EPSON LS-Series



LS3 / LS6 SCARA Robots

- Fast Cycle Throughput
- Industry Leading Ease of Use
- Compact Footprint Robot
- Arm Lengths from 400 to 600mm
- ISO 4 Clean Compliant Models
- Fully Integrated Options including: Vision Guidance, .Net Connectivity, DeviceNet, Profibus, Expansion I/O and more





Fast, Compact and Low Cost

Epson LS-Series robots were created as the reduced cost solution for factories looking for maximum value without giving up performance. But as with all Epson Robots, they are still packed with the same performance and reliability our users have come to expect from Epson. In addition, Epson LS-Series robots are able to meet the demanding space requirements in factories today by providing a small footprint solution with superior workspace usage. With outstanding cycle times, industry leading ease of use and of course Epson reliability, they are the robots of choice for high speed applications where superior performance is required at a value price.

All EPSON LS-Series SCARA robots are available with our low cost, high performance RC90 Controller that provides the ultimate experience in ease of use and reliability all at an incredibly low price. Why choose a low performance solution when you can have a high performance EPSON LS-Series SCARA robot with powerful EPSON controls?

LS-Series robots are ideally suited for applications and industries requiring demanding cycle times, high precision and high reliability such as: hard disk assembly, electronics, medical device assembly, lab automation, photonics, semiconductor, telecommunications and many more.





LS-Series Specifications



| EPSON ROBOTS | | | LS3-401x | LS6-602x |
|---|----------|----------------------|--|------------------------|
| Arm Length (mm) | | Horiz. (J1 + J2) | 225 + 175 = 400 | 325 + 275 = 600 |
| Payload (kg) | | Max. / Rated | 3/1 | 6/2 |
| Repeatability | mm | J1 + J2 | +/-0.01 | +/- 0.02 |
| | | J3 | +/-0.01 | |
| | deg | J4 | +/-0.01 | |
| Cycle Time w/ 1kg (sec) | | | 0.42 | 0.39 |
| Max. Operating Speed | mm/sec | J1 + J2 | 6,000 | 6,800 |
| | | J3 | 1,100 | |
| | deg/sec | J4 | 2,600 | 2,000 |
| Motor Wattage (W) | | | 200 / 100 / 100 / 100 | 200 / 200 / 100 / 100 |
| Insertion Force | | | 100N | |
| U inertia | kg_m² | Max. / Rated | 0.05 / 0.005 | 0.12 / 0.01 |
| Axis Motion Range | J1 (deg) | | +/-132 | |
| | J2 (deg) | | +/-141 | +/- 150 |
| | J3 (deg) | Std / Clean | 150 / 120 | 200 / 170 |
| | J4 (mm) | All | +/-360 | |
| User Lines Electric Air | | 15 lines | | |
| | | ø4 x 1, ø6 x 2 | | |
| Z Axis Diameter (mm) | | | ø16 | ø20 |
| Mounting Hole Footprint (mm) | | | 120 x 120 (4-M8) / 120 x 135 | 150 x 150 (4-M8) |
| Weight (kg) | | 14 | 17 | |
| Environmental Humic | | Temperature | 5 - 40 deg C | |
| | | Humidity | 10 - 80% (non condensing) | |
| Optional Arm Mounting Type Configurations Clean | | Tabletop | | |
| | | Clean | ISO 4 Clean | |
| Robot Cables (Meters) | | | 3M (standard) / 5M (optional) / 10M (optional) | |
| Available Controllers | | | RC90 | |
| Options | | | Vision Guide | External Control Point |
| | | | Teach Pendant (TP2) | (ECP) |
| | | | • Fieldbus I/O | VB Guide |
| | | (DeviceNet, Profibus | Expansion I/O | |
| | | | and CC-Link) | • RS-232C |

EPSON Robots

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