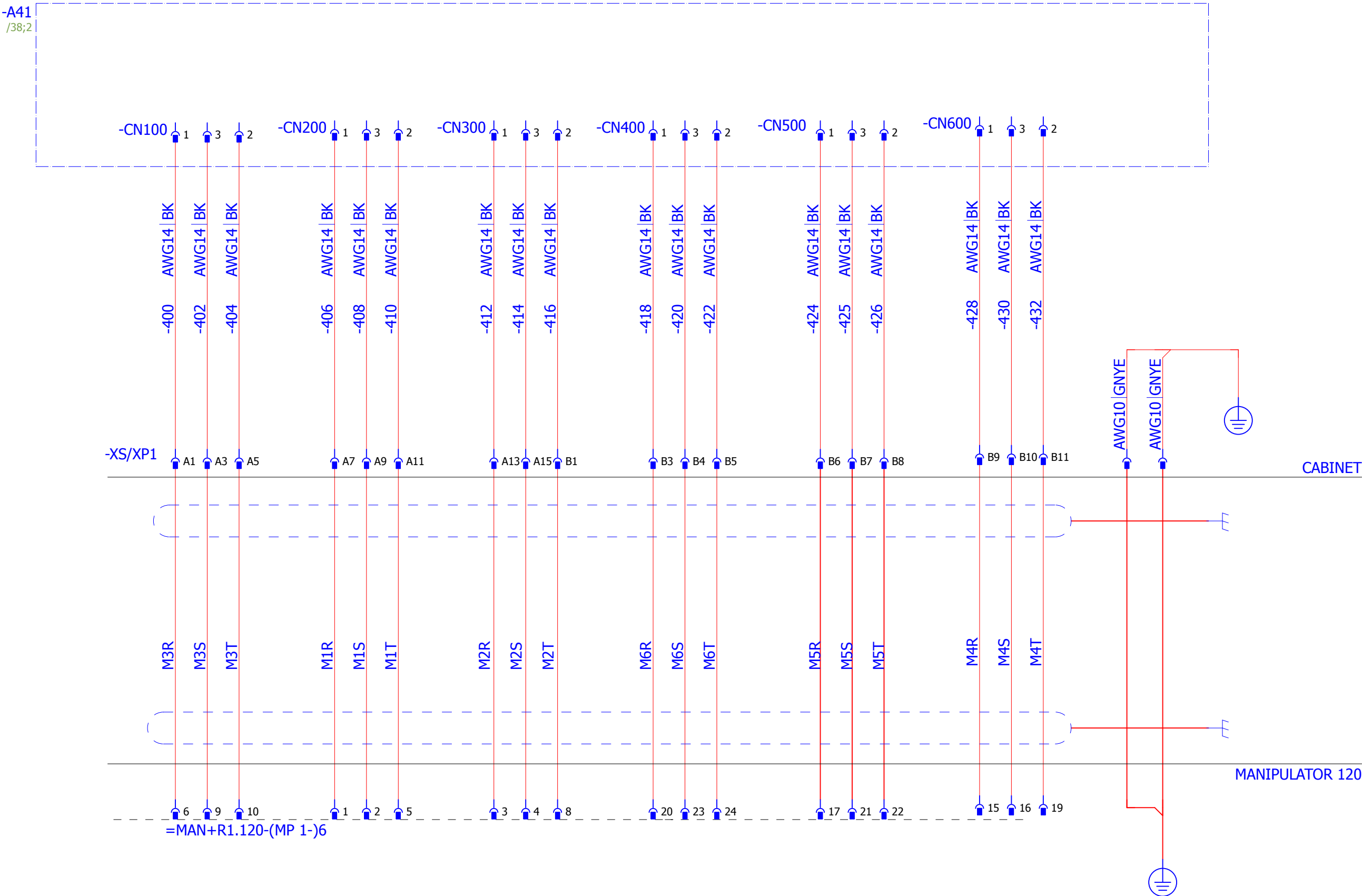
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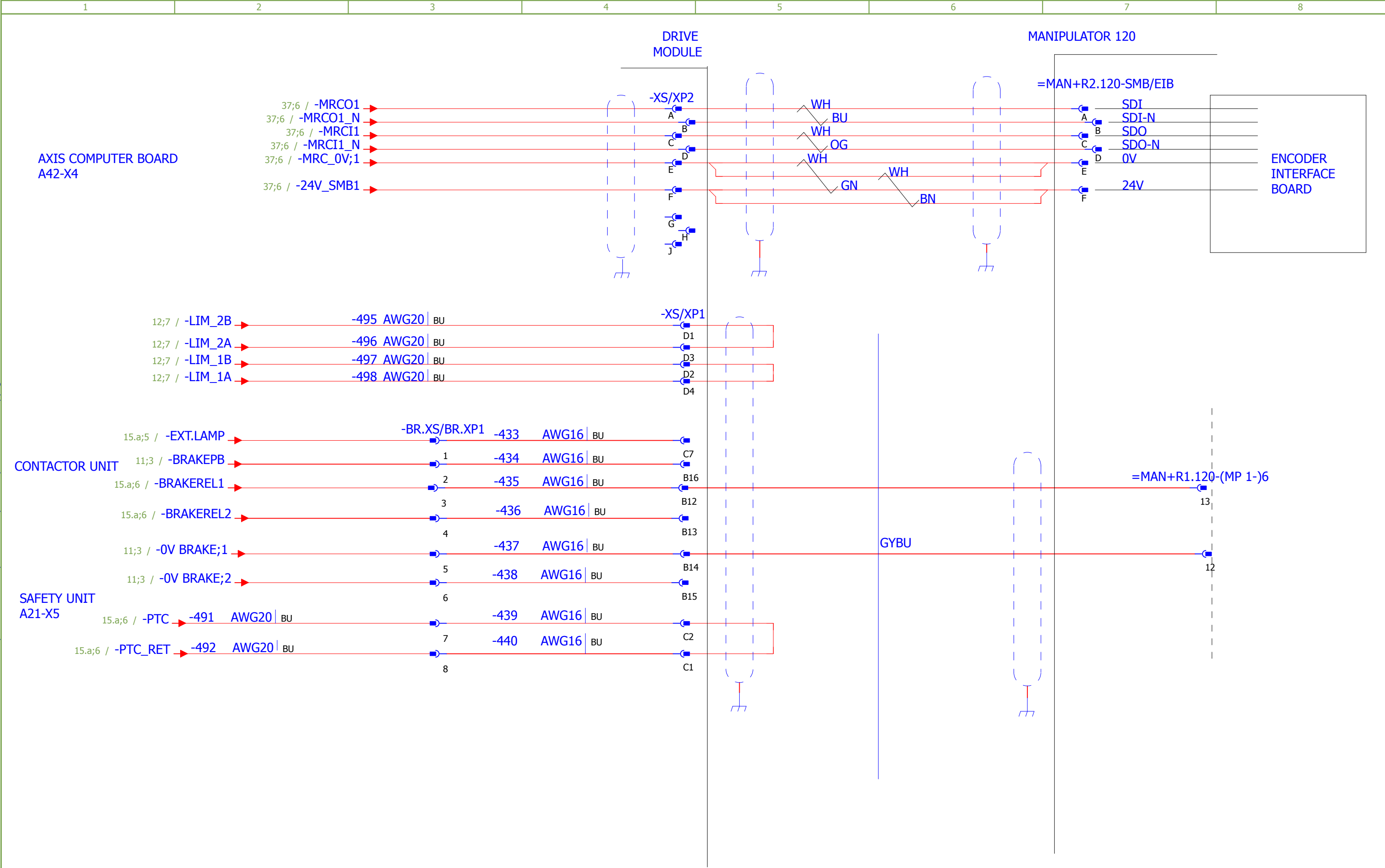
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IRB 120 cabinet module

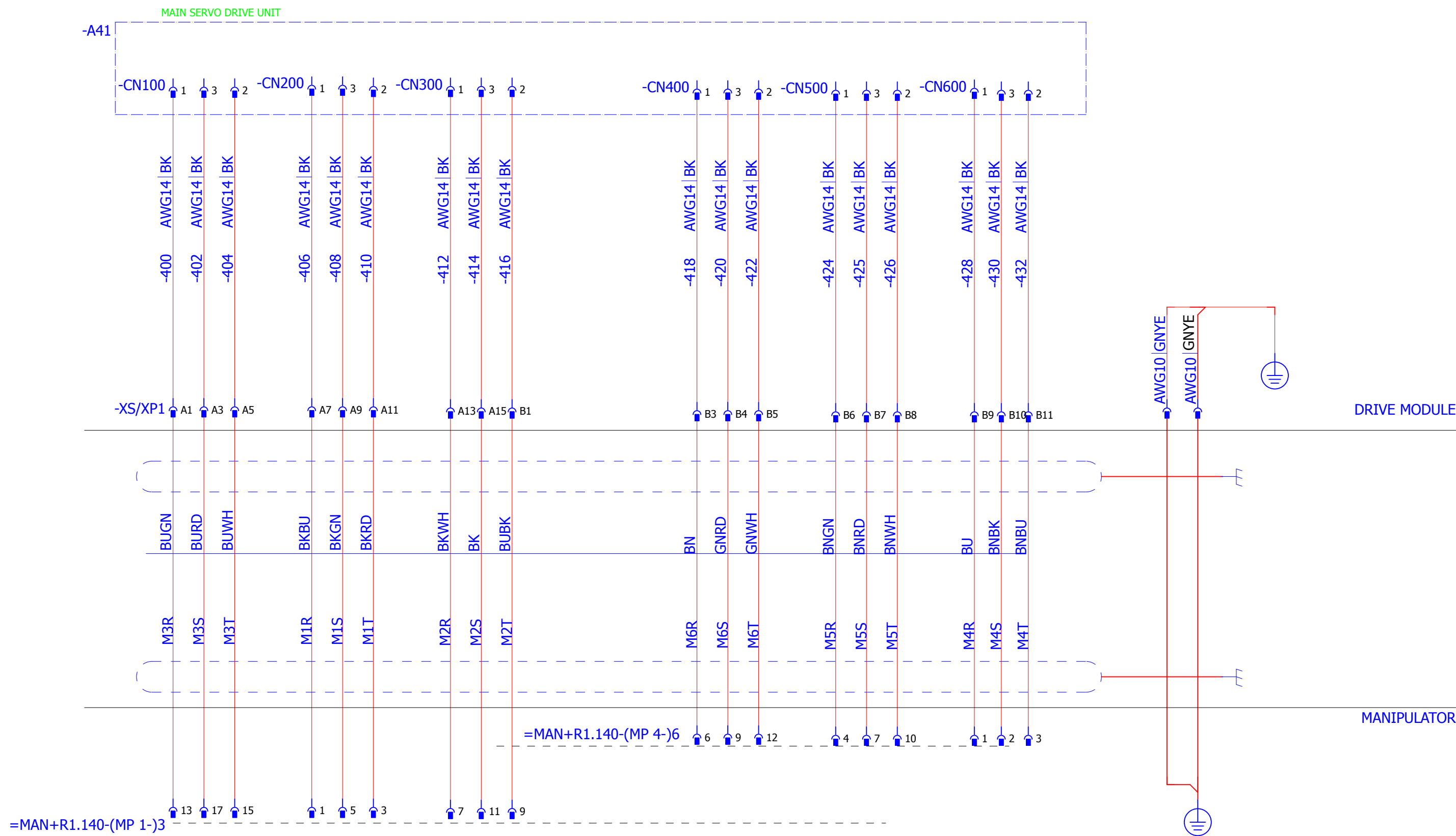


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IRB 140 cabinet module



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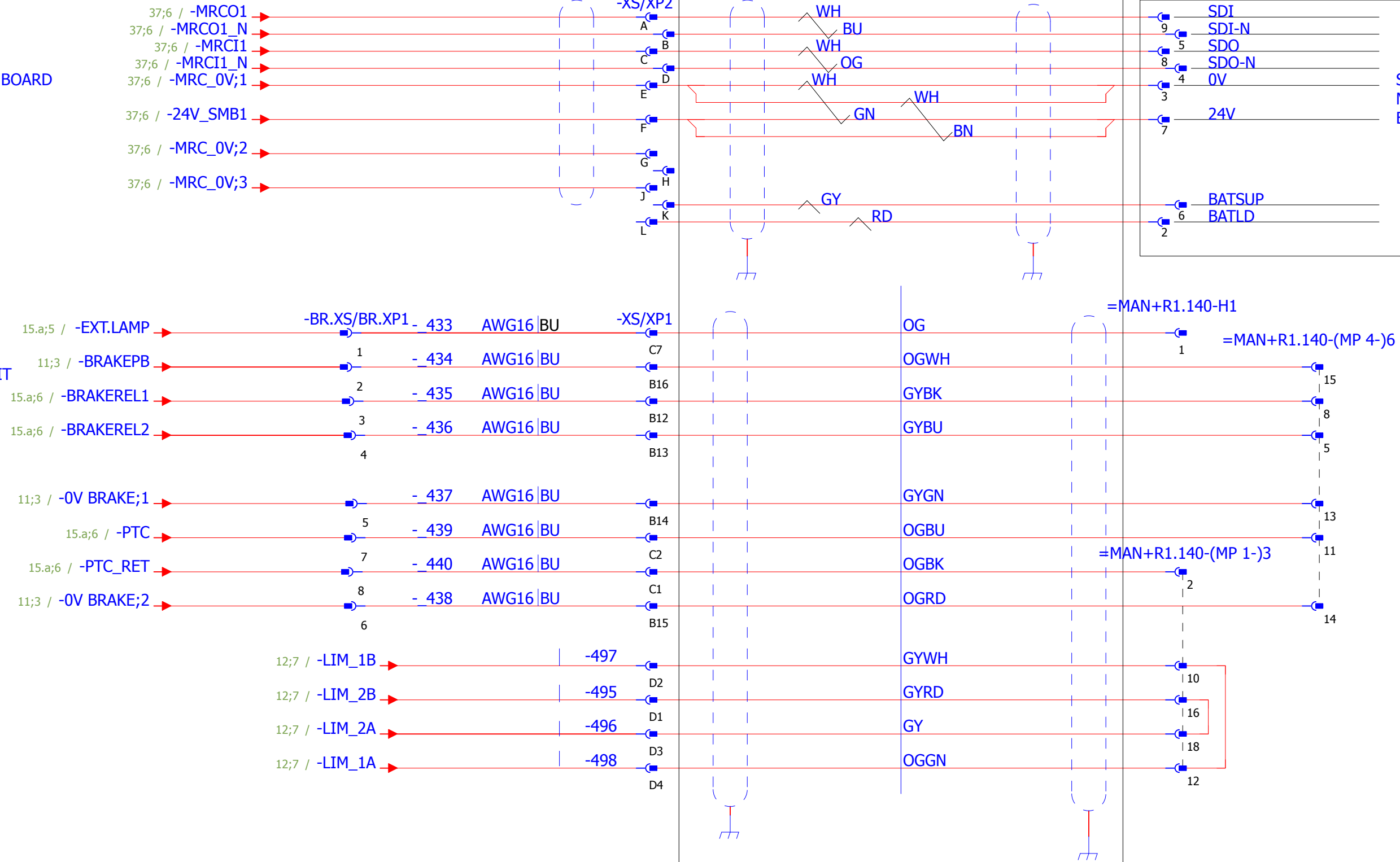
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A42-X4

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SAFETY UNIT
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DRIVE
MODULE

MANIPULATOR



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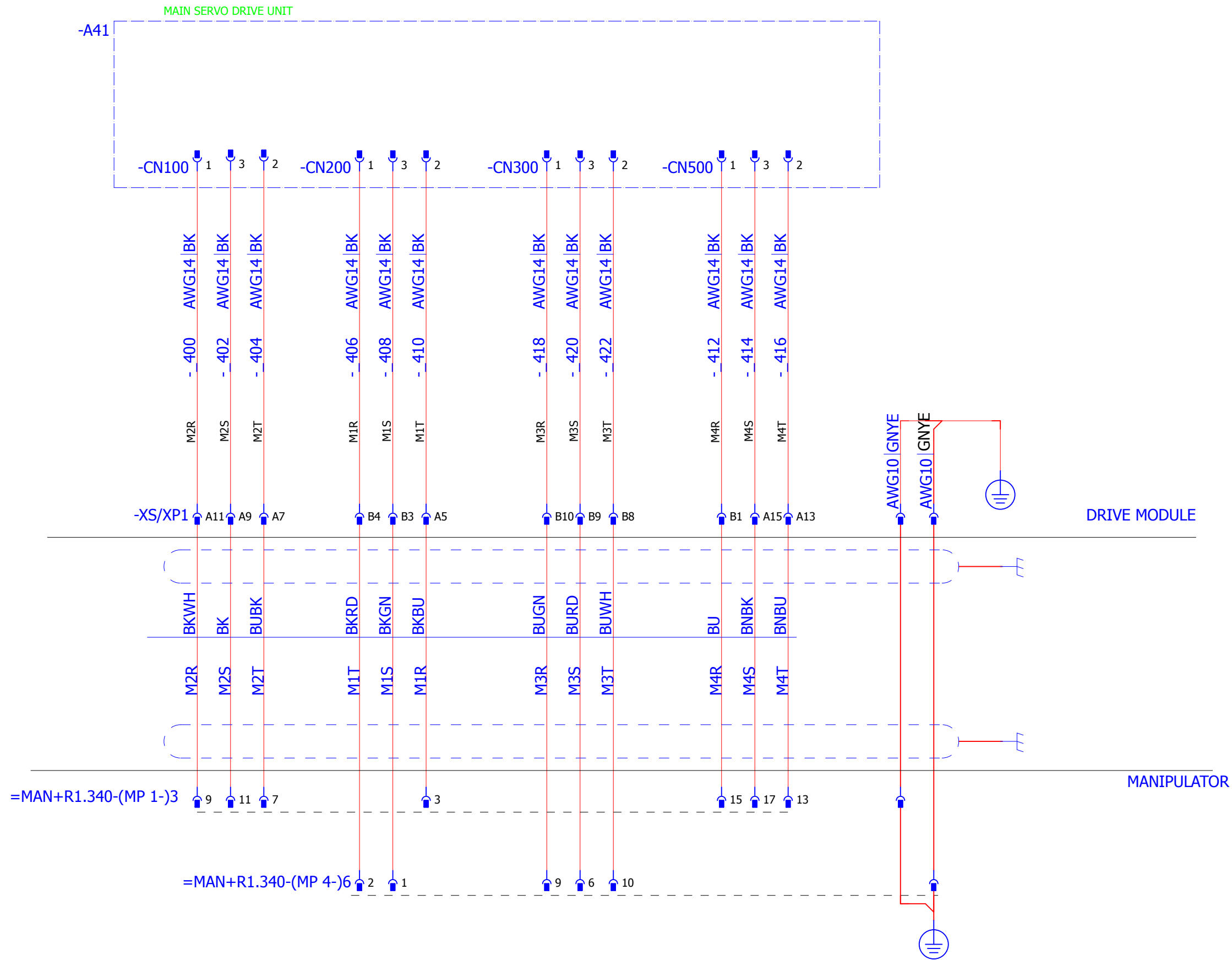
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IRB 360 cabinet module



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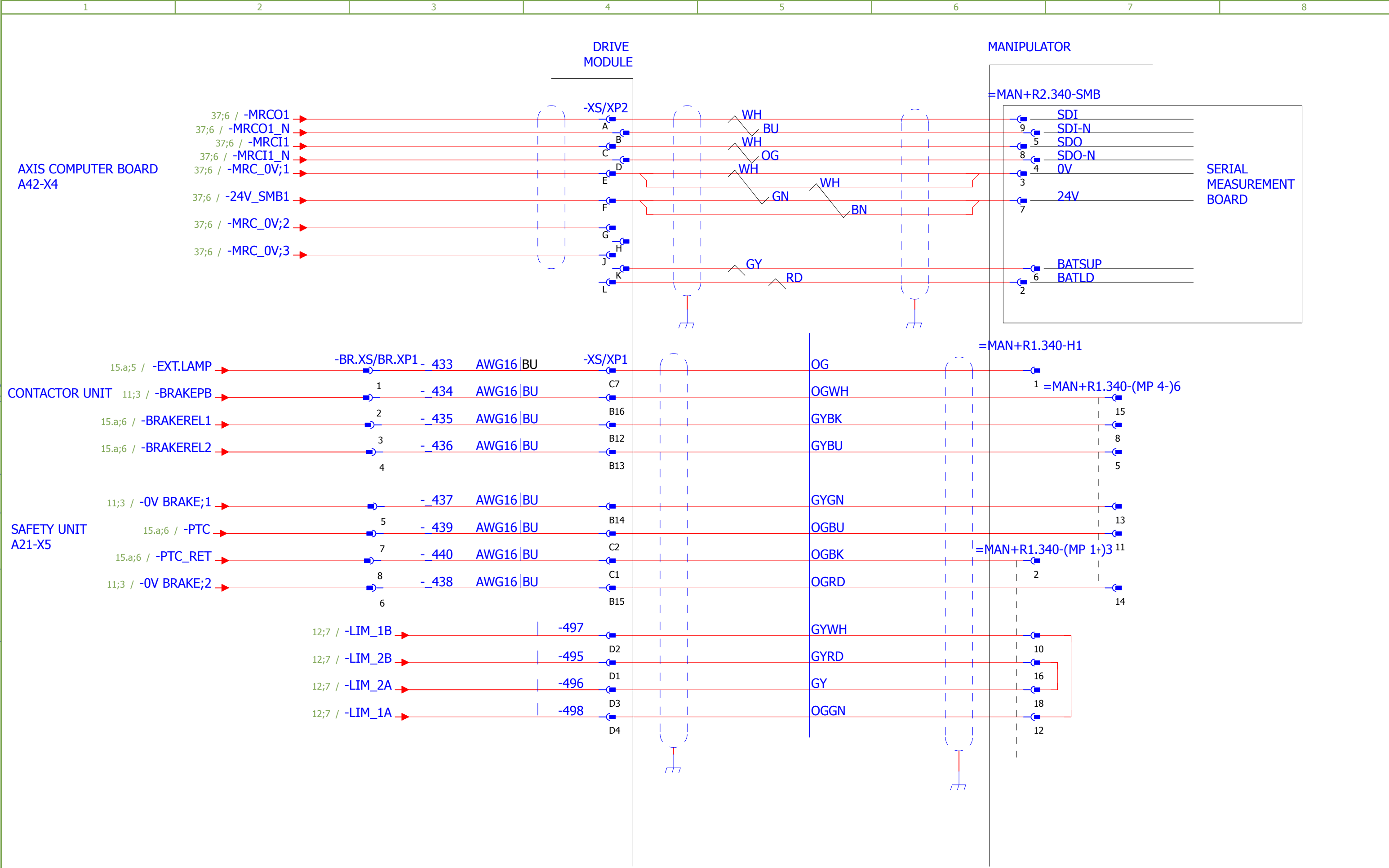
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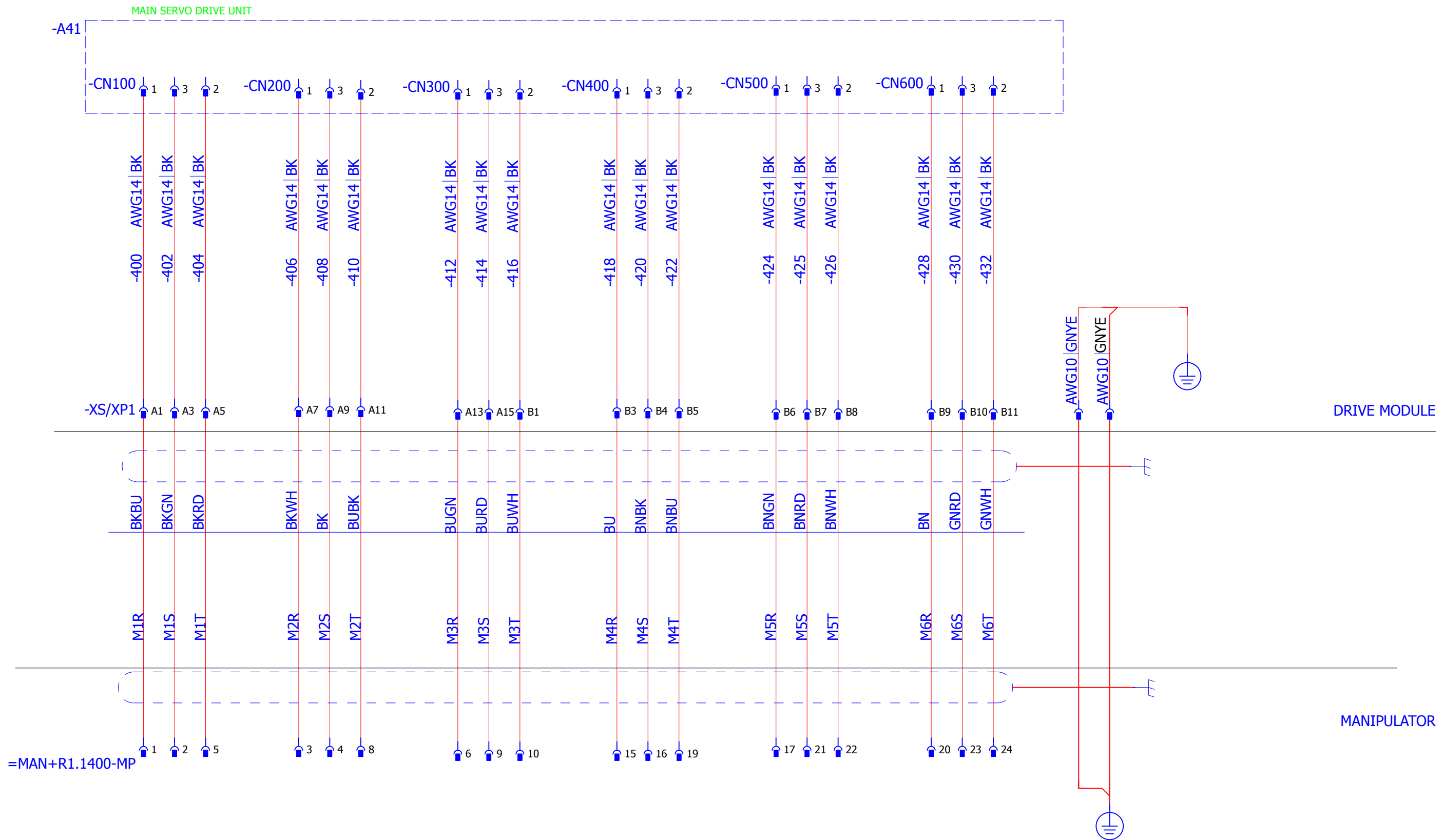
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IRB 1200 cabinet module



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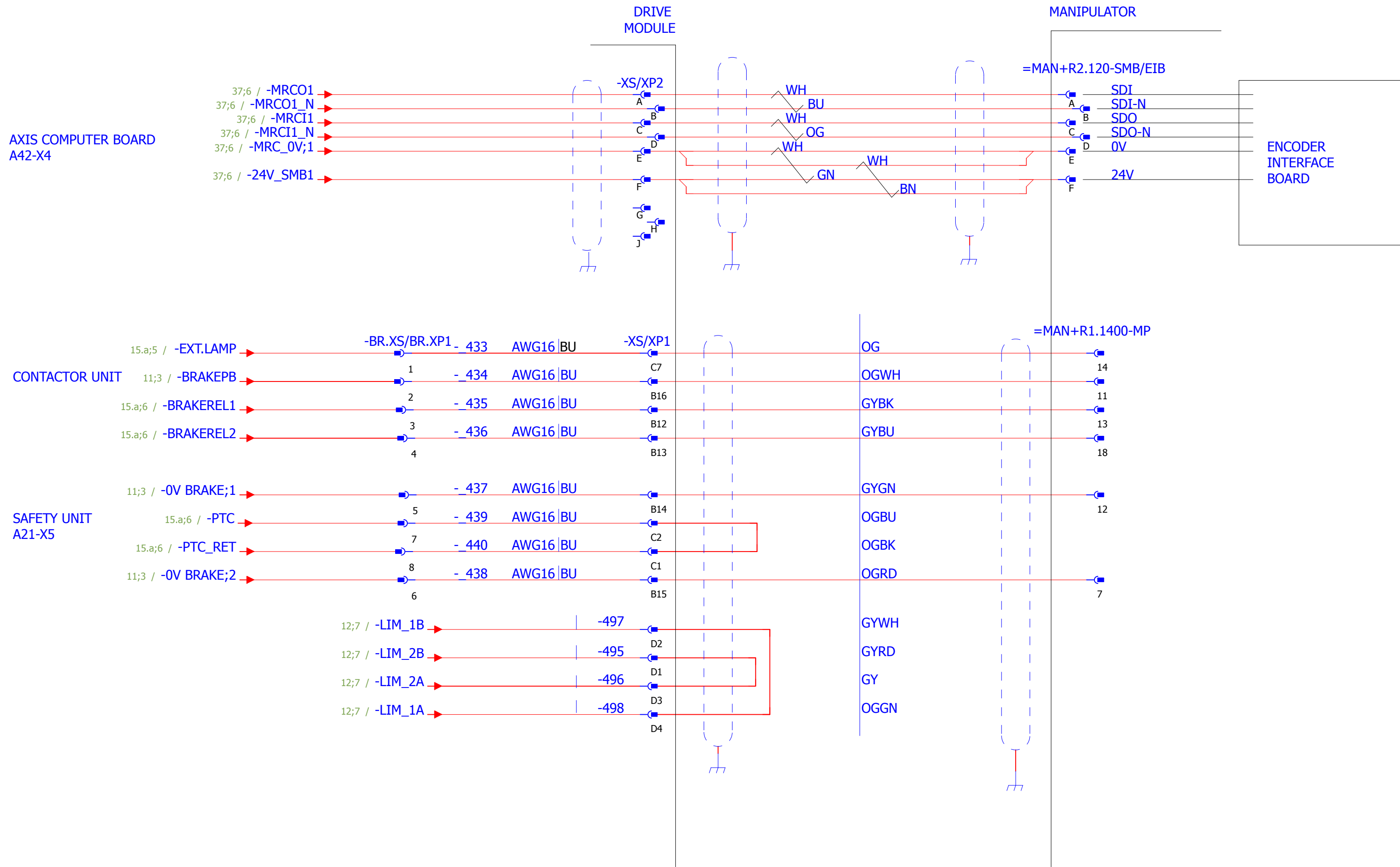
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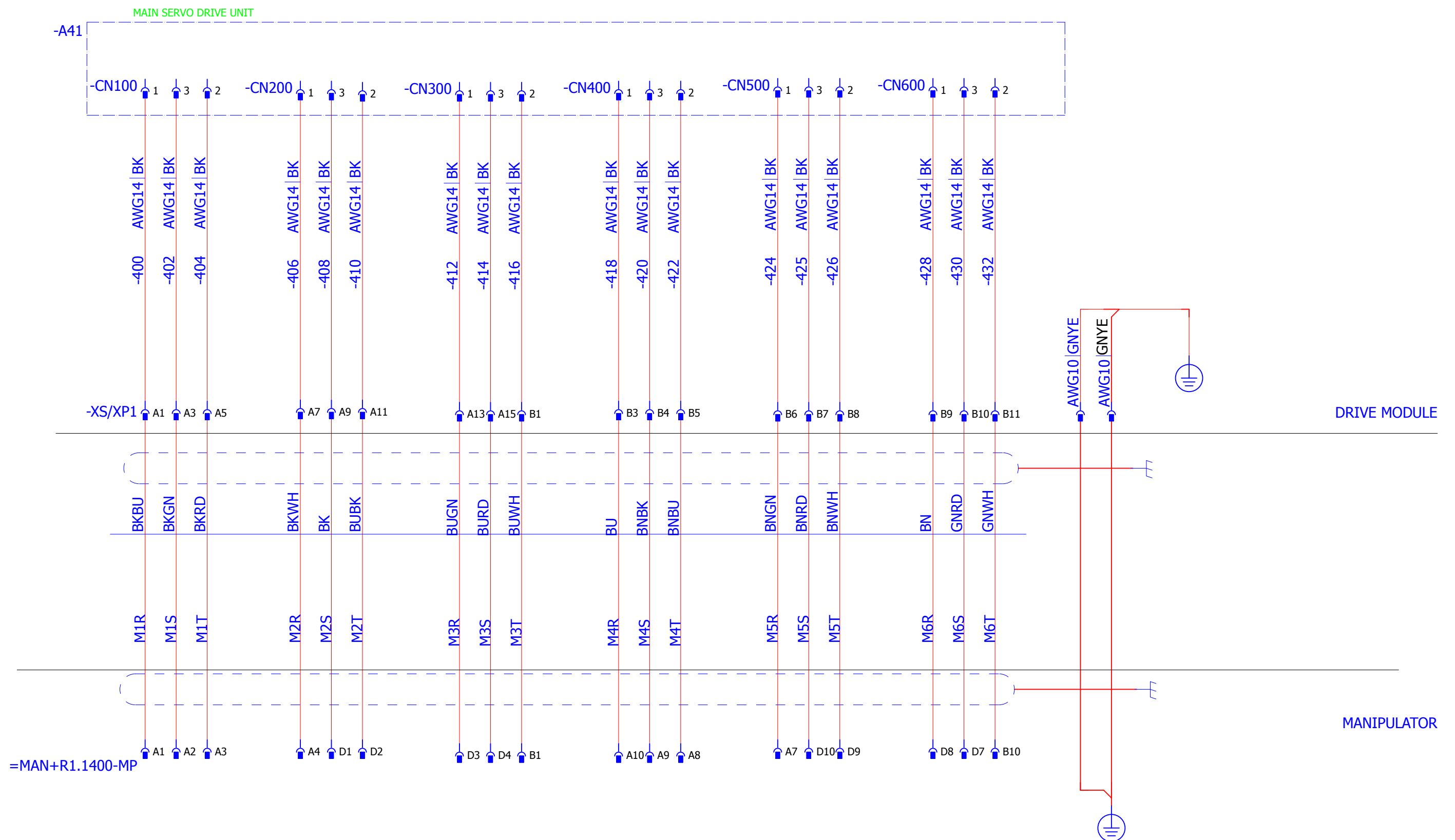
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IRB 1410, 1600, 260 cabinet module



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