

Incremental Encoder

Series TRD-N

Operation Manual

Thank you for purchasing this series TRD-N Incremental Encoder. Please read this Operation Manual carefully before applying this product.

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KEW-M8166D-E

Safety Consideration

!\Warning

This indicates contents which can cause large accidents leading to loss of life or severe injury when the indication is disregarded and wrong handling is executed.

This indicates contents which can cause injury or material damage when the indication is disregarded and wrong handling is executed.

Explanation of the pictograms

This symbol indicates a general prohibition.

This symbol indicates a compulsory item or an instruction.

[Operating environment and conditions]

Warning

- Do not use in a combustible or explosive atmosphere. Otherwise personal injury or fire may be caused.
- Do not use this product for applications related to human safety. Use is assumed in an application where an accident or incorrect use will not immediately cause danger to humans.

[Operating environment and conditions]

!Caution

Use and store the equipment within the scope of the Environment (vibrations, impact, temperature, humidity, etc.) specified in the

Otherwise fire or product damage may be caused.

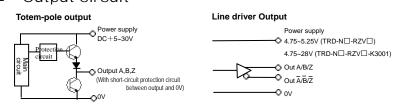
Understand the product first before use it.

[Installation and wiring]

Warning

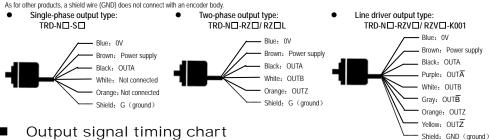
- Use only with the power supply voltage listed in the specifications. Otherwise fire, electric shock, or accidents may be caused.
- Use only with the wiring and layout specified in the specifications. Otherwise fire, electric shock, or accidents may be caused.
- Do not apply any kind of stress to the wires. Otherwise electric shock or fire may be caused

Output circuit



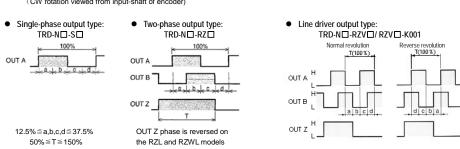
Connection

More than 2501P/R, two-phase output type and Line driver output type, a shield wire (GND) is connected to the encoder's body.



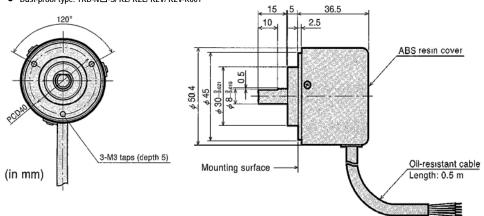
Output signal timing chart

(CW rotation viewed from input-shaft of encoder)

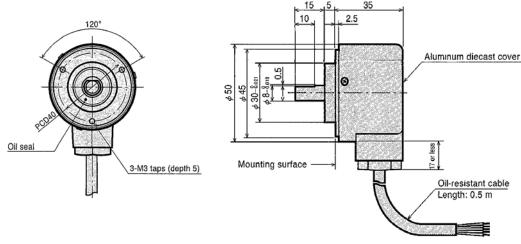


External dimensions

● Dust-proof type: TRD-N□-S/ RZ/ RZL/ RZV/ RZV-K001

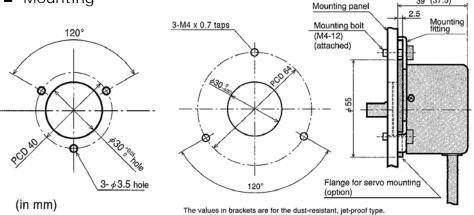


Dust-resistant, jet-proof type: TRD-N□-SW/ RZW/ RZWL/ RZVW/ RZVW-K001



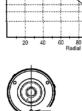
<u>39 (3</u>7.5)

Mounting



Electrical specifications

	Type No.		$TRD-N\Box-S\Box$	$TRD-N\Box-RZ\Box/RZ\Box L$	$TRD-N\Box-RZV\Box$	TRD-N□-RZV□-K001**1	 Bearing life
Power supply	Operating voltage		DC4.75V~30V	DC4.75V~30V	DC4.75V~5.25V	DC4.75V~28V	€10
	Allowable ripple		≤3%rms	≤3%rms	≤3%rms	≤3%rms	(Superpose of the Cx Log and L
	Current consumption (no load)		≤40mA	≤60mA	≪60mA	≤40mA	20 10 20
Output waveform	Signal format		Single-phase output	Two-phase output with origin	Two-phase output with origin	Two-phase output with origin	ž
	Max. response frequency		100kHz	100kHz	100kHz(200kHz:about 4096P/R)	100kHz	Bu 1
	Max. response rotating speed		(Maximum response frequency/Pulse)×60	(Maximum response frequency/Pulse)×60	(Maximum response frequency/Pulse)×60	(Maximum response frequency/Pulse)×60	
	Duty rate		50±25%	50±25%	50±25%	50±25%	
	Origin signal width		_	100±50%	100±50%	100±50%	20 40 60 80
Output	Rising/falling time × 2		≤3µs	≤3µs	≤2μs (≤2µs	Radial loa
	Output configuration		Totem-pole output	Totem-pole output	Line driver output (26C31 or equivalent)	Line driver output (OL7272 or equivalent)	
	Output logic		Positive logic (active high)	Positive logic (active high)	Positive logic (active high)	Positive logic (active high)	(((\Phi))))
	Output current	Inflow	≤30mA	≤30mA	-	=	
		Outflow	≤10mA	≤10mA	_	_	
	Output voltage	"H"	≥[(Power supply voltage)— 2.5V]	≥[(Power supply voltage)— 2.5V]	≥2.5V	≥[(Power supply voltage) — 4V] (non-loaded)	Origin position
		"L"	≤0.4V	≤0.4V	≤0.5V	≤2V (non-loaded)	Adjustment is made by
	Load power supply voltage		≤DC35V	≤DC35V			mounting hole on the cable of
	Short-circuit protection		(With short-circuit protection of	circuit between output and 0V)	_	_	side and the shaft notch (fa down).



Mechanical specifications

	Starting torque	$\label{eq:max.0.003N · m (+20 °C)} \mbox{(0.02N-m for the dust-resistant, jet-proof type.)}$	
	Shaft moment of inertia	2×10 ⁻⁶ kg • m ²	
		Radial : 50N	
N	lax. allowable shaft load	Thrust: 30N	
	Max. allowable speed	5000rpm (for the dust-resistant, jet-proof type: 3000rpm continuously and 5000rpm momentarily.)	
	Material	Oil-resistant shielded cable %1	
Cable	Nominal core cross section	0.3mm ² (Line driver: 0.14mm ²)	
	External diameter	Φ6.0mm	
We	ight (With 0.5m cable.)	Approx. 150g (Approx.200g for the dust-resistant, jet-proof type.)	

Environmental requirements

	Operation: −10~+70°C				
Ambient temperature	Store: −25~+85°C				
Ambient humidity	35~85%RH (non-condensing)				
Withstand voltage	AC500V (50/60Hz) for 1 min	A power supply, signal Line and a case			
Insulation resistance	50MΩ min.	Interval. Shield Line does not include i			
Vibration resistance	10 \sim 55Hz with 0.75mm amplitude \divideontimes 2				
Shock resistance	~500P/R(metal slit),980m/s², 11ms%3				
Shock resistance	600P/R~(glass slit),490m/s², 11ms%3				
Protection	IP50: Dust-proof proofed				
construction	IP65: Dust-resistant, jet-proof type				

%1: TRD-N□-S□/RZ□: 5-core oil-resistant shielded cable

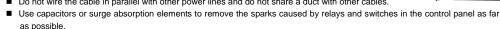
TRD-N□- RZV□/ RZV□-K001: 8-core oil-resistant shielded cable

※2: Durable for 1h along 3 axes %3: Applied 3 times 3 axes

- It is an examination condition, and it is not a thing to guarantee for consecutive us

Cautions for use





Be sure to connect all wires properly, as wrong wiring can damage the internal circuitry.

- Erroneous pulses may be caused at the time of power ON and power OFF. After power ON, wait for at least 0.5 sec. before
- Do not disassemble the product. Do not expose the product for a long time to water, even if it is a dust-resistant, jet-proof type. Wipe off any water getting onto the product.
- As the rotary encoder is composed of precision parts, its function will be impaired when it is subjected to shocks. Use sufficient care for handling and mounting.

